

Underslung Payload Tension Control from an Autonomous Unmanned Helicopter

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Virginia Polytechnic Institute and State University
in partial fulfillment of the requirements for the degree of

Master of Science

in

Mechanical Engineering

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Blacksburg, Virginia

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May 10, 2012

RE: SimplIQ Software Manual

To Whom It May Concern:

Brian McCabe has Elmo Motion Control's permission to use the SimplIQ Software Manual specifically Figure 9-1 and Figure 15-1 for the SOL-WHI product in a thesis at Virginia Tech.

Sincerely,



John McLaughlin
General Manager



Brian McCabe <brian.john.mccabe@gmail.com>

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1 message

Hess Roger <RHess@maxonmotorusa.com>
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Thu, May 10, 2012 at 3:31 PM

Hello Brian,

Please use this email as written authorization to use any images from our Web site for your school Papers/projects. Please contact me with any additional questions or needs.

Regards,

Roger Hess

Sales Engineer-Southeast

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