## Characterization and prediction of tropical cyclone forerunner surge

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## **Highlights:**

- Physical scaling laws are revealed to characterize forerunner surge from storm track parameters (central pressure, radius, and speed).
  - The physical scaling enables rapid forecasting of forerunner surge.

#### Abstract

Forerunner surge, a water level rise ahead of tropical cyclone landfall, often strikes coastal communities unexpectedly, stranding people and increasing loss of life. Surge forecasting systems and emergency managers almost exclusively focus on peak surge, while much less attention is given to forerunner surge. To address the need for fast and accurate forecasting of forerunner surge, we analyze high-fidelity surge simulations in Virginia, New York/New Jersey and Texas and extract physical scaling laws between readily available storm track information and forerunner surge magnitude and timing. We demonstrate that a dimensionless relationship between central-pressure scaled surge and wind-duration scaled time may effectively be used for rapid forerunner surge forecasting, where uncertainty is considered. We use our method to predict forerunner surge for Hurricanes Ike (2008)—a significant forerunner surge event—and Harvey (2017). The predicted forerunner surge 24 to 6 hours before Hurricane Ike's landfall ranged from 0.4 to 2.8 m, where the observed forerunner surge ranged from 0.4 to 2.6 m. This

- 22 new method has the potential to be incorporated into real-time surge forecasting systems to aid
- 23 emergency management and evacuation decisions.
- 24 Keywords: Tropical cyclones; forerunner surge; modeling; forecasting; physical scaling;
- 25 ADCIRC.

# 1 Introduction

Tropical cyclone (TC) storm surge has had devastating impacts on coastal communities
worldwide, causing tremendous loss of life and physical damage. Peak surge is most often the
dominant driver of direct damage. Consequently, surge forecasting systems and emergency
managers have focused on improving prediction of peak surge, while less attention has been
given to forecasting forerunner surge—a storm-induced early water level rise above mean sea
level well in advance of TC landfall. The significance of forerunner surge was first observed in
1900, when Galveston, Texas was hit by a forerunner surge of 1.5 m 12 hours prior to landfall
[1,2]. This forerunner surge flooded essential roadways and stranded many people on Galveston
Island, directly contributing to the shocking death of 8,000 people, and making the 1900
Galveston Hurricane the deadliest hurricane on record [3]. Forerunner surge is most dangerous
for those who are in the direct path of the cyclone, where the forerunner surge precedes a high
peak surge. Significant forerunner surges occurred in 1900 and again in 2008 (Hurricane Ike)
when these storms made landfall in Galveston. Since 1900, forerunner surge on the order of 1 to
2 m has been documented for TCs impacting both the US Gulf of Mexico and Atlantic coasts
(Table 1). Yet, while a few studies indicated that large TCs making landfall across a broad,
shallow continental shelf could potentially generate significant forerunner surges [2,4]—where
Kennedy et al. demonstrated Hurricane Ike's large forerunner surge was predominantly from
Ekman setup (water level rise arising from the influence of Coriolis force)—we lack a basic
quantitative understanding of how and when significant forerunner surge is generated.
To better inform evacuation plans and thereby reduce loss of life, it is important to
understand the conditions in which a TC generates significant forerunner surge. Surge forecasts
historically focus on the rapid and accurate prediction of peak surge, and due to the need for

rapid forecasting, either use a large ensemble set of track possibilities with low-fidelity surge simulations (e.g., NOAA's P-Surge [5,6]), use a small, discrete set of storm track possibilities with high-fidelity surge simulations (e.g., [7]), or use interpolation schemes to determine peak surge from discrete, high-fidelity simulations for a large ensemble of track possibilities (e.g., [8,9]). Some rapid surge prediction methods also consider forecasting of surge time series, where either accuracy was compromised [7] or interpolation schemes were used [10]. Forerunner surge is often overlooked when considering real-time forecasts.

Herein, to advance the physical understanding of forerunner surge generation and provide a reliable and rapid forerunner surge forecasting method, we examine time series from high-fidelity storm surge simulations for Galveston, TX, Hampton Roads, VA, and New York/New Jersey, and we characterize forerunner surge magnitude and timing using physical scaling laws based on storm track parameters.

#### 2 Methods

The forerunner surge observational record is sparse, both in terms of the number of cyclones observed and in spatiotemporal coverage, so we base our analysis on simulated wind, barometric pressure, and surge for a range of synthetic TCs representative of observed storm characteristics [11]. Here, the unstructured finite-element shallow water equations code ADCIRC [12] is used, coupled with a spectral wave model (e.g., SWAN [13] or STWAVE [14]) to include the effects of wave setup [15,16]. Runup from individual waves is not included. TC wind and pressure fields are generated from a planetary boundary layer (PBL) model [17], using storm track parameters as input, including storm position, central pressure deficit ( $\Delta p$ ) representing intensity, radii to maximum wind (R) representing storm size, forward speed ( $V_f$ ), heading ( $\theta$ ), and profile parameter Holland B [18]. Our focus herein is on characterizing the forerunner surge

anomaly (level above expected normal level). To simplify the analysis, astronomical tides are not considered.

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We conduct dimensional analysis on the simulations to find physical scaling laws relating surge timing and magnitude to storm track parameters 12 to 24 hours before landfall. Former studies have shown that the storm parameters most influencing the magnitude of peak surge are landfall location  $(x_o)$ ,  $\Delta p$ , and R, while  $V_f$  and  $\theta$  have less impact [19]. In this forerunner surge study we also focus on the storm parameters  $\Delta p$  and R. However, we identify through sensitivity analyses that  $V_f$  also significantly influences forerunner surge, while heading and landfall location have less impact. Specifically, while landfall location  $(x_0)$  is known to strongly influence peak surge [20], our sensitivity analysis indicates forerunner surge (represented by surge 12 hours before landfall) is not very sensitive to moderate shifts in track, especially at the open coast. At location TX-2 in Figure 1, as an example, our simulations exhibit differences in forerunner surge magnitude 12 hours before landfall of less than 0.1 m, when track spacing is varied up to 35 km, and when all other storm parameters are held constant. Field observations also support this conclusion (see Appendix A, Figures A2-A7). When track is varied up to 200 km to the south of Houston/Galveston (Figure A1), forerunner surge is generated, but its magnitude does not change significantly, less than 0.2 m. Storms tracking 100 km or more to the north, northeast of Houston/Galveston do not generate forerunner surge; Houston/Galveston is well to the left of the hurricane eyewall for these storms, which thus result in strong offshore winds in the study area. A sensitivity test is also conducted in terms of storm heading  $(\theta_1)$  and results show little difference between storms with different headings (less than 0.1 m increase over a heading change of  $\pm 45$  degrees at location TX-2), although results in the bay can be more complicated due to locally generated surge—a process not directly considered herein.

Thus, for each region we consider just one heading, a limited range of  $x_o$  (where forerunner surge precedes a peak along-coast surge occurring near the study location), and a wide range of  $\Delta p$ , R and  $V_f$ .

We leverage existing surge simulations for Virginia and New York/New Jersey and perform our own simulations for Texas. In Virginia and New York/New Jersey, we use the US Army Corps of Engineers (USACE) STWAVE+ADCIRC simulations [21]. For this study, 19 synthetic TCs along three tracks making landfall in or near Hampton Roads are selected (Figure 1). All storms follow headings of -60° clockwise from north. Track parameters  $\Delta p$ , R, and  $V_f$  are respectively varied from 38 to 88 hPa, 25 to 109 km, and 3.3 to 12.2 m/s at landfall. Results are shown for two representative locations near densely populated areas: Sewells Point (VA-1) within Chesapeake Bay and Virginia Beach (VA-2) on the open coast. Similarly, 18 synthetic TCs along three tracks in or near Sandy Hook, NJ are selected, with headings of -60o and track parameters  $\Delta p$ , R, and Vf varying from 28 to 78 hPa, 31 to 139 km, and 6.7 to 18.6 m/s at landfall. Results are shown for two representative locations near densely populated areas: The Battery, NY (NJ-1) and Sandy Hook, NJ (NJ-2).

In Texas, we simulate surge using SWAN+ADCIRC, employing Dietrich et al.'s [16] validated high-resolution computational mesh and model setup used in Kennedy et al.'s [2] forerunner surge study. We first assess model performance using a synthetic TC similar to Hurricane Ike in terms of these track parameters:  $\Delta p$  of 63 hPa, R of 74 km, and  $V_f$  of 18 km/h at landfall [4,22]. Wind and pressure forcing are developed using the PBL model. It should also be noted that herein we define the forerunner surge generally as the water level rise ahead of TC landfall, for the purposes of this paper the surge time series during the period from 24 to 6 hours prior to landfall. With this definition, the forerunner surge encompasses Ekman setup as well as

other processes inducing surge prior to landfall. This simulation is compared both with Kennedy et al.'s [2] observations and simulation using the best available observation-based H\*Wind wind field (Figure 2). Some differences exist between observations and our model results using parameterized wind forcing, and most of these cannot be eliminated, even when using the observation-based H\*Wind forcing. Repeating Kennedy et al.'s analysis, our surge simulation using parameterized winds when Coriolis force is disabled shows that the major part of Ike's forerunner surge indeed does arise from Ekman setup, and is captured when using the parameterized wind field. Note that the simulated surge time series herein do not show a forerunner peak that is observed during Hurricane Ike, and we think this arises for two reasons. First, although using a best wind field hindcast will certainly provide a more accurate simulated estimate with a forerunner peak, we purposefully elect to use parameterized wind fields because we want our results to be useful for forecasting purposes. Second, we hypothesize that the depthaveraged model underestimates the current speed of importance to forerunner surge (that in the upper ocean layer), thus underestimating the forerunner peak. This underestimate is also see in the simulations using H\*Wind. Thus, although exhibiting some error, the synthetic storm surge simulations analyzed herein can be used to assess trends in forerunner surge as a function of realtime forecasted storm track parameters. In Texas, we simulate surge for synthetic TCs along three tracks spaced 35 km apart and

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In Texas, we simulate surge for synthetic TCs along three tracks spaced 35 km apart and making landfall in or near Galveston (Figure 1). All storms follow tracks oriented -30° clockwise from north. Along the middle track (TX-T2), 42 combinations of  $\Delta p$ , R and  $V_f$  are simulated, respectively spanning from 53 to 113 hPa, 10 to 85 km, and 3 to 12 m/s at landfall. These 42 simulations reveal trends consistent with those seen in the Virginia simulations, so a reduced set of 19 TCs are simulated for the north (TX-T1) and south tracks (TX-T3). In all 80 unique storm

simulations are considered in Galveston. Results are shown for two representative locations near densely populated areas, Houston (TX-1) within Galveston Bay and Galveston (TX-2) on the open coast. Selected storms are simulated without Coriolis forcing in order to confirm the prominent role of Ekman setup in forerunner surge generation (Figure A8).

#### 3 Results and Discussion

To identify the relative influence of each storm parameter on forerunner surge, we investigate correlation between the forerunner surge magnitude and storm parameters. At 12 hours prior to landfall, for example, partial correlation coefficients for  $\Delta p$ , R, and  $V_f$  are respectively 0.52, 0.82, and -0.87 for Virginia, 0.71, 0.86, and -0.73 for Texas, and 0.56, 0.68, and -0.83 for New York/New Jersey. As  $\Delta p$  and R increase, so do forerunner surge (shown herein) and peak surge [19]. In contrast, while increasing  $V_f$  tends to increase peak surge somewhat [23], it serves to decrease forerunner surge magnitude. This result is expected considering the physics of forerunner surge demonstrated in Kennedy et al. [2] that shows strong wind-generated alongshore currents on the continental shelf produce Ekman setup ( $\zeta_{Ek}$ ) under the effect of Coriolis force. Approximated from the cross-shore momentum balance, Ekman setup is:

$$\zeta_{Ek} = \int \frac{fU}{g} dx \tag{1}$$

where f is the Coriolis coefficient, U is alongshore water current speed, g is gravitational acceleration, and x is in the cross-shore direction. The factors controlling timing and magnitude of forerunner surge are the alongshore-current speed and the cross-shore width of the current (Eq. 1's integration limit).

Figure 2 shows simulated surge time series, where each storm is colored based on the dimensional parameter  $\left(\frac{R}{V_f}\right)$  ( $\Delta p$ ) to reflect the positive correlation with  $\Delta p$  and R and negative correlation with  $V_f$ . Results show that for the parameter range simulated, the forerunner surge magnitude ranges from 0.0 to 2.0 m between 24 and 6 hours before landfall, in both Virginia and Texas. As expected, surge increases in magnitude closer to landfall. The results further show larger  $\left(\frac{R}{V_f}\right)$  ( $\Delta p$ ) results in larger forerunner surge. The interpretation is twofold. First,  $\left(\frac{R}{V_f}\right)$  represents the duration in which strong cyclonic winds persist over the continental shelf. The longer the wind field lingers in this relatively shallow-depth region, the more time it has to fully develop an alongshore water current. Second,  $\Delta p$  represents overall wind-field intensity. All else being equal, a more intense TC generates a more intense wind field, which in turn induces a stronger alongshore current.

To take a step further, we use dimensional analysis to develop physical scaling laws relating forerunner surge and storm track parameters near landfall. The forerunner surge magnitude and timing are scaled by  $\Delta p$  and  $\left(\frac{R}{V_f}\right)$  respectively. A region-specific characteristic intensity  $(\Delta p_{char})$  and characteristic duration  $(t_{char})$  are further integrated into the scaling to account for regional characteristics. Thus,

$$\begin{cases} \zeta' = \left(\frac{\gamma \zeta}{\Delta p}\right) \left(\frac{\Delta p_{char}}{\Delta p}\right)^{\alpha} \\ t' = \left(\frac{t}{R/V_f}\right) \left(\frac{t_{char}}{R/V_f}\right)^{\alpha} \end{cases}$$
(2a)

where  $\gamma$  is the specific weight of seawater, t is time before peak surge on the open coast, and  $\zeta$  is surge magnitude. The quantity  $\left(\frac{\gamma\zeta}{\Delta p}\right)$  in Eq. 2a is derived from the momentum balance, where  $\Delta p$  is considered proportional to surface wind stress in a quadratic form  $(\Delta p \propto u_{wind}^2)$  [20,24], and

the quantity  $\left(\frac{t}{R/V_f}\right)$  in Eq. 2b represents wind duration. The term  $\Delta p_{char}$  is regional mean 183 184 observed central pressure deficit, 58 hPa in Virginia and New York/New Jersey, and 62 hPa in Texas. The term  $t_{char}$  is defined as  $\frac{L_{shelf}}{\sqrt{g\overline{h_{shelf}}}}$ , where  $L_{shelf}$  is reference continental shelf width, 185 taken as distance from the coastline to a depth of 100 m, and  $\overline{h_{shelf}}$  is reference shelf depth, 186 taken as 50 m. The term  $L_{shelf}$  represents the Ekman setup integration limit and  $\sqrt{g \overline{h_{shelf}}}$ 187 188 represents a characteristic speed of a free wave on the shelf. The best-fit coefficient  $\alpha$  is site-189 specific. Taken as 0 in Virginia, -0.35 in Texas, and -0.35 in New York/New Jersey, α is thought 190 to arise from the effect of a curved coastline on Ekman setup. Specifically, we hypothesize the 191 concave coastline curvatures of the Galveston and New York/New Jersey regions redirect and 192 confine the driving alongshore current, while, the Hampton Roads region's convex coastline 193 curvature has less influence on the alongshore current. After scaling, Eq.2a represents the 194 dimensionless surge ( $\zeta'$ ) and Eq.2b represents the dimensionless timing (t') of forerunner surge. 195 By plotting the time series in this dimensionless space in Figure 3, the surge simulations at each 196 location collapse into a hyperbolic curve. Thus,

$$\zeta' = \frac{a}{t'+b} + c \tag{3}$$

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where *a*, *b*, and *c* are site-specific curve fitting coefficients (Table A2) that we hypothesize are related to local factors, such as continental shelf width, latitude, and bathymetry.

Uncertainty associated with this time-evolving surge response function (Eqs. 2-3) arises from two primary sources. First, these equations are based on high-fidelity synthetic storm surge simulations. Thus, uncertainties related to parameterization of the wind fields, surge, and wave model assumptions, are carried into the scaling. Based on comparing observations and high-

fidelity surge simulations for eight historical hurricanes (US Atlantic coast: Sandy [2012], Irene [2011], Isabel [2003], Gloria [1985], Josephine [1984]; US Gulf of Mexico coast: Ike [2008], Katrina [2005], and Rita [2005]) [25,26], this uncertainty is found to increase linearly as surge magnitude increases (Figure 7). Second, uncertainty arises from the curve fitting process, and is also found to scale linearly with surge magnitude (Figure 7). Thus, as a measure of uncertainty, total standard deviation of the time-evolving surge response function ( $\sigma_{tot}$ ) is:

$$\begin{cases}
\sigma_{tot}^2 = \sigma_{model}^2 + \sigma_{function}^2 \\
\sigma_{model}, \sigma_{function} = (k)(\zeta) + l
\end{cases}$$
(4a)
(4b)

where  $\sigma_{model}$  is the standard deviation of wind and surge simulations,  $\sigma_{function}$  is the standard deviation of surge prediction calculated by Eqs. 2-3 compared to the simulated results,  $\zeta$  is forerunner surge magnitude at different times, and k and l are linear regression coefficients. Uncertainty in predicting the timing of forerunner arrival is also quantified as the average prediction uncertainty for observed forerunner surges ranging from 0.3 to 2.0 m (Figure 8).

With uncertainty considered, Eqs. 2-3 may be used to rapidly predict forerunner surge for a specific storm, as well as to determine the likelihood of the occurrence of storms with potential to generate significant forerunner surge. As an example, Figure 5-6 shows forerunner surge at 24, 18, 12, and 6 hours before landfall at Virginia Beach (VA-2), Sandy Hook (NJ-2), and Galveston (TX-2), where surge is calculated as  $\zeta$  in Figure 5 and  $\zeta \pm \sigma_{tot}$  in Figure 6 using Eqs. 2-4. Within the range of storm track parameters considered, a forerunner surge of 1 m or more generally occurs earlier than 12 hours before landfall. Using track parameters (Table A1), we predict that 12 hours before landfall, the forerunner surge at Virginia Beach is 0.4-0.9 m during Hurricane Isabel (2003), which made landfall about 200 km to the south, and is consistent with an observed value of 0.5 m at the Sewells Point NOAA station ([27]; Figure A3). Hurricane Sandy (2012) made landfall about 100 km to the south of Sandy Hook, where we predict the

forerunner surge 12 hours before landfall is 0.4-1.1 m. The observed value here was 1.2 m ([27]; Figure A4). We hypothesize that the slight underestimation is due to the long hovering of Sandy's enormous wind field on the continental shelf before it changed direction to make landfall. In Galveston, we predict Hurricane Ike's (2008) forerunner surge 24, 18, 12 and 6 hours before landfall is 0.4-0.9 m, 0.5-1.1 m, 0.7-1.6 m, and 1.2-2.8 m, where observed value was respectively 0.7 m, 1.1 m, 1.8 m, and 2.6 m at the Galveston Pier 21 NOAA station ([2,27]; Figure A6). The predicted arrival for a 1.0-m forerunner during Ike is 14±7 hours before landfall (Figure S12, S13), where the observed arrival was 20 hours before landfall (Figure A6). Though Hurricane Harvey's (2017) recent landfall was 250 km to the south of Galveston Pier 21, we predict its forerunner surge 12 hours before landfall to be 0.4-0.9 m, while the observed value was 0.5 m (Figure A7). The arrival of a 0.5-m forerunner during Harvey is predicted to be 15±7 hours before landfall, while the observed was 18 hours before landfall (Figure A7).

These prediction-observation comparisons demonstrate that Eqs. 2-4 captures the predominant physical mechanisms governing forerunner surge. The slight underestimation for forerunner surge during Hurricane Ike at 18 and 12 hours before landfall is expected, considering the employed hydrodynamic model underestimates surge for this event during this period. This prediction could be more accurate with future hydrodynamic model improvements. The overall uncertainty can be reduced with improved forecasting of the spatial wind field as well as with improved operational forecast storm surge models.

Finally, we conduct extreme value analyses using Eqs. 2-4 and existing joint probability statistics in Hampton Roads [28], New York/ New Jersey, and Galveston [29,8]. To estimate 1% annual exceedance probabilities (AEP) for forerunner surge, we employ the joint probability method with optimal sampling (JPM-OS; [23]) achieved using time-evolving surge response

functions of Eqs. 2 and 3. The joint probability density function is  $f = f(R|\Delta p)f(\Delta p|x_o)f(v_f|x_o)f(x_o)$ . We use published parameterized probability density functions for the U.S. Gulf of Mexico [8,29] and U.S. Atlantic [28] coasts to define  $f(R|\Delta p)$ ,  $f(\Delta p|x_o)$ ,  $f(v_f|x_o)$ , and  $f(x_o)$ , based on best available historical track information (e.g., [30,31]; A. Cox, Oceanweather, Inc. personal communications). Only landfalling storms are considered, and dependence on storm heading is neglected. We present uncertainty ranges based on our estimated total standard deviation (Eq. 4). Results show that the 1% annual exceedance probability (AEP) forerunner surge 12 hours before landfall is  $0.53 \pm 0.21$  m at Virginia Beach,  $0.71 \pm 0.31$  at New York/ New Jersey, and  $1.37 \pm 0.54$  m at Galveston. This preliminary probabilistic hazard assessment demonstrates the Houston-Galveston area is more prone to high forerunner surge, compared with Hampton Roads and New York/ New Jersey, which is expected considering the much wider and shallower continental shelf, generally lower bottom friction from the muddy sediments along the Texas coast, and more frequent intense storms.

## **Summary and Conclusions**

Forerunner surge in advance of TC landfall can leave people stranded, preventing evacuation and rescue, thus leading to greater loss of life. With projected global sea level rise and projected changes in storm climatology, forerunner surge is expected to play an even more critical role in coastal hazards. Thus, it is of great importance to understand what storm conditions have the potential to generate large forerunner surge, and to include prediction of forerunner surge in public forecasts.

Our results confirm Ekman setup is the leading mechanism driving forerunner surge generation in surge-prone regions characterized by broad, shallow terrain. We further quantitatively prove that slow-moving, large, intense storms have the most potential for

generating dangerous forerunner surge, because such storms generate and sustain the strong alongshore currents needed to produce Ekman setup.

The physical scaling presented herein can be used to assess trends in forerunner surge as a function of real-time forecasted storm track parameters only, allows identification of the range of storm conditions in which a large forerunner surge is possible. The forecasting equations also have the potential to be incorporated into coastal flooding warning systems, and may be used to aid emergency managers and communities in evacuation planning and execution. Because the predictive equations herein are physically based, they are also of high value to regions worldwide influenced by TCs and surge threats, such as the Pacific coasts of southeast Asia, west and east Australia [32], and the Bay of Bengal. In developing regions that lack sophisticated computer modeling, the methods and findings can be applied directly to gauge data or limited simulation results to better characterize forerunner surge threat.

While the TC climatology community has studied and come to consensus that future TCs will be more intense under global warming [33,34], little attention has been given to the influence of global warming on TC size and forward speed. Yet, such investigations are in critical need given the significant influence of size and forward speed on forerunner surge.

Future work to improve understanding and ability to predict forerunner surge should consider, for example, the influence of locally generated surge in coastal bays, tides, sea level rise, and vertical flow structure (e.g, multi-layer hydrodynamic simulation) on Ekman setup.

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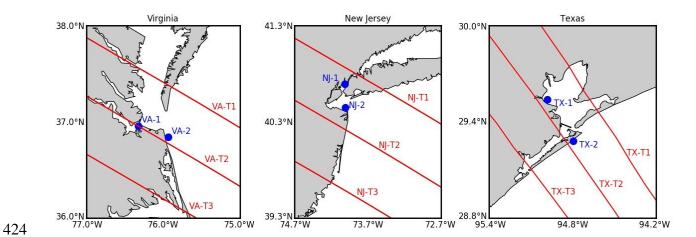
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**Table 1:** Historical TCs with recorded forerunner surges. Data source: (a) Garriott [1], (b) Stewart [35], (c) Kennedy et al. [2], (d) NOAA [27], (e) Cline [36], and (f) Fanelli et al. [37].

Tropical Cyclone	Area	Forerunner Surge (m) (~12 hours before landfall)
Unnamed, 1900	Galveston, TX	1.5 <sup>(a)</sup>
Unnamed, 1915	Galveston, TX	2.1 <sup>(b)</sup>
Ike, 2008	Galveston, TX	$1.8-2.0^{(c)(d)}$
Unnamed, 1915	Tampa, FL	1.5 <sup>(e)</sup>
Sandy, 2012	Norfolk, VA	$1.0^{(f)}$



**Figure 1:** Maps of Virginia, New York/ New Jersey, and Texas coasts with synthetic TC tracks and representative study locations. VA-1 and VA-2 are locations at Sewells Point and Virginia Beach, respectively. TX-1 is within Galveston Bay and TX-2 is near Galveston. NJ-1 and NJ-2 are locations near The Battery and Sandy Hook.

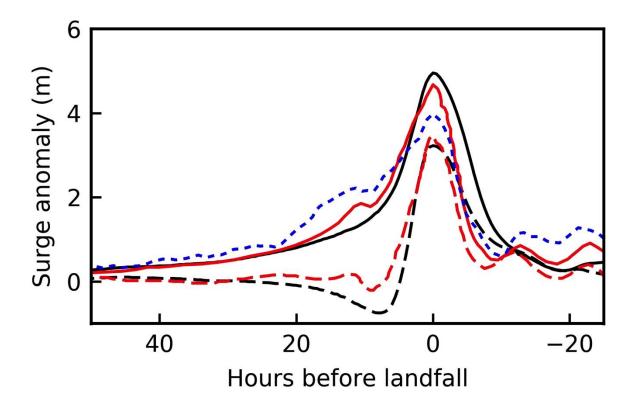
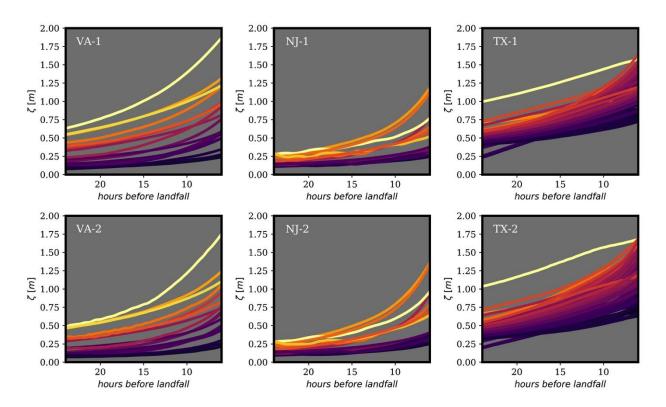
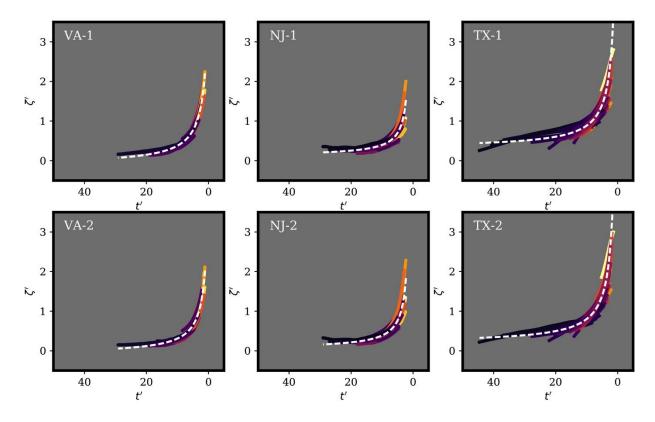


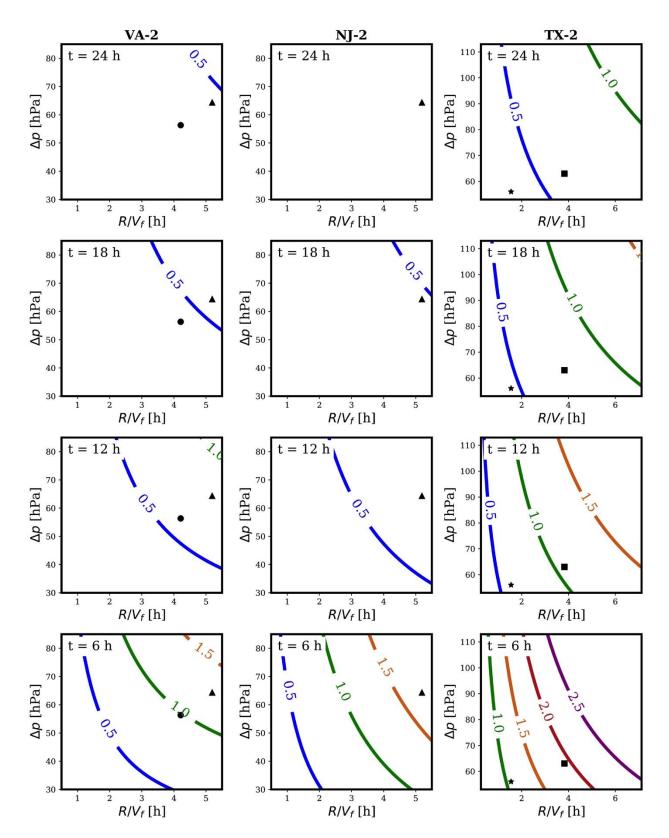
Figure 2. Surge time series validation for Hurricane Ike (2008) at location TX-2 in Figure 1. Black lines: model results with parameterized wind (PBL); red lines: model results with best reconstructed wind (H\*wind); solid lines: model results with Coriollis force; dashed lines: model results without Coriollis force; dotted line: observations. Dotted and dashed lines are observations and simulations from Kennedy et al. [2].



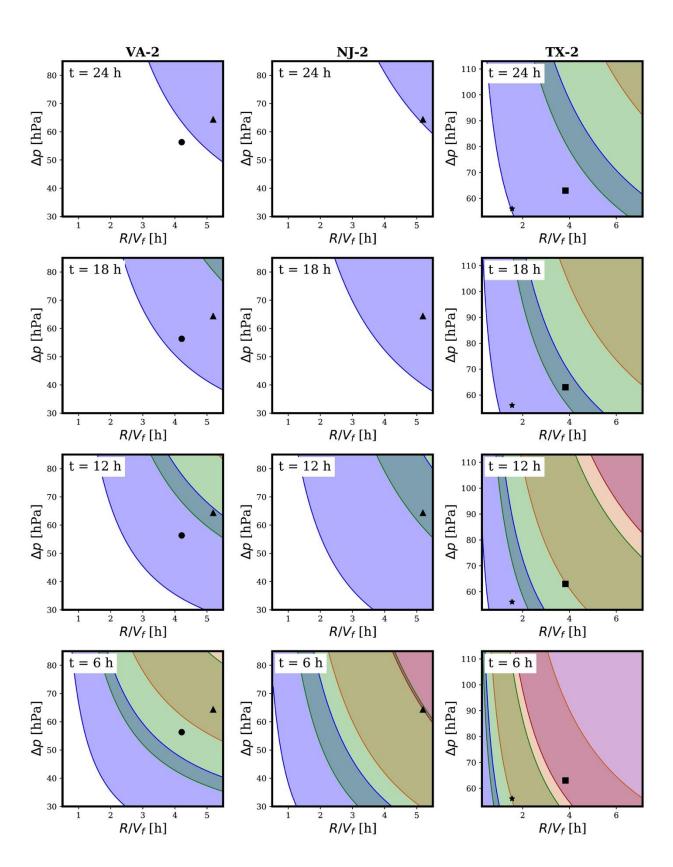
**Figure 3:** Surge time series of 19 simulations in Virginia, 18 simulations in New York/New Jersey and 80 simulations in Texas. Timing is defined as hours before storm landfall. Plots are colorized by  $(\Delta p) \left(\frac{R}{V_f}\right)$ , where lighter colors represent larger values.



**Figure 4:** Plots of dimensionless surge  $(\zeta')$  versus dimensionless time (t') at representative locations. Plots are colorized by  $(\Delta p)\left(\frac{R}{V_f}\right)$ , where lighter colors represent larger values. The dashed white lines represent fitted hyperbolic curves.



**Figure 5:** Deterministic forerunner surge forecasts at VA-2 (Virginia Beach) NJ-2 (Sandy Hook), and TX-2 (Galveston) at 24, 18, 12 and 6 hours before TC landfall, with Hurricanes Isabel (2003, circles), Ike (2008, squares), Sandy (2012, triangles), and Harvey (2017, stars) imposed. The 6-hr Sandy value at NJ-2 is extrapolated beyond the dimensionless data limits.



**Figure 6:** Forerunner surge forecasts with uncertainty bands at VA-2 (Virginia Beach) NJ-2 (Sandy Hook), and TX-2 (Galveston) at 24, 18, 12 and 6 hours before TC landfall, with Hurricanes Isabel (2003, circles), Ike (2008, squares), Sandy (2012, triangles), and Harvey (2017, stars) imposed. Blue, green, orange and purple correspond to 0.5 m, 1.0 m, 1.5 m, and 2.5 m respectively. The 6-hr Sandy value at NJ-2 is extrapolated beyond the dimensionless data limits.

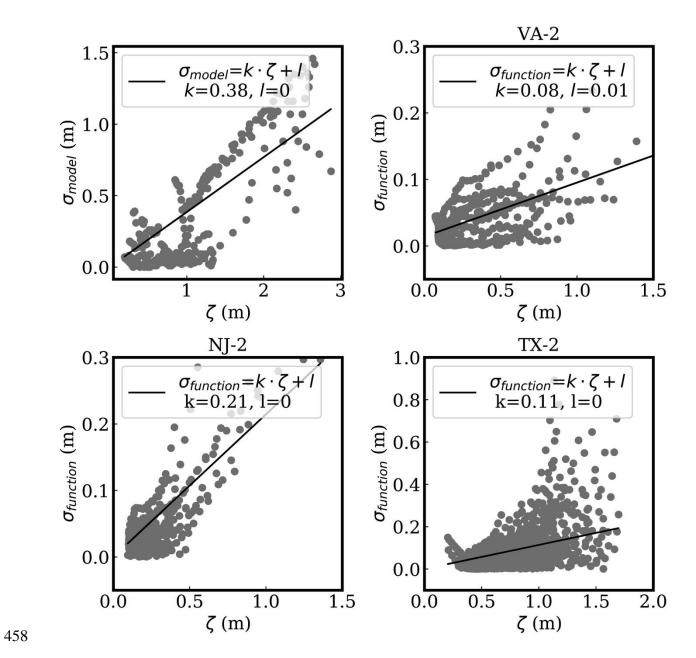


Figure 7. Surge magnitude prediction uncertainty quantification.  $\sigma_{model}$  is calculated as simulated surge standard deviation with respect to observations [27] due to wind parameterization and hydrodynamic modeling based on ADCIRC-STWAVE and ADCIRC-SWAN simulations at selected coastal locations. Shown are US Atlantic Hurricanes Sandy (2012), Irene (2011), Isabel (2003), Gloria (1985), Josephine (1984) [26] and US Gulf of Mexico Hurricanes Ike (2008), Katrina (2005), and Rita (2005) [25,26], for surge 24 to 6 hours before landfall.  $\sigma_{function}$  is calculated as error in surge prediction using Eqs. 2 and 3, represented by standard deviation between curve fit and surge simulations at VA-2 (Virginia Beach) NJ-2 (Sandy Hook), and TX-2 (Galveston), for surge 24 to 6 hours before landfall. Each gray dot represents surge values averaged over a 1-hour interval.

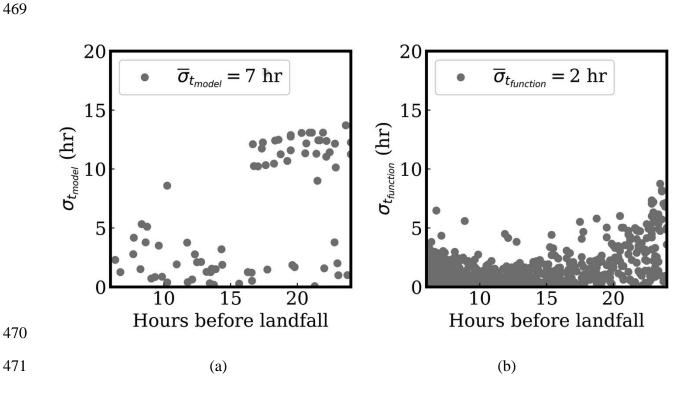
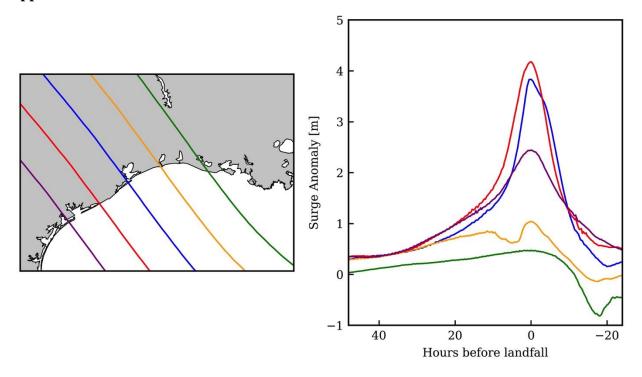
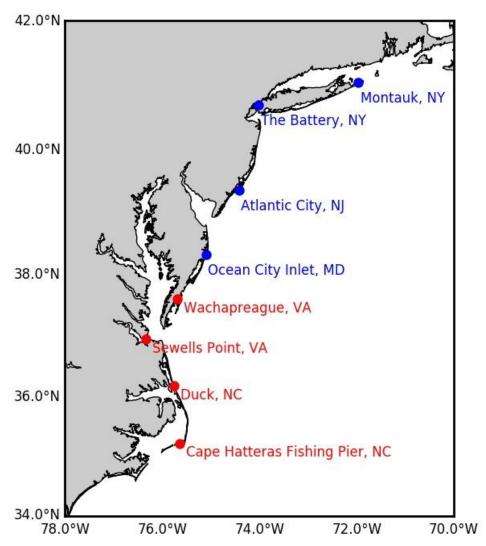


Figure 8. Surge timing prediction uncertainty quantification. (a) Simulated timing standard deviation [27] due to wind parameterization and hydrodynamic modeling based on ADCIRC-STWAVE and ADCIRC-SWAN simulations at selected coastal locations. Shown are US Atlantic Hurricanes Sandy (2012), Irene (2011), Isabel (2003), Gloria (1985), Josephine (1984) [26] and US Gulf of Mexico Hurricanes Ike (2008), Katrina (2005), and Rita (2005) [25,26], for the arrival of 0.3-m to 2.0-m surge. (b) Error in timing prediction when observed forerunner surge is between 0.3-m to 2.0-m using Eqs. 2 and 3.

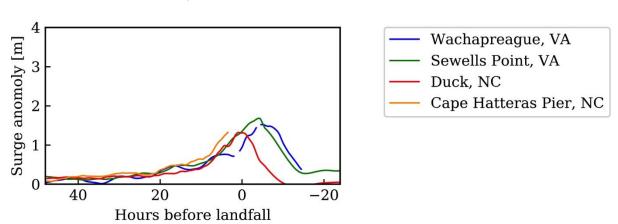
# **Appendix A**



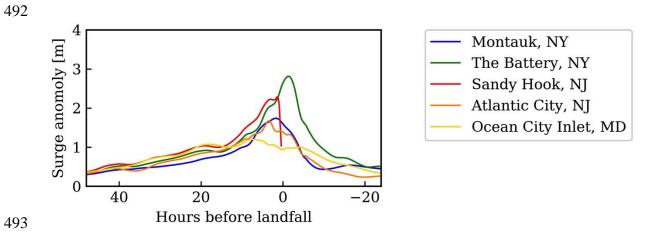
**Figure A1.** Tracks and surge time series for an Ike-like synthetic tropical cyclone that is shifting 100-km or 200-km to the south or north.



**Figure A2.** Map showing locations of NOAA (2017) observational water level data presented for Hurricane Sandy (2012, blue circles) and Hurricane Isabel (2003, red circles).



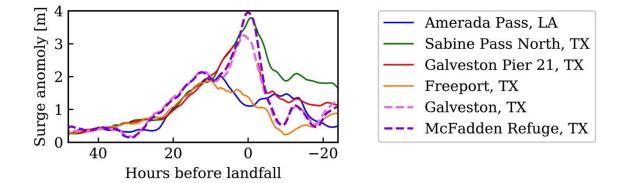
**Figure A3.** Observed water level anomaly time series (NOAA 2017) for Hurricane Isabel (2003); locations shown in Figure S3.



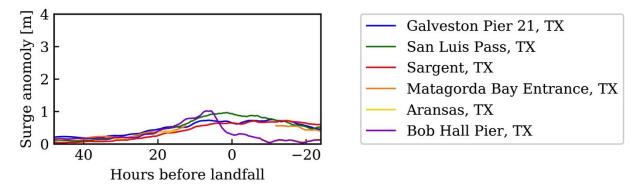
**Figure A4.** Observed water level anomaly time series (NOAA 2017) for Hurricane Sandy (2012); locations shown in Figure S3.



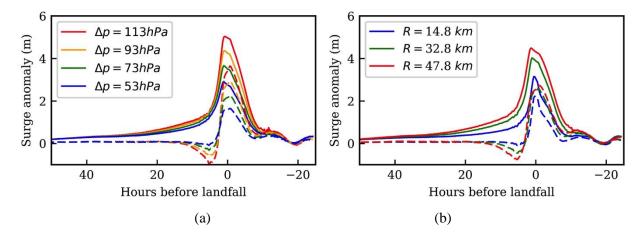
**Figure A5.** Map showing locations of observational water level data presented for Hurricane Ike (2008, blue circles and triangles) and Hurricane Harvey (2017, red circles). NOAA (2017) stations are circles and Kennedy et al. [2] stations are triangles.



**Figure A6.** Observed water level anomaly time series (NOAA 2017 and Kennedy et al. 2011) for Hurricane Ike (2008); locations shown in Figure S6.



**Figure A7.** Observed water level anomaly time series (NOAA 2017) for Hurricane Harvey (2017); locations shown in Figure S6.



**Figure A8.** Simulated surge time series with (solid lines) and without (dashed lines) Coriolis forcing for tropical cyclones along track TX-T2 with a 5.66 m/s  $V_f$  and (a) 32.8 km R, (b) 73 hPa  $\Delta p$ .

Hurricane	<b>Δp</b> ( <b>hPa</b> )	R (km)	$V_f$ (km/h)
Isabel (2003)	56 <sup>(a)</sup>	87 <sup>(b)</sup>	20 <sup>(a)</sup>
Sandy (2012)	65 <sup>(a)</sup>	135 <sup>(c)</sup>	26 <sup>(a)</sup>
Ike (2008)	63 <sup>(a)</sup>	74 <sup>(d)</sup>	18 <sup>(a)</sup>
Harvey (2017)	56 <sup>(a)</sup>	26 <sup>(e)</sup>	17 <sup>(a)</sup>

**Table A2** Dimensionless curve fitting coefficients for Equation 3.

Location	Curve fitting coefficients			
Location	a	b	c	
VA-1	5.44	1.24	-0.11	
VA-2	4.36	0.96	-0.09	
NJ-1	2.70	-0.38	0.11	
NJ-2	3.21	-0.49	0.05	
TX-1	5.96	0.42	0.31	
TX-2	6.30	0.24	0.18	