

Reaction-controlled diffusion: Monte Carlo simulations

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We study the coupled two-species nonequilibrium reaction-controlled diffusion model introduced by Trimper *et al.* [Phys. Rev. E **62**, 6071 (2000)] by means of detailed Monte Carlo simulations in one and two dimensions. Particles of type A may independently hop to an adjacent lattice site, provided it is occupied by at least one B particle. The B particle species undergoes diffusion-limited reactions. In an active state with nonzero, essentially homogeneous B particle saturation density, the A species displays normal diffusion. In an inactive, absorbing phase with exponentially decaying B density, the A particles become localized. In situations with algebraic decay $\rho_B(t) \sim t^{-\alpha_B}$, as occurring either at a nonequilibrium continuous phase transition separating active and absorbing states, or in a power-law inactive phase, the A particles propagate subdiffusively with mean-square displacement $\langle \vec{x}(t)_A^2 \rangle \sim t^{1-\alpha_A}$. We find that within the accuracy of our simulation data, $\alpha_A \approx \alpha_B$ as predicted by a simple mean-field approach. This remains true even in the presence of strong spatiotemporal fluctuations of the B density. However, in contrast with the mean-field results, our data yield a distinctly non-Gaussian A particle displacement distribution $n_A(\vec{x}, t)$ that obeys dynamic scaling and looks remarkably similar for the different processes investigated here. Fluctuations of effective diffusion rates cause a marked enhancement of $n_A(\vec{x}, t)$ at low displacements $|\vec{x}|$, indicating a considerable fraction of practically localized A particles, as well as at large traversed distances.

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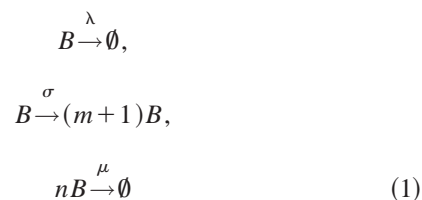
I. INTRODUCTION

The goal of statistical mechanics is to understand the relationship between microscopic and macroscopic dynamics in systems consisting of a large number of degrees of freedom. One classical success of the equilibrium formalism is the prediction of universal phase transition behavior: independent of the microscopic details of their interactions, systems with identical *overall* features, governed by their symmetries, spatial dimension d , and perhaps large-scale interaction properties, display very similar phase diagrams. Moreover, their critical points are characterized by the same small set of independent scaling exponents. Thus physical systems with very complicated interactions can often be adequately described by considerably simplified models, which in turn form the basis of simulation studies and numerical analysis.

Here we investigate a simple coupled reaction-diffusion system, which however leads to remarkably rich features. More specifically, the spatiotemporal fractal structures emerging at a *nonequilibrium* critical point of a reacting species B impose nontrivial scaling behavior onto the propagation of passive random walkers A , whose propagation is however limited to sites occupied by at least one B particle. One may envision this system to model virus (represented by the A particles) propagation in a carrier B population that is set close to its extinction threshold; the virus remains dormant when there are no B organisms present. Below, we shall encounter and characterize the ensuing scaling laws by means of Monte Carlo simulations, and compare our numerical results with the predictions of a mean-field approximation.

In nonequilibrium systems, the detailed balance conditions are violated; i.e., the probability of at least one closed loop of transitions between microscopic configurations depends upon the direction the loop is traversed. This is the case even in stationary states in open systems, through which a steady particle or energy current from the outside is maintained. Outside physics nonequilibrium models may describe, for example, population dynamics, chemical catalysis, and financial markets. Yet reassuringly, universal behavior has also been found to persist for nonequilibrium models that display phase transitions between different stationary states.

Prominent examples are continuous transitions between active and inactive/absorbing states in diffusion-limited "chemical" reactions [1]. The class of models we will be studying involves competing annihilation and offspring reactions of a single species B , performing unbiased random walks on a d -dimensional hypercubic lattice:



with integers $m \geq 1$, $n > 1$. For large branching rate σ , the system is in an active state with a nonzero and essentially homogeneous particle density. In contrast, when the decay processes with rates λ and μ dominate, the B particle density reaches zero, and the dynamics ceases entirely in this inactive, *absorbing* state. By appropriately tuning the reaction

rates a continuous phase transition between these two stationary states can be observed [2].

Generically, such transitions fall into the *directed percolation* (DP) universality class [3] with upper critical dimension $d_c=4$. The standard example is represented by the Gribov process $B \rightarrow \emptyset$, $B \rightleftharpoons 2B$. Equivalently, one may use scheme (1) with $m=1$ and $n=2$. Directed percolation was initially devised to characterize the transition from finite- to infinite-sized clusters in directed media (such as a porous rock in a gravitational field) [4]. Other applications include certain models of catalytic reactions, interface growth, turbulence, and the spread of epidemics [5]. Experimental evidence for DP critical behavior was recently observed in spatiotemporal intermittency in ferrofluidic spikes [6].

For active to absorbing state phase transitions in single-species reactions that include first-order processes, in the absence of memory effects and quenched disorder, the so-called *parity conserving* (PC) universality class appears to represent the only scenario for non-DP critical behavior [1]. In the above reaction scheme (1), PC scaling is observed for branching and annihilating random walks with $\lambda=0$, $n=2$, and even offspring number m . In that situation, reactions either create or annihilate an even number of particles. Thus the number of B particles remains either even or odd throughout the system's temporal evolution. Indeed, the distinct nontrivial scaling exponents of the PC universality class, albeit limited essentially to $d=1$, can be attributed to this special symmetry of local particle number parity conservation. Moreover, for $d \leq d'_c \approx 4/3$, fluctuations cause the emergence of a power-law inactive phase, characterized by the algebraic decay laws of diffusion-limited pair annihilation $2B \rightarrow \emptyset$ ($\lambda = \sigma = 0, n = 2$) [7].

When $\lambda > 0$ or m is odd (for $n=2$), however, parity conservation is destroyed. The case $\lambda > 0$ immediately yields a transition in the DP universality class with $d_c=4$. Yet for odd m , even if $\lambda=0$ initially, fluctuations *generate* sufficiently strong decay processes $B \rightarrow \emptyset$ in $d \leq 2$ dimensions to produce a transition to an inactive phase with DP critical exponents. For $\lambda=0$ and $d > 2$, one encounters only an active phase for any $\sigma > 0$, as predicted by the mean-field rate equation [7].

At the nonequilibrium continuous phase transition, the reacting particles form spatiotemporal fractal structures characterized by algebraic decay of the correlation functions (one example is depicted in Fig. 1). In Ref. [8] it was suggested to employ these *dynamic* fractals of reacting agents B as backbones for nearest-neighbor hopping processes of another, otherwise passive, particle species A . The A particles are then allowed to move to a nearest-neighbor site only if that site is occupied by at least one B particle. In an active state of the B system, with a largely homogeneous particle distribution, the A particles follow Fick's normal diffusive propagation law, $\langle \vec{x}(t)_A^2 \rangle = 2Dt$, with diffusion constant $D \sim a_0^2/\tau_0$, where a_0 denotes the lattice constant of the hypercubic lattice, and τ_0^{-1} the microscopic hopping rate. On the contrary, in a DP-type inactive phase with an exponentially decaying B particle density, the A species will become localized, i.e., $\langle \vec{x}(t)_A^2 \rangle \rightarrow \text{const}$ as $t \rightarrow \infty$. In precisely this sense the inactive to ac-

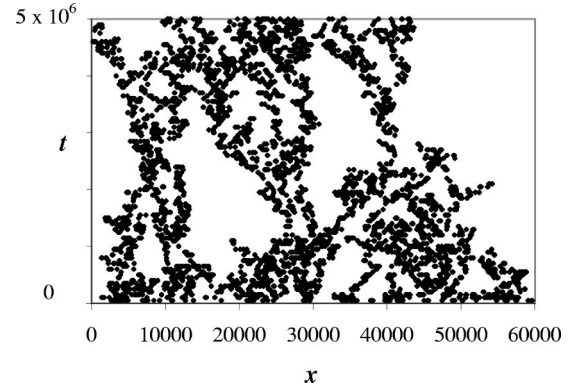


FIG. 1. Space-time plot for the one-dimensional reactions $B \rightarrow 3B$, $2B \rightarrow \emptyset$ at the active/absorbing critical point (PC universality class).

tive state transition of the B system thus induces a *localization transition* for the A particles. At the transition itself, as well as in the PC-inactive phase, the B density decays algebraically,

$$\rho_B(t) \sim t^{-\alpha_B} \quad (2)$$

with $0 < \alpha_B \leq 1$. Correspondingly, the A species propagates *subdiffusively*,

$$\langle \vec{x}(t)_A^2 \rangle \sim t^{1-\alpha_A}, \quad (3)$$

where again $0 < \alpha_A \leq 1$. In fact, a simple mean-field approach suggests $\alpha_A = \alpha_B$ [8]. Our goal here is to further elucidate the scaling laws for the ensuing anomalous A particle diffusion through Monte Carlo simulations in one and two dimensions. We shall also numerically determine the full time-dependent probability distribution for the A species displacements and compare it with the Gaussian distribution predicted by mean-field theory [8].

Before we proceed, we note that our model is related to, but quite distinct from, studies of anomalous diffusion on *static* fractal structures. These have been used to describe a variety of physical phenomena, such as percolation through porous or fractured media and electron-hole recombination in amorphous semiconductors [9]. Anomalous diffusion may also ensue for particle transport in a random medium with quenched disorder, provided the obstacles are sufficiently strong to effectively reduce the number of diffusive paths on large length scales [10]. We emphasize again that in the system under investigation here the fractal structure evolves *dynamically*, which provides an alternative mechanism for subdiffusive propagation. When Eq. (2) holds, the number of available paths decreases with time. Yet notice that A particles that have become localized on an isolated B cluster for some time may still become linked to a large connected region of available sites later.

In Sec. II we briefly review the theoretical considerations of Ref. [8], and list the central results from the mean-field approach for the A species propagation on the dynamic B fractal. In Sec. III we give an overview of the Monte Carlo simulation methods employed in our study. Next, in Sec. IV

TABLE I. Critical exponents for the parity conserving (PC) and directed percolation (DP) universality classes of active to absorbing phase transitions, as determined from Monte Carlo simulations in one and two dimensions [2]. Here, r denotes the deviation of a relevant control parameter from the critical point. For directed percolation, the first-order results from the ϵ expansion near $d_c=4$ dimensions are given as well.

Critical exponents	PC, $d=1$	DP, $d=1$	DP, $d=2$	DP, $d=4-\epsilon$
$\rho_s \sim r ^\beta$	$\beta \approx 0.92$	$\beta \approx 0.276$	$\beta \approx 0.584$	$\beta = 1 - \epsilon/6 + O(\epsilon^2)$
$\xi \sim r ^{-\nu}$	$\nu \approx 1.84$	$\nu \approx 1.097$	$\nu \approx 0.734$	$\nu = 1/2 + \epsilon/16 + O(\epsilon^2)$
$t_c \sim \xi^z \sim r ^{-z\nu}$	$z \approx 1.75$	$z \approx 1.581$	$z \approx 1.764$	$z = 2 - \epsilon/12 + O(\epsilon^2)$
$\rho_c(t) \sim t^{-\alpha}$	$\alpha \approx 0.285$	$\alpha \approx 0.159$	$\alpha \approx 0.451$	$\alpha = 1 - \epsilon/4 + O(\epsilon^2)$

we first present our results for the anomalous A diffusion as induced by pure annihilation kinetics of the B species ($\sigma=0$). Section V is devoted to the central issue in our investigation, namely the subdiffusive behavior of the A particles at the localization transition caused by the active to inactive/absorbing phase transition of the reacting agents B . We summarize our results in Sec. VI, add concluding remarks, and point out a few open problems.

II. THEORETICAL PREDICTIONS

For the specific combination of B particle reactions studied here, the asymptotic scaling behavior is well understood. In particular, we shall consider both systems with pure annihilation kinetics ($nB \rightarrow \emptyset$), and models with competing annihilation and offspring reactions, as listed in (1), in the vicinity of their nonequilibrium phase transition from active to inactive, absorbing states. These phase transitions either fall into the directed percolation (DP) or parity conserving (PC) universality class, both of which have been previously investigated in detail [1]. Specifically, the exponents α_B characterizing the long-time decay of the particle density are well established through simulations (see Table I).

Let us first consider pure annihilation kinetics with reaction rate μ . The corresponding mean-field rate equation for the B particle density reads

$$\partial_t \rho_B(t) = -n\mu \rho_B(t)^n. \quad (4)$$

For $n > 1$ this yields

$$\rho_B(t) = \frac{\rho_B(0)}{(1 + t/\tau_n)^{1/(n-1)}}, \quad \tau_n = \frac{\rho_B(0)^{1-n}}{n(n-1)\mu}, \quad (5)$$

whence at sufficiently large times $\rho_B(t) \sim (\mu t)^{-1/(n-1)}$, independent of the initial density $\rho_B(0)$. For $n=1$, i.e., spontaneous death with rate λ , one naturally finds exponential decay,

$$\rho_B(t) = \rho_B(0)e^{-\lambda t}. \quad (6)$$

We expect these results to be valid (at least qualitatively) in dimensions above an upper critical dimension d_c , which can be determined through straightforward dimensional analysis: since the B particles undergo ordinary diffusion, we expect $[t] = [x]^2$, and of course in d dimensions, $[\rho_B] = [x]^{-d}$. Then by Eq. (4), $[\mu] = [x]^{d(n-1)-2}$. Thus μ is di-

mensionless (marginal in the RG sense) at $d_c(n) = 2/(n-1)$. The mean-field description (4) fails in lower dimensions where there is a non-negligible probability that a particle will retrace part of its trajectory. For $n=2,3$ anticorrelations between surviving particles are induced in dimensions $d \leq 2$ and $d=1$, respectively, since many of the nearby particles along a specific agent's trajectory are annihilated in the first trace. The annihilation processes then become diffusion limited rather than reaction limited. For the pair process, the particles need to traverse a distance $\ell(t) \sim (Dt)^{1/2}$ before they can meet and annihilate, where D denotes the B particle diffusion constant. Hence the particle density should scale as $n(t) \sim \ell(t)^{-d} \sim (Dt)^{-d/2}$. Indeed, a renormalization group analysis predicts for $2B \rightarrow \emptyset$ (as well as for pair coagulation $2B \rightarrow B$) [11]

$$\rho_B(t) \sim (Dt)^{-d/2} \quad \text{for } d < 2, \quad (7)$$

$$\rho_B(t) \sim (Dt)^{-1} \ln Dt \quad \text{at } d_c(2) = 2, \quad (8)$$

in agreement with exact solutions in $d=1$. Thus particles survive considerably longer than Eq. (5) would suggest. For triplet annihilation ($3B \rightarrow \emptyset$), in one dimension there remain mere logarithmic corrections to the mean-field result [11],

$$\rho_B(t) \sim \left(\frac{\ln Dt}{Dt} \right)^{1/2} \quad \text{at } d_c(3) = 1. \quad (9)$$

The higher-order ($n \geq 4$) annihilation processes should all be aptly described by the mean-field power laws (5).

Exact results for the critical behavior of the DP and PC universality classes cannot be derived analytically, but the scaling exponents have been measured quite accurately by means of computer simulations [1], see Table I. The universal properties of directed percolation can be represented through Reggeon field theory [12], which allows a systematic perturbational calculation of the critical exponents in an ϵ expansion near its upper critical dimension $d_c=4$. The one-loop fluctuation corrections to their mean-field values are listed in Table I as well. At least for DP, the scaling relation $\beta = z\nu\alpha$ holds. A similarly reliable analytic computation of the PC critical exponents has as yet not been achieved, owing to the absence of a corresponding mean-field theory (see Ref. [7] for further details).

In Ref. [8], the reaction-controlled diffusion model was defined as follows. Otherwise passive agents A perform independent random walks to those sites that are occupied by

at least one B particle; the B species is subject to diffusion-limited reactions of the above type. In our simulations, we have assumed the A hopping rate τ_0^{-1} to be independent of the number of B particles at adjacent sites. This contrasts the model of Ref. [8], where the A hopping probability to a given site was taken to be proportional to the number of B particles on that site. Yet as we are mostly interested in the asymptotic behavior at low B densities, this distinction should be largely irrelevant. Moreover, in the majority of systems studied here the B pair annihilation reaction was set to occur with probability 1, which eliminates multiple site occupations.

To be specific, consider B particles undergoing the Gribov reactions $B \rightarrow \emptyset$, $B \rightleftharpoons 2B$, with an ensuing critical point in the DP universality class. The effective theory near the phase transition then becomes equivalent to a Langevin equation for a fluctuating field $b(\vec{x}, t)$ [3,12,13]:

$$\partial_t b = D(\nabla^2 - r)b - 2\mu b^2 + \eta. \quad (10)$$

With $\langle \eta(\vec{x}, t) \rangle = 0$, the ensemble average of b over noise realizations yields the mean B particle density, $\langle b(\vec{x}, t) \rangle = \rho_B(t)$. For the correlator of the stochastic noise one finds

$$\langle \eta(\vec{x}, t) \eta(\vec{x}', t') \rangle = 2\sigma b(\vec{x}, t) \delta(\vec{x} - \vec{x}') \delta(t - t'), \quad (11)$$

which is to be understood as the prescription to always factor in the local particle density when noise averages are taken. According to Eq. (11), all fluctuations vanish in the absorbing state, as they should. As before, λ , σ , and μ represent the B particle decay, branching, and coagulation rates, respectively. The control parameter r denotes the deviation from the critical point, e.g., $r = (\lambda - \sigma)/D$ in the mean-field approximation.

With the model definition in Ref. [8], the effective diffusivity of the agents A becomes proportional to the local B density. In fact, starting from the classical master equation, one can derive the following continuum stochastic equation of motion for a coarse-grained field $a(\vec{x}, t)$ that describes the A species [8]

$$\partial_t a = \bar{D}(\nabla^2 a)b - \bar{D}a(\nabla^2 b) + \zeta \quad (12)$$

with noise correlations

$$\langle \zeta(\vec{x}, t) \zeta(\vec{x}', t') \rangle = 0,$$

$$\begin{aligned} \langle \zeta(\vec{x}, t) \eta(\vec{x}', t') \rangle &= \bar{D}[\nabla^2 a(\vec{x}, t)]b(\vec{x}, t) \delta(\vec{x} - \vec{x}') \delta(t - t') \\ &\quad - \bar{D}a(\vec{x}, t) \nabla^2 [b(\vec{x}, t) \delta(\vec{x} - \vec{x}') \delta(t - t')]. \end{aligned} \quad (13)$$

The fluctuations of the b field thus influence the A diffusion in a nontrivial manner.

Certainly outside the critical regime, well inside either the active or inactive phases, which for DP are both characterized by exponentially decaying correlations in space and time, one may apply a mean-field type of approximation. To this end, we consider the B particle density to be spatially homogeneous, and neglect the noise cross-correlations in Eq.

(13). Upon rescaling, the equation of motion (12) then reduces to a mere diffusion equation [8]

$$\partial_t n_A(\vec{x}, t) = \bar{D} \rho_B(t) \nabla^2 n_A(\vec{x}, t) \quad (14)$$

for the probability n_A of finding a particle A at point \vec{x} at time t , with time-dependent effective diffusivity $\bar{D} \rho_B(t)$. We may interpret this result as follows. In the original model, the hopping rate to an adjacent site is proportional to the number of B particles on that site. At sufficiently low densities that multiple B particle occupation of a given site can be neglected, the average B density represents the fraction of lattice sites available for the A particles to hop to. Thus we expect the A species diffusion rate to be approximately proportional to the global B particle density. For this assumption to be accurate, the A particle distribution must also be assumed to be at least roughly uniform. However, local fluctuations of the B density may induce some clustering for many A particles as well, though certainly to a lesser degree since in regions with small disjoint B clusters, the A particles become localized. Any deviations from the uniform effective diffusion coefficient caused by an inhomogeneous B particle distribution would be diminished by this simultaneous clustering. We will discuss these effects in more detail below as we measure deviations from the mean-field behavior.

Under the above mean-field assumption, we may employ the diffusion equation (14) to determine how the probability distribution $n_A(\vec{x}, t)$ evolves in time for a system of independent A particles that all start initially at a particular location $\vec{x} = 0$, i.e., $n_A(\vec{x}, 0) = \delta(\vec{x})$. Even with a time-dependent diffusion coefficient, Eq. (14) is readily solved via spatial Fourier transformation, resulting in a Gaussian:

$$n_A(\vec{x}, t) = \frac{1}{[4\pi D'(t)]^{d/2}} \exp\left(-\frac{\vec{x}^2}{4D'(t)}\right). \quad (15)$$

But the expression Dt in Fick's law for standard diffusion becomes replaced with an integral over the evolving B density,

$$D'(t) = \bar{D} \int_0^t \rho_B(t') dt'. \quad (16)$$

Naturally, the odd moments of distribution (15) vanish, while $\langle \vec{x}(t)_A^k \rangle = \langle |\vec{x}(t)_A|^k \rangle > 0$ for k even. We then compute

$$\begin{aligned} \langle |\vec{x}(t)_A|^k \rangle &= \int |\vec{x}|^k n_A(\vec{x}, t) d^d x, \\ &= \frac{[4D'(t)]^{k/2}}{\Gamma(d/2)} \Gamma\left(\frac{k+d}{2}\right). \end{aligned} \quad (17)$$

For $k=2$ in particular, this reduces to

$$\langle \vec{x}(t)_A^2 \rangle = 2dD'(t). \quad (18)$$

For a constant B particle density, e.g., the saturation value ρ_s in an active phase, we recover ordinary diffusion with

effective diffusivity $D = \bar{D}\rho_s$. In an inactive phase with exponential density decay (6), we find instead

$$\langle \vec{x}(t)_A^2 \rangle = \frac{2d\bar{D}\rho_B(0)}{\lambda}(1 - e^{-\lambda t}). \quad (19)$$

Thus, asymptotically the A particles become localized, with $\langle \vec{x}(t)_A^2 \rangle \rightarrow 2d\bar{D}\rho_B(0)/\lambda$ in the limit $t \rightarrow \infty$. On the other hand, if the B density decays algebraically, see Eq. (2), then for $0 < \alpha_B < 1$ our mean-field solution predicts subdiffusive propagation (3) with $\alpha_A = \alpha_B$, whereas asymptotically

$$\langle \vec{x}(t)_A^2 \rangle \sim \bar{D} \ln Dt \quad (20)$$

if $\alpha_B = 1$. Finally, for pair annihilation processes at the critical dimension $d_c = 2$, governed by Eq. (8), one finds

$$\langle \vec{x}(t)_A^2 \rangle \sim \bar{D}(\ln Dt)^2, \quad (21)$$

and similarly we obtain for triplet annihilation in one dimension, see Eq. (9),

$$\langle x(t)_A^2 \rangle \sim \bar{D}(Dt \ln Dt)^{1/2}. \quad (22)$$

III. MONTE CARLO SIMULATION METHODS

Our goal was to employ Monte Carlo simulations to compare α_A with α_B , as well as to determine the displacement probability distribution $n_A(\vec{x}, t)$ for the A particles, and look for deviations from the Gaussian distribution (15) predicted by the mean-field approach. The simulations discussed here were executed on a cubic lattice with periodic boundary conditions in each spatial direction. In one dimension the lattice contained between 10^4 and 10^5 sites, and the two-dimensional lattice ranged in size from 100×100 to 800×800 . In each simulation the system was initialized by putting one B particle at each site [initial density $\rho_B(0) = 1$ [14]], and by randomly placing throughout the lattice a fixed number of A particles with no site exclusion. For all of the data given below (except where otherwise noted), the density of A particles in the lattice was fixed at $\rho_A = 0.5$. Each time step involved a complete update of the A species, followed by a complete update of the B particles. The simulation was terminated either when the number of B particles reached a certain lower limit (usually 0.1% of the number of lattice sites), or after a fixed number of time steps (typically $\approx 10^6$).

With the exception of some particular runs in which the B particles were noninteracting (i.e., subject only to the decay $B \rightarrow \emptyset$) and could thus be updated serially, we proceeded as follows. Given N particles at the beginning of the time step, N random B particles on the lattice were chosen to be updated. In a given time step, some B particles might then be addressed more than once while others not at all. This is appropriate even though the number of B particles is changing in time, because the net loss of B particles per time step becomes less than one on time scales short compared to the simulation length. The B particles were, in general, subjected to the reactions listed in (1), and a single update proceeded in that sequence. To implement the process $B \rightarrow \emptyset$, the B par-

ticle was deleted with probability λ . Next, the B particle underwent an offspring reaction $B \rightarrow (m+1)B$ with probability σ . In the simulations discussed here, we chose $m = 1, 2$, or 4 . The offspring particle(s) were placed on the parent particle's nearest neighboring sites such that no offsprings were placed on identical places, and were then subject to the annihilation reaction $nB \rightarrow \emptyset$ (with $n = 2, 3$, or 4) if applicable. If the B particle being updated did not undergo an offspring reaction, it subsequently hopped to a nearest-neighbor site with some probability and was then subject to annihilation, which required all nB particles to be located on the same site.

Initially, the A particles were also updated via Monte Carlo. To this end, a random direction was chosen, and the A particle was moved one step in that direction provided at least one B particle was present on the destination site. However, since the A particles were independent, it was later determined that they could be processed serially (i.e., by simply passing through the list of A particles). Technically this represents a microscopically different method, since the Monte Carlo procedure causes some particles to be updated more than once, and others not at all at a given time step. Yet we found that both variants produced identical macroscopic results.

Our main interest was to determine the asymptotic scaling behavior of the global B particle density in the lattice, as well as to measure the mean-square displacement of the A species, both as functions of time t . Henceforth, lengths will be measured in units of the lattice constant a_0 , and time in units of Monte Carlo steps. In most of our simulations we expect spatial inhomogeneity in the B particle distribution. In particular, anticorrelations should develop in low dimensions for pure B annihilation kinetics. At the critical point for systems exhibiting phase transitions, at sufficiently large times the B species distribution should become a scale-free spatial fractal at length scales large compared to the lattice constant and smaller than the system size (compare Fig. 1). Therefore we also periodically recorded the coordinates of both A and B particles in order to compute probability distributions and correlation functions. For example, the B density correlation function is defined as

$$C_B(\vec{x}, t; \vec{x}', t') = \langle \rho_B(\vec{x}, t) \rho_B(\vec{x}', t') \rangle - \langle \rho_B \rangle^2. \quad (23)$$

By the translational and rotational invariance of the lattice, the equal-time density correlations are really a function of $|\vec{x} - \vec{x}'|$ only. At criticality, we have

$$C(\vec{x}, t; \vec{x}', t) = C(|\vec{x} - \vec{x}'|) \sim |\vec{x} - \vec{x}'|^{-2\beta/\nu}, \quad (24)$$

whence we find at equal positions

$$C(\vec{x}, t; \vec{x}, t') = C(|t - t'|) \sim |t - t'|^{-2\beta/z\nu}, \quad (25)$$

as a consequence of dynamic scaling.

To compute the equal-time correlation function (24) in one dimension numerically, we fix a particular B site and observe the distribution of all other B particles as a function of the distance from it. We measure this distribution for each

B particle fixed and then average the resulting distributions to obtain $\langle \rho_B(x,t)\rho_B(x',t) \rangle$. In higher dimensions, we use the lattice directions as representative of the full distribution and compute $C(|\vec{x}-\vec{x}'|)$ for pairs (\vec{x},\vec{x}') with a common lattice coordinate in one direction.

In many situations we expected the measured quantities to be power laws as a function of time t . The simplest approach to computing the exponent α in a power-law relationship $\rho \propto t^{-\alpha}$ naturally is linear regression on $\ln \rho$ versus $\ln t$. At the continuous phase transition separating active and absorbing states, one expects such a power-law dependence. However, when the system is slightly above or below the critical parameters, it usually behaves critically for some time before crossing over to supercritical or subcritical behavior (either an exponential approach to the final B particle density, or a power law with a different exponent α'). If the system is not precisely at criticality (at least for the time scales simulated), then offcritical behavior could lead to incorrect determination of the critical exponent via linear regression. However, one can also compute a local exponent α_b for a measured quantity ρ given by the expression [15]

$$\alpha_b = -\log_{b^2}[\rho(bt)/\rho(t/b)]. \quad (26)$$

Thus at time t , supposing a power-law dependence on t , α_b is the exponent inferred from the values of ρ at bt and t/b ; i.e., these two data points define a line on a log-log plot whose slope is $-\alpha_b$.

The most time-consuming procedure in this study involved finding the critical parameters for which the system was at criticality. Typically, the parameters λ and μ were fixed, and σ was varied. The critical value of σ was deduced by simultaneously increasing the lower bound by definitely identifying systems as subcritical, and decreasing the upper bound by characterizing supercritical systems. In either case, the system behaved critically for some time (longer for σ closer to the true critical value σ_c) before crossing over to its asymptotic behavior, and so critical power laws could be approximated from the system's intermediate scaling behavior. As noted previously, the B species phase transition between active and absorbing states induces a localization transition for the A particles, with critical subdiffusive behavior. The phase transitions for both A and B particles clearly occur at the same value of σ_c , and hence σ_c can be determined independently by measuring both the B particle density decay and the A species mean-square displacements as a function of time. We estimate our typical errors in determining critical exponents and the subdiffusive A species power laws to be $\approx \pm 0.01$.

We also attempted to improve the precision of our estimation of σ_c by a method suggested in Ref. [15], which we now briefly describe. For the measured quantity ρ , which at the critical parameter value σ_c depends only on some power of time t , i.e., $\rho(\sigma_c, t) \sim t^{-\alpha}$ with some exponent α , one expects in the critical regime $\sigma \approx \sigma_c$:

$$\rho(\sigma, t) \approx \rho(\sigma_c, t)[1 + ct^{1/\nu_t}(\sigma - \sigma_c)]. \quad (27)$$

Here $\nu_t = z\nu$ describes the critical slowing down as the control parameter σ approaches the phase transition at σ_c , $\tau_c \sim |\sigma - \sigma_c|^{-\nu_t}$. One first estimates σ_c , ν_t , and c from relatively short simulations at various values of σ . A simulation reaching large values of t is then performed at the estimated σ_c . One obtains an improved estimate for σ_c by replacing σ and $\rho(\sigma, t)$ in Eq. (27) with the long simulation measurements, and then finding the value of σ_c for which $\rho(\sigma_c, t)$ is a straight line. This process may then be repeated to obtain the desired or computationally accessible accuracy. Note that inaccuracies in the estimates of c and ν_t result in second-order inaccuracies for σ_c and α [15]. However, this method only works when σ is already sufficiently close to σ_c so that this first-order approximation is valid. In addition, statistical fluctuations in the data must be smoothed as much as possible through averaging over multiple runs for each σ value so that c and ν_t can be somewhat accurately determined. Unfortunately, we found that our simulations were not extensive enough in most cases to apply this method and obtain even more reliable estimates of c , ν_t , and σ_c .

IV. ANNIHILATION KINETICS AND ANOMALOUS DIFFUSION

We begin with the results of our Monte Carlo simulations for pure B species annihilation reactions. These serve to test the mean-field description of the ensuing A particle anomalous diffusion in dimensions below, at, and above the critical dimension $d_c(n) = 2/(n-1)$, and moreover provide a means to estimate the magnitude of errors to be expected in our data. In addition, the results for the B pair annihilation model should describe the subcritical behavior for the reactions exhibiting active to absorbing transitions in the PC universality class.

A. Spontaneous decay $B \rightarrow \emptyset$

We first verified that our simulations correctly reproduced the $n=1$ solution (6) to the mean-field equation (4) giving exponential B density decay. This result should be valid in any dimension since all particles evolve independently. The mean-field description for the A particles then predicts their localization according to Eq. (19). We ran simulations in both one (system size 10 000) and two dimensions (system size 100×100) using a decay rate $\lambda = 0.01$, and indeed found excellent agreement at large times with prediction (19). Initially, however, the A particles moved slower than suggested by Eq. (19), consistent though with our different microscopic realization of the reaction-controlled diffusion model: the rules adopted in the simulations only distinguish between sites that are occupied or unoccupied by B particles, and so multiple site occupation effectively corresponds to lower local densities ρ_B in the analytical description. Yet at low B particle densities multiple site occupation becomes negligible, leading to A species localization precisely as described by Eq. (19). We also computed the actual A particle displacement distribution as a histogram of final net displacements. Using the measured average final mean-square displacement as input to Eq. (15) rather than estimating the

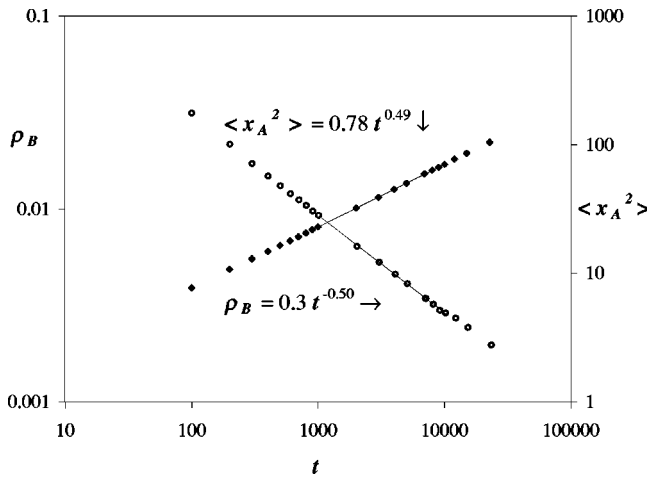


FIG. 2. The B particle density and corresponding A species mean-square displacement for the pair annihilation reaction $2B \rightarrow \emptyset$ with $\mu=0.5$ in $d=1$ demonstrating excellent agreement with the predicted asymptotic power laws.

coefficient \tilde{D} , we found good agreement with the predicted Gaussian distribution in both one and two dimensions, although in $d=1$ the data perhaps indicate a slight excess of particles localized very near their initial location.

In the results summarized above, at each Monte Carlo step the updated B particles hopped to a nearest-neighbor site with probability 1. We also investigated the effect of varying this probability. Initially, the mean-square A displacement then grows faster in situations with low B particle diffusivity because the probability of multiple B site occupation is reduced, leaving a larger fraction of available sites for the A species. However, as the B particles are depleted the connectivity of the lattice decreases, and the movement of the B species quickly becomes the dominant mechanism for A particle diffusion. We found an overall monotonic increase of final A particle mean-square displacements as a function of the B diffusivity. In one dimension the (temporary) localization of an A particle requires only two sites unoccupied by B particles, compared with four sites in two dimensions. Therefore the connectivity decreases more sharply in $d=1$ as a function of the B density. Consequently diminishing the B species random walk probability has a more pronounced effect in one dimension than in $d=2$.

B. Pair annihilation $2B \rightarrow \emptyset$

Since the critical dimension for the B particle pair annihilation reaction is $d_c(2)=2$, the mean-field prediction (5) does not apply to either the one- or two-dimensional simulations executed. In $d=1$ we expect according to Eq. (7) $\rho_B(t) \sim t^{-1/2}$, and using Eqs. (18) and (16) the mean-field approach suggests $\langle x(t)_A^2 \rangle \sim t^{1/2}$. Figure 2 shows the simulation results (averaged over 20 runs) for B pair annihilation in one dimension (system size 10 000) with annihilation probability $\mu=0.5$. At first the B density decays faster than Eq. (7) predicts: initially the effective power law should be close to the mean-field result $\rho_B(t) \sim t^{-1}$ since the anticorrelations described in Sec. II develop only after some time has

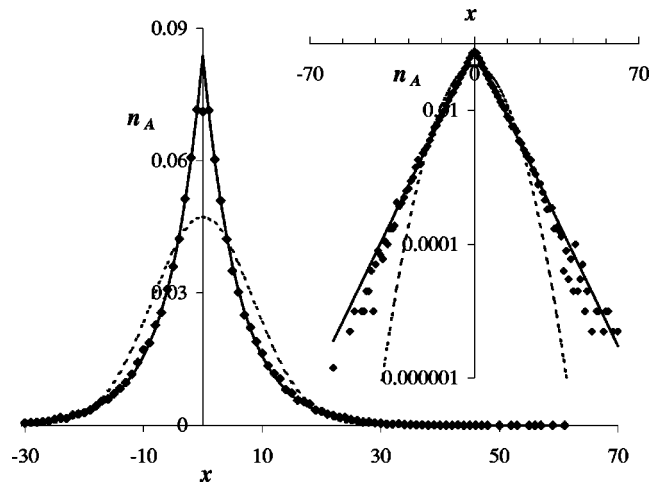


FIG. 3. The measured distribution of the A particle displacements corresponding to the system shown in Fig. 2 (B pair annihilation in one dimension, $\mu=0.5$, measured at $t=10\,000$). Both Gaussian (dashed) and exponential fits (full line), uniquely determined by normalization and fixing the second moment with the simulation data, are depicted, on linear and logarithmic (inset) scales. The exponential fit works very well, although the value at 0 and perhaps the tails of the observed distribution appear smaller than in the fit.

elapsed, whereupon the asymptotic decay $\sim t^{-1/2}$ is approached. Indeed, the graph verifies that the theoretical exponent $\alpha_B=1/2$ is adequately reproduced in the late time interval $10^3 < t < 10^4$. We measured the corresponding exponent α_A for the mean-square A particle displacement in this regime as well, and found that the simulation results agree nicely with the mean-field exponent $\alpha_A=1/2$, to the precision obtained in our simulations.

We may also infer $\tilde{D} \approx 0.69$ by matching our numerical integral of $\rho_B(t)$ with $\langle x(t)_A^2 \rangle$, though incomplete knowledge of $\rho_B(t)$, particularly in the transient regime, introduces some errors to this estimate. A value $\tilde{D} > 0.5$ indicates that more than one A particle is hopping to the same B particle site on average. When some A - B correlations develop there may be a higher density of A particles in the vicinity of a given B , which would in turn enhance the average A diffusivity rate.

Figure 3 demonstrates that the predicted Gaussian distribution Eq. (15) is *not* observed, despite the agreement in the time dependence of the mean-square displacement resulting from the distribution. Compared to a Gaussian with matching second moment, there is a distinct excess of essentially localized particles (with very small displacements), which necessarily implies longer “tails” at large displacement values. A closer examination reveals that the simulation results for the A particle displacement distribution agree over a large range of displacements with the normalized exponential distribution

$$n_A(x,t) = \frac{1}{2L(t)} e^{-|x|/L(t)}, \quad (28)$$

where $L(t)$ denotes a time-dependent characteristic length

scale. As will be discussed below, the distribution (28) obeys dynamic scaling, so we determined L by matching the second moment of this function with the simulation data at $t = 10\,000$. As is evident from Fig. 3, the only significant deviations from this fit appear for particles with zero displacement and at the tails of the distribution, where simulation data contain greater error.

We can understand the qualitative features of this non-Gaussian distribution as a result of the low connectivity of a one-dimensional lattice. In small regions where all B particles have been annihilated, the A species are temporarily localized and will have few subsequent chances to escape, thus lowering their effective diffusivity. Direct measurement of the B pair correlation function, as well as the slow B density decay, clearly indicates that particle anticorrelations have developed. These anticorrelations enhance the probability of finding substantial regions of zero B particle density. However, as mentioned before in the discussion of the variation of the B particle random walk probability in Sec. IV A, a significant part of A movements probably result from hopping along with a particular B particle through several time steps (especially in $d = 1$). Thus the effective diffusion coefficient is (at least temporarily) much higher for such particles, and this effect contributes results in the longer “tails” in the displacement distribution. We may think of a *local* diffusion rate $D(\vec{x}, t)$ which is proportional to the distribution of available sites $b(\vec{x}, t)$. Thus a particular particle will be subject to a temporally varying diffusion rate that depends on its trajectory through the field $b(\vec{x}, t)$, recall Eqs. (12) and (13), just as the diffusing particle’s trajectory must be considered for understanding diffusion on a static fractal. The distribution depicted in Fig. 3 suggests a sort of phase separation into different populations: many particles are primarily subject to small diffusion rates, i.e., are mainly localized in regions with low B density, while some others experience quite large diffusivities (by remaining in areas of high local B particle densities).

The variation of local A diffusion rates is the result of inhomogeneities in $b(\vec{x}, t)$ and the coupling that allows an A particle to be carried along by a particular wandering B particle. Yet our earlier mean-field description for the A species displacement distribution assumed that on average each A particle evolves with an identical effective diffusion coefficient; i.e., the total number of hops for each A particle should be about the same. However, spatial inhomogeneities over scales larger than the distances traveled by typical A particles will cause the effective diffusivities for a particular time interval to vary spatially in a noticeable amount. This effect should be especially pronounced in the case of the B pair annihilation process because the emerging anticorrelations will leave many regions of space rather devoid of B particles. A particles with larger effective diffusion coefficients probably follow a particular B particle for some time, since the B anticorrelations render them unlikely to be present in a region of high local B density. This distribution of B density spatial fluctuations should persist to a large extent throughout the simulation runs, which in turn should yield large variations in the average diffusion coefficient experienced by the A species.

We may construct a simple model to accommodate such variations as follows. Suppose the number of B particles, i.e., the number of available hopping sites for the A species, is decreasing proportional to some negative power of time, as is on average often the case in our simulations. If Eq. (2) holds, we find for the fraction f of B particles that disappear during a small time interval $\Delta t \ll t$: $f(t) = \alpha_B \Delta t / t$. Now assume that initially all of the A particles are diffusing ordinarily with an effective diffusivity D , and then after each small time interval Δt , a fraction f of the active A particles becomes localized and remains immobile for the remainder of the simulation. This suggests that the A particle distribution will be a superposition of normalized Gaussians of increasing width but multiplied by a factor to be found recursively from the condition that the A particle number be conserved. More precisely, in $d = 1$ this distribution becomes (with initial time t_0 and final time $t = t_M$, $M \geq 1$):

$$P(x, t) = \sum_{k=0}^M p(t_k) \frac{1}{(4\pi D t_k)^{1/2}} \exp\left(-\frac{x^2}{4D t_k}\right). \quad (29)$$

The prefactors $p(t_k)$ are then determined by keeping the integral of $P(x, t)$ normalized to unity: $\sum_{k=0}^M p(t_k) = 1$. Recursively, one thus arrives at $p(t_0) = f(t_0)$, $p(t_k) = f(t_k) \prod_{j=0}^{k-1} [1 - f(t_j)]$ for $1 \leq k \leq M - 1$, and at last $p(t_M) = \prod_{j=0}^{M-1} [1 - f(t_j)]$. This picture assumes that the entire region surrounding an A particle is depleted of B particles nearly simultaneously, and that this region is not subsequently visited by other B particles. While this may be a decent approximation under the condition of B particle anticorrelations, it is rather more difficult to justify in cases of emerging positive correlations (as we shall discuss below when offspring reactions are introduced). However, even then some B clusters are eventually eliminated, leaving the nearby A particles localized, at least temporarily. Furthermore the active A particles are diffusing normally with $\langle x(t)_A^2 \rangle \sim t$ in their local B cluster until they become trapped.

Applying this simplified model to the pair annihilation system, we set $\alpha_B = 0.5$, and we have chosen $D = 0.2$. We then summed Gaussian distributions for simulation times ranging from $t = 5$ to 100, localizing a fraction $f(t) = \alpha_B \Delta t / t$ at each integer t . The result is depicted in Fig. 4, after appropriately rescaling the axes to match normalization and the measured second moment of the simulation data. Apart from large deviations for small displacements, this “continuous localization” fit appears to agree remarkably well with the simulation results. Indeed this generated A displacement distribution even begins to decrease more quickly near its tails, as may also be observed in the simulation data. The disagreement between the data and model may of course be traced to the simplifications assumed in its construction. However, the error also might arise from choosing the initial distribution: at the beginning of the simulation the number of B particles decreases sharply before anticorrelations have developed, and the above estimate for the fraction of localized A particles is not valid for $\Delta t / t \sim 1$. Despite its shortcomings, the model seems to capture most of the features we have observed in the A species displacement distribution. We

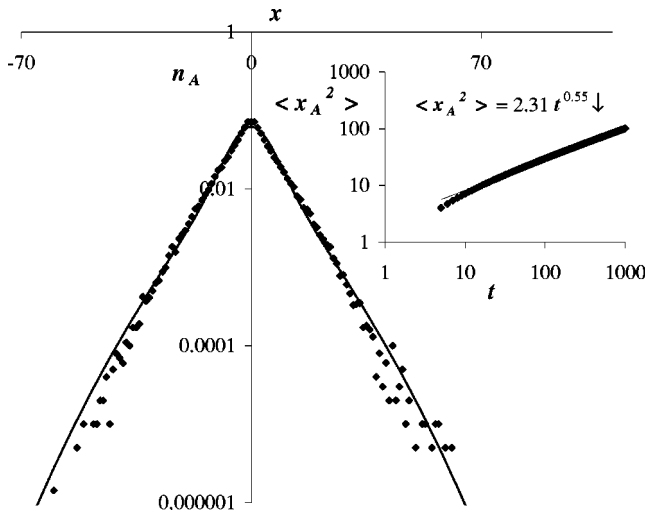


FIG. 4. The results from the “continuous localization” model superimposed with the measured distribution of the A particle displacements corresponding to the system shown in Fig. 2. The model reproduces the faster than exponential drop-off in the tails of the distribution, but still underestimates the fraction of highly localized particles. The inset depicts the power-law increase of $\langle x(t)_A^2 \rangle$ as computed from the model.

also computed the time dependence of the mean-square displacement using the “continuous localization” model. Following a transient behavior, the inset in Fig. 4 shows $\langle x(t)_A^2 \rangle \sim t^{0.55}$, close to the expected power law with $1 - \alpha_A = 0.5$ (which we also observed in the simulation). By trying a variety of α_B values one can generate different approximate power laws, but the measured subdiffusive A displacement exponent was always found to be slightly larger than $1 - \alpha_B$.

To examine the non-Gaussian character of $n_A(x, t)$ further, we measured its higher moments as a function of time. In $d=1$, Eq. (17) yields for the even moments of the mean-field Gaussian distribution: $\langle x(t)_A^{2k} \rangle = (2k-1)!! \langle x(t)_A^2 \rangle^k$. While this factorization of higher moments still holds to the accuracy of our simulation data, we found the prefactors $c_k = \langle x(t)_A^{2k} \rangle / \langle x(t)_A^2 \rangle^k$ in our measurements to differ from the predicted values $c_2=3$, $c_3=15$, and $c_4=105$: we measured the considerably larger values $c_2 \approx 5.5$, $c_3 \approx 55$, and $c_4 \approx 1100$. These numbers are actually closer to the values one would obtain from the exponential distribution (28), namely $c_k = (2k)!/2^k$, i.e., $c_2=6$, $c_3=90$, and $c_4=2520$, but still off by a factor of about 2 for the higher moments. Thus the exponential fit cannot entirely describe the measured distribution either. Nevertheless, the factorization property $\langle x(t)_A^{2k} \rangle \propto \langle x(t)_A^2 \rangle^k$ found in the simulation data is significant, for it indicates *dynamic scaling*: once the time dependence of the characteristic length scale $L(t) = \langle x(t)_A^2 \rangle^{1/2} \sim t^{(1-\alpha_A)/2}$ is factored out, the shape of the probability distribution should remain constant in time. The distributions (15) and (28) clearly display this feature. Since the probability distribution is fully determined by all its moments, our measurements of the first four moments indicate that the true $n_A(x, t)$ obeys dynamic scaling as well.

At $d_c(2)=2$ one obtains the typical logarithmic correc-

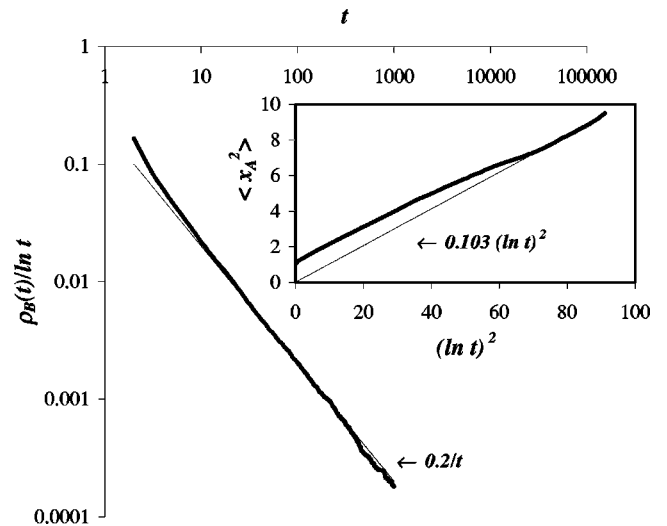


FIG. 5. The B particle density and corresponding A species mean-square displacement for the pair annihilation reaction $2B \rightarrow \emptyset$ with reaction probability $\mu=1$ in $d=2$. At long times, both plots indicate the expected logarithmic corrections to the mean-field scaling laws.

tions to the mean-field result, viz., Eq. (8) for the B particle density, and Eq. (21) for the A species mean-square displacement. Simulations were also carried out at various values of μ for a two-dimensional system. Figure 5 illustrates the apparent agreement with the above predictions at long times for simulations run with annihilation probability $\mu=1$ (averaged over five runs on a 100×100 lattice). However, such a large annihilation rate severely suppresses the A particle diffusion, so one should not really draw too firm conclusions from these measurements. We have again measured the corresponding distribution of the A particle displacements. In Fig. 6 we see that $n_A(\vec{x}, t)$ is non-Gaussian and resembles its one-dimensional counterpart (Fig. 3), though the deviations from Eq. (15) are less pronounced. When $\mu \ll 1$, anticorrelations develop over much larger time scales and as the corrections

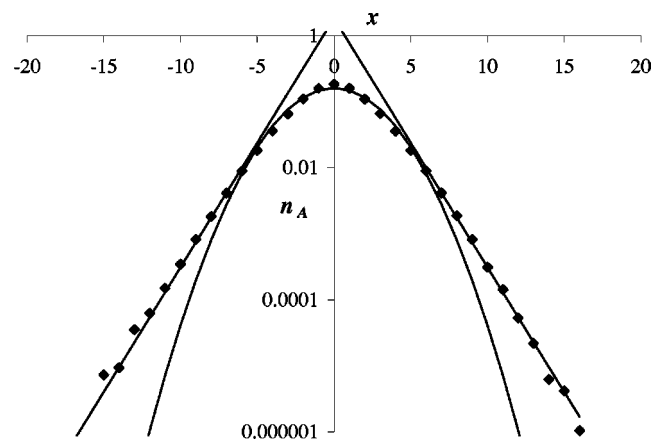


FIG. 6. The measured distribution of the final A particle displacements corresponding to the system shown in Fig. 5 (B pair annihilation in two dimensions, $\mu=1$), shown with Gaussian and unnormalized exponential fits.

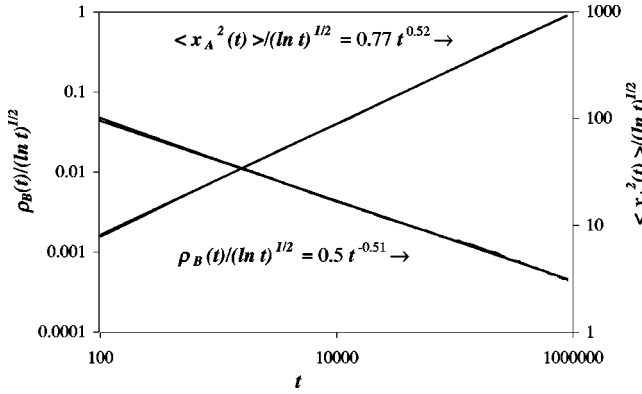


FIG. 7. The B particle density and corresponding A species mean-square displacement for the triplet annihilation reaction $3B \rightarrow \emptyset$ with $\mu=1$ in $d=1$, both displaying the expected logarithmic corrections to the mean-field scaling laws.

are only logarithmic, for $\mu=0.01$ (20 runs on a 200×200 lattice) we merely recovered the mean-field results in the regime accessible to our simulations. Though not shown here, the B density decay was captured by the mean-field power law on the time scales of our runs, and the A particle mean-square displacement followed the integral of that quantity after some initial transient behavior. Accordingly, the A particle distribution was essentially Gaussian in this situation.

C. Triplet annihilation $3B \rightarrow \emptyset$

Next we consider the triplet annihilation reaction $3B \rightarrow \emptyset$. The upper critical dimension here is $d_c(3)=1$. Hence in one dimension we expect logarithmic corrections to the mean-field power-law B density decay, as given in Eq. (9). According to the simple mean-field picture, this leads to Eq. (22) for the A species mean-square displacement. Figure 7 shows our simulation results (averaged over 20 runs on a lattice with 10 000 sites, annihilation probability $\mu=1$). We are able to clearly detect the logarithmic corrections even at $\mu=1$ since this reaction is a much slower process than pair annihilation (requiring three particles to meet on a site). The power-law regression on $\langle x(t)_A^2 \rangle / (\ln t)^{1/2}$ yields a value of $1 - \alpha_A \approx 0.52$, whereas the expected value is 0.50. Supposing the mean-field result fully applies here, this gives an idea of the overall precision of our simulation data. The A particle displacement distribution also agrees well with the predicted Gaussian, apart from a slight excess of presumably localized particles around $\langle x_A^2 \rangle = 0$ and correspondingly longer “tails” of the distribution. Yet the deviation is much smaller than in the pair annihilation case because the anticorrelations are less pronounced here.

For $d=2 > d_c$, the mean-field result (5) should provide a correct description, i.e., for $n=3$ in the long-time limit $t \gg \tau_3$: $\rho_B(t) \sim t^{-1/2}$ and $\langle \vec{x}(t)_A^2 \rangle \sim t^{1/2}$. Figure 8 demonstrates agreement with these mean-field predictions after 10^3 or fewer time steps (from 3 runs on a 100×100 lattice with again $\mu=1$). In fact, to our resolution the mean-square displacement of the A species converges to the mean-field

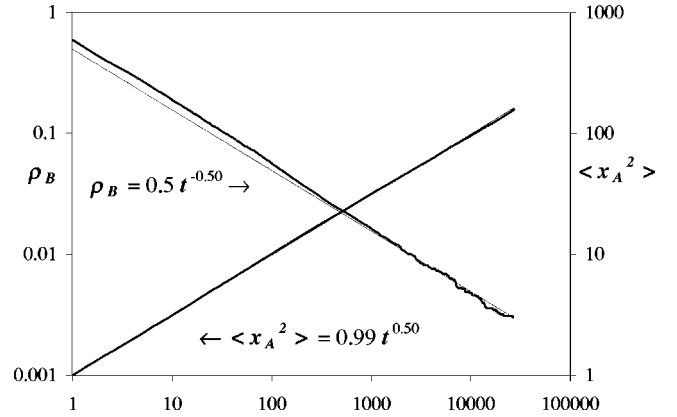


FIG. 8. The B particle density and A species mean-square displacement for the triplet annihilation reaction $3B \rightarrow \emptyset$ ($\mu=1$) in $d=2$, confirming the mean-field power laws.

power law markedly faster than the B particle density. As yet we have no explanation for this surprising observation.

D. Quartic annihilation $4B \rightarrow \emptyset$

The kinetics of quartic annihilation should be aptly described by the mean-field rate equation (4) in all physical dimensions since $d_c(4)=2/3$. Setting $n=4$ in Eq. (5) we thus expect $\rho_B(t) \sim t^{-1/3}$ for sufficiently large $t \gg \tau_4$. According to Eqs. (18) and (16), $\langle \vec{x}(t)_A^2 \rangle \sim t^{2/3}$. We ran simulations in two dimensions on a 100×100 lattice (with $\mu=1$, averaged over 8 runs) and found good agreement with these mean-field scaling laws at sufficiently long times both for the B particle density decay and the A species mean-square displacement. For the annihilation processes, larger n values imply longer crossover time scales τ_n since n particles must meet for a reaction to occur, see Eq. (5). Indeed, by comparing with the results for the triplet reactions, we noticed that the time interval of transient behavior prior to convergence to the asymptotic mean-field power law was at least an order of magnitude longer for the $n=4$ system. As in the triplet simulations, the convergence to mean-field behavior occurred faster for the A particle mean-square displacement than for the total B density.

V. ACTIVE TO ABSORBING STATE PHASE TRANSITION AND LOCALIZATION

After this preliminary study with pure B annihilation kinetics, we now turn our attention to the primary goal of our investigation, namely anomalous diffusion on a dynamic fractal (see Fig. 1). Each reaction discussed below exhibits a continuous phase transition separating active and absorbing stationary states. At the critical point, the B particle distribution is known to be fractal in space and time. Thus the assumption of a homogeneous B particle distribution is significantly violated, and we expect the mean-field description for the A species propagation to be inadequate. Our aim has been to measure and characterize the deviations from the mean-field predictions. All of the phase transitions in the B particle system to be discussed here are described either by the directed percolation (DP) or parity conserving (PC) universal-

ity classes. The accepted critical DP exponents are listed in Table I. As mentioned in Sec. I, a PC phase transition is observed in $d=1$ when $\lambda=0$ in the reaction scheme (1), and m is even; in higher dimensions the (degenerate) critical point occurs at zero branching rate and is governed by mean-field exponents [7]. The PC exponents in $d=1$ are also given in Table I.

Knowledge of the B particle density behavior of these systems in the active and absorbing states near the phase transition is also important, both in locating the critical point and for comparison with the asymptotic critical scaling laws. In fact, in simulations we will inevitably always be slightly away from the precise critical control parameter values. However, in the vicinity of the phase transition we expect the system to exhibit the critical power laws for some time interval before crossing over to subcritical or supercritical behavior. The closer the system parameter values are to the critical ones, the longer this critical regime lasts, as also suggested by Eq. (27), and the more precisely critical exponents can be measured. When m is odd (independent of λ), we expect systems in the absorbing state (i.e., dominated by annihilation reactions) to exhibit behavior dictated by Eq. (6), the solution to B particle radioactive decay, with some effective rate λ_{eff} , dependent on λ , σ , and μ . To be more precise, let us consider reactions (1) with $m=1$ and $n=2$ as is the case in many of the situations examined below. Recalling that the branching reactions are local (offspring particles are placed on the parents' neighboring sites), in low dimensions there is a significant probability that the parent and offspring will meet in the next few time steps after the branching reaction and undergo pair annihilation. Together, the branching and subsequent annihilation reactions generate the decay $B \rightarrow \emptyset$, even if $\lambda=0$ on the outset. Generally, this is true when $n=2$ and m is odd. However, when $n=2$ and m is even, local parity conservation eliminates the possibility to generate "spontaneous" death processes. Thus in the PC universality class the inactive phase is characterized by the power laws of the pair annihilation reactions $2B \rightarrow \emptyset$, whence in subcritical systems one should asymptotically observe the behavior given in Eq. (7) with $d=1$. In the active phases of both DP and PC systems, the B density will approach its stationary value exponentially. This follows immediately from linearizing the corresponding mean-field rate equations.

A. Directed percolation universality class, $d=1$

To search for the DP transition in one dimension, we considered reactions (1) with $m=1$ and $n=2$, with $\lambda=0.01$ and $\mu=1$ fixed while σ was varied. Notice that setting $\mu=1$ eliminates the possibility of multiple B particles occupying the same site, so that the B particle density exactly corresponds to the density of available lattice sites for A particle hopping. According to the list in Table I, $\rho_B(t) \sim t^{-0.159}$ at criticality, which implies within the mean-field approximation ($\alpha_A = \alpha_B$) that $\langle x(t)_A^2 \rangle \sim t^{0.841}$. Our closest estimate of the critical point is $\sigma_c \approx 0.8975$. Figure 9 shows the power-law dependence of $\rho_B(t)$ and $\langle x(t)_A^2 \rangle$, obtained from 26 runs on a lattice with 10 000 sites. The double-logarithmic linear regressions yield values $\alpha_B = 0.161$ and $\alpha_A = 0.167$ over

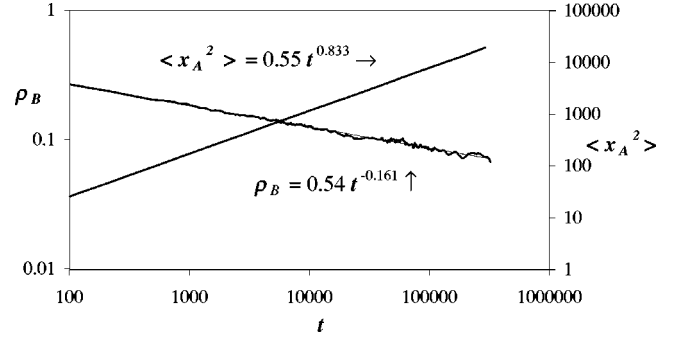


FIG. 9. The B particle density and A species mean-square displacement for the DP reactions $B \rightarrow \emptyset$ ($\lambda=0.01$), $B \rightarrow 2B$ ($\sigma=0.8975$), $2B \rightarrow \emptyset$ ($\mu=1$) in $d=1$.

more than three decades, i.e., $\alpha_A - \alpha_B \approx 0.006$. As we estimate the numerical uncertainty of the measured exponents to be at least ± 0.01 , we observe agreement both between α_B and the DP prediction as well as between α_B and α_A within our error bars. We also computed local exponents, as defined in Eq. (26) setting $b=2$. Figure 10 indicates that after following some transient behavior, $\alpha_A \approx 0.158$, in excellent agreement with the critical DP value. Thus we conclude that our mean-field prediction of the A particle mean-square displacement time dependence works excellently for this reaction at least on the time scales we were able to access with our simulations.

In Fig. 11 (inset) we demonstrate the algebraic dependence of the B particle correlation function on particle separation, indicating the spatially fractal structure at criticality. The data were taken at $t=50\,000$, averaged over nine simulations. The measured exponent $2\beta/\nu$ agrees well with the DP prediction 0.50 in $d=1$ over two decades. We remark that for small distances we observed that the correlation function scales as $C_B(|x|) \sim |x|^{-\beta/\nu}$, i.e., with precisely one half the asymptotic scaling exponent. The origin of this can be understood as follows: at low B particle densities, the site occupation number $n(x)$ is either zero or one; hence for $|x| < \xi$ $\langle n(x)n(0) \rangle \approx \langle n^2 \rangle = \langle n \rangle - \rho_B \sim \xi^{-\beta/\nu}$. The proportionality factor here must be a scaling function $f(r/\xi)$, and demanding that the ξ dependence must cancel at criticality, we

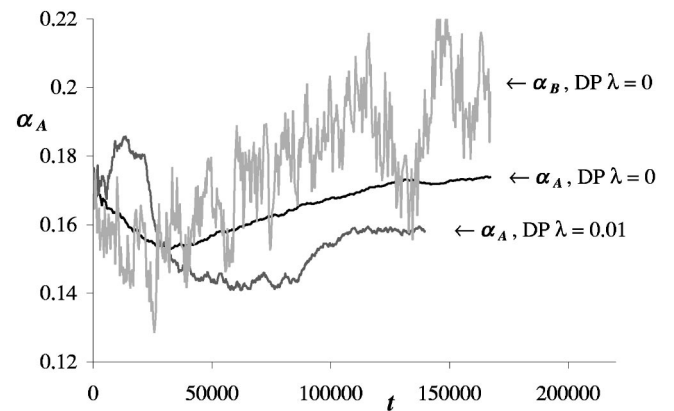


FIG. 10. The local exponent α_A corresponding to data shown in Fig. 9 (with $b=2$) and Fig. 14 (with $b=4$).

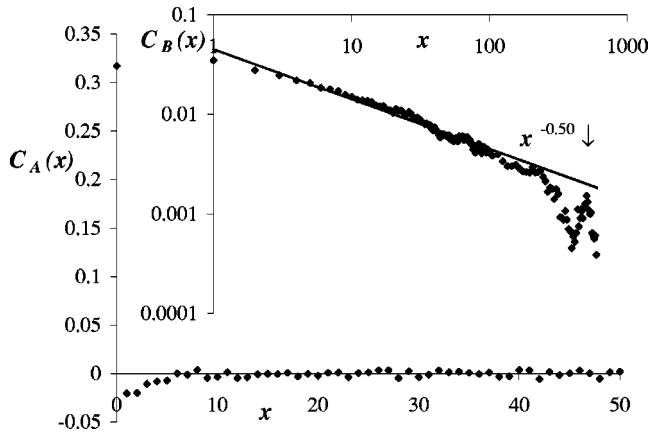


FIG. 11. The A and B particle pair correlation functions $C_A(x)$ and $C_B(x)$ (inset) at the DP critical point ($d=1$, measured at $t = 50\,000$). $C_B(x) \sim |x|^{-2\beta/\nu}$ is approximately scale invariant. The A particles are very likely to be found on the same site, but there is a slight negative correlation with nearby sites. $C_A(x)$ is essentially zero at distances $|x| > 10$.

obtain the aforementioned scaling law. As we are not precisely at the critical point, we see a crossover to exponential decay at large distances.

Figure 12 depicts the measured full A particle displacement distribution at $t = 50\,000$. It displays an excess of localized particles and corresponding long tails of the distribution, similar to the pair annihilation case. But the deviation from a Gaussian distribution appears much less pronounced in this system. The power-law dependence of B particle spatial correlations qualitatively suggests the observed distribution. Such strong correlations yield macroscopic regions of relatively large B densities which an A particle may traverse and thus acquire a large displacement. However, such clusters necessarily indicate compensating large regions of very low B particle density, where the A particles become highly localized. The A particles at the fractal “boundary,” which by its nature accounts for a significant fraction of the system volume, appear to behave in accord with the mean-field prediction. This is suggested by the fact that the data in Fig. 12

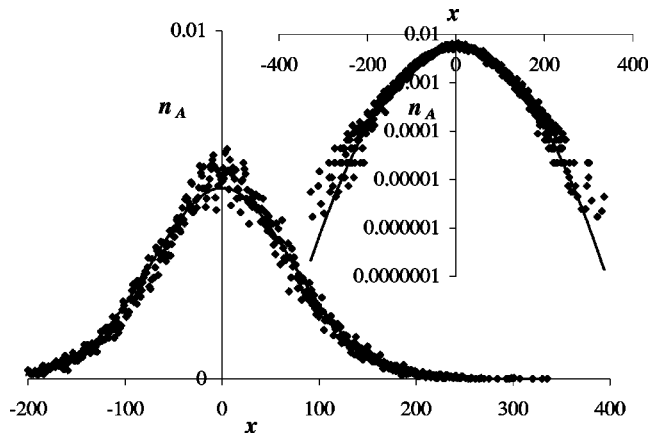


FIG. 12. The measured distribution of the A particle displacements corresponding to the system shown in Fig. 9 (DP critical point for the B system in $d=1$, measured at $t = 50\,000$).

agree well with a Gaussian distribution for intermediate displacement values.

Yet it was in these fractal boundaries that we expected the deviation from the mean-field approximation to arise. One possibility we had imagined is that A particles in the boundary region are driven towards denser B regions owing to the particle density gradient expected from the formation of clusters, thus destroying the spatial homogeneity of the A particles and resulting in a higher net diffusion rate than assumed by mean-field theory. This behavior can be distinguished by computing the A - A particle correlations. If the described large-scale A - B coupling were strong enough, then we would expect to see some A particle correlations as they congregate in regions of high B density. But these correlations were not observed, as demonstrated in Fig. 11. We may attribute the inability of the B particles to induce significant correlation in the A system to the low connectivity of a one-dimensional lattice. However, $C_A(0)$ does indicate a significantly increased probability to find multiple occupation of a given site. A weak negative correlation seems to have developed for $0 < |x| < 5$. Such a distribution may be the result of the “piggy-back” effect discussed earlier: several A particles may in fact follow a single B particle through a number of time steps. If the B particle is subsequently annihilated, the “piggy-backing” A particles are all (temporarily) localized at their current site. The negative correlation may just be the compensation for the effective mutual attraction of a group of nearby A particles all following the same B .

We have also measured the higher moments of the A displacement distribution $n_A(x, t)$. We found $\langle x(t)_A^{2k} \rangle = c_k \langle x(t)_A^2 \rangle^k$, indicating dynamic scaling, albeit with $c_2 = 3.3$, $c_3 = 20$, and $c_4 = 185$ compared with the values 3, 15, and 105 that would result from a Gaussian. A few distinctions between the pair annihilation case and this DP phase transition may account for the significant differences in the corresponding deviations from the mean-field A displacement distribution. First, the B particle density decays much slower in the DP case ($\alpha_B \approx 0.16$ as compared with 0.5). This slower decay may cause the DP distribution to be dominated by the “active” A particles. For a fixed system size we will also observe the DP system for longer durations. Since the B particles undergo ordinary diffusion while reacting, these extended time scales imply that previously localized regions (where the local B density is zero) are likely to be visited by wandering B particles. Thus the localized portion of the A particle distribution becomes smeared as these A particles are reactivated, which makes it more likely that all A particles experience roughly the same average effective diffusion coefficient throughout the simulation (as assumed in the mean-field approach). Finally, at the DP phase transition, the B particles are positively correlated, whereas the pair annihilation process induces negative correlations. Positive correlations may also contrive to weaken particle localization, since the A species in regions of high local B density are less dependent on single B particles for their mobility. We also note that as a consequence of the effective “slaving” of the A species by the B particles, the correlation length exponents ν and $\nu_t = z\nu$ should be identical for both the active to absorbing transition in the B system and the induced A local-

ization transition. Indeed, to the accuracy we could determine those exponents by means of Eq. (27) and the method described in Ref. [15], this equality appeared to hold.

The expected time independence of the equal-time B density correlation function and the extent of the B particle clusters explain the time independence of the A displacement distribution. Recall that the origin of the non-Gaussian distribution is that the A particles experience different effective diffusivities depending on their location with respect to B clusters. What determines an A particle's placement in the distribution is the average diffusion coefficient experienced over the length of the simulation, neglecting the possibility of biased diffusion due to B particle gradients. For the shape of the displacement distribution to remain constant in time, the shape of the distribution of time-averaged effective diffusion rates most likely remains constant as well (even while on average the effective A species diffusion rate is decreasing with time). Subsequent measurement of the A diffusivity distribution supports this interpretation, see Fig. 27 in Sec. VI below. This is only possible if A particles are able to remain in a dense B region for a large portion of the simulation, made possible by large cluster sizes implied by the power-law correlation function, while others remain in a low-density region for long durations. These two persisting extremes maintain the non-Gaussian nature of the A species displacement distribution. However, A particles at the fractal boundary, which comprises a considerable volume of the system and thus contains a large fraction of the A particles, may all see roughly the same effective diffusion rate over the length of the simulation, which results in the Gaussian mid region of $n_A(x, t)$. Furthermore, the stationarity of the shape of the distribution of effective A diffusivities is likely the reason we see such good agreement between α_A and α_B . For instance, even if the global average instantaneous diffusion rate evolved as $\bar{D}\langle\rho_B(t)\rangle$ (as we should expect), a changing distribution shape, such as increasing enhancement of the phase separation between “localized” and “active” regions while maintaining the proper global diffusion rate, would induce additional time dependence and cause deviations from Eq. (18). However, we have no precise argument for the apparent time independence of these distributions.

We also sought to verify the predicted behavior away from the phase transition. Setting $\sigma=0.910$, sufficiently above the critical branching rate, we observed almost immediate convergence of the B particle density to its active state saturation value $\rho_s=\langle\rho_B(t)\rangle\approx 0.26$, with standard deviation 0.009. As expected and depicted in the inset of Fig. 13, the A species then exhibits normal diffusion ($\alpha_A=0$). (The slight deviation at the end of the single run on 10 000 sites may be a finite-size effect.) By Eqs. (18) and (16) we also expect the prefactor to be $2\bar{D}\rho_s$, wherefrom we estimate $\bar{D}\approx 0.39$. For ordinary diffusion, in the absence of any correlations, $\bar{D}=0.5$. Indeed, our algorithm dictates choosing a hopping direction first, and then checking for the presence of a B particle at the destination site. Thus on average one of two neighboring A particles will hop to a B site. To observe subcritical behavior, we set $\sigma=0.890$. Figure 13 illustrates the convergence to the expected exponential density decay with

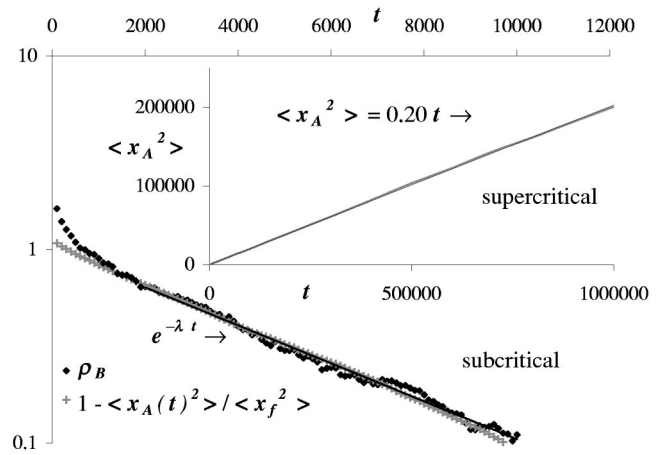


FIG. 13. A species mean-square displacement in the supercritical and subcritical regimes for the DP processes of Fig. 9 ($d=1$). For $\sigma=0.910>\sigma_c$, one finds normal A diffusion. In the subcritical regime ($\sigma=0.890$), the B particle density decays exponentially with $\lambda_{\text{eff}}\approx 0.0002$, and the mean-square A displacement approaches the asymptotic value exponentially with the same time constant. (Both subcritical datasets are rescaled to a unit prefactor.)

an effective decay rate $\lambda_{\text{eff}}\approx 0.0002$ (ten runs on a system with 10 000 sites). Initially (for $t<1000$), a brief quasicritical regime is visible with power-law decay $\rho_B(t)\sim t^{-0.26}$ and correspondingly $\langle x(t)_A^2 \rangle\sim t^{0.77}$. For $t>2000$ we then observe exponential convergence to $\rho_B=0$ and the stationary value for $\langle x(t)_A^2 \rangle$, both with the same time constant $\lambda_{\text{eff}}\approx 0.0002$.

As discussed above, we expect the macroscopic properties of the DP phase transition to be independent of the value of λ , for $d\leq 2$ even persisting to $\lambda=0$, i.e., the absence of spontaneous decay. To check this, we ran simulations for reactions (1) with $m=1$ and $n=2$, setting $\lambda=0$, $\mu=1$, and varying σ . We estimated $\sigma_c\approx 0.8930$, slightly below the value found when $\lambda=0.01$. Figure 14 demonstrates the critical behavior deduced from data taken over more than three

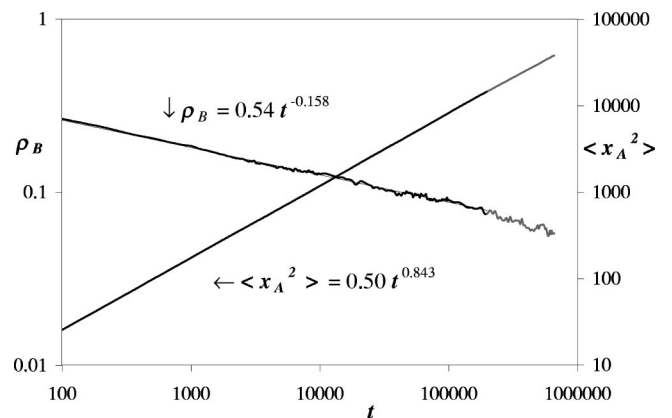


FIG. 14. The B particle density and A species mean-square displacement for the DP reactions (branching and annihilating random walks with odd offspring number) $B\rightarrow 2B$ ($\sigma=0.8930$) and $2B\rightarrow\emptyset$ ($\mu=1$) in $d=1$. For $t<200\,000$, the critical power laws are observed. Subsequently a crossover to subcritical behavior can be seen.

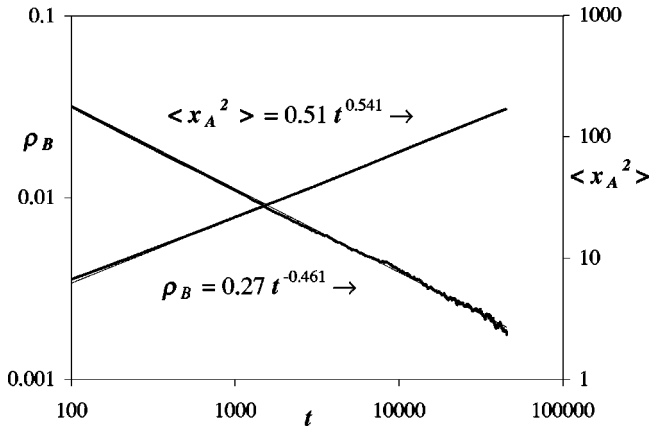


FIG. 15. The B particle density and A species mean-square displacement for the DP reactions $B \rightarrow \emptyset$ ($\lambda = 0.01$), $B \rightarrow 2B$ ($\sigma = 0.2233$), $2B \rightarrow \emptyset$ ($\mu = 1$) in $d = 2$.

decades (20 runs in a lattice with 20 000 sites), before the transition to subcritical behavior becomes evident. We found $\alpha_B \approx 0.158$, in superb agreement with the expected DP value 0.159. We measured $\alpha_A = 0.157$, so $\alpha_B - \alpha_A \approx 0.001$. Again any significant deviations from the mean-field prediction at the critical point, if present at all, must arise at time scales inaccessible to our simulations.

However, the local exponents α_A and α_B , setting $b = 4$ in Eq. (26), turned out not to be constant. In the regime from which we inferred the global values of α_B , the local values oscillate about their averages by ≈ 0.01 , whereas the local α_A is a much smoother function in time (see Fig. 10). The steady increase in α_A (and α_B) indicates that the system is actually in the inactive phase. We found the increase in the local α_B exponent to be significantly faster. However, this is not an indication of deviation from the mean-field prediction for the mean-square displacement of the A species. We, in fact, computed numerically the integral of the B particle density and compared it with the measured mean-square A displacement. We found that for $t > 10\,000$, the error between the two measurements was less than 1%. We estimated $\tilde{D} = 0.39$ for this reaction in order to obtain the best match between the measured mean-square A displacement and the integral of $\rho_B(t)$. This value is in good agreement with estimates from other reactions. Both the B and A particle correlation functions and the A species displacement distribution were basically identical to Figs. 11 and 12.

B. Directed percolation universality class, $d = 2$

To investigate the properties at a DP transition in two dimensions, we used the same reactions and rates as in $d = 1$, namely $B \rightarrow \emptyset$ ($\lambda = 0.01$), $B \rightarrow 2B$ (varying σ), and $2B \rightarrow \emptyset$ ($\mu = 1$). For $d = 2$, Table I predicts $\rho_B(t) \sim t^{-0.451}$, which implies, according to our mean-field description, that $\langle \vec{x}(t)_A^2 \rangle \sim t^{0.549}$. Our best estimate of the critical branching rate is $\sigma_c \approx 0.2233$. Figure 15 shows the power-law dependence of $\rho_B(t)$ and $\langle \vec{x}(t)_A^2 \rangle$, inferred from 40 runs on a 800×800 square lattice. The initial A density was set to 0.01 (as opposed to the usual 0.5) here. The power-law fits imply

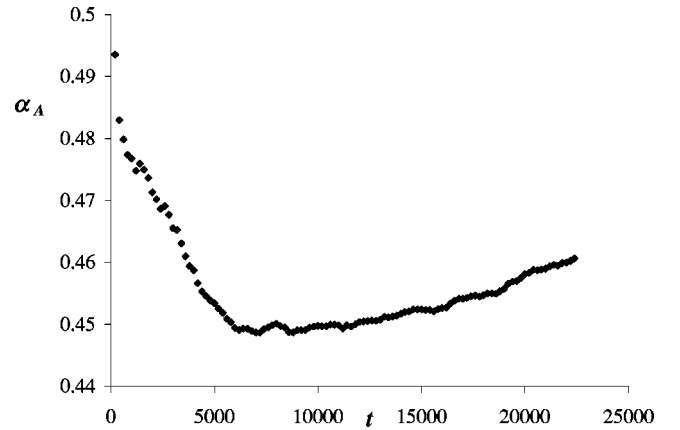


FIG. 16. The local exponent α_A corresponding to data shown in Fig. 15 (with $b = 2$).

$\tilde{D} = 0.256$, very close to the expected 0.25 from ordinary diffusion in two dimensions (since on average one A particle will hop to each available B site). The slight error in computing \tilde{D} is probably a result of the transient behavior at the beginning of the simulation, where the B density is still larger than what the power-law fit would predict. Figure 16 shows the local exponent α_A (computed with $b = 2$), indicating that the system is indeed subcritical, as α_A is increasing with time for large t . But the minimum plateau value is very close to the predicted $\alpha_A \approx 0.45$. Figure 17 demonstrates that the B particle distribution is still fractal at $t = 50\,000$, yielding an effective exponent value $2\beta/\nu$ close to 1.59 (as expected from DP) at intermediate distances. Figure 18 depicts the A species displacement distribution at $t = 50\,000$ together with the mean-field Gaussian and an (unnormalized) exponential fit of the distribution tails. As in previous cases, the “tails” of the distribution are longer than a Gaussian would suggest, and instead appear to be matched well by an exponential.

At last, we verify the DP transition in two dimensions when $\lambda = 0$, and compare the A particle anomalous diffusion to the nonzero λ case, using the same reaction rates as before in $d = 1$. Because α_B is so large for DP in $d = 2$, we had to use quite sizable systems (800×800) to measure exponents over several decades in search of the critical point. Thus our

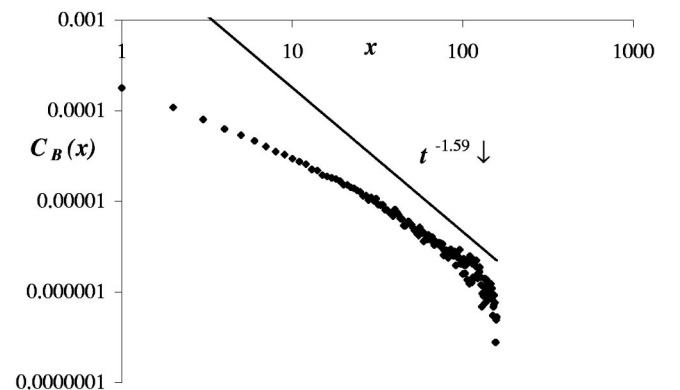


FIG. 17. The B particle pair correlation function $C_B(x)$ at the DP critical point ($d = 2$, measured at $t = 50\,000$).

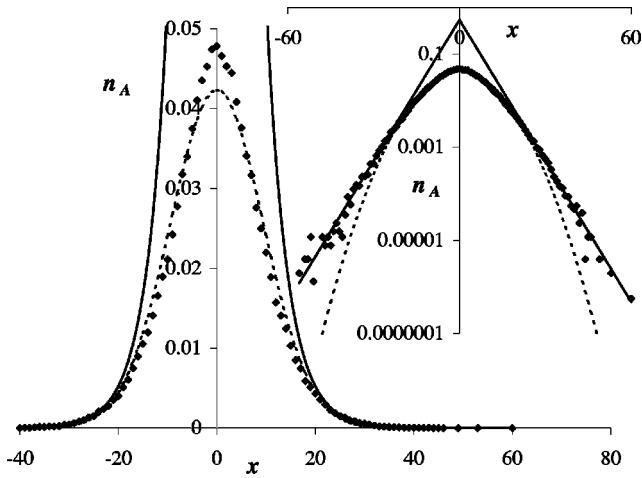


FIG. 18. The measured distribution of the A particle displacements corresponding to the system shown in Fig. 15 (DP critical point for the B system in $d=2$, measured at $t=50\,000$). The dashed line indicates a Gaussian fit, and the solid line represents an unnormalized exponential fit to the distribution tails.

determination of σ_c was not as precise. For the B particle density and A species mean-square displacement as functions of time, the measured exponents are $\alpha_B \approx 0.47$, approximately 0.02 larger than the DP value, and $\alpha_A \approx 0.48$. We found our system close to but below criticality, and therefore observed time-dependent local exponents α_A and α_B . We also completed fewer (20) runs for this system, and so expect a larger error on our measurements of the exponents. The power-law fit prefactors imply $\tilde{D} \approx 0.29$, in fair agreement with our expectation of 0.25 and previous measurements. In summary, we have not uncovered any significant deviations from the behavior observed for $\lambda > 0$.

C. Parity conserving universality class, $d=1$

In order to observe the phase transitions from active to inactive/absorbing states in the PC universality class, we looked at branching and annihilating random walks with even number of offspring particles, i.e., set $\lambda=0$, $n=2$, and either $m=2$ or 4 in the reaction scheme (1). In the former case, $2B \rightarrow \emptyset$ combined with $B \rightarrow 3B$, we were forced to set the annihilation probability to $\mu=0.5$ in order to detect the phase transition (at varying branching probability σ). Figure 19 shows the power laws for the B particle density decay and the A species mean-square displacement as a function of time near the phase transition (at $\sigma_c \approx 0.2175$). Our measurement of $\alpha_B = 0.269$ agrees fairly well with the expected PC exponent 0.285 (from 20 runs, each with 60 000 sites). Furthermore, $\alpha_A = 0.271$ is in excellent agreement with α_B . The power-law fits shown imply $\tilde{D} = 0.45$ for this reaction. Figure 20 depicts a measurement of the B density correlation function at $t=50\,000$, and the predicted PC exponent ratio 1.15 according to Table I. Measurements of $C_B(x)$ at $t=50\,000$ and $t=100\,000$ yielded distributions very similar to that shown in Fig. 20. Figure 1 shows a space-time plot for these reactions illustrating the fractal nature of the process at criticality.

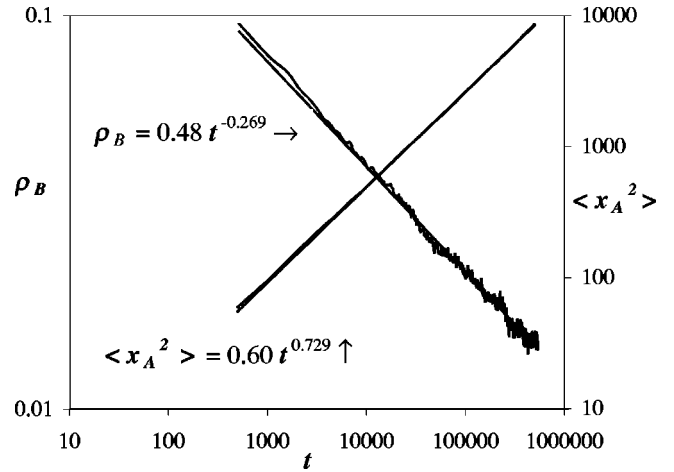


FIG. 19. The B particle density and A species mean-square displacement for the PC reactions $B \rightarrow 3B$ ($\sigma=0.2175$), $2B \rightarrow \emptyset$ ($\mu=0.5$) in $d=1$.

We also observed the critical behavior for the PC reactions $2B \rightarrow \emptyset$ ($\mu=1$) combined with $B \rightarrow 5B$. Setting $\mu=1$ helps to minimize the number of necessary random numbers, as well as prohibits the multiple occupation of lattice sites and thus avoids discrepancies between the B particle density and the density of available sites for the A species. In Fig. 21 we display the B density and A species mean-square displacement as a function of time near the phase transition (at $\sigma_c \approx 0.2795$), implying $\tilde{D}=0.50$ (averaged over 20 runs on the lattice with 60 000 sites). Indeed we again find good agreement $\alpha_B \approx 0.274 \approx \alpha_A$, as well as with the simulation data depicted in Fig. 19, and the predicted PC value. In addition, we measured the A displacement distribution at three distinct times: $t=50\,000$, $t=100\,000$, and $t=600\,000$. By scaling the ordinate by a factor $s=(t_2/t_1)^{(1-\alpha_A)/2}$, and the abscissa by $1/s$, the three curves are seen to be essentially identical in shape, see Fig. 22, which supports the dynamic scaling conjecture that the A particle distribution maintains its shape as it evolves in time. In Fig. 23 we show the paths of five A particles in one of the simulations contributing to the data in Fig. 21. The selected A particles are those with the

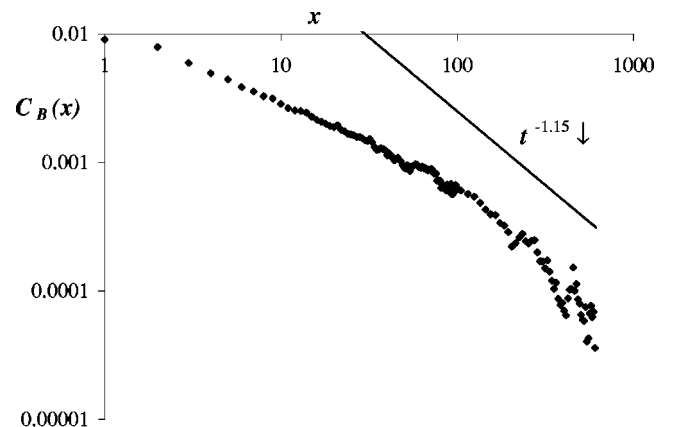


FIG. 20. The B particle pair correlation function $C_B(x)$ at the PC critical point in $d=1$ (measured at $t=500\,000$).

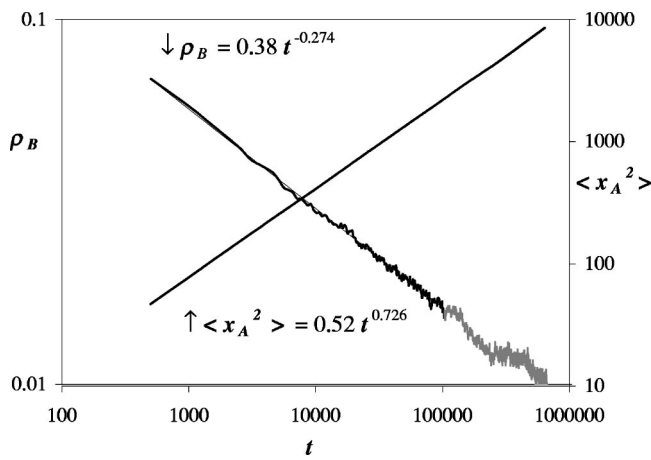


FIG. 21. The B particle density and A species mean-square displacement for the PC reactions $B \rightarrow 5B$ ($\sigma=0.2795$), $2B \rightarrow \emptyset$ ($\mu=1$) in $d=1$.

greatest displacements. The trajectories consist of periods of localization (very little activity) interspersed with periods of much movement. This diagram resembles those for other cases of anomalous diffusion such as Levy flights. We also examined a subcritical system, setting $\sigma=0.277$. Figure 24 shows an initial critical regime with $\rho_B(t) \sim t^{-0.26}$, crossing over very quickly to the subcritical behavior dominated by pair annihilation, $\rho_B(t) \sim t^{-0.48}$. We see that throughout these regimes the mean-square displacement of the A particles agrees remarkably well with the integral of the B density, setting $\tilde{D}=0.425$ (from seven runs, each with 40 000 sites).

To uncover the origins of the non-Gaussian distributions observed in the systems thus far examined, we also considered a simple model in which the B particle distribution remained uncorrelated, while still exhibiting the desired overall density decay. The algorithm allowed the B species to diffuse through the lattice without site exclusion, but removed sufficiently many of them at random so that the B density followed the prescribed global behavior. For example, we forced the B density to decay as observed in Fig.

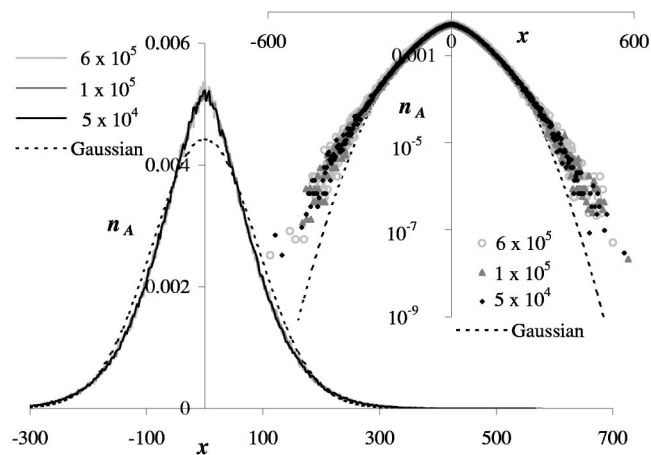


FIG. 22. The measured distribution of the A particle displacements corresponding to the system shown in Fig. 21 (PC critical point for the B system, $d=1$) at different times as indicated.

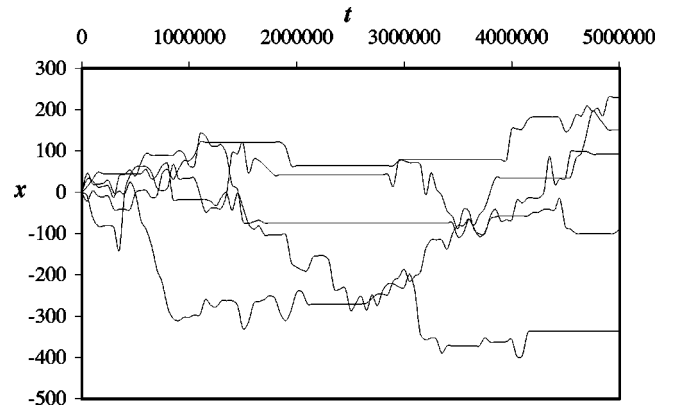


FIG. 23. The paths of the five A particles with largest displacements in a simulation contributing to the data plotted in Fig. 21. Notice the long intervals of particle localization interspersed with brief periods of high mobility.

21, near the PC phase transition in $d=1$. As would be expected, the time dependence of the mean-square displacement of the A species agreed with the integral of the B particle density with the absolute error bounded by 10. The required choice for this agreement was $\tilde{D}=0.95$, a puzzlingly large value, considering all previous observations gave $\tilde{D} \approx 0.5$. Since in this algorithm the B particles are not being continuously created and annihilated, the A - B coupling is actually stronger, and thus on average there is probably a higher density of A particles surrounding a typical B site, thereby increasing the effective A diffusivity. We may now compare the A displacement distributions at $t=100\,000$ for the homogeneous and true PC systems, see Fig. 25. Different effective diffusivities required an area-preserving rescaling. While there does appear to be some deviation from a Gaussian even in the artificial model, the figures suggest that the deviation is not as great as in the true PC system with B particle correlations. Though not shown, a rescaled version

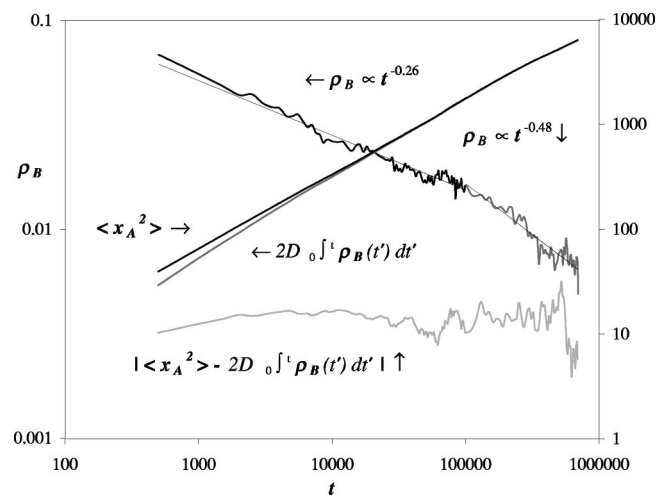


FIG. 24. The B particle density and A species mean-square displacement for the PC system of Fig. 21 in the subcritical regime ($\sigma=0.277 < \sigma_c$). The crossover from the critical power laws to those of the inactive phase is clearly visible.

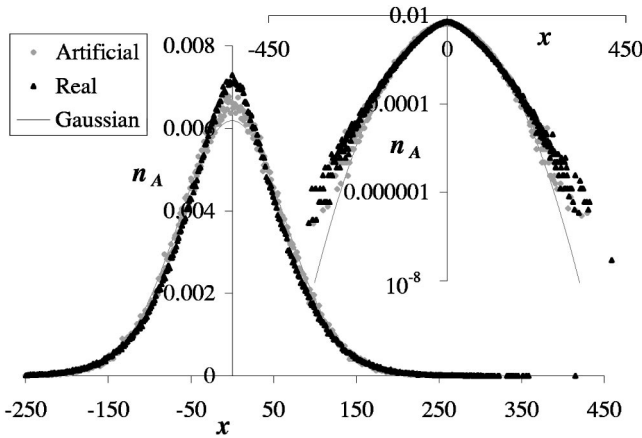


FIG. 25. The measured distribution of the A particle displacements corresponding to the system shown in Fig. 21 (PC critical point for the B system, $d=1$), compared with the one resulting from the artificial model with uncorrelated B particles. Notice that different effective diffusivities were applied to obtain equal second moments.

of the radioactive decay A displacement distribution agrees well with the “artificial” distribution shown here, as one might expect. We suggest that the low connectivity of the one-dimensional lattice necessarily causes significant deviations from the average effective diffusivity $\tilde{D}\langle\rho_B(t)\rangle$ for the A species, which then yields a non-Gaussian distribution of the A particle displacements. However, Fig. 25 demonstrates that B particle correlations are also significant in producing deviations from the mean-field prediction.

We also explored a few other algorithms to verify that our results were not particular to our implementation. First we adapted the A species hopping algorithm, so that whenever an A particle could hop, it would with probability 1. Previously, A particle hopping was implemented by choosing a direction to hop, and then checking to see if the destination nearest-neighboring site was occupied by a B particle. We executed the maximal A particle hopping algorithm for $\sigma = 0.2795$, our best estimate of the critical point for the PC system with $m=4$. The time dependence of the mean particle displacement agreed very closely with the integral of the B particle density, with $\tilde{D}=0.87$. At $t=100\,000$ the A displacement distribution coincided with that in Fig. 22, apart from a scaling factor to account for the discrepancy in \tilde{D} . The increase in this value simply indicates that A particles will hop whenever a neighboring site is available.

Next we evolved the B particles until $t=500$, when the B density was down to 0.07. Thus clusters and relatively vacant regions should have begun to form. The algorithm then placed A particles on the existing B particles and studied the A diffusion thereafter. Though after a longer transient, the mean-square A displacement approached the integral of the B density (setting $\tilde{D}=0.5$). Finally we examined an algorithm that removed A particles from the system after they had been localized for a certain time interval (here chosen as 10 000 Monte Carlo steps). We found the number of active A particles to be a sharply decreasing function of time. The local-

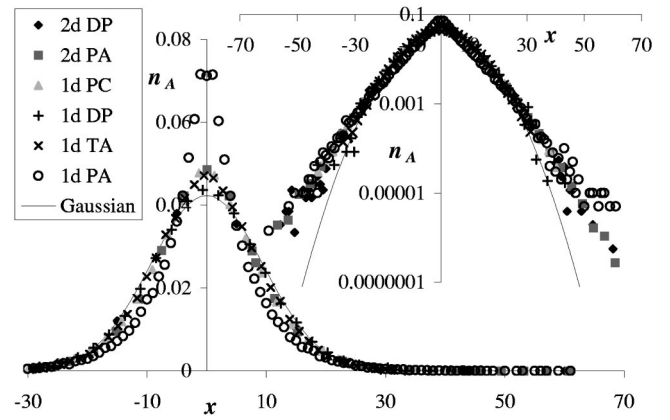


FIG. 26. The measured A species displacement distributions for the majority of systems investigated here (PA and TA represent the pure B particle pair and triplet annihilation processes, respectively). We see that most of the data collapse to roughly the same scaling function (except for the result for one-dimensional B pair annihilation with the strongest anticorrelations). The observed distribution clearly deviates from the mean-field Gaussian both at small and large displacements.

ized particles being removed from the computation had lower effective diffusion rates than the remaining active particles, overall increasing the mean-square A displacement. This observation supports the hypothesis that the effective diffusion rate for the A species is not uniform, indicating that in the previous models, a significant fraction of the A species was localized over time scales at least as large as 10 000 Monte Carlo steps. Thus most A particles are not truly diffusing through the dynamic fractal, but rather execute an occasional hop when passed over by B particles.

VI. CONCLUDING REMARKS

We have numerically investigated the reaction-controlled diffusion model introduced in Ref. [8] for various B species reaction systems, and studied the ensuing anomalous diffusion for the A particles on the emerging dynamic fractal B clusters. We found excellent agreement for all examined systems of the A species mean-square displacement $\langle\vec{x}(t)_A^2\rangle$ with the integral of the mean B particle density $\langle\rho_B(t)\rangle$, at least within the accuracy of our data. However, the mean-field Gaussian distribution (15) for the A particle displacements was not observed. We have argued that the primary factor in creating this deviation is a variation in the effective diffusion rate of the A particles, which is proportional to the number of hops executed by an A throughout the simulation run. The shape of the resulting A displacement distribution was seen to be the same at different times and also over many different systems (see Fig. 26), thus suggesting that the distribution shape of effective diffusion rates also remains the same over different time scales and systems.

The contributing factors to producing the diffusion rate distribution were identified as persisting spatial fluctuations in the local B particle density (enhanced in situations with strong B correlations), the low connectivity of the one- and two-dimensional lattices examined here, and the fact that the

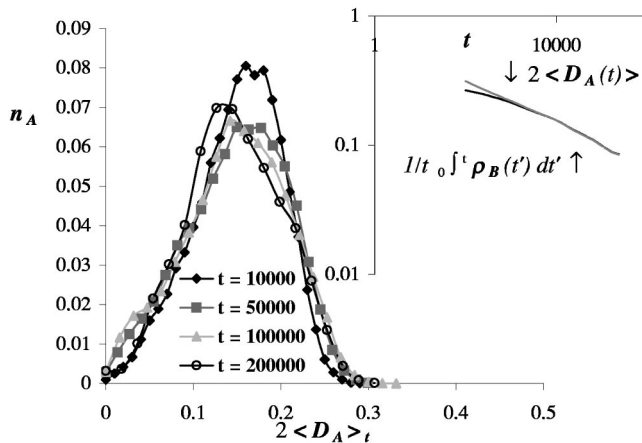


FIG. 27. The distribution of effective A diffusivities, obtained as the average number of hops per unit time, at various times during simulations for critical DP processes for the B system in $d=1$. The inset shows that the average diffusion coefficient becomes identical with the temporal average of the B species density. The diffusion rate distributions are rescaled to the same average for better comparison.

A species tend to be carried along with diffusing B particles (the “piggy-back” effect). As mentioned above, the distribution of effective diffusivities is constrained in that the average diffusion rate should equal $\bar{D}\langle\rho_B(t)\rangle$. The evolution of this average diffusion rate according to $t^{-1}\int_0^t\rho_B(t')dt'$ (see Fig. 27) coupled with the time independence of the A distribution shape, i.e., dynamic scaling, essentially yields the mean-field time behavior of $\langle\vec{x}_A^2(t)\rangle$, Eq. (18). Also, as the mean-square displacement is an integral quantity, the noise associated with fluctuations in the B particle density becomes suppressed. Consequently, under the assumption that $\alpha_A = \alpha_B$ to a very good approximation at least, one may measure critical exponents of the reacting B particle system via the passive A species using fewer simulation runs and with reduced statistical noise.

Fluctuation effects really become manifest in the higher moments only, and in the overall shape of the A displacement distribution. Figure 26 shows the A species displacement distributions $n_A(\vec{x},t)$ measured at different times from most of the systems examined thus far (apart from the case of radioactive B decay), all scaled to have approximately the same second moment $\langle\vec{x}_A^2\rangle$. Aside from the case of one-

dimensional B pair annihilation with its strong anticorrelations, all distributions appear to at least approximately collapse to the same scaling function. As we have seen previously, compared with a Gaussian this common distribution features an excess of particles both in its “tails” and peak. For the one-dimensional pair annihilation case these deviations are markedly enhanced. We find this apparent universality in the A particle displacement distribution quite surprising. Yet in each case depicted in Fig. 26, correlations developed between the B particles, leading to significant inhomogeneities in their spatial distribution.

However, assuming that the A - B coupling is sufficiently weak that approximate A spatial homogeneity is maintained, the distribution of the time-averaged effective A diffusivities is constrained by the global value $\bar{D}\langle\rho_B(t)\rangle$. We compared these quantities for a one-dimensional DP system (system size 10 000, ten runs with $\lambda=0.01$) and indeed saw excellent agreement at long times (see the inset of Fig. 27), indicating that at each time step on average one A particle hops to each B site. The discrepancy at small times can be attributed to numerical errors in computing the integral. Apparently the time-averaged diffusion rate distribution over the A particles is common to the bulk of the reaction systems studied here. To address the apparent universality in systems of positive or weak (but existing) B species correlations, we should note that localization, by which we mean the annihilation of the nearest B particle to the newly localized A , is often impermanent when the A resides in a B cluster that results from positive correlations. Figure 27 shows the effective A diffusion rate distribution at various times for the one-dimensional DP system. The distribution at $t=10\,000$ is still fairly peaked, which may be accounted for by the initial high density of B particles leading to homogenization of the diffusion rates. The distributions at later times (scaled to match the average value of the $t=10\,000$ distribution) seems approximately constant, though perhaps the peak is slowly shifting towards smaller values. Finally, we note that the measured values of \bar{D} were approximately the same for all systems, namely, $\bar{D}\approx 0.5$ in $d=1$ and $\bar{D}\approx 0.25$ in $d=2$.

ACKNOWLEDGMENTS

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[1] For recent overviews, see, e.g., H. Hinrichsen, *Adv. Phys.* **49**, 815 (2000); G. Ódor, e-print cond-mat/0205644; U.C. Täuber, *Acta Phys. Slov.* **52**, 505 (2002); M.A. Muñoz, e-print cond-mat/0210645; G. Ódor, e-print cond-mat/0304023; U.C. Täuber, e-print cond-mat/0304065.

[2] Since we allow any number of B particles to occupy the same lattice site, the last reaction in Eq. (1) is required to maintain a finite particle density in the active phase. Alternatively, one

could apply a restriction of the site occupation numbers, e.g., to 0 and 1 only.

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- [13] As a cautionary note, however, we remark that for reactions of type (1) a representation in terms of stochastic Langevin-type equations of motion is *not* generally possible; for detailed discussions, see Refs. [1].
- [14] Henceforth, ρ_A and ρ_B denote the A and B particle number densities, and we shall refer to λ , σ , and μ as the probabilities (rather than rates) for spontaneous B particle decay, offspring production, and n th order annihilation processes, respectively.
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