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Matt Paluszek <mattiep9@vt.edu>  Fri, Aug 26, 2016 at 9:10 AM
To: Steve Powell <stevep7@vt.edu>

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-Matt Paluszek

Sent from my iPhone

Thesis submission
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Regards,
Mike

Warm Regards,
Mike Stevens
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Figure 5.

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Figure 6.

Title: The DEXMART hand: Mechatronic design and experimental evaluation of synergy-based control for human-like grasping:

Author: G. Palli, C. Melchiorri, G. Vassara, U. Scarca, L. Mongillo, G. Beradelli, A. Cavallo, G. De Maria, C. Natale, S. Prozzi, C. May, F. Cipociello, B. Siciliano

Publication: International Journal of Robotics Research

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Figure 7.

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