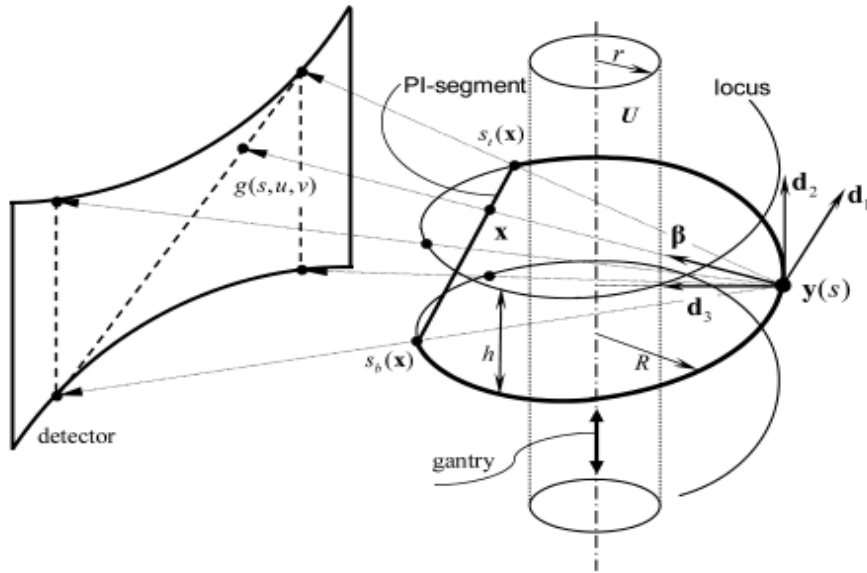


Fast CT Reconstruction — Practical Performance via Parallelization



Parallel computing has been used to solve large-scale problems in many fields. While CT is being developed towards high-resolution, volumetric, dynamic and spectral imaging, datasets become increasingly large, and reconstruction speeds are often too slow. To meet this challenge, in 2004 Drs. Wang and Ni co-founded a High performance Computing Lab, and have been working in this area ever since. **In 2006, we designed and implemented the first parallel Katsevich algorithm.** We have also parallelized EM, OS-EM, SART and OS-SART algorithms, respectively.

Quotation from Distinguished Peers

The above four algorithms were proposed in the theoretical detector-free form, with filtering lines derived for a flat panel detector. Later, Noo et al. [13] showed that using the so-called “native geometry,” that is, the geometry associated with a detector in use (which is curved for medical CT scanners, and flat for C-arm systems), results in more efficient implementation. Noo et al. provided the equations of the filtering curves in native detector coordinates and processing steps for implementation of the KVD-1PI algorithm. Another practical implementation scheme was proposed by Yu and Wang [14]. **This type of work is essential for implementing of the exact algorithms on commercial CT scanners.**

Katsevich A, Taguchi K, Zamyatin AA: Formulation of Four Katsevich Algorithms in Native Geometry. *IEEE Trans. Medical Imaging* 25:855-868, 2006

Publications by Our Team

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