

Design of a Helicopter Deployable Ground Robotic System for Hazardous Environments

Michael S. Rose

Thesis submitted to the Faculty of the
Virginia Polytechnic Institute and State University
in partial fulfillment of the requirements for the degree of

Master of Science
in
Mechanical Engineering

Kevin B. Kochersberger, Chair
David C. Conner
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January 25, 2010
Blacksburg, Virginia

Keywords: Robotics, Tracked Vehicle, Motion Planning, Teleoperation, Situational
Awareness

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Michael Rose

From: thomas sheridan [sheridan@MIT.EDU]
Sent: Monday, January 11, 2010 9:42 AM
To: Michael Rose
Subject: Re: Use of figure

Michael,

Permission granted, not a problem, assuming you will cite the source.

Tom

On Jan 11, 2010, at 8:30 AM, Michael Rose wrote:

Dr. Sheridan –

I am writing my master's thesis at Virginia Tech and would like permission to use a figure from your book *Telerobotics, Automation, and Human Supervisory Control*. The figure is in the introduction that demonstrates the differences between full manual control, supervisory control and full automation. If I need to contact the publisher directly for this permission, please inform.

Regards,

Michael Rose
Virginia Tech
[Unmanned Systems Lab](#)
Plantation Road
Blacksburg, VA 24060
miker2@vt.edu
801-318-3421

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Michael Rose

From: David I Gertman [David.Gertman@inl.gov]
Sent: Monday, January 11, 2010 2:52 PM
To: Michael Rose
Subject: Re: Permission to cite article

Michael

Please feel free to cite the paper. Here is another link. Godd luck with your thesis. Keep me posted on your progress.

http://www.osti.gov/bridge/product.biblio.jsp?osti_id=927622

David I Gertman, PhD
Consulting Scientist
Human Factors & Instrumentation and Controls Department
Idaho National Laboratory
EROB Bldg, MS 3605
Idaho Falls, ID 83415

208.526.1756 (O)
208.521.5606 (C)
208.526.2777 (Fax)

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Michael Rose

From: Steven M LaValle [lavalle@uiuc.edu]
Sent: Monday, January 11, 2010 2:17 PM
To: Michael Rose
Subject: Re: Permission to use a figure

HI Michael,

Feel free to use it. Good luck with your thesis!

Best wishes,

Steve

On Mon, 2010-01-11 at 07:34 -0600, Michael Rose wrote:

> Dr. LaValle -

>

>

>

> I am working on writing my master's thesis, and your Planning
> Algorithms book has been very helpful in understanding the different
> planning algorithms available. I am using some of the discrete domain
> planning algorithms in my research and am wondering if I might be able
> to use some figures from your books in my Thesis. I would like to use
> figure 2.3 from the book. May I have permission to use this figure in
> my thesis? If I need to contact the publisher directly for this
> permission, please advise.

>

>

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> Thanks,

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>

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> Michael Rose

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