

# Piezoelectric MEMS for energy harvesting

Sang-Gook Kim, Shashank Priya, and Isaku Kanno

Piezoelectric microelectromechanical systems (MEMS) have been proven to be an attractive technology for harvesting small magnitudes of energy from ambient vibrations. This technology promises to eliminate the need for replacing chemical batteries or complex wiring in microsensors/microsystems, moving us closer toward battery-less autonomous sensors systems and networks. To achieve this goal, a fully assembled energy harvester the size of a US quarter dollar coin (diameter = 24.26 mm, thickness = 1.75 mm) should be able to robustly generate about 100  $\mu$ W of continuous power from ambient vibrations. In addition, the cost of the device should be sufficiently low for mass scale deployment. At the present time, most of the devices reported in the literature do not meet these requirements. This article reviews the current state of the art with respect to the key challenges such as high power density and wide bandwidth of operation. This article also describes improvements in piezoelectric materials and resonator structure design, which are believed to be the solutions to these challenges. Epitaxial growth and grain texturing of piezoelectric materials is being developed to achieve much higher energy conversion efficiency. For embedded medical systems, lead-free piezoelectric thin films are being developed, and MEMS processes for these new classes of materials are being investigated. Nonlinear resonating beams for wide bandwidth resonance are also being developed to enable more robust operation of energy harvesters.

## Introduction

The vast and continuing reduction in the size and power consumption of sensors and complementary metal oxide semiconductor (CMOS) circuitry has led to a focused research effort on onboard power sources that can replace batteries. The concern with batteries has been that they must be charged before use. Similarly, sensors and data acquisition components in distributed networks require centralized energy sources for their operation. In applications such as sensors for structural health monitoring in remote locations, geographically inaccessible temperature or humidity sensors and battery charging or replacement operations can be tedious and expensive. The need to replace batteries in a large-scale sensor network can be problematic and costly and is nearly impossible in hazardous, harsh, and large terrain deployment. An example would be embedded sensor networks in urban battlefields. Logically, the emphasis in such cases has been on developing on-site generators that can transform any available form of energy at that location into electrical energy.<sup>1</sup> Recent advances in low-power very

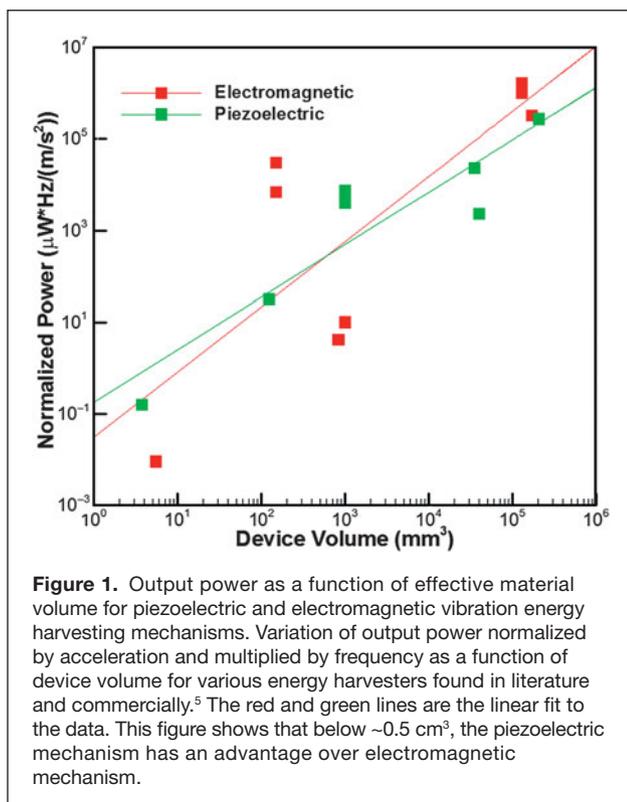
large-scale integration design have enabled ultrasmall power integrated circuits, which can run with only tens of nW to hundreds of  $\mu$ W of power.<sup>2</sup> This scaling trend has opened the door for on-chip energy harvesting solutions, eliminating the need for chemical batteries or complex wiring for microsensors, thus forming the foundation for battery-less autonomous sensors and network systems.

An alternative to conventional batteries as the power supply is to make use of the parasitic energy available locally in the environment. Unused energy is produced by industrial machines, human activity, vehicles, structures, and environment sources, which could be excellent sources for capturing small amounts of power without affecting the source itself. In recent years, several energy harvesting approaches have been proposed using solar, thermoelectric, electromagnetic, piezoelectric, and capacitive schemes at the meso-, micro-, and nano-scales.<sup>1,3,4</sup> These can be simply classified into two categories: (1) energy harvesting for sensor and communication networks using a microelectromechanical systems (MEMS)/thin-film

Sang-Gook Kim, Department of Mechanical Engineering, MIT, Cambridge, MA; sangkim@mit.edu  
Shashank Priya, Center for Energy Harvesting Materials and Systems, Virginia Tech, Blacksburg, VA; spriya@vt.edu  
Isaku Kanno, Department of Mechanical Engineering, Kobe University, Japan; kanno@mech.kobe-u.ac.jp  
DOI: 10.1557/mrs.2012.275

approach, and (2) energy harvesting for other electronic devices using bulk devices. This article mainly focuses on small-scale power energy harvesting techniques ( $\sim 1\text{--}100\ \mu\text{W}$ ) using the MEMS/thin-film approach for the self-supported operation of portable or embedded microdevices and systems. Further, we focus on mechanical vibration energy as the prime source for generating electric power since it is abundant and has an infinite life time.

The question one might ask at this stage is: “What is the best mechanism for converting mechanical energy into electrical energy at  $\sim\text{mm}^3$  dimensions?” There are several mechanisms that can be utilized to convert vibration mechanical energy into electrical energy, including electromagnetic, piezoelectric, magnetoelectric, dielectric elastomers, and electrets. Marin et al. have studied the scaling of output power as a function of effective material volume ( $v$ ) for different mechanisms.<sup>5</sup> By taking into account constitutive equations for the respective conversion mechanisms, the output power of the electromagnetic mechanism is proportional to  $v^2$ , while that of the piezoelectric mechanism is proportional to  $v^{3/4}$ . Thus, at smaller scales, the piezoelectric mechanism becomes more attractive as compared to electromagnetics. To obtain an approximation of the critical size where piezoelectricity becomes more useful, **Figure 1** plots harvester volume versus normalized output power (normalized by acceleration and multiplied by frequency) for various piezoelectric and electromagnetic prototypes reported in the literature.<sup>5</sup> From Figure 1, it can be determined that the critical size is in the vicinity of  $\sim 0.5\ \text{cm}^3$ . At a smaller device volume than this critical size, the electromagnetic



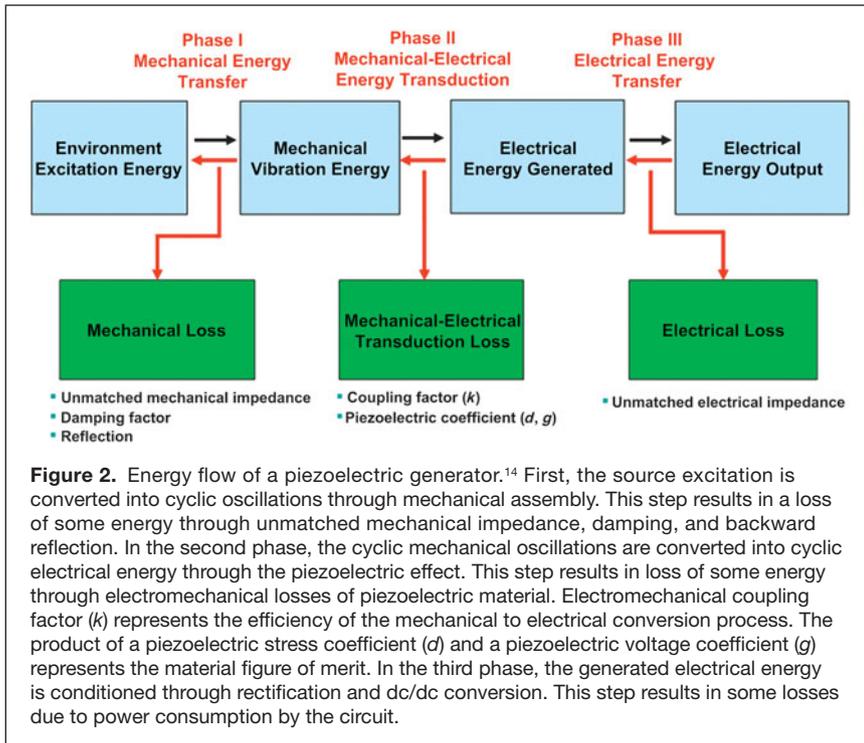
transformation factor (similar to electromechanical coupling in piezoelectrics)

$$\Phi_T \cong \sum B(y_c, z_c)(\Delta L_{\text{coil}})\cos(\theta(y_c, z_c))\Phi(y_b) \quad (1)$$

reduces sharply with a decrease in magnitude of induction and length of the coil. Here  $B$  represents the magnetic field,  $L$  is the length of the coil,  $\theta$  is the angle between  $\vec{z} \times \vec{B}$  and the differential conductor length  $d\vec{l}$ ,  $y_c$  and  $z_c$  are coordinates in the plane of the coil, and  $y_b$  is the coordinate on the beam. The transformation factor directly couples the input mechanical energy to the output electrical energy. A reasonable assumption for four-bar electromagnetic energy harvesters is that coil velocity ( $dz/dt$ ) is orthogonal to the magnetic field vector  $\mathbf{B}$  given the close proximity of magnets and coil. In order to estimate the voltage, the expression in Equation 1 is integrated over the length of the coil. Thus,  $dl$  is the integral variable. Another major problem with inductive harvesters at small scales is their low output voltage, which makes it difficult to use rectification and ac/dc conversion circuits.<sup>6</sup> In addition to the normalized power and output voltage, assembly at this scale critically affects the cost of the system. Below the critical volume, assembly of the conductive coil and magnetic layer becomes challenging since monolithic MEMS fabrication is not readily available at the present time. The mechanisms at this scale can be cost-effective if they can be fabricated by monolithic MEMS processes without substantial post-assembly efforts. Thus, for MEMS-scale energy harvesters smaller than  $\sim 0.5\ \text{cm}^3$ , piezoelectric transduction is the most appropriate scenario since standard MEMS processes are available for many piezoelectric materials. Electrostatic harvesters need separate voltage sources and are relatively bulkier than piezoelectric harvesters at the same power output.<sup>7</sup> Most importantly, piezoelectric harvesters can directly convert mechanical energy into electrical energy and can be directly integrated into monolithic MEMS-scale systems.<sup>3,8–13</sup>

Another question often posed is, “How can one achieve self-powering when the power required is much larger than what can be achieved by MEMS-scale piezoelectric harvesters?” Most reported piezoelectric devices show orders of magnitude smaller normalized power density than required by the sensors and systems at the present time. In scenarios where multiple environmental resources are available besides mechanical energy, self-powering may be achieved by developing a smart architecture, which utilizes all the environmental resources, such as wind, magnetic fields, light, sound, temperature gradients, and radio frequency waves. However, the best scenario for cost and size is to develop MEMS-scale piezoelectric harvester technology to generate sufficient power.

The general principle for conversion of low frequency mechanical stress into electrical energy using a piezoelectric transducer is shown schematically in **Figure 2**.<sup>14</sup> This transformation from mechanical to electrical energy is obtained through the direct piezoelectric effect. The resulting energy can be stored after using a rectifier and dc-dc converter circuit.



There are three primary steps in power generation as outlined in this schematic: (1) trapping the mechanical ac stress from the available source, (2) converting the mechanical energy into electrical energy with the piezoelectric transducer, and (3) processing and storing the generated electrical energy. Depending on the frequency and amplitude of the mechanical stress, one can design the required transducer, its dimensions, vibration mode, and the desired piezoelectric material. The power density of a harvesting system is dependent upon the strategies that maximize the trapping of energy and that reduce the losses occurring at each step, namely, mechanical loss due to mismatch in mechanical impedance and electromechanical loss depending upon the magnitude of the electromechanical coupling factor of the piezoelectric material.<sup>15–18</sup> The electromechanical coupling factor represents the ratio of input mechanical energy to the output electrical energy or vice-versa.

Most reported piezoelectric harvesters utilize the resonance of a cantilever beam structure, which amplifies the small ambient vibration into an in-plane strain governed by the Euler–Bernoulli beam equation.<sup>1,3,8</sup> This standard governing equation of motion can be used to find the relative displacement that is a function of position and time. The natural frequency of transversal vibration of a continuous cantilever beam can be obtained analytically from the decoupled form of the equation. In order to harvest power robustly, the resonance bandwidth of a linear cantilever beam harvester should be wide enough to accommodate the uncertain variance of ambient vibrations.<sup>9</sup> Therefore, the resonance bandwidth is an important characteristic for trapping a sufficient amount of energy onto the beam and should be accounted for in determining the performance of energy harvesters.

Piezoelectric MEMS technology is a cost-effective energy harvesting technology if it can meet the requirements for power density and bandwidth. Three major attributes to make the piezoelectric MEMS energy harvesting technology deployable for real applications are the cost of the system, the normalized power density, and the operational frequency range (bandwidth and the center frequency). The current state of the art of piezoelectric MEMS technology is reviewed in this article with respect to these attributes. The physics behind piezoelectric-based power sources is reviewed in this article along with approaches to enhance the power density by addressing the performance of piezoelectric materials and nonlinear structural designs.

## Review of piezoelectric energy harvesting

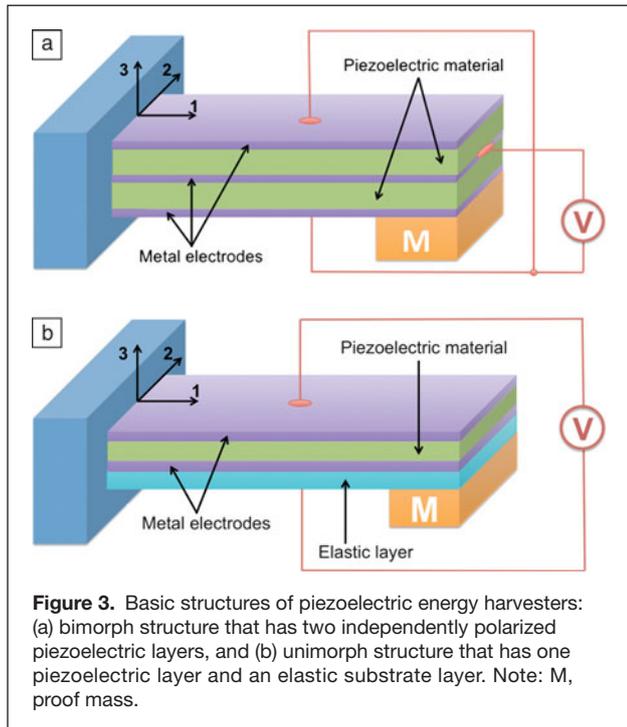
The basic principle of piezoelectric cantilever based energy harvesting can be explained by accounting for the flow of energy between different domains in Phase I and Phase II in Figure 2. Ambient vibrations inject energy

into the system through the base excitation at each cycle. This input energy is converted to kinetic energy of the proof mass,  $M$ , in Figure 3 and then to potential energy stored as the beam's mechanical strain.<sup>19</sup> Part of the elastic energy stored in the beam is transformed into electrical energy in the form of induced charge across the piezoelectric layer, which is deposited on the beam. Piezoelectric energy harvesters generally have bimorph or unimorph cantilever beam structures<sup>11,20</sup> (Figure 3). However, at the MEMS scale, bimorph piezoelectric cantilevers are less manufacturable with existing microfabrication processes. For example, lead zirconate titanate (PZT) MEMS devices are mostly spin coated, which makes it very difficult to deposit PZT on the top and bottom of a beam. As a result, MEMS cantilevers mostly have a unimorph configuration. A proof mass is usually attached at the tip of the cantilever to adjust the resonant frequency to the available environmental frequency, normally below 100 Hz.<sup>21,22</sup>

Recently, MEMS technologies have been applied toward the development of integrated energy harvesters, and many piezoelectric MEMS energy harvesters have been developed.<sup>3,9,12,21–45</sup> Useful metrics in comparing these devices are their active area, active volume, resonant frequency, harvested power, and power densities in volume or area. Devices with relatively higher power densities (in volume or area) or non-PZT materials such as AlN and lead-free potassium sodium niobate (KNN) are selectively shown in Table I. In order to understand the performance attributes defined earlier and to better compare the devices reported, basic models of vibration kinematics and piezoelectrics are summarized.

**Vibration kinematics**

Vibration as a common ambient energy source can be found in household appliances (refrigerators, microwave ovens, washing machines), large civil structures (buildings, bridges), industrial plants (refineries), automobiles, and many other common



locations. **Table II** shows some of the common sources of mechanical energy that can be harnessed through piezoelectrics. **Table III** quantifies the vibration energy available in some of these environments.<sup>46,47</sup>

The general model of a vibration energy harvester is a typical mass-spring-damper system. Maximum power is achieved when the excitation frequency  $\omega$  is equal to the natural frequency  $\omega_n$  of the system. All practical systems dissipate energy when they vibrate. To account for this, we must consider damping. Maximum extractable electrical power in terms of mass,  $m$ , mechanical damping ratio  $\zeta_m$ , electrical damping ratio  $\zeta_e$ , and acceleration  $A$  becomes,

$$P = \frac{\zeta_e}{4\omega_n(\zeta_e + \zeta_m)^2} mA^2. \quad (2)$$

Several conclusions can be drawn from Equation 2.<sup>48</sup> The extractable power from the beam is inversely proportional to the resonance frequency at a fixed acceleration,  $A$ ; therefore the energy harvester should be designed for the lowest possible frequency to achieve the highest power. The extractable power is also proportional to the (acceleration)<sup>2</sup> which limits the energy available for conversion with low acceleration vibrations whatever the specific design is chosen. It can also be seen that power is proportional to the proof mass, so a large proof mass is always desirable for energy harvesting. Finally, the term composed of the mechanical and electrical damping ratio implies that the maximum power is achieved when the electrical damping matches the mechanical damping.<sup>49</sup> When the electrical damping is equal to mechanical

**Table I. Comparison of recent small-scale piezoelectric energy harvesters.**

Reference	Active Material	Active Area, mm <sup>2</sup>	Active Volume, mm <sup>3</sup>	Acceleration, g	Frequency, Hz	Power, $\mu$ W	Power Density, $\mu$ W/mm <sup>3</sup>
Murali 2009 <sup>25</sup>	PZT, $d_{33}$	0.96	0.48	2.0	870	1.4	7.78
Morimoto 2010 <sup>13</sup>	PZT, $d_{31}$	92.5	0.26	0.5	126	5.3	20.5
Hajati 2010 <sup>19</sup>	PZT, $d_{33}$	120	0.02	4.0	1300	22	1100.0
Durou 2010 <sup>28</sup>	PZT	9.45	1.89	0.2	76	13.9	7.35
Defosseux 2011 <sup>30</sup>	AlN, $d_{31}$	3.573 (est.)	2.8	0.275	214	0.63	0.23
Marzencki 2008 <sup>31</sup>	AlN, $d_{31}$ (vac.)	1.573 (est.)	–	0.126	214	0.55	–
Hirasawa 2010 <sup>32</sup>	AlN	–	1.63	1.0	857	0.18	0.110
Elfrink 2010 <sup>38</sup>	AlN	–	15	0.2	599	69	4.60
Xu 2011 <sup>39</sup>	PZT	–	20.9	1.0	329	7.35	0.35
Lei 2011 <sup>40</sup>	PZT	–	18.6	1.0	235	14	0.75
Park 2010 <sup>41</sup>	PZT, $d_{33}$	1.8	1.05	0.39	528	1.1	1.05
Fang 2006 <sup>42</sup>	PZT, $d_{31}$	2.65	0.78	1.0	608	2.16	2.77
Aktakka 2011 <sup>45</sup>	PZT, $d_{31}$	49	27	1.5	154	205	7.59
Kanno 2012 <sup>76</sup>	KNN, $d_{31}$	56.1	0.168	1.0	1036	1.1	6.54

Initial data were taken from Park et al.<sup>41</sup> and Aktakka.<sup>45</sup> Devices with typical non-PZT material are selected. PZT, lead zirconate titanate; KNN, potassium sodium niobate.

**Table II. Sources of energy available in the surroundings that can be tapped for generating electricity.**

Human Body	Vehicles	Structures	Industrial	Environment
Walking, arm motion, finger motion, jogging, swimming, eating, talking	Aircraft, unmanned air vehicle, helicopter, automobiles, trains	Bridges, roads, tunnels, farm house structures	Motors, compressors, chillers, pumps, fans	Wind, solar, temperature gradient, daily temperature
Breathing, blood pressure, exhalation, body heat	Tires, tracks, peddles, brakes, shock absorbers, turbines	Control switch, heating ventilation and air conditioning systems, ducts, cleaners, etc.	Conveyors, cutting and dicing, vibrating machine	Ocean currents, acoustic waves, electromagnetic waves, radio frequency signal

The two rows in this table represent the difference in the scale of the mechanical energy.

damping ( $\zeta_c = \zeta_m$ ), the maximum electrical power that can be generated is given as

$$P_{e,max}(\omega_n) = \frac{mA^2}{16\omega_n\zeta_m} = \frac{mY^2\omega_n^3}{16\zeta_m}, \quad (3)$$

where the acceleration amplitude  $A$  and proof mass deflection  $Y$  are related by the relationship

$$A = \omega_n^2 Y. \quad (4)$$

Equation 3 represents the theoretical maximum of extractable power, which can be dissipated in the electrical load. This is actually a limiting factor for all linear resonator based energy harvesters if the transformation capacity of the piezoelectric layer is not a limiting factor. It has been reported that a nonlinear resonator based energy harvester can circumvent this limit and is able to generate much higher power than the mechanical damping, which will be discussed in the next section. Another parameter of interest in the design of thin-film harvesters is the generalized electromechanical coupling (GEMC) factor,  $K$ .<sup>20</sup> The GEMC factor is obtained from the equation:

$$K^2 = \frac{\omega_{short}^2 - \omega_{open}^2}{\omega_{short}^2}, \quad (5)$$

where  $\omega_{short}$  and  $\omega_{open}$  are the angular resonance frequencies of the associated short and open circuits, respectively. The GEMC represents the power generation performance of the vibration harvesters, and this value can be theoretically derived from the mechanical properties, thickness ratio, and electromechanical coupling factors of piezoelectric thin films.<sup>50</sup>

### Piezoelectrics, energy conversion, and figures of merit

Piezoelectricity is one common outcome of the lack of center of inversion symmetry in the crystal lattice. Piezoelectric generators produce high voltages and low currents and require no voltage source to operate. Some believe they are more difficult to integrate into microsystems due to the high temperature required for crystallization,<sup>21</sup> but there have been several successful implementations of MEMS scale piezoelectric energy harvesters (see Table I). Piezoelectric energy harvesters can be categorized by their power sources, such as ambient vibrations, impacts, fluid, and human power. Regardless of the vibration energy sources, the basic working principle is the same—the environment applies a stress on the piezoelectric material, and by the direct piezoelectric effect, the input mechanical energy is converted to electrical energy.

Two piezoelectric modes,  $d_{31}$  or  $d_{33}$ , are commonly used in piezoelectric microdevices (**Figure 4**). The relative directions of the electric field and the strain distinguish them:  $d_{31}$  when the electric field is perpendicular to the input strain, and  $d_{33}$  when they are parallel.<sup>51</sup> Conventional MEMS piezoelectric devices/actuators have a  $d_{31}$  configuration in which a piezoelectric layer is sandwiched between top and bottom electrodes. For a  $d_{31}$  mode energy harvester, the generated voltage is proportional to the thickness of the piezoelectric layer ( $t_{xx}$ ), the effective piezoelectric constant,  $g_{31,f}$  (Vm/N), and the applied stress,  $\sigma_{xx}$ .

$$V_{31} = \sigma_{xx} g_{31,f} t_{xx}. \quad (6)$$

For typical values of  $g_{31,f}$  and acceleration, the generated voltage becomes too small for the rectifying circuits, as the thickness of the piezoelectric layer drops below 1  $\mu\text{m}$  (mostly less than 0.5  $\mu\text{m}$ ) in MEMS-scale harvesters. Therefore, the  $d_{31}$  mode of the piezoelectric device is often not favorable for energy harvesting applications even though the generated power could be higher. For high permittivity ferroelectric piezoelectrics, the  $d_{33}$  mode can generate higher open-circuit voltages by increasing the spacing between the interdigitated electrodes where polarization wraps from one electrode to the next in alternating directions, as shown in Figure 4. Jeon et al. showed that operating piezoelectric elements

**Table III. Peak acceleration and frequency of common structures.**<sup>46,47</sup>

Vibration Source	Peak Acceleration (m/s <sup>2</sup> )	Frequency (Hz)
Base of a 5 HP 3-axis machine tool	10	70
Notebook computer while CD is being read	0.6	75
Clothes dryer	3.5	120
Second story floor of a wood frame office building	0.2	100
Railway	1.078–1.568	12–16
Truck	1.96–3.43	8–15
Ship	0.98–2.45	12–13

in the  $d_{33}$  mode is more advantageous than in the  $d_{31}$  mode for MEMS-scale PZT harvesters.<sup>12</sup> But, recently developed high  $e_{31,f}$  coefficient piezoelectric materials such as epitaxial PZT,  $\text{Pb}[\text{Mg}_{1/3}\text{Nb}_{2/3}]\text{O}_3\text{-PbTiO}_3$  (PMN-PT) or AlN can circumvent this problem, enabling  $d_{31}$  mode harvesters.

The power trapped in each cycle from Equation 2 is dissipated to structural and aerodynamic damping as well as to electrical energy via the piezoelectric effect. To maximize the harvested power, the electrical damping needs to be increased, while the structural and aerodynamic damping need to be minimized. With the strain and electromechanical coupling, the electrical power generated via the  $d_{33}$  mode piezoelectric effect of a unimorph cantilever can be expressed as

$$P_{\text{piezo}} = v_{\text{piezo}} E_{\text{piezo}} S^2 f_{\text{exc}} k_{33}^2 \quad (7)$$

and

$$k_{33}^2 = \frac{\text{stored\_energy}}{\text{input\_mechanical\_energy}} = \frac{d_{33}^2 E_{\text{piezo}}}{\epsilon_{\text{piezo}}} = \frac{e_{33}^2}{\epsilon_{\text{piezo}} E_{\text{piezo}}}, \quad (8)$$

where  $v_{\text{piezo}}$ ,  $E_{\text{piezo}}$ ,  $S$ ,  $f_{\text{exc}}$ ,  $k_{33}$ , and  $\epsilon_{\text{piezo}}$  are the volume of the piezo material, Young's modulus, strain, excitation frequency (Hz), electromechanical coupling coefficient, and dielectric permittivity, respectively. As long as the beam's stored energy minus the mechanical loss (dissipated via structural and aerodynamic damping), which can be defined as "extractable energy," is bigger than the "conversion energy" from Equation 7, the maximum harvested energy is determined by the piezoelectric layer volume and coupling coefficient. A similar statement can be made for the  $d_{31}$  mode piezoelectric harvesters.

The coupling coefficient described in Equation 7 may only be applied to conditions where the passive elastic layer stiffness can be neglected. For most MEMS energy harvesters where the piezoelectric layer is much thinner compared to the passive elastic layer, Equation 8 may not be accurate. For an energy

harvester, which consists of a thin layer of piezoelectric material and a much thicker passive elastic layer, the coupling factor can be written as:<sup>52</sup>

$$k^2 = \frac{(\text{stored electrical energy})}{(\text{total input mechanical energy})} = \frac{(\text{stored electrical energy})}{(\text{mechanical energy input to elastic layer} + \text{mechanical energy input to piezoelectric layer})}. \quad (9)$$

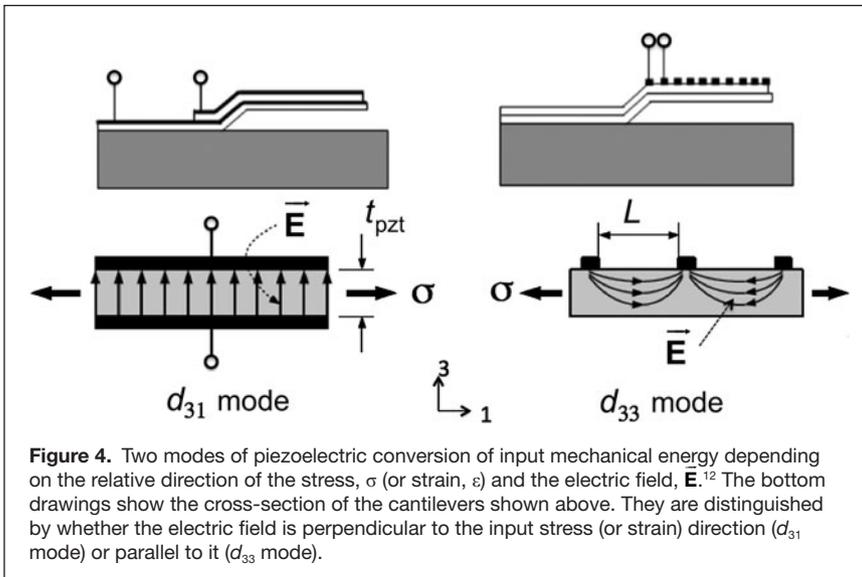
It can be readily seen that only a portion of the input mechanical energy is injected into the piezoelectric layer to be converted into electrical energy, while much of the energy stays in the elastic layer as strain energy and will not be converted. Therefore, the coupling coefficient will be lower than the real conversion rate of the piezoelectric material.

A more precise figure of merit (FOM) for the piezoelectric energy harvesters can be derived by considering the power response of the piezoelectric transducer. Recently, Oliver and Priya conducted detailed modeling of the piezoelectric cantilever<sup>53</sup> and proposed a dimensionless figure of merit (DFOM) for the piezoelectric transducer material in an energy harvesting application as<sup>54</sup>

$$\text{DFOM} = \left( \frac{k_{31}^2 \cdot Q_m}{s_{11}^E} \right)_{\text{on-resonance}} \left( \frac{d_{31} \cdot g_{31}}{\tan \delta} \right)_{\text{off-resonance}}, \quad (10)$$

where  $k_{31}$  is the transversal electromechanical coupling factor,  $Q_m$  is the mechanical quality factor (inverse of the  $Q_m$  represents the mechanical loss),  $s_{11}^E$  is the elastic compliance at the constant field condition,  $d_{31}$  is the transversal piezoelectric strain constant,  $g_{31}$  is the transversal piezoelectric voltage constant,  $\tan \delta$  is the loss factor, and  $\delta$  is the phase lag between the real and imaginary components of the dielectric constant. Please note the reduced tensor notation here. For example, elastic compliance is a fourth-order tensor but has been written in the reduced form as  $s_{11}$ . The variable 11 indicates that the stress and strain are occurring along the 1-axis of the chosen coordinate system. The DFOM is a product of two FOMs representing off-resonance and on-resonance conditions.

By comparing DFOMs for commercial piezoelectric compositions, the better piezoelectric composition could be identified for energy harvesting applications. Defossez et al. compared the off-resonance FOM for PZT and AlN and noticed a higher magnitude for AlN ( $7.8 \times 10^{-11} \text{ m}^2/\text{C}$  as compared to  $4 \times 10^{-11} \text{ m}^2/\text{C}$  for PZT).<sup>55</sup> For PZT, the values were taken to be  $\epsilon_{33}/\epsilon_0 = 935$ ,  $d_{31} = -110 \times 10^{-12} \text{ m/V}$ , and  $\tan \delta = 3.6\%$  (measured on PZT 53/47 {100}-textured  $2 \mu\text{m}$  thin film<sup>56</sup>). For AlN, the values were taken to be  $\epsilon_{33}/\epsilon_0 = 10$ ,  $d_{31} = -2.6 \times 10^{-12} \text{ m/V}$ , and  $\tan \delta = 0.1\%$  (dielectric properties measured at 10 kHz for a film with a thickness of  $2 \mu\text{m}$  by Martin et al.,<sup>57</sup> and piezoelectric properties were reported by Tsubouchi and Mikoshiba for a  $1\text{-}\mu\text{m}$ -thick film<sup>58</sup>). Considering



**Figure 4.** Two modes of piezoelectric conversion of input mechanical energy depending on the relative direction of the stress,  $\sigma$  (or strain,  $\epsilon$ ) and the electric field,  $\vec{E}$ .<sup>12</sup> The bottom drawings show the cross-section of the cantilevers shown above. They are distinguished by whether the electric field is perpendicular to the input stress (or strain) direction ( $d_{31}$  mode) or parallel to it ( $d_{33}$  mode).

that AlN processing can be made compatible with CMOS, these results indicate the promise of AlN films for developing MEMS energy harvesters.

### Challenges of piezoelectric MEMS energy harvesters

Many piezoelectric MEMS energy harvesters have been developed, as listed in Table I. Their form factors are all different and can only be compared with the power density that can be defined as the ratio of generated power over the active material volume (volume power density,  $\mu\text{W}/\text{mm}^3$ ) or over the active material area (area power density,  $\mu\text{W}/\text{mm}^2$ ). But harvesters with high resonant frequency or those that require high acceleration ambient vibration are less favorable considering the low frequency, low g characteristics of most ambient vibrations. In order to generate a comparative figure, normalization was done with respect to both area and volume of harvesters, natural frequency, and input acceleration.

Based upon Equation 3, the maximum extractable output power is proportional to  $(1/\text{frequency})$  and  $(\text{acceleration})^2$ . From Equation 7, the converted electrical power is proportional to the excitation frequency. Thus, some researchers have taken into account both frequency and acceleration variations by normalizing the power with frequency or  $(\text{acceleration})^2$ . Most reported devices show orders of magnitude smaller normalized power density than required (see Table I). One of the direct solutions to address this challenge is to improve the electromechanical coupling coefficient of the piezoelectric thin films. Another approach is to seek new resonating beam structure designs from which more energy can be extracted at lower frequency and acceleration.<sup>9</sup>

Another metric commonly used in literature is the normalized FOM, which takes into account bandwidth.<sup>59</sup> Bandwidth is also an important characteristic and should be accounted for in order to determine the performance of piezoelectric harvesters under unpredictable or uncontrollable spectra of ambient vibrations. Most piezoelectric energy harvesters have been designed based on a linear resonator (e.g., a cantilever with a proof mass). The extractable power of an energy harvester based on a linear resonator is proportional to the gain (quality factor) of the resonator, which is inversely proportional to the bandwidth. If the center frequency of a beam is off by about 2% from the input frequency, the amplitude of the beam bending drops to about 50% of the resonance peak. If it is off by 5%, then there is no resonance to amplify the strain on the piezoelectric material. Accordingly, there is a trade-off between the output power

and the bandwidth. Since we cannot control the frequency of ambient vibrations, an energy harvester with a narrow bandwidth (most linear resonators) is impractical in most real applications. Several approaches have been adopted to circumvent this gain-bandwidth dilemma. For example, the natural frequency of resonating beams can be tuned by changing the axial tension of a beam through non-contact mechanisms, such as magnetic attractive and repulsive forces. Beam dimensions and proof mass have also been tuned mechanically to widen the bandwidth.<sup>60,61</sup> However, frequency tuning inevitably consumes power, the tuning efficiency is low, and the tuning range is limited. Multiple beams of different lengths have also been utilized to address this challenge, which may not be practical in terms of size and cost. Simpler and less costly methods have been sought that can provide both the wide bandwidth and high power density required for practical MEMS-scale devices are described later.

### Recent advances in piezoelectric MEMS energy harvesting

In order to address the challenges described previously, advances have been achieved recently in piezoelectric materials and resonating beam structures to achieve higher power densities and wider bandwidth.

#### Grain textured and epitaxial piezoelectric films

The most simple and direct solution to enhance the output power at the fixed size of a device is to increase the piezoelectric coefficient value. Grain texturing has been shown to be an effective method for improving the magnitude of physical constants in piezoelectrics by achieving a domain-engineered state. In the vicinity of the morphotropic phase boundary (MPB), a rhombohedral composition oriented along the  $\langle 100 \rangle$  direction is known to exhibit optimum magnitudes of electromechanical coefficients.<sup>62</sup> Several studies have been conducted on tuning the piezoelectric properties through interfacial stress. Recent results by Han et al. have shown ~90% enhancement of ferroelectric and piezoelectric properties in MPB composition PZT thick films by tailoring the magnitude of residual stress by choosing substrates with different coefficients of thermal expansion.<sup>63–66</sup> The results of this study are summarized in **Table IV**. The electrical properties showed that the films on yttria-stabilized zirconia (YSZ) substrates with highest in-plane compressive stress had the best piezoelectric properties, while that on a Si wafer with tensile in-plane compressive stress

**Table IV. Relationship between in-plane stress and electric/piezoelectric properties in PZT thick films deposited on various substrates.**

Substrate	In-Plane Stress [MPa]	$d_{33}^{\text{eff}}$ [pm V <sup>-1</sup> ]	$\epsilon_r$ [1 kHz]	$\tan\delta$ [1 kHz]	$\Delta P_r/2$ [ $\mu\text{C cm}^{-2}$ ]	$\Delta E_c/2$ [kV cm <sup>-1</sup> ]
Silicon	119.5 ± 4.1 (Tensile)	26.4	1026	0.025	17.0	52.6
Sapphire	-131.5 ± 1.1 (Compressive)	59.8	1260	0.023	23.4	37.4
YSZ	-270.6 ± 4.9 (Compressive)	66.1	1265	0.039	25.5	30.0

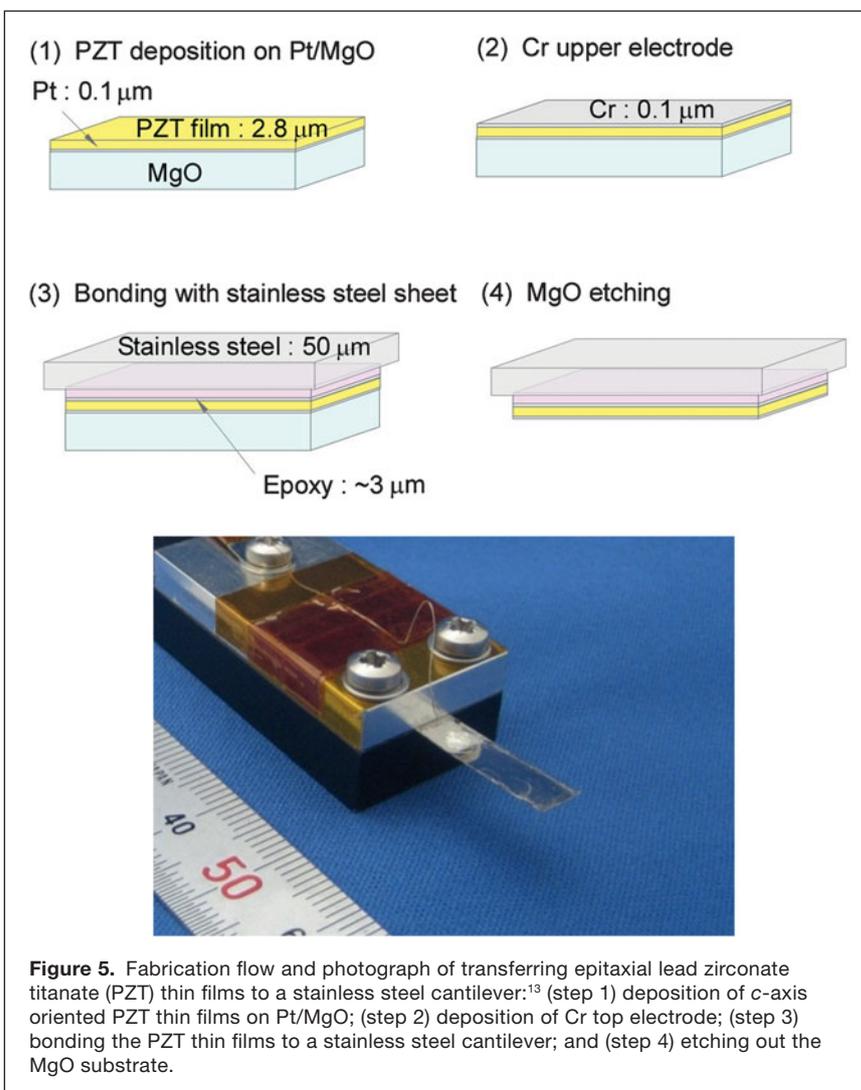
The effective piezoelectric constants ( $d_{33}^{\text{eff}}$ ) were measured by the laser beam interferometry method.<sup>63</sup>  $\epsilon_r$ , dielectric constant;  $\tan\delta$ , dielectric loss factor;  $P_r$ , remanent polarization;  $E_c$ , coercive field; YSZ, yttria-stabilized zirconia.

showed lower properties. The enhanced piezoelectric properties were attributed to the fact that the *c*-domains parallel to the thickness direction were easy to form under in-plane compressive stress. This technique of inducing a compressive stress in the films is quite appealing, as it can be easily implemented in the fabrication of MEMS components.

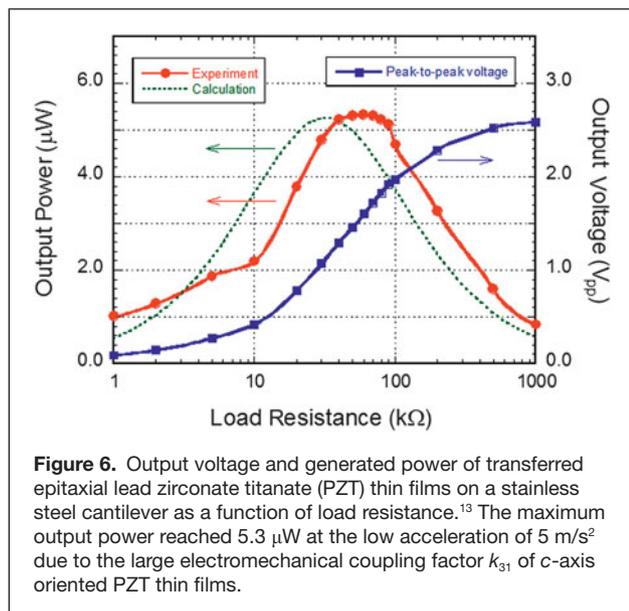
Epitaxial PZT thin films with *c*-axis orientation are also ideal materials for MEMS energy harvesters because the *c*-axis orientation of the tetragonal PZT results in large piezoelectric properties and a low dielectric constant.<sup>29,67</sup> However, epitaxial substrates, such as MgO and SrTiO<sub>3</sub>, are usually not suitable for unimorph cantilevers because of their brittleness and difficulty of microfabrication. One solution is to transfer the epitaxial PZT films onto flexible cantilevers. Qi et al. transferred epitaxial PZT thin films deposited on MgO substrates to flexible polydimethylsiloxane substrates and evaluated fundamental piezoelectric characteristics.<sup>68</sup> Morimoto et al. developed high efficiency piezoelectric energy harvesters using *c*-axis oriented PZT thin films, which were transferred onto stainless steel.<sup>13</sup> The fabrication process from this study is shown in **Figure 5**. The *c*-axis oriented PZT thin films were grown on (100) MgO single crystals with epitaxial (001) Pt bottom electrodes. Reciprocal lattice space maps of the (204) PZT before and after the transfer process clearly show spotty diffractions of the (204) PZT, indicating that the transfer process did not degrade the crystal structure of the epitaxial PZT film. After the PZT film was bonded to 50- $\mu\text{m}$ -thick stainless steel sheets with epoxy resin, the MgO substrate was etched out using phosphoric acid. A photograph of a stainless steel cantilever beam covered with the epitaxial PZT is shown in Figure 5. The relative dielectric constant  $\epsilon_r$  of the transferred films on stainless steel was as low as 166, while the piezoelectric coefficient  $e_{31,f}$  of the transferred PZT films was around  $-6 \text{ C/m}^2$ . The thickness and length of the stainless steel cantilever were 50  $\mu\text{m}$  and 18.5 mm, respectively. Because of the thin dimensions of the metal cantilever, the first resonance was found to occur at 126 Hz.<sup>13</sup> Experimental peak-to-peak voltage, and experimental and calculated averaged output power are plotted in **Figure 6** (acceleration: 5  $\text{m/s}^2$ ). A maximum output electric power of 5.3  $\mu\text{W}$  across a load resistance of 50  $\text{k}\Omega$  was measured. In this measurement, the GEMC,  $K^2$ , was calculated to be  $1.3 \times 10^{-2}$ , which is much larger than the value for polycrystalline PZT thin films on Si substrates.<sup>20</sup> This result was attributed to the large electromechanical coupling coefficient  $k_{31}$  of *c*-axis oriented epitaxial PZT thin films. The output power increased monotonically with

acceleration, reaching 244  $\mu\text{W}$  at 50  $\text{m/s}^2$ . The flexible metal cantilever enables considerable reduction of the resonant frequency and offers enhanced toughness compared with brittle Si-based cantilevers.

It is well-known that oriented relaxor ferroelectric single crystals, such as  $\text{Pb}(\text{Mg}_{1/3}\text{Nb}_{2/3})\text{O}_3\text{-PbTiO}_3$  (PMN-PT) and  $\text{Pb}(\text{Zn}_{1/3}\text{Nb}_{2/3})\text{O}_3\text{-PbTiO}_3$  (PZN-PT), show about a 10 times larger piezoelectric coefficient than conventional PZT ceramics due to the domain engineered state.<sup>69,70</sup> Recently, Baek et al. successfully grew epitaxial PMN-PT thin films on SrTiO<sub>3</sub>-buffered miscut Si substrate by off-axis sputtering (see the Baek et al. article in this issue). The piezoelectric coefficient  $e_{31,f}$  in their work was reported to be  $-27 \text{ C/m}^2$ , which is the highest value ever reported.<sup>71</sup> Using these films, they fabricated a unimorph micro-cantilever and confirmed the excellent inverse piezoelectric performance. Because of the large electromechanical coupling coefficient  $k_{31}$  (or figure of merit:  $e_{31,f}^2/\epsilon_r$ ) of PMN-PT epitaxial thin films, this system is quite promising for improving the performance of current MEMS energy harvesters.



**Figure 5.** Fabrication flow and photograph of transferring epitaxial lead zirconate titanate (PZT) thin films to a stainless steel cantilever:<sup>13</sup> (step 1) deposition of *c*-axis oriented PZT thin films on Pt/MgO; (step 2) deposition of Cr top electrode; (step 3) bonding the PZT thin films to a stainless steel cantilever; and (step 4) etching out the MgO substrate.



### Lead-free piezoelectric films

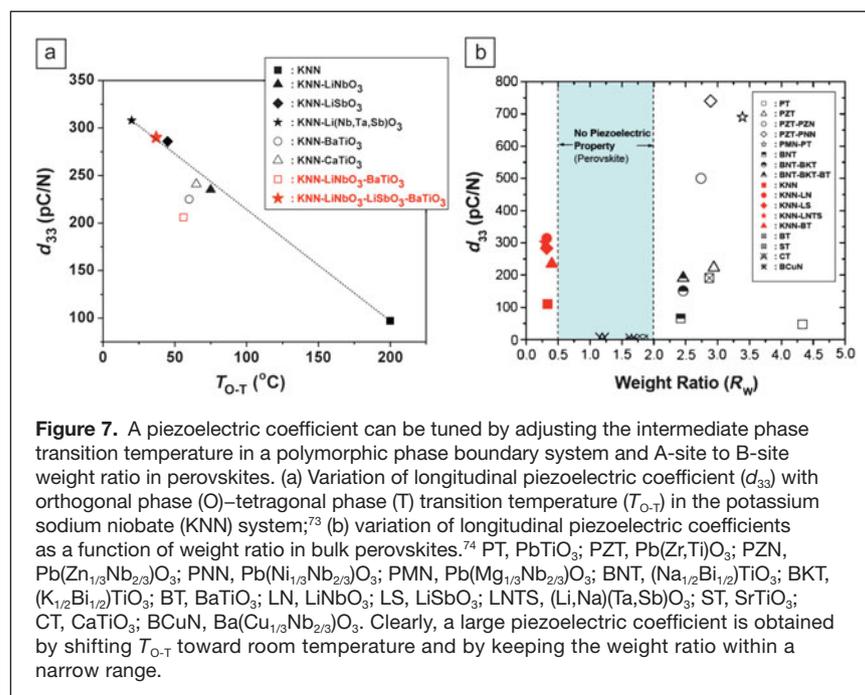
For powering medical implants and human use of energy harvesters, a lead-free piezoelectric material is desirable due to the toxicity of Pb. Potassium sodium niobate ( $\text{K}_x\text{Na}_{1-x}\text{NbO}_3$ ), or KNN, is considered to be a very promising lead-free piezoelectric material owing to its high Curie temperature and high ferroelectric orthorhombic—ferroelectric tetragonal transition temperature.<sup>72</sup> The piezoelectric properties of KNN-based compositions are directly correlated to the fraction of orthorhombic (O) and tetragonal (T) phases, as shown in **Figure 7a**. One of the strategies for achieving a higher piezoelectric response has been to modulate the composition such that the O/T transition lies close to room temperature.<sup>73</sup> Another strategy adopted for designing lead-free compositions is based upon the trend between the atomic weight ratio of A to B sites ( $R_w = W_a/W_b$ ) and the longitudinal piezoelectric constant  $d_{33}$ , as shown in **Figure 7b**.<sup>74</sup> It can be observed that  $1/R_w$  for KNN ceramics (for Na/K ratio of 0.5) is similar to  $R_w$  for PZT ceramics at the MPB composition, and both of these materials exhibit high piezoelectric response. Piezoelectric compositions show a large response when  $R_w$  for A-site heavy perovskites and  $1/R_w$  for B-site heavy perovskites are higher than 2.0.

The fabrication process of these lead-free piezoelectric materials in thin-film form is still under development, and it is expected that these materials will be utilized in the design of MEMS energy harvesters in the near future. Recently, Shibata et al. reported that KNN thin films deposited by radio frequency (RF) magnetron sputtering showed large transverse piezoelectric properties comparable to those of PZT thin films.<sup>75</sup> Kanno et al. have compared

the energy harvesting performance of KNN thin films with PZT thin films by using simple unimorph Si-cantilevers.<sup>76</sup> The piezoelectric coefficient of both KNN and PZT films showed almost the same value of  $e_{31,f} = -10 \text{ C/m}^2$ .<sup>77</sup> The relative dielectric constants of the KNN and PZT films were 744 and 872, respectively. Measurements were performed at the resonance frequency of each cantilever (KNN: 1.0 kHz, PZT: 0.89 kHz; acceleration 10  $\text{m/s}^2$ ). Peak output power for the KNN and PZT films was 1.1  $\mu\text{W}$  at 1.7  $\text{k}\Omega$  and 1.0  $\mu\text{W}$  at 1.2  $\text{k}\Omega$ , respectively. Because KNN and PZT thin films have almost the same dielectric and piezoelectric properties, the KNN film performs comparably to the PZT film with respect to power generation. GEMC  $K^2$  of KNN and PZT energy harvesters was around  $0.6\text{--}1.7 \times 10^{-3}$ , as determined by fitting the calculated value of Equation 5 to experimental results.<sup>76</sup>

### Aluminum nitride—A MEMS compatible piezoelectric film

Recently, significant progress has been made toward incorporating AlN films in energy harvesting applications. van Schaijk et al. have demonstrated the performance of micromachined AlN cantilevers and have shown that a device with dimensions of  $3 \times 1.3 \text{ mm}^2$  was able to provide 10  $\mu\text{W}$  at the resonance frequency of 1155 Hz under 8g acceleration.<sup>78</sup> Under practical acceleration values of 1g or lower, the power generated was smaller than 1  $\mu\text{W}$ . Heidrich et al. have investigated the energy generation from [001] textured AlN cantilevers and corrugated membranes for bio-implants.<sup>79</sup> The growth was conducted on Si(001) substrates, which resulted in tensile ( $< +300 \text{ MPa}$ ) and compressive strains ( $> -100 \text{ MPa}$ ), depending upon the deposition parameters. In the non-resonant condition of 70 Hz, for a  $3 \times 4$  corrugated membrane array (radius of individual



membrane = 400  $\mu\text{m}$ ), a peak power of 10  $\mu\text{W}$  was measured across 10 k $\Omega$  with a bias of 1 V and an acceleration of 0.01g.<sup>79</sup> Yen et al. conducted detailed experimentation and modeling of the corrugated AlN cantilever structures. At a resonance frequency of 853 Hz, a cantilever with a width of 2400  $\mu\text{m}$ , a length of 500  $\mu\text{m}$ , and a 2- $\mu\text{m}$ -thick piezoelectric layer was able to provide 0.17  $\mu\text{W}$  under an acceleration of 1g using a tip mass of dimensions 2400  $\times$  500  $\times$  680  $\mu\text{m}^3$ .<sup>80</sup>

Stoppel et al. conducted a simulation study in this area that computed the effect of thickness on power generation.<sup>81</sup> It was pointed out that since the Young's modulus of AlN (345 GPa) is about 4x that of PZT, the thickness of AlN for maximum power output is about 3x smaller than that of PZT. For a cantilever with 2- $\mu\text{m}$ -thick AlN operating at a resonance frequency of 105.6 Hz under an acceleration of 1 m/s<sup>2</sup>, an output power of 0.8  $\mu\text{W}$  was measured across a 21 M $\Omega$  load. Based upon the experimental data available in the literature, the normalized output power (power/frequency  $\times$  acceleration) for AlN microdevices ranges between  $2.034 \times 10^{-5}$  and  $757 \times 10^{-5}$   $\mu\text{W}/(\text{Hz} \times \text{m/s}^2)$ . Ignoring the data from Stoppel et al., the spread is more reasonable from  $2.034 \times 10^{-5}$  to  $11 \times 10^{-5}$   $\mu\text{W}/(\text{Hz} \times \text{m/s}^2)$ . These values are quite good, and considering the compatibility of AlN with CMOS processing and the long history in optimizing the deposition process, we expect that this area will continue to grow.

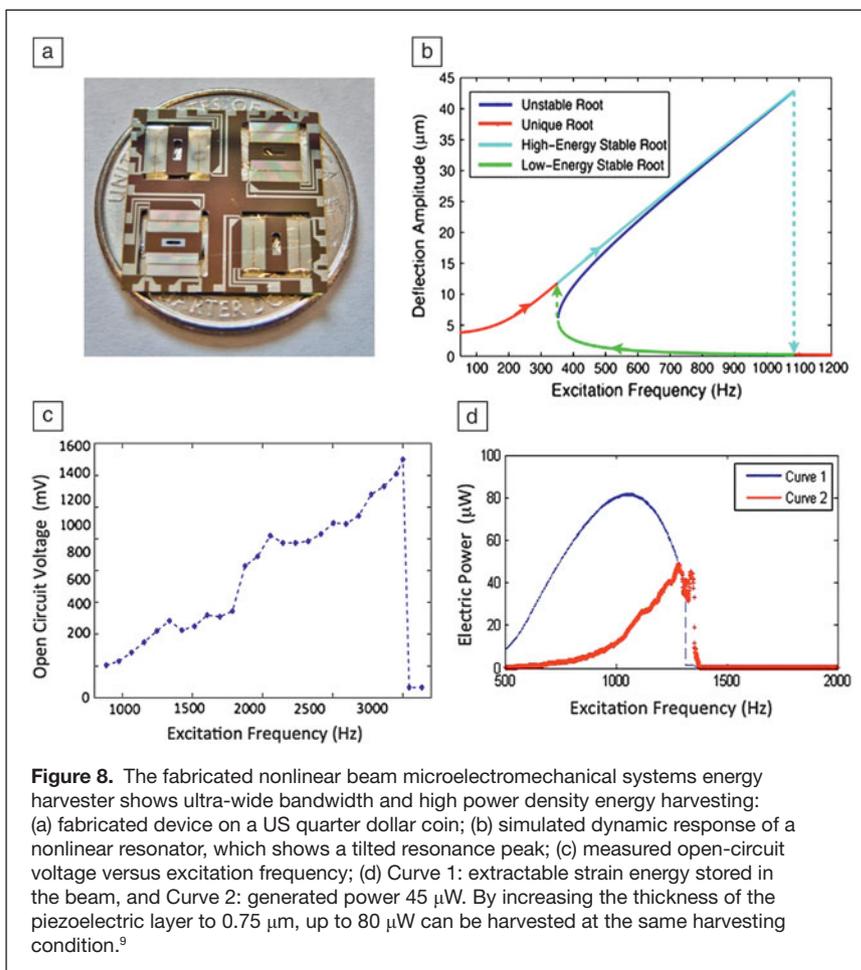
### Nonlinear resonance-based energy harvesting structures

Most of the reported vibration energy harvesters use a linear cantilever resonator structure to amplify small ambient vibrations. While such structures are easy to model, design, and build, they typically have a narrow bandwidth. In contrast, nonlinear resonators have a different dynamic response and greatly increase the bandwidth by hardening or softening the resonance characteristics of the beam structure. In addition, it has been found that nonlinear resonating beams can extract more electrical energy than linear resonating beams.<sup>9,82</sup>

Nonlinearity may come from a magnetic force or constrained mechanical structures. The magnetic force between the iron mass at the tip of a cantilever and an external magnet (or vice versa) creates a nonlinear spring, whose nonlinearity is determined by the strength of the magnets and the size of the air gap between the magnets and the iron stator. Due to the mutual attraction, the ferromagnetic beam has three equilibrium positions (statically bi-stable configuration), and the vibration mode has the form of the bi-stable *Duffing* resonance. Electromagnetic energy harvesters have been reported showing hardening or softening resonance characteristics.<sup>83–86</sup> However, magnet-based beams require assembly of hard

magnets, which is expected to be costly as the size of the device shrinks.

Nonlinear resonance could be better achieved by monolithically fabricated MEMS structures. Efforts have been made to achieve wide bandwidth piezoelectric energy harvesters by exerting axial compression and forming a buckled configuration to make a bi-stable oscillator.<sup>87</sup> Recently, Hajati et al. demonstrated a monolithic MEMS-based nonlinear resonant piezoelectric micro energy harvester, which achieved an ultra-wide bandwidth of >20% of the center frequency and generated power more than 22  $\mu\text{W}$  (see **Figure 8**).<sup>9</sup> More than one order of magnitude improvements were demonstrated compared to devices previously reported for the power bandwidth (see Table I). The basic design is based on a doubly clamped beam resonator with dimensions of 6 mm  $\times$  6 mm  $\times$  5.5  $\mu\text{m}$  (length  $\times$  width  $\times$  height) and a PZT thickness of 0.25  $\mu\text{m}$ . Four of these resonators are arranged perpendicular to each other and form one energy harvester, which is about the size of a US quarter coin (Figure 8a). At large deflection (exceeding 2–3 times the thickness of the beam), a net stretching in addition to bending results, changing the dynamic response to a nonlinear one (Figure 8b). Based on the measured open-circuit voltage in Figure 8c, the internal capacitance (8.5 nF), and resistance (3.5 M $\Omega$ ) of the measurement circuit, the generated power is



estimated as shown in Figure 8d. The result shows orders of magnitude improvement in bandwidth, as compared in Table I.

Unlike a linear resonance system, where the electrical damping cannot exceed the mechanical damping,<sup>49</sup> Hajati et al. showed that electrical damping in a nonlinear resonance system could surpass the mechanical damping, extracting a much higher output power than that of the linear systems. The nonlinear impedance serves as a negative feedback and stabilizes the deflection when the electrical damping changes.<sup>88</sup> This is why the power bandwidth of nonlinear systems can be much wider than that of linear systems at equivalent beam dimensions. A smart electronic interface such as adaptive synchronized switch harvesting on an inductor will be ideal to extract high power from nonlinear beam harvesters.<sup>89</sup>

## Summary

Microelectromechanical system (MEMS) piezoelectric energy harvesters with  $\sim\text{mm}^3$  dimensions will lead to battery-less autonomous sensor systems and networks with 10s to 100s of  $\mu\text{W}$  of power that can be extracted from the ambient vibration continuously, robustly, and at low cost. The key attributes to make a good piezoelectric MEMS energy harvester include its compactness, output voltage, bandwidth, operating frequency, input vibration amplitude, lifetime, and cost. Among them, higher power density and wider bandwidth of resonance are the two biggest challenges currently facing the technology. But the state of the art is still about one order smaller than what is needed for practical applications. Recent advances in piezoelectric materials and harvester structural design, individually or in combination, are bringing us closer to battery-less autonomous sensor systems and networks. Giant piezoelectric coefficient materials, epitaxially grown films, grain textured piezoelectric materials and thin films, and high performance lead-free piezoelectric materials are recent advancements made toward increasing the electromechanical energy conversion of piezoelectric harvesters. Nonlinear resonators are extremely promising to extract more electrical energy from the beam with much wider bandwidth. We expect that in the near future, a coin-sized harvester will be able to harvest about  $100\ \mu\text{W}$  of continuous power below  $100\ \text{Hz}$  at less than  $0.5\ \text{g}$  vibration and at reasonable cost.

## Acknowledgments

The authors acknowledge the support from the Office of Basic Energy Sciences, Department of Energy (#DE-FG02-07ER46480) and (DE-FG02-09ER46577), AFOSR Young Investigator Program, DARPA Grant (HR0011-06-1-0045), MIT-Iberian Nanotechnology Laboratory Program.

## References

1. S. Priya, D. Inman, Eds., *Energy Harvesting Technologies* (Springer, NY, 2009).
2. A. Chandrakasan, R. Amirtharajah, J. Goodman, W. Rabiner, *Proc. of the IEEE International Symposium on Circuits and Systems, ISCAS '98* (1998).
3. S.P. Beeby, M.J. Tudor, N.M. White, *Meas. Sci. Technol.* **17** (2006).
4. Z. Wang, J. Song, *Science* **312**, 242 (2006).
5. A. Marin, S. Bressers, S. Priya, *J. Phys. D: Appl. Phys.* **44**, 295501 (2011).

6. D.C. Bono, A. Sliski, J. Huang, R.C. O'Handley, US Patent 7,569,952 B1, (2009).
7. P. Kruljevitch, A.P. Lee, P.B. Ramsey, J.C. Trevino, J. Hamilton, M.A. Northrup, *J. Microelectromech. Syst.* **5** (4), 270 (1996).
8. P. Muralt, R.G. Polcawich, S. Troler-McKinstry, *MRS Bull.* **34** (9) (2009).
9. A. Hajati, S.G. Kim, *Appl. Phys. Lett.* **99**, 083105 (2011).
10. H.-U. Kim, W.-H. Lee, H.V. Rasika Dias, S. Priya, *IEEE Trans. Ultrason. Ferroelectr. Freq. Control* **56**, 1555 (2009).
11. S. Roundy, P.K. Wright, *Smart Mater. Struct.* **13**, 1131 (2004).
12. Y.B. Jeon, R. Sood, J.H. Jeong, S.-G. Kim, *Sens. Actuators* **122**, 16 (2005).
13. K. Morimoto, I. Kanno, K. Wasa, H. Kotera, *Sens. Actuators, A* **163**, 428 (2010).
14. H. Kim, S. Priya, H. Stephanou, K. Uchino, *IEEE Trans. Ultrason. Ferroelectr. Freq. Control* **54**, 1851 (2007).
15. J. Jiang, R.N. Miles, *J. Sound Vib.* **220** (4), 683 (1999).
16. D. Findeisen, *System Dynamics and Mechanical Vibrations: An Introduction* (Springer, NY, 2000).
17. J.H. Ginsberg, *Mechanical and Structural Vibrations: Theory and Applications* (Wiley, NY, 2001).
18. K. Uchino, *Ferroelectric Devices* (Marcel Dekker, NY, 2000).
19. A. Hajati, PhD thesis, Massachusetts Institute of Technology (2010).
20. M. Renaud, K. Karakaya, T. Sterken, P. Fiorini, C. Van Hoof, R. Puers, *Sens. Actuators, A* **145-146**, 380 (2008).
21. S. Roundy, P.K. Wright, J.M. Rabaey, *Energy Scavenging for Wireless Sensor Networks* (Kluwer Academic Publishers, Boston, 2003).
22. E.K. Reilly, L.M. Miller, R. Fain, P. Wright, *Proc. PowerMEMS* 312 (2009).
23. A. Erturk, D.J. Inman, *J. Intell. Mater. Syst. Struct.* **19**, 1311 (2008).
24. S. Roundy, P.K. Wright, J. Rabaey, *Comput. Commun.* **26** (11), 1131 (2003).
25. P. Muralt, M. Marzencki, B. Belgacem, F. Calame, S. Basrour, *Proc. Chem.* **1**, 1191 (2009).
26. A. Massaro, S. De Guido, I. Ingrosso, R. Cingolani, M. De Vittorio, M. Cori, A. Bertacchini, L. Larcher, A. Passaseo, *Appl. Phys. Lett.* **98**, 053502 (2011).
27. L.M. Miller, E. Halvorsen, T. Dong, P.K. Wright, *J. Micromech. Microeng.* **21**, 045029 (2011).
28. H. Durou, G.A. Ardilla-Rodriguez, A. Ramond, X. Dollat, C. Rossi, D. Esteve, *PowerMEMS* (Leuven, Belgium, 2010).
29. D. Isarakorn, D. Briand, P. Janphuang, A. Sambri, S. Gariglio, J.-M. Triscone, F. Guy, J.W. Reiner, C.H. Ahn, N.F. de Rooij, *Smart Mater. Struct.* **20** (2), (2011).
30. M. Defosseux, M. Allain, P. Ivaldi, E. Defay, S. Basrour, *Proc. of 16th International Conference on Solid-State Sensors, Actuators and Microsystems (Transducers 2011)* (Beijing, China, June 2011), pp. 1859-1862.
31. M. Marzencki, Y. Ammar, S. Basrour, *Proc. Int. Conf. on Solid-State Sensors, Actuators, and Microsystems, Lyon* (2007), pp. 887-890.
32. T. Hirasawa, T.-T. Yen, P.K. Wright, A.P. Pisano, L. Lin, *Int. Workshop on Micro and Nanotechnology for Power Generation and Energy Conversion Applications (PowerMEMS 2010)* (Leuven, Belgium, 2010), pp. 211-214.
33. T.-T. Yen, T. Hirasawa, P.K. Wright, A.P. Pisano, L. Lin, *J. Micromech. Microeng.* **21**, 085037 (2011).
34. A. Bertacchini, S. Scorcioni, D. Dondi, L. Larcher, P. Pavan, M.T. Todaro A. Campa, G. Caretto, S. Petroni, A. Passaseo, M. De Vittorio, *Proceedings of the European Solid-State Device Research Conference (ESSDERC) 12-16 September 2011* (2011), pp. 119-122.
35. R. van Schaijk, R. Elfrink, T.M. Kamel, M. Goedbloed, *IEEE Sensors Conference* (2008), pp. 45-48.
36. R. Elfrink, V. Pop, D. Hohlfield, T. Kamel, S. Matova, C. de Nooijer, M. Jambunathan, M. Goedbloed, L. Caballero Guindo, M. Renaud, J. Penders, R. van Schaijk, *IEEE International Electron Devices Meeting (IEDM)* (2009), pp. 543-546.
37. R. Elfrink, T.M. Kamel, M. Goedbloed, S. Matova, D. Hohlfield, Y. Van Andel, R. van Schaijk, *J. Micromech. Microeng.* **19**, 095005 (2009).
38. R. Elfrink, M. Renaud, T.M. Kamel, C. de Nooijer, M. Jambunathan, M. Goedbloed, D. Hohlfield, S. Matova, V. Pop, L. Caballero, R. van Schaijk, *J. Micromech. Microeng.* **20**, 104001 (2010).
39. R. Xu, A. Lei, T.L. Christiansen, K. Hansen, M. Guizzetti, K. Birkelund, E.V. Thomsen, O. Hansen, *Proc. of 16th International Conference on Solid-State Sensors, Actuators and Microsystems (Transducers'11)* (Beijing, China, 2011), pp. 679-682.
40. A. Lei, R. Xu, A. Thyssen, A.C. Stoot, T.L. Christiansen, K. Hansen, R. Lou-Møller, E.V. Thomsen, K. Birkelund, *Proc. of The 24th International Conference on Micro Electro Mechanical Systems (MEMS'11)* (Cancun, Mexico, 2011), pp. 125-128.
41. J.C. Park, J.Y. Park, Y.-P. Lee, *J. Microelectromech. Syst.* **19** (5), 1215 (2010).
42. H.-B. Fang, J.-Q. Liu, Z.-Y. Xu, L. Dong, L. Wang, D. Chen, B.-C. Cai, Y. Liu, *Microelectron. J.* **37**, 1280 (2006).
43. D. Shen, J.-H. Park, J. Ajitsaria, S.-Y. Choe, H.C. Wickle III, D.-J. Kim, *J. Micromech. Microeng.* **18**, 055017 (2008).

44. B.S. Lee, S.C. Lin, W.J. Wu, X.Y. Wang, P.Z. Chang, C.K. Lee, *J. Micromech. Microeng.* **19** (6), 065014 (2009).

45. E.E. Aktakka, PhD thesis, University of Michigan (2012).

46. S. Priya, *J. Electroceram.* **19**, 165 (2007).

47. A. Marin, S. Priya, *Active and Passive Smart Structures and Integrated Systems 2012*, H.A. Sodano, Ed. (SPIE, San Diego, CA), p. 83411L.

48. R. Xu, MS thesis, Massachusetts Institute of Technology (2012).

49. N. Dutoit, B. Wardle, S.-G. Kim, *Integr. Ferroelectr.* **71** (1), 121 (2005).

50. Q.-M. Wang, X.-H. Du, B. Xu, L.E. Cross, *IEEE Trans. Ultrason. Ferroelectr. Freq. Control* **46**, 638 (1999).

51. J.J. Bernstein, J. Bottari, K. Houston, G. Kirkos, R. Miller, B. Xu, Y. Ye, L.E. Cross, *IEEE 1999 Ultrasonics Symposium* (Lake Tahoe, NV, 1999).

52. R. Xu, S.G. Kim, *Power MEMS 2012*, accepted.

53. V. Bedekar, J. Oliver, S. Priya, *IEEE Trans. Ultrason. Ferroelectr. Freq. Control* **57**, 1513 (2010).

54. S. Priya, *IEEE Trans. Ultrason. Ferroelectr. Freq. Control* **57**, 2610 (2010).

55. M. Defosseux, M. Allain, P. Ivaldi, E. Defay, S. Basrour, *Transducers '11, Beijing, China*, 5–9 June 2011 (2011), pp. 1859–1862.

56. N. Ledermann, P. Muralt, J. Baborowski, S. Gentil, K. Mukati, M. Cantoni, A. Seifert, N. Setter, *Sens. Actuators, A* **105**, 162 (2003).

57. F. Martin, P. Muralt, M.-A. Dubois, A. Pezous, *J. Vac. Sci. Technol., A* **22**, 361 (2004).

58. K. Tsubouchi, N. Mikoshiba, *IEEE Trans. Sonics Ultrason.* **SU-32**, 634 (1985).

59. K. Najafi, T. Galchev, E.E. Aktakka, R.L. Peterson, J. McCullagh, *Transducers 2011, Beijing, China*, pp. 1845–1850 (2011).

60. W. Al-ashdari, M. Hunstig, T. Hemsel, W. Sextro, *Mechatronics* **35019** (2012).

61. M.O. Mansour, M.H. Arafat, S.M. Megahed, *Sens. Actuators, A* **163** (1), 297 (2010).

62. K. Uchino, *Ferroelectric Devices, 2nd ed.* (CRC Press, Boca Raton, FL, 2009).

63. G. Han, J. Ryu, W. Yoon, J. Choi, B. Hahn, J. Kim, D. Park, C. Ahn, S. Priya, D. Jeong, *J. Appl. Phys.* **110**, 124101 (2011).

64. B.A. Tuttle, J.A. Voigt, T.J. Garino, D.C. Goodnow, R.W. Schwartz, D.L. Lamppa, T.J. Headley, M.O. Eatough, *Proceedings of the 8th IEEE International Symposium on Application of Ferroelectrics* (1992), p. P344.

65. G.L. Brennecke, W. Huebner, B.A. Tuttle, P.G. Clem, *J. Am. Ceram. Soc.* **87**, 1459 (2004).

66. S. Yokoyama, T. Ozeki, T. Oikawa, H. Funakubo, *Jpn. J. Appl. Phys.* **41**, 6705 (2002).

67. I. Kanno, S. Fujii, T. Kamada, R. Takayama, *Appl. Phys. Lett.* **70**, 1378 (1997).

68. Y. Qi, J. Kim, T.D. Nguyen, B. Lisko, P.K. Purohit, M.C. McAlpine, *Nano Lett.* **11** (3), 1331 (2011).

69. S.E. Park, T.R. Shrout, *J. Appl. Phys.* **82**, 1804 (1997).

70. J. Kuwata, K. Uchino, S. Nomura, *Jpn. J. Appl. Phys.* **21**, 1298 (1982).

71. S.H. Baek, J. Park, D.M. Kim, V.A. Aksyuk, R.R. Das, S.D. Bu, D.A. Felker, J. Lettieri, V. Vaithyanathan, S.S.N. Bharadwaja, N. Bassiri-Gharb, Y.B. Chen, H.P. Sun, C.M. Folkman, H.W. Jang, D.J. Kreft, S.K. Streiffer, R. Ramesh, X.Q. Pan, S. Trolier-McKinstry, D.G. Schlom, M.S. Rzchowski, R.H. Blick, C.B. Eom, *Science* **334**, 958 (2011).

72. C.W. Ahn, C.H. Choi, H.Y. Park, S. Nahm, S. Priya, *J. Mater. Sci.* **43**, 6784 (2008).

73. C.W. Ahn, C.S. Park, D. Viehland, S. Nahm, D.H. Kang, K.S. Bae, S. Priya, *Jpn. J. Appl. Phys.* **47**, 8880 (2008).

74. C.W. Ahn, D. Maurya, C.S. Park, S. Nahm, S. Priya, *J. Appl. Phys.* **105**, 114108 (2009).

75. K. Shibata, K. Suenaga, K. Watanabe, F. Horikiri, A. Nomoto, T. Mishima, *Jpn. J. Appl. Phys.* **50**, 041503 (2011).

76. I. Kanno, T. Ichida, K. Adachi, H. Kotera, K. Shibata, T. Mishima, *Sens. Actuators, A* **179**, 132 (2012).

77. P. Muralt, *J. Am. Ceram. Soc.* **91**, 1385 (2008).

78. R. van Schaijk, R. Elfrink, T.M. Kamel, M. Goedbloed, *IEEE Sensors 2008 Conference* (2008), pp. 45–48.

79. N. Heidrich, F. Knoebber, R.E. Sah, W. Pletschen, S. Hampl, V. Cimalla, V. Lebedev, *Transducers'11, Beijing, China*, 5–9 June 2011 (2011), pp. 1642–1644.

80. T.-T. Yen, T. Hirasawa, P.K. Wright, A.P. Pisano, L. Lin, *J. Micromech. Microeng.* **21**, 085037 (2011).

81. F. Stoppel, C. Schroeder, F. Senger, B. Wagner, W. Benecke, *Procedia Eng.* **25**, 721 (2011).

82. B. Marinkovich, H. Koser, *Appl. Phys. Lett.* **94**, 103505 (2009).

83. B.P. Mann, N.D. Sims, *J. Sound Vib.* **319**, 515 (2009).

84. D.A.W. Barton, S.G. Burrow, L.R. Clare, *J. Vib. Acoust.* **132**, 1 (2010).

85. A. Erturk, D.J. Inman, *J. Sound Vib.* **330** (10), 2339 (2011).

86. B. Andò, S. Baglio, C. Trigona, N. Dumas, L. Latorre, P. Nouet, *J. Micromech. Microeng.* **20**, 125020 (2010).

87. F. Cottone, L. Gammaitoni, H. Vocca, M. Ferrari, V. Ferrari, *Smart Mater. Struct.* **21** (2012).

88. R. Xu, A. Hajati, S.G. Kim, *Power MEMS 2011* (Seoul, Korea, 2011).

89. A. Badel, D. Guyomar, F. Lefeuvre, C. Richard, *J. Intell. Mater. Syst. Struct.* **16**, 889 (2005). □

# Nano Particles and Coatings



Iron and carbon multi-layer film.



MRS BOOTH 713

The ULVAC Arc Plasma Deposition System (APD) produces extremely smooth thin films and uniformly sized nano particles. The APD System deposits magnetic, DLC and metal films in R&D, material science, fuel cell and automotive applications.

## The APD System delivers:

- Extremely smooth ultra-thin films – 0.01 to 0.3 nm/sec
- Size-controlled nano particles – 1 nm to 30 nm dia.
- Dense film formation without process gas
- Small target size: 10 mm dia. x 17 mm
- Uniformity +/- 10% over 50 mm diameter coated area

**Need Nano particles or coatings?**

**Call 800-99ULVAC or  
email sales@us.ulvac.com.**

**ULVAC**

Methuen, MA • Tel: 978-686-7550  
sales@us.ulvac.com • www.ulvac.com