

**Increasing Capacity by the Use of Optimal Runway Exits, Automated Landing,
Roll Out and Turnoff in an Airport Environment**

by

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(ABSTRACT)

This study outlines the development and use of several techniques providing an automated landing, roll out and turnoff of an aircraft, in an airport environment. A maximum runway occupancy time and a certain level of reliability are achieved by the use of a computer software called the Probabilistic Computer Model of Optimal Runway Turnoffs.

A bunching of eight optimal high speed exits, representing four TERPS categories, is performed on a single runway. Feasibility of the system is determined by the use of Inertial Navigation and other aids such as the Microwave Landing System, Filtering Devices, Electronic Cockpit Airfield Display Formats, Real Time Flight Simulation and Field Testing, and a Braking Guidance Policy. It is suggested that future testing and a review of the Model be done.

ACKNOWLEDGEMENTS

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CHAPTER 1 INTRODUCTION

1.1 AVIATION FORECASTS

The expanding demand of air transportation between 1971 and 1979 has led to compare the air transportation industry to an infant industry, growing at an exponential rate. The number of persons carried jumped from 174 millions to 321 millions in 8 years. US air passenger mileage was 4.3 billion passenger miles in 1944. In 1980, it grew up to 203 billion passenger miles (1).

The success of air transportation can be measured in terms of the overall increase of the domestic aviation activities since World War Two (2). In the United States, the Air traffic volume is expected to increase at a growing rate in the future. The Federal Aviation Administration (FAA) provides forecasts of the air travel activities which are summarized below for the years 1983 through 1994 (2&3).

1.1.Air carriers

- 5.1 percent annual increase in revenue passenger-miles
- 1.8 percent annual increase in air operations
- 4.6 percent annual increase in passenger enplanements

- about 60 percent increase in domestic load factor

1.1.2 Commuter carriers

- 5.8 percent annual increase in all fare paying passengers in scheduled domestic flights
- 10.2 percent annual increase in revenue passenger miles
- 8.4 percent annual growth in passenger enplanements

1.1.3 General Aviation

- 110 percent increase in the number of turbine powered general aviation aircrafts
- 48 percent increase in total number of general aviation aircrafts

1.1.4 Operations

- 5.8 percent increase of aircraft operations at FAA towers
- average annual growth rate by user groups are: general aviation, 4.9 percent; air carrier, 1.8 percent; commuter, 7.0 percent; military, 0.7 percent.

Figure 1 shows the historic trends of projections of world passenger movements.

1.2 THE PROBLEM

The number of airport operations in the United States has grown steadily during the last two decades. As of 1980, the FAA has published a report on the total aircraft and air carrier operations for annual and busy-hour traffic at selected hub and general aviation airports as shown in table 1.

As the table indicates, there is a need to accommodate the unprecedented growth in the demand for air transportation services, which are being stressed beyond the airports' design capabilities. This has caused a considerable emphasis on research to analyze the level and causes of capacity deficiencies. The FAA Advisory Circular (4) defines the concepts of capacity and delay as follows: "Capacity is the throughput rate i.e. the maximum number of operations that can take place in an hour. Delay is the difference in time between a constrained and an unconstrained aircraft operation".

This definition of capacity is referred to as the ultimate capacity, for an infinite queue. However demand is fluctuating and an airport capacity is influenced by other factors including FAA regulations, wake vortex turbulence, weather, airfield and airspace configurations, etc...

POSTWAR TRENDS IN AIR TRANSPORT

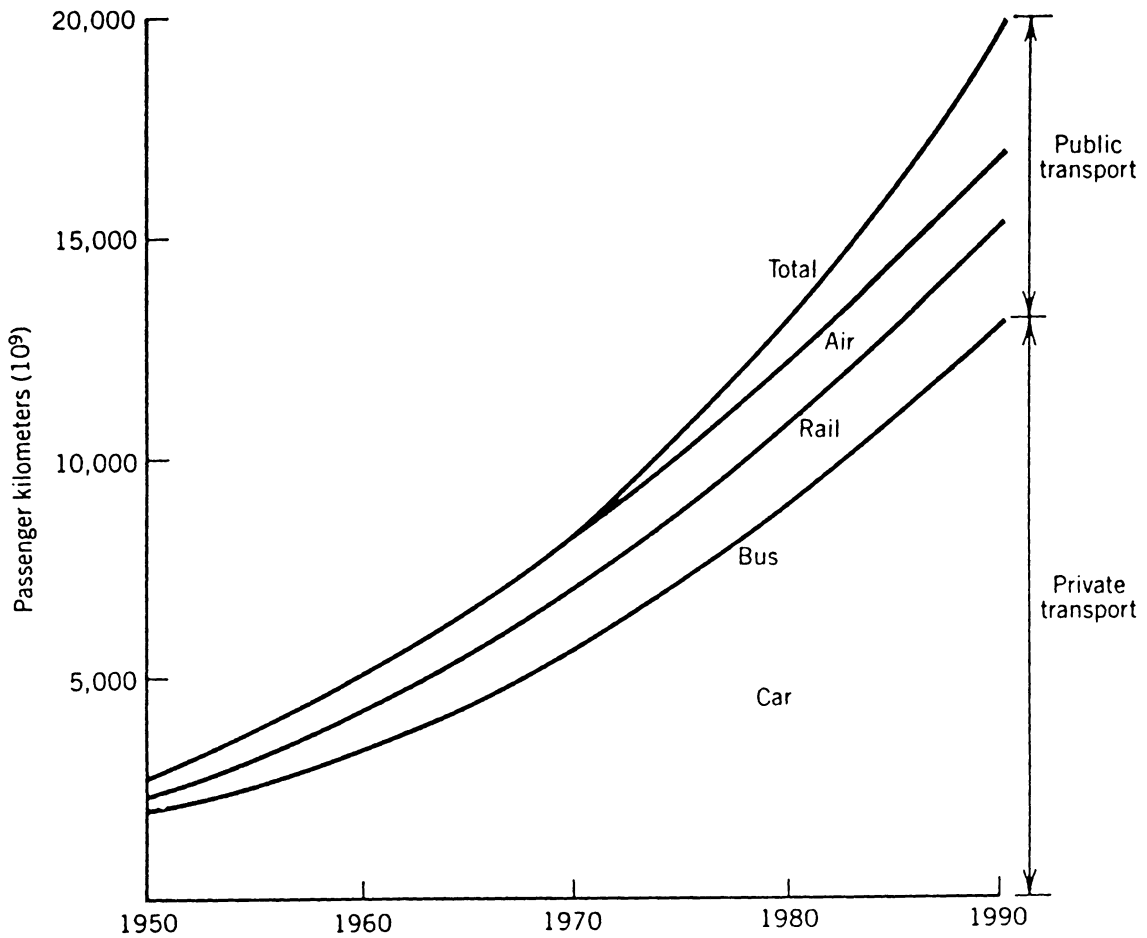


Figure 1. World Total Passenger Movements Distributed by Principal modes

(Source: Adapted from Reference 1)

Table 1. Annual and Busy-Hour Aircraft Operations at Selected U.S. Air Traffic Hub and General Aviation Airports, Fiscal Year 1980

(Source: Adapted from Reference 2)

Airport	Annual		Busy hour	
	Total	Air carrier	Total	Air carrier
Large hub airports:				
Chicago O'Hare International	734,555	577,671	178	141
Hartsheld-Atlanta International	609,466	541,440	145	181
Los Angeles International	534,414	419,506	133	88
Denver Stapleton International	485,695	316,664	169	105
Miami International	376,820	283,457	111	84
Washington National	354,717	204,560	108	56
Boston Logan International	340,896	204,159	112	59
Medium hub airport:				
Memphis International	377,603	143,294	115	48
Salt Lake City International	285,104	83,723	155	27
Milwaukee-Mitchell Field	247,290	85,011	136	35
Portland International	219,404	75,827	107	37
Orlando Jetport	157,535	115,936	67	42
San Diego International	155,914	69,513	54	18
Greater Cincinnati	119,088	59,733	68	25
Small hub airports:				
San Jose Municipal	415,513	47,255	183	19
Daytona Beach Regional	292,534	15,030	164	9
Wichita Mid Continent	230,128	37,439	169	37
Sacramento Metro	170,733	36,749	106	20
Grand Rapids Kent County	167,922	27,334	126	11
Richmond Byrd International	163,998	33,813	75	17
Knoxville McGhee-Tyson	143,575	19,598	71	7
General Aviation:				
Fort Worth Meacham	400,722		284	
Pontiac	274,686		220	
Seattle Boeing Field	408,207		247	
Tamiami	422,867		236	
Teterboro	308,413		231	
Torrance Municipal	370,398		284	
Van Nuys	567,055		310	

The problem of how to increase capacity and minimize delay at airports can then be expressed in terms of time saved when the actual delay is reduced to an acceptable level. In 1980, the national cost associated with delay was estimated at 1.395 billion of dollars with an average delay of 5.9 minutes per operation (3). Table 2 shows the average delay per operation at some leading Air Carrier Airports. The average delay is the summation of delays during the four phase cycle. The four phases are: gate hold, taxi-out, airborne and taxi-in. Delay is common and becomes more critical during peak periods, when it can reach unreasonable values.

Then, the average delay an aircraft experiences per operation, in an airport system, takes place at different levels. It can be in the landing process, on the runway, on the taxiways or in the terminal area. Many techniques are available to minimize delay in the queueing system.

Even though airport congestion and delay problems are more likely to increase in major hub airports, aviation experts have predicted that no new major airport will be constructed in the U.S. for many reasons. Some of the major factors are (1) expensive land acquisition (2) strong community objections to the potential environmental pollution (3) lead time of at least a decade between inception and completion of the project.

Several issues are being addressed by NASA and FAA in an effort to increase the airport system's capacity. These issues deal with:

Table 2. Average Delay Per Operation at Leading Air Carrier Airports

(Source: Adapted from Reference 3)

(Minutes: Ranked by 1980 Delays)

Airport	1978	1977	1978	1979	1980
Atlanta (ATL)	8.85	10.61	10.11	10.81	9.46
New York (LGD)	9.35	8.20	9.34	9.76	9.31
New York (JFK)	10.75	9.99	11.14	9.76	9.25
Chicago (ORD)	9.09	9.30	9.67	10.17	8.89
Denver (DEN)	6.42	7.01	9.52	8.78	8.09
Boston (BOS)	6.60	7.49	6.98	7.90	7.15
St Louis (STL)	4.75	6.07	6.31	7.63	7.15
Los Angeles (LAX)	4.76	5.07	6.42	6.32	7.09
Washington D.C. (DCA)	6.22	6.82	6.67	6.74	6.41
Miami (MIA)	5.27	5.00	5.53	5.44	6.01
San Francisco (SFO)	5.42	4.95	4.62	5.22	5.89
Honolulu (HNL)	4.58	5.47	5.57	5.80	5.45
Dallas-Ft. Worth (DFW)	5.16	4.46	4.88	5.67	5.22
Houston (IAH)	4.19	4.13	4.93	5.42	5.17
Detroit (DTW)	4.13	4.67	4.91	4.74	3.99

- providing an efficient aircraft spacing, using the Microwave Landing System
- reducing the effects of wake vortex between small and bigger aircrafts
- upgrading the air traffic control
- optimizing the use of the facilities without degrading the system's safety
- introducing new techniques such as the high speed exit with automated landing, roll out and turnoff or the Brandt Drift-off

In that respect the National Aeronautic and Space Administration (NASA) has directed research and development programs in order to alleviate the problem previously stated. The programs have focused on several efforts. One of them is the high speed exit design with an early goal of maximum runway occupancy time of 40 seconds and an automated landing, roll out and turnoff (5&6).

The technique investigated in this study lies in increasing the landing capacity of the runway, airside/landside interface, and in decreasing the time separation between successive aircrafts in their landing approach with regard to FAA regulations related to wake turbulence. The minimum allowable horizontal separation is from 2 to 5 nautical miles (1).

The focus of this investigation is in the areas of optimal exit locations, the development of high speed turnoffs, the guidance of the aircraft by an automated curved path approach, landing, roll out and turnoff. These are studied as dependent solutions in increasing landing capacity.

1.3 RESEARCH OBJECTIVE AND SCOPE

The first part of this research is to slightly modify an existing computer software called the Probabilistic Computer Model of Optimal Runway Turnoffs (5) so that it can be run on the Personal Computer IBM PC XT in order to determine optimal exit locations on a single runway. An exit is said optimal for an aircraft when the maximum runway occupancy time is 40 seconds and the probability of making such an exit is 99.99 percent. The maximum runway occupancy time is the time elapsed between an aircraft crossing the runway threshold and its clearing of the runway edge along the exit path. At high speed, the wingtip is the part of the aircraft the most critical in clearing the runway.

Secondly, it is proposed a bunching of the optimal exit locations and path profiles, which would accommodate most aircraft mixes in a major airport environment. To cover the wide range of aircraft mixes, the four TERPS Categories A, B, C and D are used. The B 747 and Lockheed F 104 are added in the research to give an example of how a particular aircraft can fit in the design. The design must meet the requirements of time, safety and reliability.

The last part of the research is to perform a literature review on the Microwave Landing System and Guidewire Sensors, and the different components of the High Speed Exit Research that play important roles in smoothing and expediting the air traffic flow.

CHAPTER 2 AVIATION SYSTEM

2.1 AIRSIDE

2.1.1 Runway

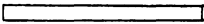
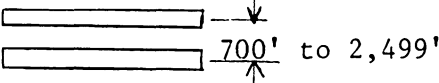
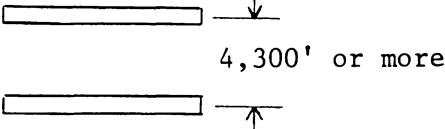
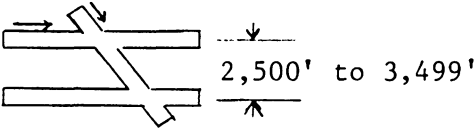
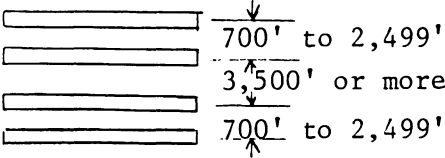

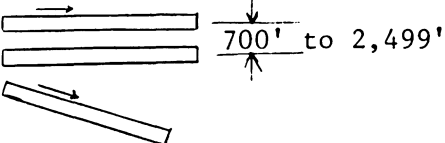
Many runway configurations exist, from the single runway to the parallels plus crosswinds R/W as shown in table 3. For the purpose of this study, it is used a single runway with different high speed turnoffs. In VFR its capacity is somewhere between 50 and 100 operations per hour; while in IFR, the capacity is reduced to between 50 and 70 operations (2). An operation consists of a landing, a take-off or a touch-and-go. The runway structural width is assumed to be 150 feet (5&6).

2.1.2 Taxiway

A taxiway connects the runway to the terminal building and service hangers. In cross section, it is similar in appearance to a runway. The dimensions are of course smaller. The usual procedure is to locate a taxiway parallel to the runway centerline.

Table 3. Runway Configuration Diagram

(Source: Adapted from Reference 1)

Configuration	Runway Configuration Diagram
A Single Runway	
B Dual Lane	
C Independent IFR Parallels	
D Parallels plus Crosswind R/W	
E Four Parallels	
F Open V Runways	
G Parallels plus Crosswind R/W	

2.2 TERMINAL AIRSPACE AND ENROUTE AIRSPACE

Terminal Airspace is commonly referred to as a distance of 25 to 50 miles from the airport; whereas the enroute airspace is comprised of the airways, jet routes and other parts of the airspace.

2.3 LANDSIDE

The landside is comprised of the terminal buildings and the vehicular circulation parking. It will not be an area of interest in this report. Fig 2 shows a diagram of the aviation system.

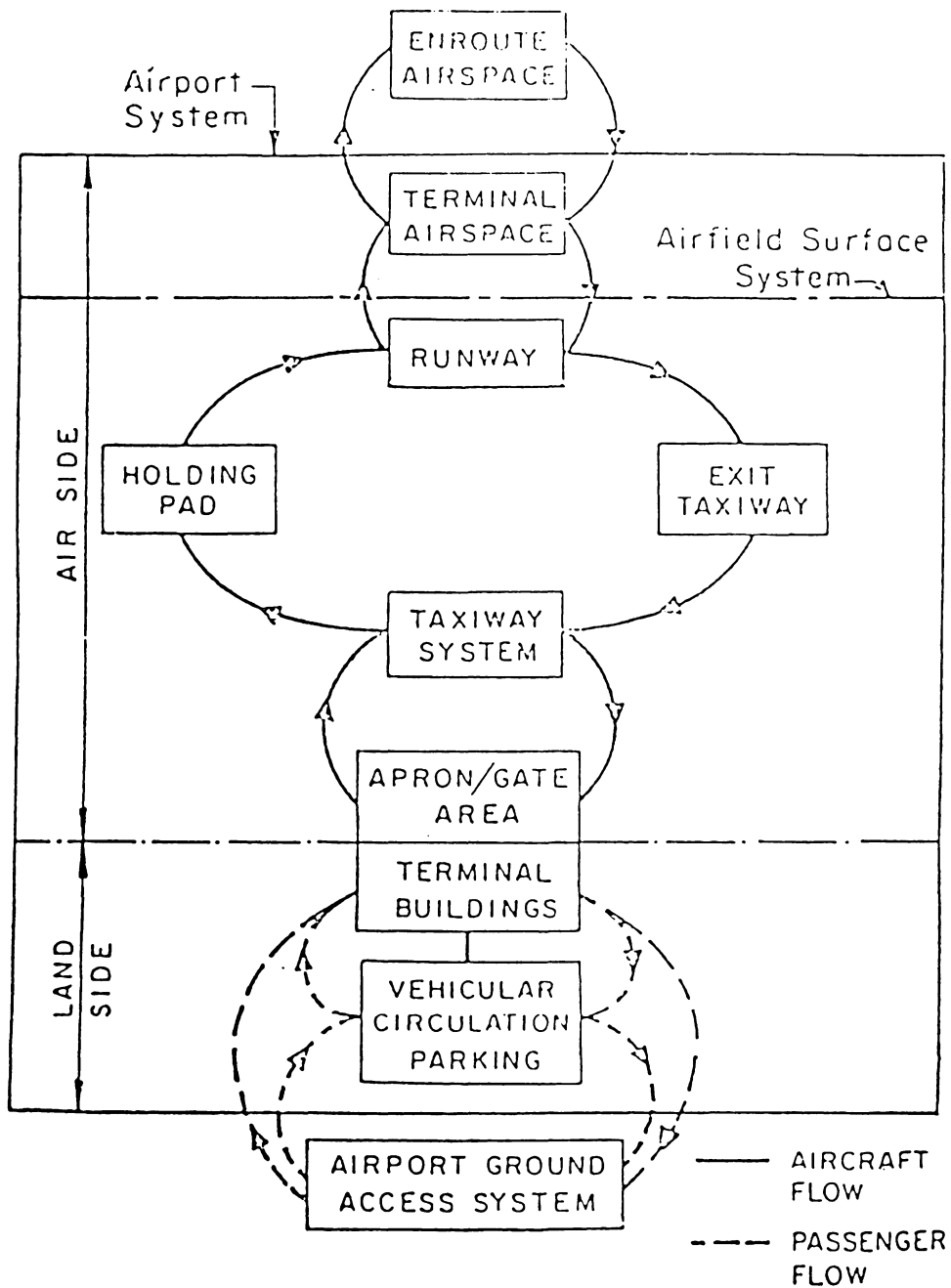


Figure 2. The aviation system

(Source: Adapted from Reference 16)

2.4 AIR TRAFFIC CONTROL

The control of traffic, arrivals and departures, from the boundary of the air traffic control tower to the limit of the terminal airspace, is under the jurisdiction of the terminal approach control facility. The air route traffic control centers have the responsibility of controlling the movement of aircrafts in the en route airspace.

The air traffic control system, which must accommodate the wide variety of airspace need in heavily trafficked areas, must meet the requirements of safety and efficiency. To be of value, this protection is to be achieved while capacity is increasing.

Visual Flight Rules (VFR) prevail when weather conditions are good enough and when traffic densities are low enough . The principle of "see and be seen" is generally accepted. However, when the visibility or the ceiling fall beyond the above limits, the Instrument Flight Rules apply. In the latter case, after some data are collected and processed, a decision is made and transmitted to the pilot to avoid air conflicts.

In the immediate area of the terminal, the landing operations require, in addition, the use of special navigation aids. These include the Instrument Landing System (ILS), Precision Approach Radar (PAR), the Airport Surveillance Radar (ASR), the Microwave Landing System (MLS).

2.4.1 Instrument Landing System (ILS)

ILS is the most widely used method as an approach and landing aid. The system guides the pilot by the use of two radio transmitters located in the airport. These radio transmitters are the localizer and the glide slope. Their function is to indicate to the pilot what his position should be, relative to the runway centerline, so that a safe landing can be achieved. In addition to the transmitters, two low power fan markers are located along the runway to inform the pilot of his closeness. Figure 3 shows a schematic diagram of the ILS.

But the ILS has some limitations:

- it is not completely reliable because the signals can be deteriorated by mobile and stationary objects
- it restricts the pilot in his landing approach, confining him in the airspace from many miles out
- it aggravates the queueing subsystem associated with the fix, for arriving aircrafts. The queue discipline is on a first-come first-served basis.

AIR TRAFFIC CONTROL

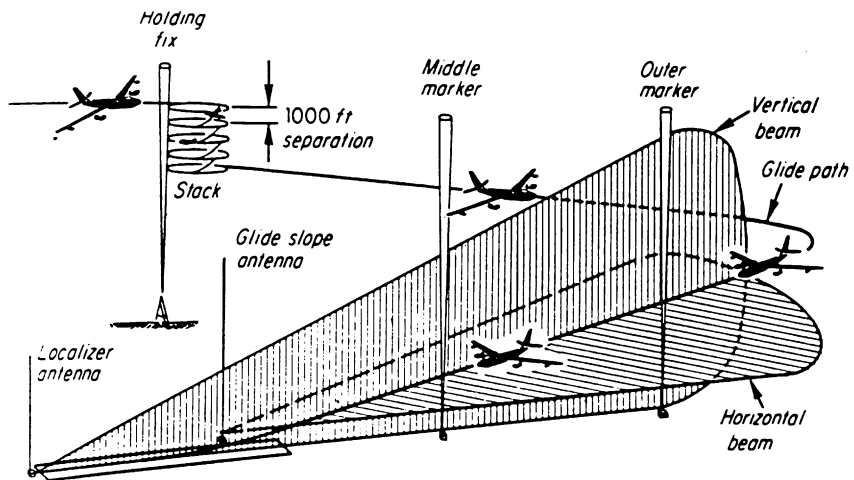


Figure 3. Schematic Diagram of the ILS

(Source: Adapted from Reference 2)

2.4.2 Microwave Landing System

The MLS which eliminates most of the problems present in the ILS is still at the testing age. Its coordinate system shown in Fig 4 uses conical coordinates of azimuth, elevation and range. A coordinate transformation is made to position the aircraft in the runway inertial system. Fig 5 shows a schematic diagram of the MLS.

The beam transmitted by the localizer is confined by a waveguide antenna and is less likely to be distorted. By providing a multitude of paths in space in the horizontal plane, within an angle of 120 degrees around the runway centerline, it also allows the pilot to approach the runway at a much steeper angle, up to 20 degrees in the vertical plane. At the same time, the use of higher frequencies increases the number of frequency channels available, over the many routes. Continuous information on the aircraft closeness to the runway is provided.

As can also be seen in fig 6, due to the flexibility of the system, the problems of wake vortex, aircraft separation and delay associated with the fix (ILS) are greatly reduced, and capacity is increased.

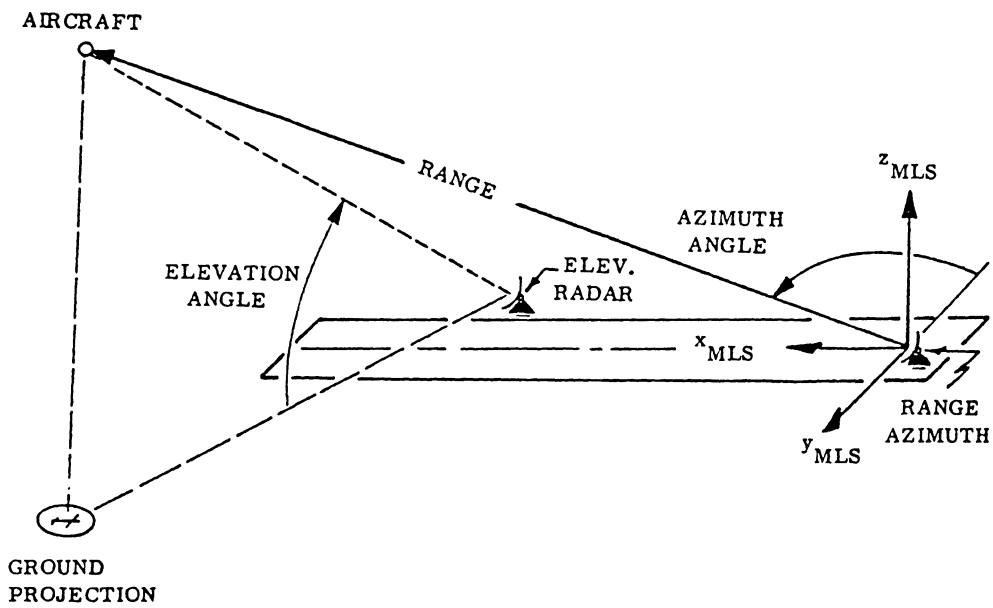


Figure 4. The MLS Coordinate System

(Source: Adapted from Reference 8)

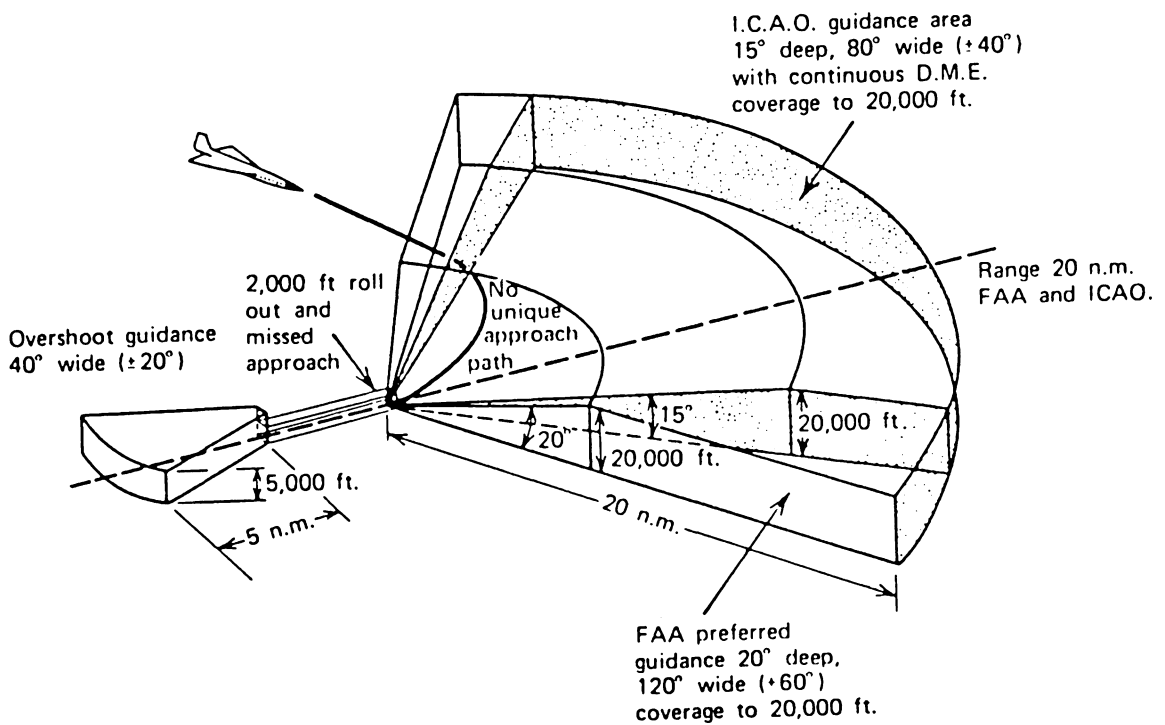


Figure 5. The Microwave Landing System

(Source: Adapted from Reference 1)

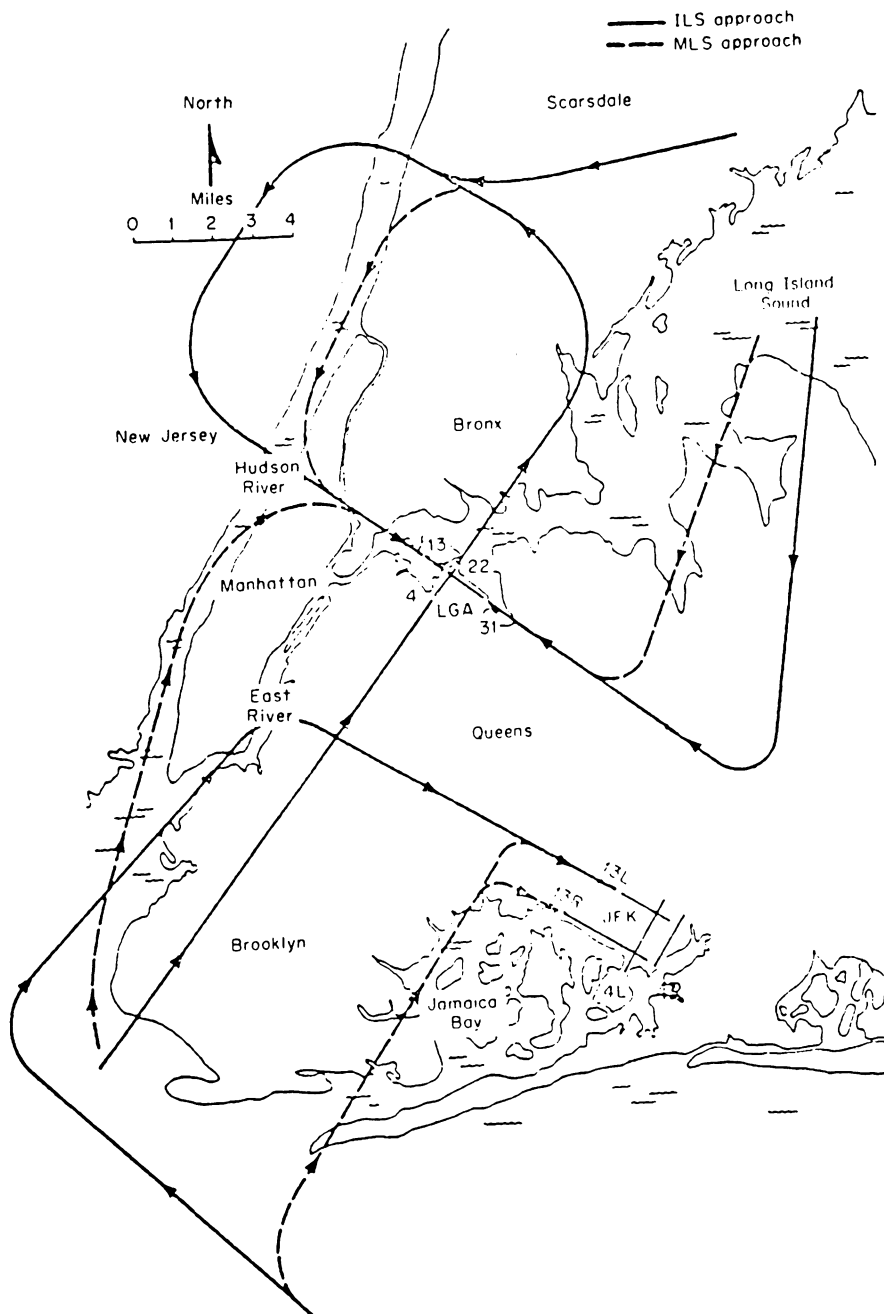


Figure 6. Differences Between an ILS and an MLS Approach to Kennedy (JFK) and La Guardia (LGA) Airports in the New York Area

(Source: Adapted from Reference 2)

CHAPTER 3 LITERATURE REVIEW

Research has started in the early 1950's and was mainly done through observations. Robert Horenjeff, a pioneer in this domain, has conducted field testing in order to determine the minimum permissible turning radius for different types of aircraft. The empirical work gives the cornering limits of an aircraft, as can be seen in fig 7. These results were validated by flight simulation and flight test data later by the Langley Visual Motion Simulation and at Columbia Airport, at speeds averaging 60 knots (10).

The literature review developed in this research has the purpose of identifying the important features related to the high speed exit feasibility.

3.1 MATHEMATICAL MODEL FOR LOCATING EXIT TAXIWAYS

Traffic handling capacity has been a concern since the 1950's. A team of Operations Researchers and Engineers got involved with the problem (9) and studied a Mathematical Model for locating exit taxiways in 1958 in order to determine the effectiveness in terms of acceptance rate. The results showed that "the optimal locations and the corresponding acceptance rates are quite sensitive to aircraft population, exit speed and number of exits".

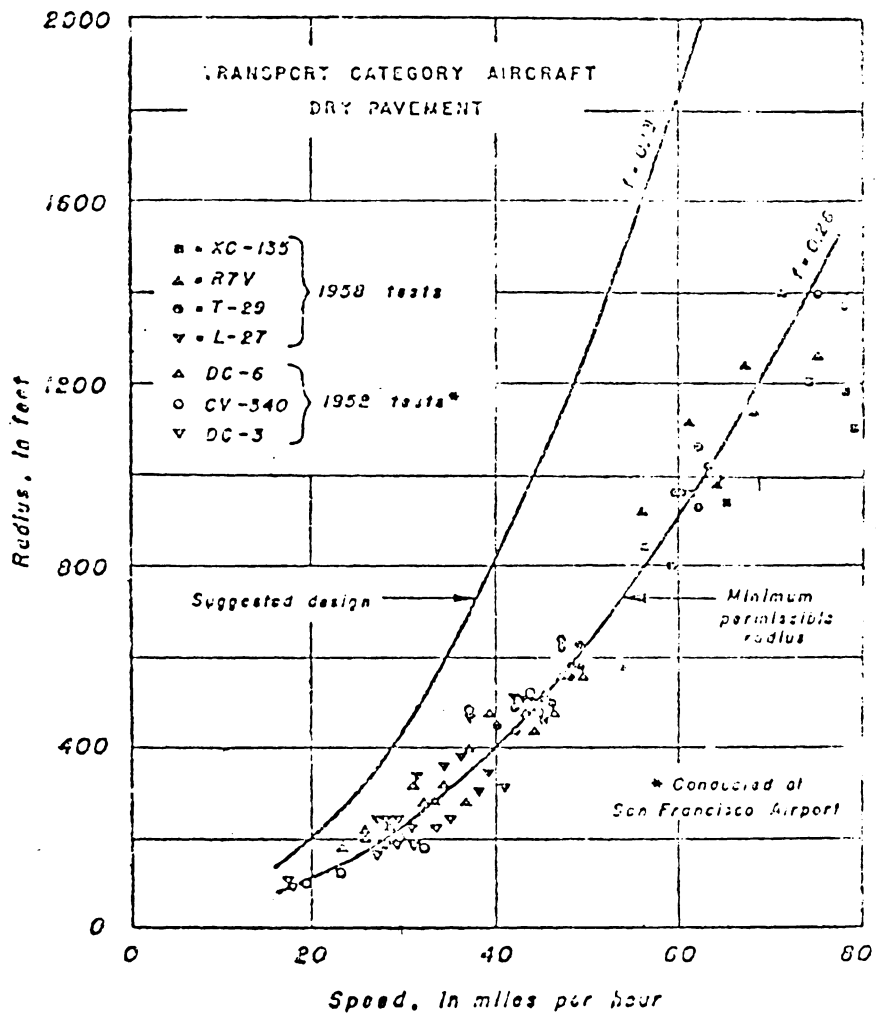


Figure 7. Radius vs. Speed; Transport Category Aircraft; Dry Pavement

(Source: Adapted from Reference 6)

Due to the lack of data and avoiding over complexity, the mathematical model was oversimplified, assuming for example that:

- no accident would occur
- no change in environmental patterns
- fixed interval of time and distance
- fixed exit speeds of 40 and 60 mph
- fixed aircraft mix

The results were presented in the form of charts and graphs, or probabilities of wave off and optimization of acceptance rates. This approach can be somewhat controversial as said in the analysis of of results: "Suppose it is desirable to provide exits so that the runway could accept about 60 aircrafts per hour. In terms of acceptance rate, two exits would practically do the job (55.73 aircrafts). A third exit increases the acceptance rate to 59.87 aircrafts, a gain of only 4 aircrafts. If the designer bases his decision strictly from the view point of acceptance, the addition of a third exit might be difficult to justify. If, however, the percentage of wave offs is considered, the picture is somewhat different. For three exits, the percentage of wave offs is considerably lower than for two exits. This points to the facts that a prime justi-

fication for an additional taxiway may not be to increase the acceptance rate but to decrease wave offs".

3.2 AUTOMATED LANDING, ROLL OUT, AND TURNOFF USING THE MLS AND MAGNETIC CABLE SENSORS

A simulation program, which is proved to be both feasible and practical for commercial type aircraft in the terminal area control, is described in a NASA report (8). The report studies the landing approach, roll out and turnoff of the B 707-100, using the new inertial navigation aids and the present navigation aids in order to: "(1) investigate the compatibility of existing autoland guidance laws utilizing a Microwave Landing System in place of the conventional Instrument Landing System navigation aids during landing approach; and (2) to expand the concept of automated flight to roll out and turnoff for reduced runway occupancy time during normal and adverse landing conditions."

For more accurate results, a magnetic cable is buried in the runway and the aircraft is equipped with three coil magnetic pickups to correct for errors. In addition, a Kalman type filtering and a fixed gain complementary filtering are induced in the model to correct for error sources generated in the simulation run by a computer program called ALERT. The error sources include gyro drift, accelerometer and sensor aid biases, etc....

3.2.1 Description of the Simulation Model

A coordinate transformation of the aircraft is made from the rectangular coordinates to the three-unit-body-axes vectors in terms of the Euler angles of roll, pitch and yaw, from magnetic north, as shown in figures 8, 9 and 10. Then the aircraft forces and moments are calculated using the equations of motion in respect to constant wind, gust and wind shear vectors, and friction and rolling coefficients, during the different phases of landing, roll out and turnoff.

The main forces on the so called aircraft stability axis system (a_1 a_2 a_3) are the lift, the drag and the side forces. The estimated aircraft position in the body and runway frame, called "dread reckoning" are first corrected by the Kalman filter which uses an a-priori statistical technique. Then a second fixed gains complementary filter is applied based on the observation residuals.

3.2.2 Navigation and Kalman Filtering

The aircraft is equipped with a computer which monitors acceleration gyro rates. It is reported that "past experience has shown that the square root implementation of the optimal filter algorithm can reduce the effects of numerical errors to insignificant levels. The square root implementation is therefore incorporated in the proposed design. Modeling errors

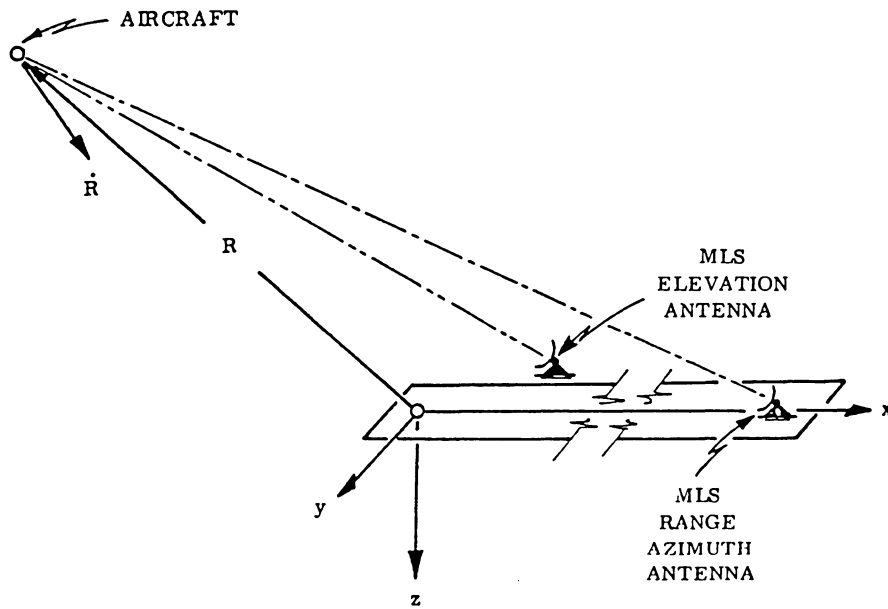


Figure 8. Runway (Inertial) Coordinates and Aircraft Position, Velocity Vectors

(Source: Adapted from Reference 8)

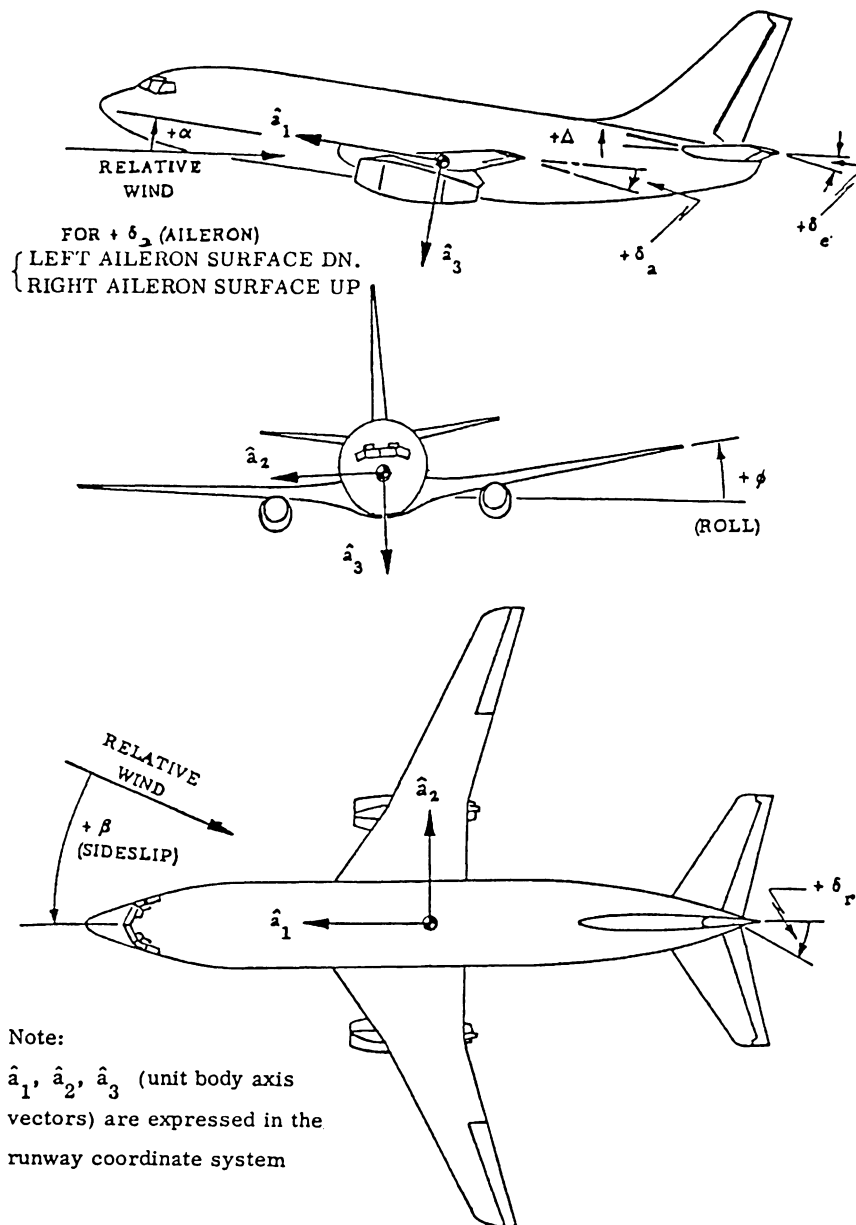


Figure 9. Aircraft Body Coordinate System, Control Surface Deflections, and Aerodynamic Angles

(Source: Adapted from Reference 8)

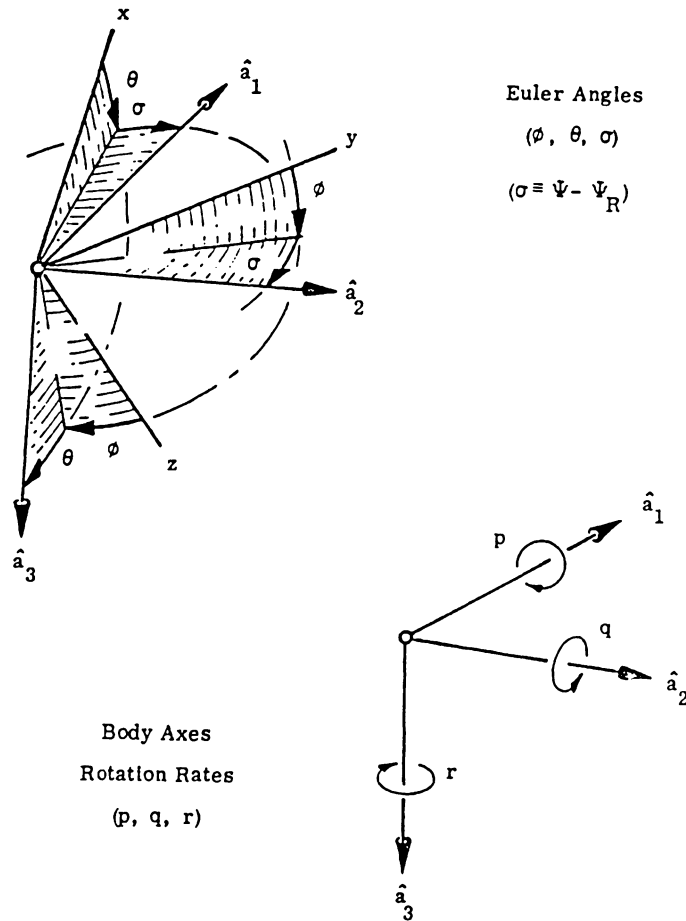


Figure 10. Euler Angles and Rotation Rates Defined

(Source: Adapted from Reference 8)

are compensated for by the appropriate use of random forcing functions. This technique causes the more recent measurements to be weighed higher than past measurements; therefore the estimates tend to follow the more recent measurements."

An error state vector of 15 variables is used. It consists of errors in position, velocity, vertical accelerometer scale factor, horizontal wind, biases in observables and gyro drift rate. The Kalman filter updates are every second for the aircraft coordinates and .05 second for the dead reckoning estimates. The accelerometers and gyros, the observations, and the filter are sampled respectively at rates of 20, 10 and 1 Hz. The error rate is assumed to obey a linear differential equation.

3.2.3 Complementary Filter

It is reported that "A complementary filter can be designed to provide a set of non varying gains, without any relationship to the uncertainty in the aircraft state or the biases in the INS and MLS measurements. By adjusting the complementary filter gains to pass the relative low frequency of the true aircraft acceleration, it is possible to filter out the high frequency noise in the MLS measurements. The main criteria for such a filter is to provide a stable estimator, one that decays disturbances exponentially and let the low frequency motions persist."

It is also noted that "the complementary filter provides no corrections to the errors in the estimates of aircraft altitude due to gyro drift or the position errors due to MLS biases".

3.2.3 Magnetic Leader Cable Sensors

There is a need of a navigation sensor aid to correct for multipath distortion and other biases still present in the MLS, upon touchdown. A single magnetic leader cable is embedded along the runway centerline. Then, a magnetic field is created by a detector to generate voltage. The detector consists of three (3) coils mounted as shown in figure 11. The 3 induced voltages are used to correct the yaw and lateral displacement errors.

Nevertheless, few distortions are still present; but, they remain in a narrow range of plus or minus 2 ft. They are due partly to ground conduction increasing with the presence of steel, and non-linearity.

Such navigational aids as Vortac Range and bearing devices, and a baroaltimeter are used for navigation between way points away from the terminal area. The relatively large bias they produce need only be corrected by a kalman filter for the purpose they fulfill.

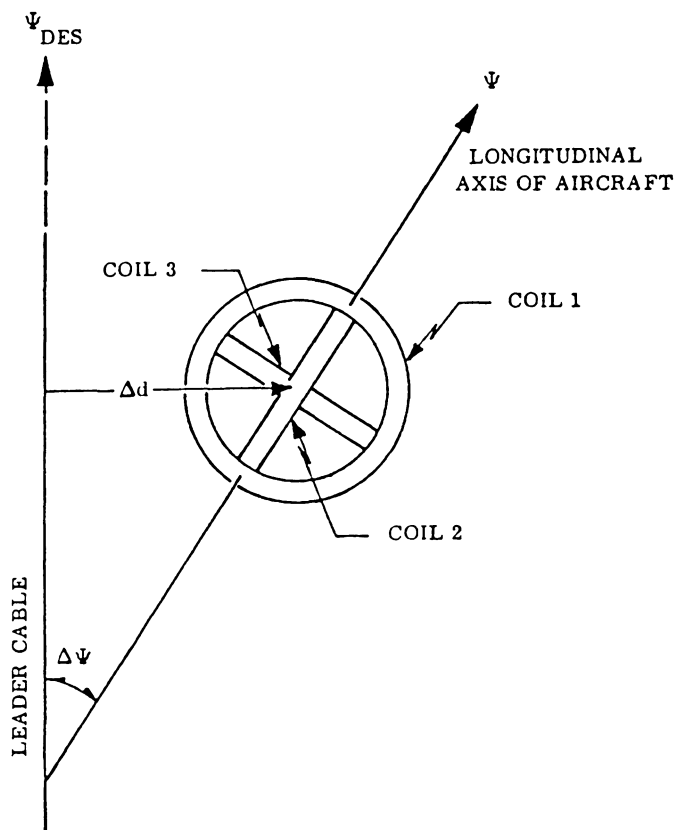


Figure 11. Magnetic Leader Voltage Signals

(Source: Adapted from Reference 8)

3.3 TERMINAL AREA AUTOMATIC NAVIGATION, GUIDANCE, AND CONTROL USING THE

MLS

In an effort to reduce runway occupancy time, an automated uniform braking and reverse thrust guidance policy is modeled for dry and wet runways. Different aids such as the inertial navigation system, the MLS and the buried magnetic cable leader, aircraft sensors, and modern digital computers are used so that landing, roll out and turnoff can be executed more precisely and at a very short period of time.

Under the effects of drag, reverse thrust and braking, the deceleration of an aircraft can be expressed mathematically (12). Closed loop guidance laws for braking and reverse thrust are used as functions of the landing speed, the desired taxi speed and the distance to go. Braking is used as a modulating feedback device in coordination with the reverse thrust to achieve the desired deceleration. The ground rule is "to decelerate mainly with reverse thrust using modulated braking for fine control and using nominal braking only if the maximum specified reverse thrust cannot decelerate the aircraft to the specified exit".

The desired reverse thrust is calculated and additional brake deceleration is computed depending on the runway conditions. Tire skidding is taken into account by brake limitations for wet runway conditions. For dry conditions, braking is limited to prevent excessive tire wear. Hydroplaning is also checked by computing the speed at which it occurs. It is given by the following formula:

$X_h \text{ (knots)} = .9 * \text{tire pressure}$

A steering guidance logic is also incorporated to track the aircraft through straight line segments, circular segments and centered parabolic segments.

However certain types of errors occur. Continuous measurements of acceleration are provided by body mounted accelerometers. These measurements are noisy and are subject to errors (misalignment and scale factor errors). They can be filtered by using methods described earlier.

It is said that "upon touchdown the major error source in the aircraft position is the down range position error due to the MLS range bias which cannot be removed by filtering. The range bias produces errors in the guidance signals which result in large tracking errors during the turn. To eliminate this error source we recommend that the aircraft should receive a short radio blip signal as it passes a known position along the runway during roll out. By correcting the X coordinate to the known runway position, the offset problem disappears and good turnoff may be realized".

During the simulation runs, a sensitivity study of the Langley TCV B 747 aircraft was made by varying numerous factors. It is concluded that "In

general, runway occupancy time can be significantly reduced by use of automated roll out and turnoff capability. The aircraft can be clear of the runway within 20 sec for dry runway and 30 sec for wet runway".

It is recommended that roll out and turnoff guidance laws be investigated to reduce cross track errors due to wind and that "slow in" logic be also investigated to ease the onset of turn acceleration".

3.4 ASSESSMENT OF AN ELECTRONIC COCKPIT AIRFIELD DISPLAY FORMAT FOR AUTOMATED RUNWAY EXITS

Experiments have been made to monitor the automatic landing, roll out and turnoff, and to track an aircraft along an exit path. The experiments consist of a real time flight simulation displaying the aircraft dynamic characteristics in the system, in the cockpit.

It is said that (11) "considerable research and development have brought electronic type air navigational display concepts to applications (DC 9-80, 1011, B 757 aircrafts), but the Category 3 (c) (zero ceiling, zero runway visual range) landing and exit capability has yet to be put into practice".

The Automatic Microwave Landing System/Guidewire System provides the aircraft coordinates and it is displayed in the aircraft cockpit the Automatic Turnoff Predictor (ATP), the Critical Distance Predictor (CDP) and the Breaking Distance Predictor (BDP).

As their names indicate, the CDP is the critical point on the runway where the aircraft should be to reach a given velocity at exit, at maximum deceleration rate. It is noted that maximum deceleration is federally certified on the basis of wheel braking, only. The BDP projects the point in the runway where the exit velocity will be achieved if the braking rate is fixed. The ATP assigns the pilot an exit number.

Displaying all these informations in the dynamic electronic cockpit allows the pilot to read the data provided and to take his own decision after correcting for weather conditions. This illustrates the independence of the display logic. During the observations, the ATP was unavailable to the pilots. The procedure provided an adequate validation of the model.

Reliability of the design could be expressed in the following terms: "the assessment process was primarily qualitative based on the credibility which the pilots found in the displayed information and confidence that the displays communicated navigation information useful for zero visibility runway maneuvers".

Two basic test plans were used: the Chronodrasic Aided Limit Turn Vector Display (LTVD) and the Spatiumdrasic Aided Display. The Chronodrasic display provides the pilot with a matrix of exit conditions depending on the exit velocity; whereas the Spatiumdrasic display used the Glide Path Intercept Points. The Boeing Chronodrasic Monitor uses a proprietary time critical algorithm. Zero time is indicated on a clock device when the

required exit velocity cannot be reached and the aircraft has to take another exit. The Spatiumdrasic Monitor uses a distance critical algorithm. The critical distance concept takes into account the Limit Turn Vector Display.

Reliability of the system was measured by the prediction success rate and the relative pilot confidence number. Four research pilots were selected to fly the Terminal Configured Vehicle (TCV) flight simulator. These tests were said to be feasible and encouraging as noted in the concluding remarks "Real time flight simulation tests of landing, deceleration , turnoff, and exiting taxi maneuvers in zero visibility conditions have demonstrated the feasibility of cockpit CRT type displays as monitors for automatic ground navigation systems. Automatic ground guidance and control algorithms, displayed runway surfaces, ground navigation and maneuvering information, and critical decision making features were integrated into a comprehensible cockpit display format which resulted in significantly encouraging research pilot's confidence in zero visibility ground operations. The Limit Turn Vector Concept was found effective for monitoring turns and the distance-referenced turnoff prediction symbology was favored by the research pilots over the time-referenced format. Further ground navigation displays testing is required in order to obtain additional piloting experience with the formatting under all surface conditions and to assess display effectiveness during manual reversions".

Other aiding symbologies such as braking status and digital display of ground speed, planned exit velocity and map scale are incorporated in the simulation model.

3.5 ASSESSMENT OF HIGH SPEED RUNWAY EXIT MANEUVER SMOOTHNESS

Ernest W. Millen (9) researching on the Assessment of High Speed Runway Exit Maneuver Smoothness stated that "the study showed that the use of large, constant radii entrance curves need not be constrained by a rapid onset of lateral acceleration at high speeds; however, maneuver smoothness could be improved by the use of non-circular, hyperbolic-type exit paths. The test data also validated an extrapolation of the Horenjeff minimum permissible radii-criteria for narrow-body, transport-type aircraft on ungrooved, dry pavement".

The approach consists of investigating the increase of exit velocities instead of optimizing the braking capabilities of the aircraft which would result in the drastic increase of the maintenance cost of the air carrier fleet. However concern must be given to the effect of adverse surface responses and smoothness of turning maneuvers. An indication of the smoothness of a turning maneuver is achieved by measuring the intensity of both lateral acceleration and lateral jerk, and by counting the number of jerks.

Lateral acceleration is a function of the mass, ground speed and turn radius of the aircraft. It also varies along the exit path profile from

zero to some value. Jerk is a product of the rate of change of lateral acceleration through onset as perceived by the aircraft passengers.

Field tests were made using the Transport Systems Research Vehicle (TSRV), a narrow-body jet type transport. It is a sophisticated aircraft equipped with electronic devices and operating at exit speeds ranging from 30 to 90 knots. A real time flight simulator was also used. Even though early studies have been made on assessing passenger comfort in the field of rail and road transportation since the 1960's, there is much to be done about an aircraft using a high speed runway exit. Lateral jerks are reported to be perceptible at 0.03 g/sec and comfortable up to .07 g/sec by approximately 90 percent of train passengers. Acceptable longitudinal jerks caused by normal braking reach the value of 0.3 g/sec for train passengers facing forward or backward, while emergency braking jerks extend the acceptable level to 3.-4. g/sec.

Only one researcher, Hirshfeld, documented empirical data relating human responses to combined acceleration and jerk values. The scale was called an "Index of Disturbance". He acknowledged that "although the work was based upon a particular position, he felt that it would apply to other positions as well".

No experimental lateral jerk data were found in the extensive aeronautical literature reviewed. The following algorithm derived from rail transportation is proposed:

$$G/G_{\max} + J/J_{\max} = 1, \text{ where}$$

- G = lateral acceleration
- G_{\max} = maximal permissible G value (.12g)
- J = lateral jerk
- J_{\max} = maximum permissible J value (.055g/sec)

3.6 LANDING GEAR FRICTION CHARACTERISTICS

The decelerative forces normally developed on the aircraft during landing, roll out and turnoff are generated from reverse thrust, drag and wheel brakes. As shown in figure 12, the major force is from the application of brakes. At speeds above 80 knots, aerodynamic drag and reverse thrust play an important role.

But with the introduction of modern aircrafts, an autobraking system is made available by the use of avionics equipment. This system provides a constant deceleration rate by using different combinations of the decelerative forces. However a conservative deceleration rate was used (5) to determine the optimal exit locations.

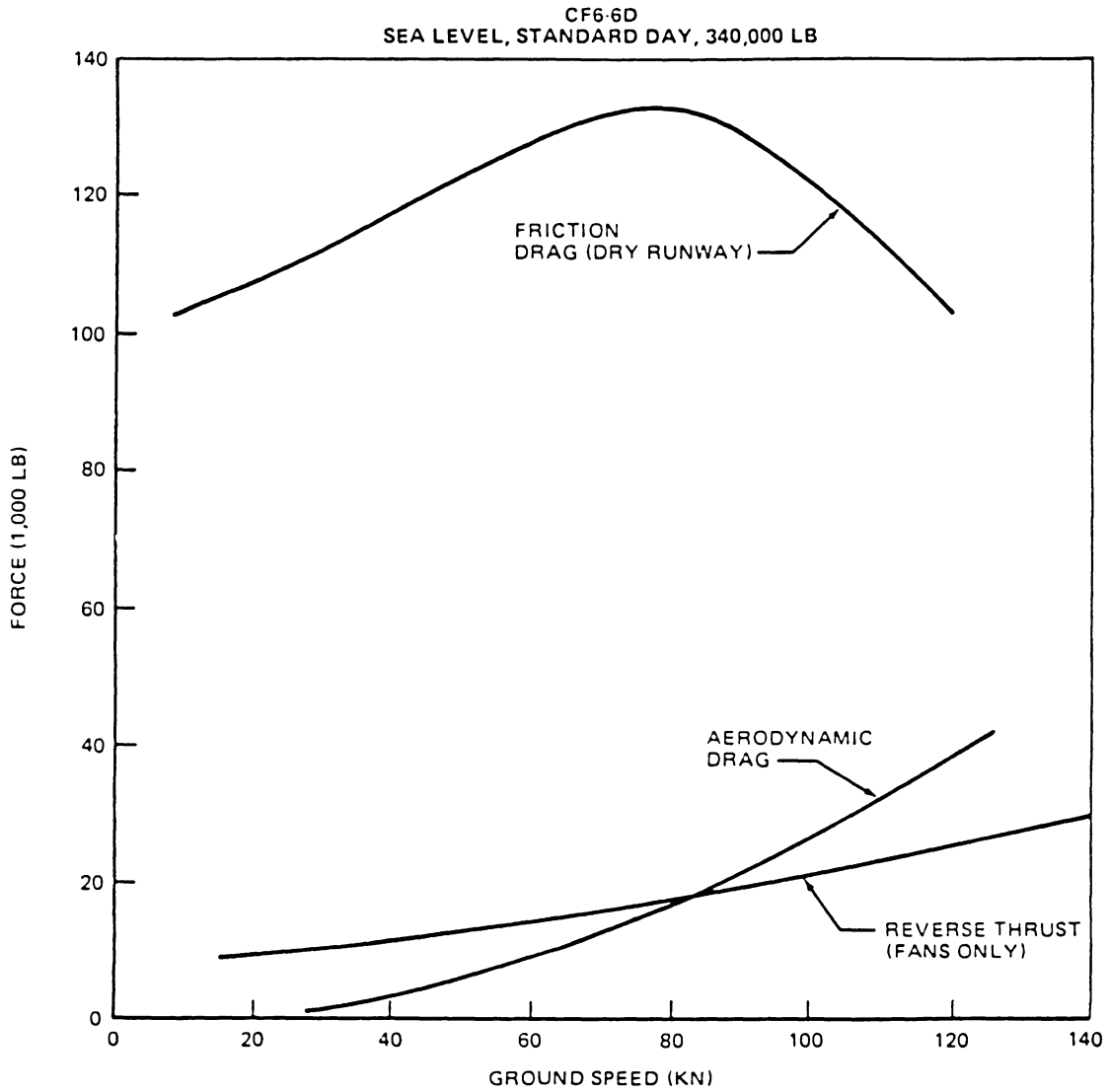


Figure 12. Summary of Airplane Forces during Landing Ground Run-
Model DC 10 Series 10

(Source: Adapted from Reference 5)

It has been shown from an Aircraft Accident Report (13) that: "optimum braking force is achieved when the aircraft's wheels are rotating at a speed about 8 to 10 percent slower than a free wheeling tire would rotate"; and that "after the airplane lands, however, the aerodynamic surfaces continue to produce some lift, which balances a percentage of the weight and thus reduces the braking force. The extension of ground spoilers, the application of reverse thrust, and subsequent deceleration of the airplane will reduce the lift and increase the effective weight of the airplane acting through the tire to the runway thus increasing the braking force which can be generated etc.... The runway coefficient of friction and thus the braking coefficient which an airplane can develop after landing are significantly reduced if the runway surface is covered with standing water, snow, ice or any combination of such contaminants".

As the stability of the aircraft during touchdown and roll out can be expressed by the ratio: side load on nose gear/vertical load on nose gear, called its Cng, a comparison to the available ground coefficients of friction leaves the pilot with a margin of 2 against skidding on wet surface and a margin of 4 against skidding on dry surface (5).

It is also noted that "low weight and aft center of gravity are the most critical. Aft center of gravity results in the least weight to the nose gear. Both rotational inertia and main gear turning resistance remain fairly high at low weight".

3.7 BRAKING OF AN AIRCRAFT TIRE ON GROOVED AND POROUS ASPHALTIC CONCRETE AND ON PORTLAND CONCRETE CEMENT

Concern should be given to the danger of hydroplaning, which increases at high speed, particularly at touchdown, on a water covered runway. Dynamic and viscous hydroplaning are predominant at the tire-runway interface in the presence of water. Different techniques are used to relieve the fluid viscous pressures in both cases. One efficient solution lies in using transverse runway grooving and micro textural aggregates. Figure 13 shows the effects on tire wear and braking performance for different runway conditions.

A series of tests have been conducted to show the effects of the surface treatment on the braking performance of an aircraft tire (14). It is proved in a two phase experimental program over a speed range from 70 to 150 knots, that in a portland cement concrete surface, "the conventional saw-cut grooves spaced at 3 inches or less will provide "acceptable braking performance" to an aircraft tire on water covered runways, and the installation cost of the 3 inch spaced grooves could be 25 percent less than that of the installation cost of grooves spaced at 1 1/4 inch. The results further showed that the reflex-percussive grooves, an alternative to conventional saw cut grooves, provided sufficient braking to allow an aircraft to stop without experiencing hydroplaning".

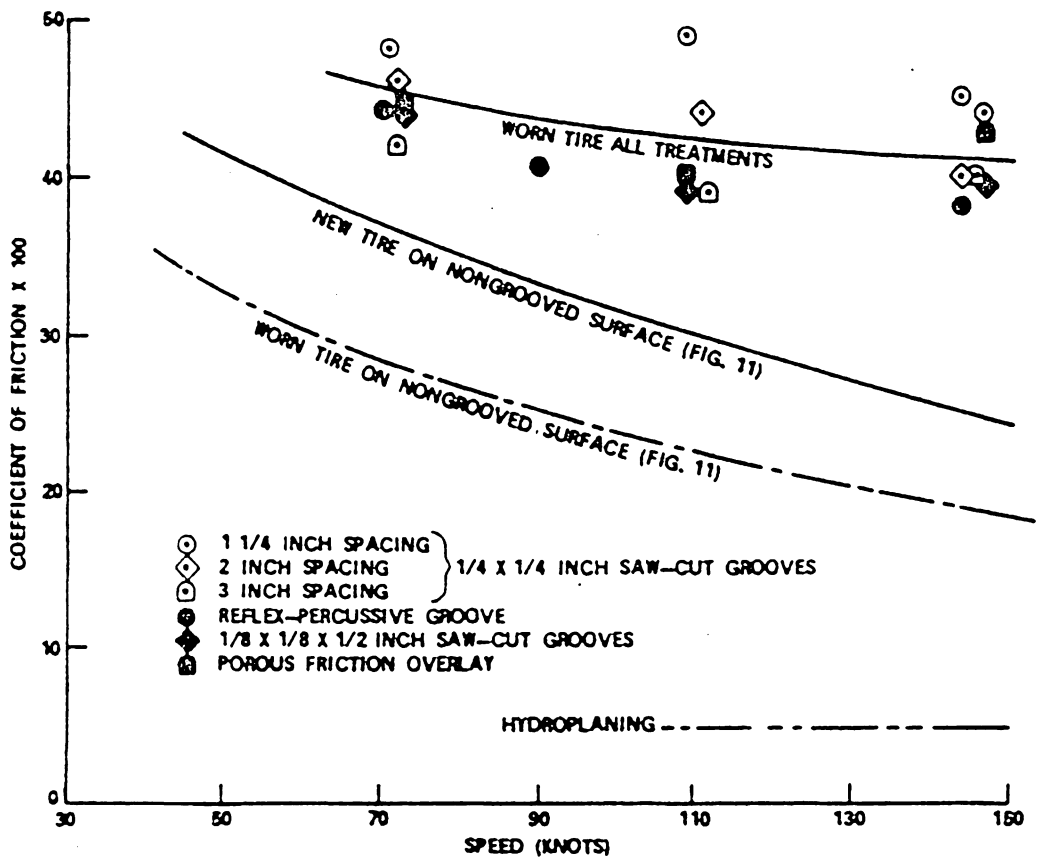


Figure 13. Braking Performance of a Worn Tire on Wet Surface
 (Source: Adapted from Reference 14)

On the other hand, on asphaltic concrete surfaces, it was showed that: "the reflex-percussive grooves, the porous friction overlay and the conventional saw grooves spaced at 3 inches perform comparably. The closely spaced conventional saw-cut grooves are desirable where the seasonal and topographical conditions consistently produce "puddled" water conditions on the runways. The "puddled" conditions represent average water depth of approximately 0.10 inch".

3.8 TAXIWAY GUIDANCE AND CONTROL SYSTEM

Confusion is of primary concern if a certain degree of reliability is to be achieved during the process of exiting. The problem becomes more acute when poor visibility conditions prevail. A state-of-the-art (15) Survey has focused in that and has reached the same conclusions of the Visual Aids Panel, in 1966. It is recommended that green exit lights be used along the runway centerline as it was first introduced in the Gatwick Airport of London in the late 1950's. The recommendations also included a 50 foot spacing for simulated visibilities of 200 feet and more.

The guidance element should provide information which enables the pilot to expeditiously exit the runway. He should also be directed by the air traffic controllers to follow a designated route by visual means, without using oral instructions transmitted by radio.

The need of such warnings was demonstrated by some flight tests in fog an was expressed by Charles A. Douglas (15): "As a result of the problems

encountered during flight tests conducted in visibilities as low as 300 ft, the Landing Aids Experiments Station recommended that "taxiway markings be devised and standardized to give a prewarning of turns and intersections".

The research recommended also that "the type L-829 designed for use both as directional signs and as intersection locators..., were required to be at least at a distance of 500 ft. However, these signs are so large that they cannot be placed sufficiently close to the runway edge to serve as exit locators".

CHAPTER 4 PROBABILISTIC COMPUTER MODEL OF OPTIMAL RUNWAY TURNOFFS

In the attempt to reduce runway occupancy time for landing aircrafts, NASA/Langley conducted a contract with MC Donnel Douglas Corporation (5). A goal was set for the purpose of optimizing a high speed turnoff under the constraints of time and reliability allowing a maximum occupancy time of 40 seconds and a reliability of one miss for 10000 landing aircrafts. A model has been developed and is comprised of two parts: (1) a main program defining an optimal exit location, an exit speed and a probability of making such an exit; (2) a subroutine tracking the aircraft along an optimized compound-curve exit path.

The model contributes in increasing capacity. FAA regulations prohibit that an aircraft be allowed to operate on the runway when it is occupied by a landing aircraft. A good parameter of the runway occupancy time and its related standard deviation provides the best tool to the air traffic controllers to schedule aircraft spacing in the terminal airspace.

Therefore, a maximum runway occupancy time is preferred to an average runway occupancy time due to variations. Compared to the present day situation of 40 to 50 landings per hour, the application of the model, allowing 90 landings per hour, represents a very substantial increase of 80 percent in landing capabilities.

4.1 DESCRIPTION OF THE MODEL

4.1.1 Main program

After reading the data input, the program computes sequentially, the following:

- distances A and B
- speeds during landing at B and C
- standard deviations of the speeds at A, B and C
- occupancy times at A, B and C
- distances A, B and C for aircraft travelling one standard deviation below the average
- speeds at A, B and C for aircraft travelling one standard deviation below the average
- occupancy time at A, B and C for aircraft travelling one standard deviation below average
- specification of arbitrary speed range

- probability associated with speed range
- discrete intervals of speed range
- probability of exiting
- discrete probability and cumulative probability
- minimum occupancy time
- initialization of arbitrary occupancy time
- Z values of occupancy time (Normal distribution assumed)
- interval midpoints
- discrete probability and cumulative probability
- average runway occupancy time
- average runway occupancy time + 3 times its standard deviation
- percent aircraft exiting
- average speed at exit

4.1.2 Subroutine Expath

It tracks the aircraft from the beginning of the turn to the clearing of the runway, based upon the speed at exit calculated by the main program and the Path data. It performs the following steps:

- computation of X and Y coordinates of the aircraft at 1/1000 seconds along an optimized exit path, the shortest path with which sliding doesn't occur
- checking for the aircraft performance limits
- time at which the aircraft clears the runway edge after exiting

A flowchart of the probabilistic model is shown in table 4.

Table 4. Flowchart-probabilistic runway turnoff model

(Source: Adapted from Reference 5)

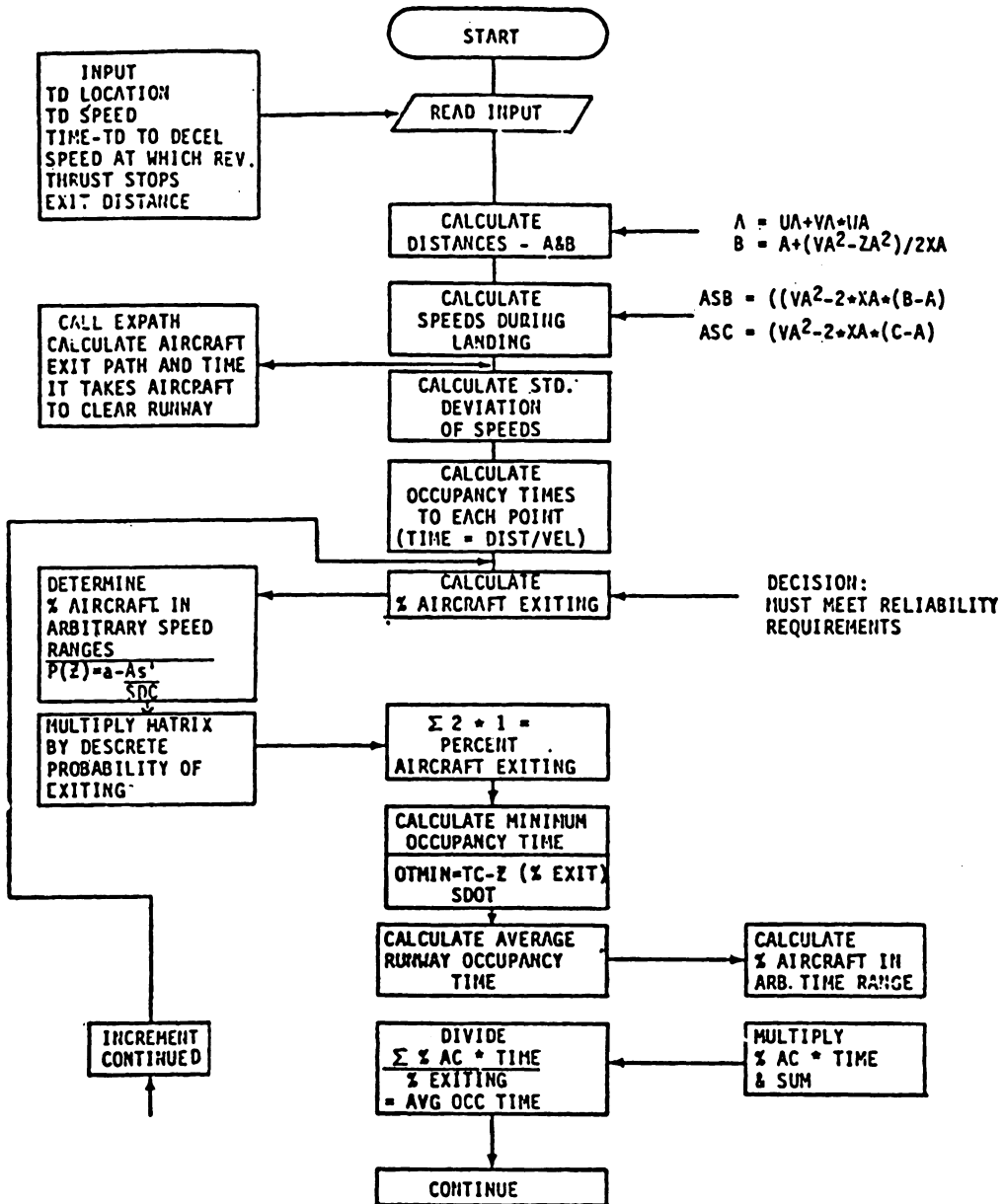


Table 4. (continued)

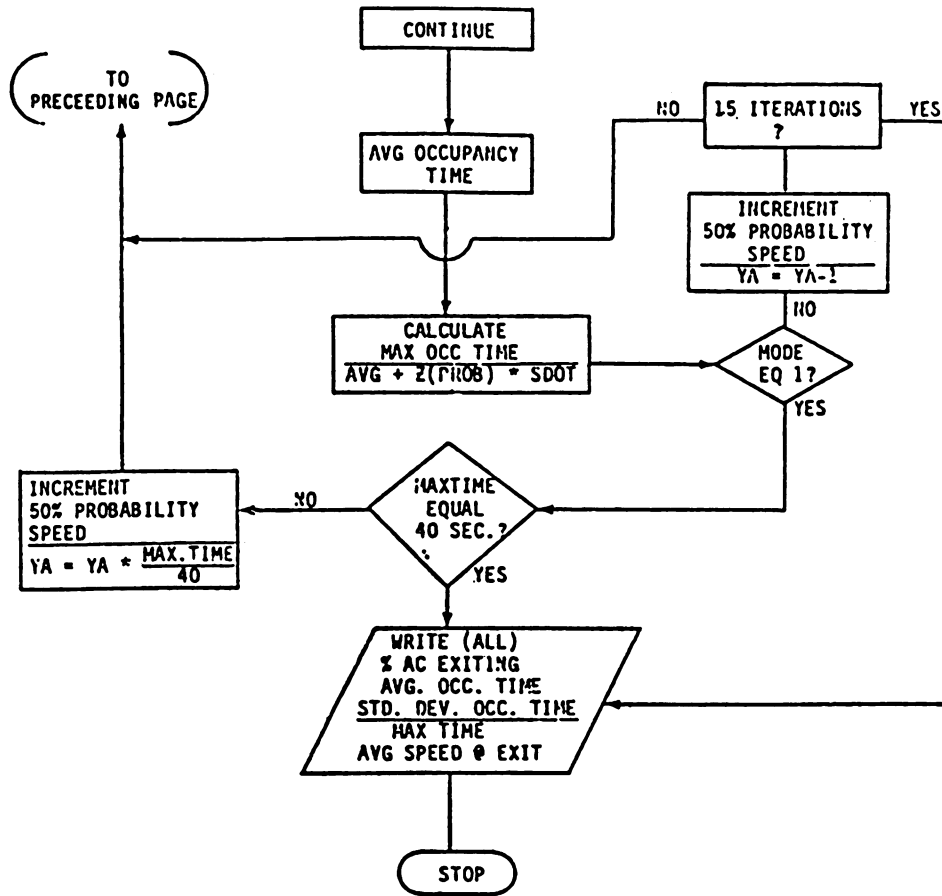
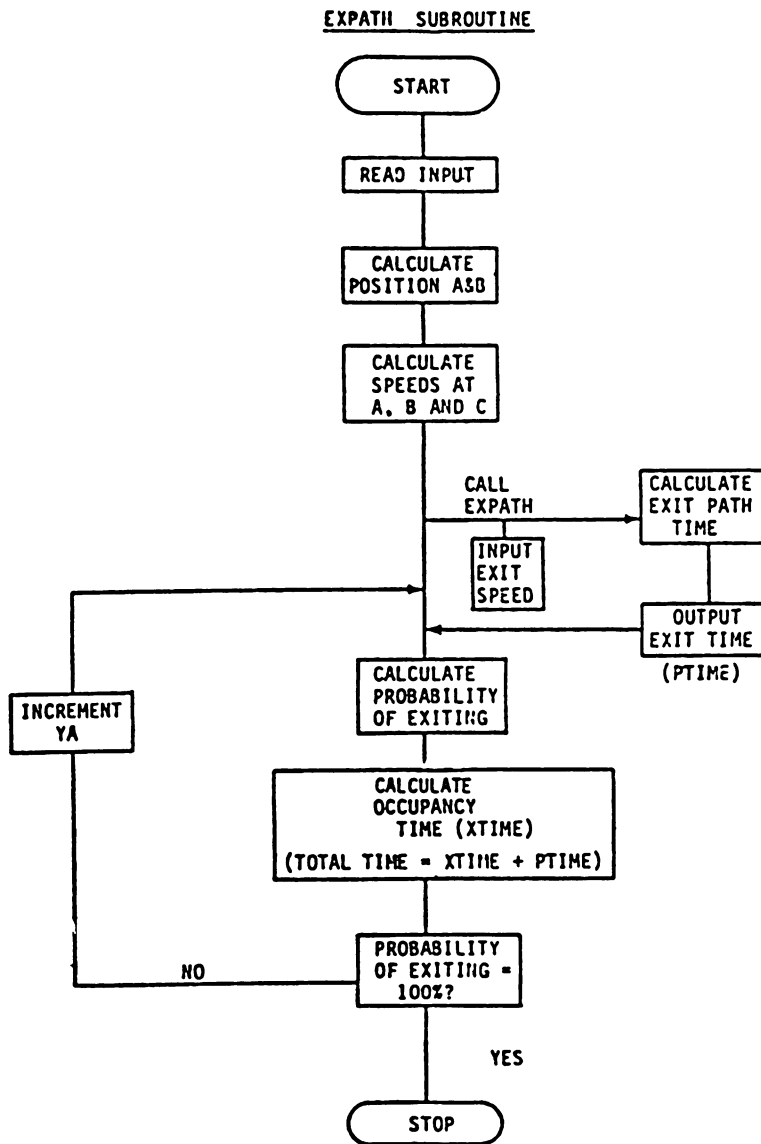


Table 4. (continued)



4.2.1 Mode 1

Initially, the Mode 1 process was used to solve for the maximum 40 seconds occupancy time. The process is iterated until the total runway occupancy is equal to 40 seconds. YA, the 50 percentile exit speed distribution is prorated using the following formula:

$$YA = YA * MAX.TIME/40$$

But this is a very long process, leaving no control in the desired speed range.

4.2.2 Mode 2

Mode 2 has been added to the model to allow the user to choose his speed values over a range which goes from YA to YA minus 14. It is faster than mode 1.

4.2.3 Mode 3

This mode also allows the user to choose its own speed value. After each YA entry and a complete run, the user is asked a new YA value until he is satisfied with the exiting probability. Because Mode 3 is the fastest of all and it allows to test the model's sensitivity more easily, it will be referred to.

4.3 DATA FILE

Use of the model requires data files for both the main program and the subroutine.

4.3.1 Main Program

4.3.1.1 High Speed Exit Data or Hispex Data

Hispex data is a collection of data related to the landing characteristics and their corresponding standard deviations. They are:

- UA (ft) : touchdown location, from threshold
- US (ft) : standard deviation of UA
- VA (ft/sec) : the aircraft speed at touchdown
- VS (ft/sec) : standard deviation of VA
- WA (sec) : time from touchdown to start of deceleration before exit
- WS (sec) : standard deviation of WA
- XA (ft/sec**2) : deceleration rate or rate of change of aircraft speed before exit

- XS (ft/sec**2) : standard deviation of XA
- YS (ft/sec) : standard deviation of YA, 50-percentile cumulative normal distribution of speeds at exit entrance
- CDIST (ft) : exit location,distance from threshold to exit entrance
- ZA (ft) : speed at which reverse thrust is shut off
- NTIP (ft) : distance from aircraft nose to wingtip

The high speed exit (Hisplex) data are shown in the following table 5.

Table 5. Hispex Data

(Source: Adapted from Reference 5&6)

GENERIC AIRCRAFT						
UA	US	VA	VS	WA	WS	
XA	XS	YS	C	ZA	NT	
GENERIC AIRCRAFT AS						
500.	10.	66.	5.	3.	1.	
2.5	1.	1.		.55.	39.	
GENERIC AIRCRAFT AF						
500.	10.	118.	5.	3.	1.	
2.5	1.	1.		.55.	40.	
GENERIC AIRCRAFT BS						
1000.	20.	110.	10.	4.	1.	
4.	.5	1.		.90.	34.	
GENERIC AIRCRAFT BF						
1000.	20.	164.	10.	4.	1.	
4.	.5	1.		.155.	56.	
GENERIC AIRCRAFT CS						
1500.	30.	181.	10.	5.	1.	
5.	.5	1.		.155.	48.	
GENERIC AIRCRAFT CF						
1500.	30.	230.	10.	5.	1.	
5.	.5	1.		.175.	103.	
GENERIC AIRCRAFT DS						
1500.	30.	211.	15.	5.	1.	
5.	.5	1.		.175.	87.	
GENERIC AIRCRAFT DF						
1500.	30.	260.	15.	5.	1.	
5.	.5	1.		.225.	150.	
GENERIC AIRCRAFT WIDE BODY						
1500.	30.	230.	10.	5.	1.	
5.	1.	1.		.190.	130.	
TERPS CATEGORY E-LOCKHEED F-104						
1500.	30.	370.	25.	5.	1.	
6.	2.	1.		.150.	35	

4.3.1.2 SND Data

SND data is a standard table of the Normal distribution and is shown in table 6.

Fig 14 shows a schematic diagram of the runway operations, where

- A : distance from threshold where deceleration starts
- B : distance from threshold where reverse thrust stops
- C : distance from threshold to exit entrance

4.3.2 Subroutine Expath

Besides the exit speed given by the probabilistic model, it is required a set of data called Path data. They are:

- aircraft weight(lbs) : landing critical weight
- yaw inertia (slug-ft**2) : resistance to movement
- wheel base (ft) : distance from nose gear to main gear

Table 6. Standard Normal Table

(Source: Adapted from Reference 5)

.0000	.0040	.0080	.0120	.0160	.0199	.0239	.0279	.0319	.0359
.0398	.0438	.0478	.0517	.0557	.0596	.0636	.0675	.0714	.0753
.0793	.0832	.0871	.0910	.0948	.0987	.1026	.1064	.1103	.1141
.1179	.1217	.1255	.1293	.1331	.1368	.1406	.1443	.1480	.1517
.1554	.1591	.1628	.1664	.1700	.1736	.1772	.1808	.1844	.1879
.1915	.1950	.1985	.2019	.2054	.2088	.2123	.2157	.2190	.2224
.2257	.2291	.2324	.2357	.2389	.2422	.2454	.2486	.2517	.2549
.2580	.2611	.2642	.2673	.2704	.2734	.2764	.2794	.2823	.2852
.2881	.2910	.2939	.2967	.2995	.3023	.3051	.3078	.3106	.3133
.3159	.3186	.3212	.3238	.3264	.3289	.3315	.3340	.3365	.3389
.3413	.3438	.3461	.3485	.3508	.3531	.3554	.3577	.3599	.3621
.3643	.3665	.3686	.3708	.3729	.3749	.3770	.3790	.3810	.3830
.3849	.3869	.3888	.3907	.3925	.3944	.3962	.3980	.3997	.4015
.4032	.4049	.4066	.4082	.4099	.4115	.4131	.4147	.4162	.4177
.4192	.4207	.4222	.4236	.4251	.4265	.4279	.4292	.4306	.4319
.4332	.4345	.4357	.4370	.4382	.4394	.4406	.4418	.4429	.4441
.4452	.4463	.4474	.4484	.4495	.4505	.4515	.4525	.4535	.4545
.4554	.4564	.4573	.4582	.4591	.4599	.4608	.4616	.4625	.4633
.4641	.4649	.4656	.4664	.4671	.4678	.4686	.4693	.4699	.4706
.4713	.4719	.4726	.4732	.4738	.4744	.4750	.4756	.4761	.4767
.4772	.4778	.4783	.4788	.4793	.4798	.4803	.4808	.4812	.4817
.4821	.4826	.4830	.4834	.4838	.4842	.4846	.4850	.4854	.4857
.4861	.4864	.4868	.4871	.4875	.4878	.4881	.4884	.4887	.4890
.4893	.4896	.4898	.4901	.4904	.4906	.4909	.4911	.4913	.4916
.4918	.4920	.4922	.4925	.4927	.4929	.4931	.4932	.4934	.4936
.4938	.4940	.4941	.4943	.4945	.4946	.4948	.4949	.4951	.4952
.4953	.4955	.4956	.4957	.4959	.4960	.4961	.4962	.4963	.4964
.4965	.4966	.4967	.4968	.4969	.4970	.4971	.4972	.4973	.4974
.4974	.4975	.4976	.4977	.4977	.4978	.4979	.4979	.4980	.4981
.4981	.4982	.4982	.4983	.4984	.4984	.4985	.4985	.4986	.4986
.4987	.4987	.4987	.4988	.4988	.4989	.4989	.4989	.4990	.4990
.4990	.4991	.4991	.4991	.4992	.4992	.4992	.4992	.4993	.4993
.4993	.4993	.4994	.4994	.4994	.4994	.4994	.4995	.4995	.4995
.4995	.4995	.4995	.4996	.4996	.4996	.4996	.4996	.4996	.4997
.4997	.4997	.4997	.4997	.4997	.4997	.4997	.4997	.4997	.4998
.4998	.4998	.4998	.4998	.4998	.4998	.4998	.4998	.4998	.4998
.4998	.4998	.4999	.4999	.4999	.4999	.4999	.4999	.4999	.4999
.4999	.4999	.4999	.4999	.4999	.4999	.4999	.4999	.4999	.4999
.4999	.4999	.4999	.4999	.4999	.4999	.4999	.4999	.4999	.4999
.5000	.5000	.5000	.5000	.5000	.5000	.5000	.5000	.5000	.5000

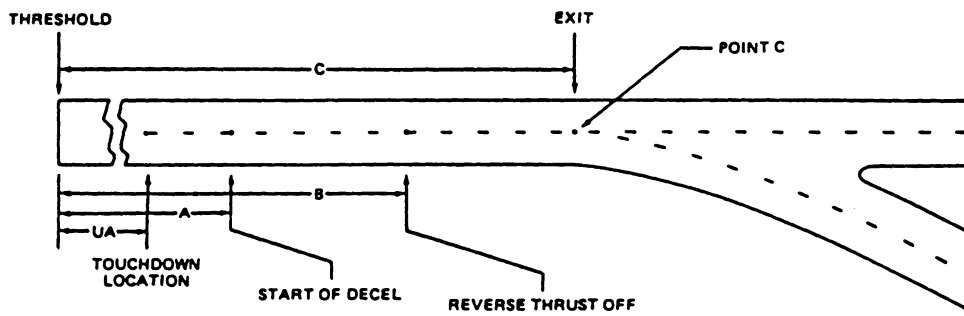


Figure 14. Runway Operations

(Source: Adapted from Reference 5)

- percent weight on main gear
- $Y_{mu \max}$: measure of maximum resistance offered by nose gear
- $\theta \max$ (deg) : the angle formed by the longitudinal axis of the aircraft and an imaginary line joining the edges of the wingtip and the stabilizer, as shown in figure 15
- deceleration rate (ft/sec**2) : rate of change of aircraft speed from the start of exit
- runway width (ft) : width of runway surface
- wingspan (ft) : distance between the wingtips
- distance to taxiway (ft) : distance between the centerlines of the and a parallel taxiway
- $Y_{mu \text{ scrub}}$ and radius (ft) : these values refer to the scrubbing characteristics of the aircraft on curves, as shown in fig 16

The data input or path data are shown in table 7

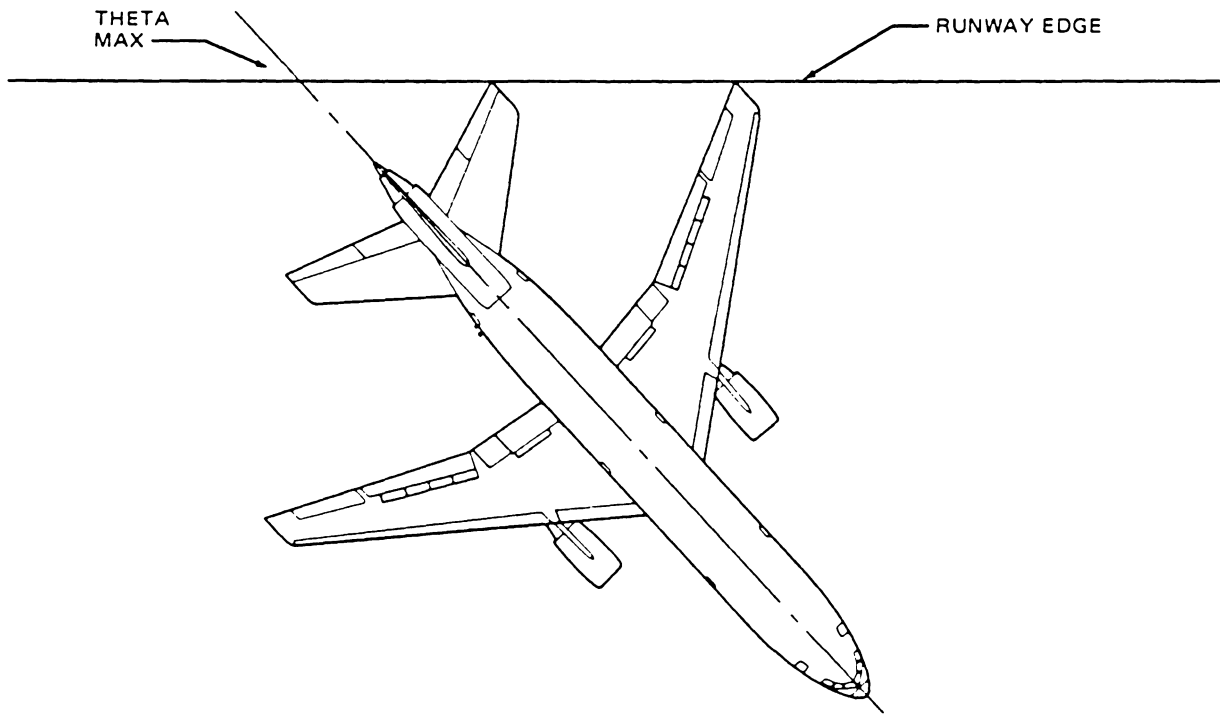


Figure 15. Theta max

(Source: Adapted from Reference 5)

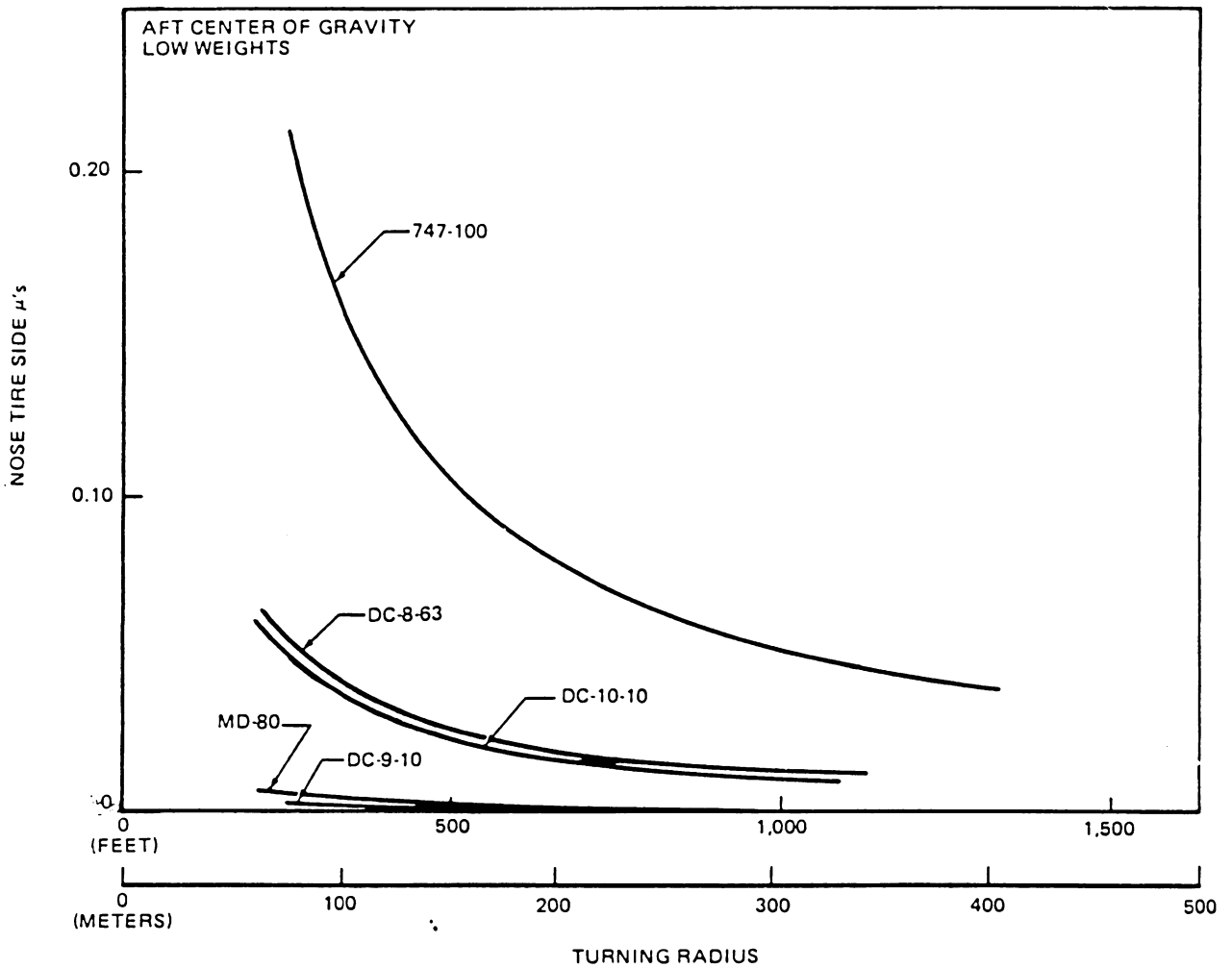


Figure 16. Ymu scrub and radius

(Source: Adapted from Reference 5)

Table 7. Path Data

(Source: Adapted from Reference 6)

A/C Weight	Yaw Inertia	Wheel Base	% Weight on Main Gear
Theta Max	YMU	Deceleration	
R/W Width	Wingspan	Dist to T/W	
YMU Scrub(1)	Raduis(1)		
YMU Scrub(N)	Raduis(N)		

GENERIC AIRCRAFT AS

2040.	2310.	5.3	72.
90.	.25	-1.5	
150.	32.	600.	
.00	1.0 E+31		
.02	50.		

Generic Aircraft AF

24000.	300000.	23.	93.
41.	.25	-2.	
150.	42.	600.	
.00	1.0 E+31		
.02	50.		

GENERIC AIRCRAFT BS

24000.	300000.	23.	93.
38.	.25	-1.5	
150.	36.	600.	
.00	1.0 E+31		
.023	50.		

GENERIC AIRCRAFT BF

48000.	800000.	36.	95.
38.	.25	-1.5	
150.	49.	600.	
.00	1.0 E+31		
.023	50.		

GENERIC AIRCRAFT CS

48000.	800000.	36.	95.
33.	.25	-1.75	
150.	85.	600.	
.00	1.0 E+31		
.025	50.		

GENERIC AIRCRAFT CF

120000.	4.2E+6	61.	95.
39.	.25	-1.75	
150.	141.	600.	
.00	1.0 E+31		
.025	50.		

Table 7. (continued)

GENERIC AIRCRAFT DS			
120000.	4.2E+6	61.	95.
37.	.25	-1.75	
150.	87.	600.	
.000	1.0 E+31		
.01	5000.		
.012	2000.		
.018	1000.		
.023	500.		
.03	50.		
GENERIC AIRCRAFT DF			
400000.	40.0E+6	84.	96.
45.	.25	-1.75	
150.	207.	600.	
.000	1.0 E+31		
.01	5287.		
.019	2638.		
.039	1318.		
.059	877.		
.079	657.		
.099	534.		
WIDE BODY AIRCRAFT			
564000.	42000000.	84.	96.4
45.	0.2	-2.	
150.	195.7	600.	
0.00	1.0 E+31		
0.01	5287.		
0.019	2638.		
0.039	1318.		
0.059	877.		
0.079	657.		
0.099	524.		
.153	347.		
.212	257.		
.353	167.		
.548	121.		
.793	99.		
LOCKHEED F 104			
22000.	137776.	15.0	92.3
20.	.2	-2.	
150.	21.9	600.	
.00	.1 E+32		
.02	50.		

4.4 TECHNICAL APPROACH AND ASSUMPTIONS

Practical utilization of the model required a categorization of the aircrafts to cover a wide range of weight and speed, a runway clearance algorithm, the use of realistic aircraft characteristics, a lateral ride-comfort algorithm and some assumptions. The concepts of reliability and runway occupancy time are defined.

4.4.1 Reliability

Along with the efforts of reducing runway occupancy time, reliability is a major factor. Reliability can be expressed in terms of probability. A goal of one miss for every 10000 turnoffs or a reliability of 99.99 percent seems very appropriate compared to the present level experienced in major airports, as shown in table 8.

4.4.2 Runway Occupancy Time

Runway occupancy time is defined as the average occupancy plus 3 standard deviations. Its maximum has been set at 40 seconds, which corresponds to 90 landings per hour. It is the time elapsed from the threshold until the aircraft has cleared the runway. It is also the summation of times calculated in the two (2) parts of the probabilistic model.

Table 8. Reliability of runway operations

(Source: Adapted from Reference 5)

Number of Weekly landing per runway	Probability of one missed per week per landing	Number of STD from the mean	Example airport experiencing this activity per R/W
1200	.00083	3.15	LAX
1700	.00059	3.23	La Guardia
4000	.00025	3.45	N/A
5000	.0002	3.75	N/A
10000*	.0001	3.9	GOAL

* not weekly

4.4.3 Categorization of aircrafts

A variety of aircrafts operate in an airport environment, from the general aviation type to the wide body jet transport. Such characteristics as an aircraft mass and its dimensions, or its cornering limits play a very important role in the design of an airport in general, and the design of a high speed exit in particular. In order to bracket the high speed turnoff performance variability that could occur in a given category, two generic aircrafts are defined in each category. The categorization of aircraft is influenced by the wide range of approach speeds and aircraft weights. The four TERPS Categories are used (6) "since the cornering characteristic is a strong function of mass, the selection of aircraft categories for the study was influenced by the obsolete TERPS document rather than by the current revision which classifies on the basis of approach speed, only".

TERPS stands for the U.S. Standards For Terminal Instrument Procedures (7). Its article 212 related to approach categories stipulates that "Aircraft performance differences have an effect on the airspace and visibility needed to perform certain maneuvers. Because of the differences, aircraft manufacturer/operational directives assign an alphabetical category to each aircraft so that the appropriate obstacle clearance areas and landing and departure minimums can be established in accordance with the criteria in this manual. The categories (CAT) used and referenced through this manual are: CAT A, B, C, D and/or E. Aircraft categories are defined in Federal Aviation Regulations (FAR) Part 97".

Thus, the maximum landing weight is varied from 2040 to 400000 lbs and the touchdown speed ranges from 66 to 260 ft/sec (5). In addition the Boeing 747 and the Lockheed F 104 have been included in the research to reach a maximum landing weight and a touchdown speed as high as, respectively, 564000 lbs and 370 ft/sec (5). The F104 is classified in the category E.

4.4.4 Runway Clearance Algorithm

High speed turnoffs are assumed so that the runway clearance is a function of the wingtip length and theta max. At low ground speeds, the wingtip may not be critical. This happens when the aircraft tail is the last part to clear the edge of the runway. The model checks whether the heading change, theta angle, is greater than the maximum angle, theta max. If so, the program stops running.

4.4.5 Lateral Ride Comfort

Lateral acceleration and jerk, in consideration of ride comfort, are included in the expath subroutine. However, they are ignored in the computations because the optimal values are set equal to infinity. The algorithm assumed that the two parameters are related by the following formula:

$$G/GMAX + J/JMAX = 1$$

The lateral ride comfort is discussed in an earlier chapter.

4.4.6 Assumptions

- arrival separations and runway occupancy times are mutually exclusive events
- touchdown speed and touchdown location are normally distributed
- time from touchdown until start of deceleration is normally distributed
- speed is constant from threshold to start of deceleration
- deceleration rate is constant
- speeds at start of exit follows a normal distribution

4.4.7 Maneuvering Demand on the Nose Gear

The total maneuvering gear demand, C_{ng} , is given by the following equation, where

$$C_{ng} = C_{ay} + C_i + C_s$$

- C_{ay} comes from centrifugal force
- C_i from rotation inertia resistance

- C_s from scrubbing resistance

A maximum C_{ng} of 0.2 is assumed to be practical. Compared to the ground coefficient of friction, it leaves a margin of 2 against skidding on wet surfaces and a margin of 4 against skidding on dry surfaces.

CHAPTER 5 RESULTS AND ANALYSIS

5.1 OPTIMAL EXIT LOCATIONS

As can be seen from table 9 and figure 17, the optimal exit locations vary from 1286 ft to 5860 ft for the 8 generic aircrafts of the 4 TERPS Categories. The B 747 and Lockheed F 104 have their optimal exit locations at 5170 ft and 8400 ft. Table 9 also shows the maximum occupancy times, the deceleration rates before and after exit.

5.2 BUNCHING OF EXITS

The smallest distance between any two consecutive optimal exits is 70 ft (2355-2285), corresponding to BS and AF generic aircrafts. Further investigation gives in table 10 the distance separations between the successive exit locations.

Eight different exits would be necessary if it were to accommodate the 8 generic aircrafts. A close look at the exit separations suggests that the exit locations are closely spaced. Concerns are that there is a potential of aircraft collision, confusion of the pilot about the exit to take, inefficient operation control and non-cost efficiency of the system.

Table 9. Optimal Exit Locations

Exit	Generic Aircrafts									
	AS	AF	BS	BF	CS	CF	DS	DF	WB	F104
1286	* 2.5									
	** 1.5									
	*** 39.76									
2285			4.0							
			1.5							
			39.97							
2355		2.5								
		2.0								
	**** 38.01									
3654				4.0						
				1.5						
				39.99						
4225					5.0					
					1.75					
					39.95					
4805							5.0			
							1.75			
							39.96			
5515						5.0				
						1.75				
						40.00				
5860								5.0		
								1.75		
								39.95		
5170									5.0	
									2.0	
									39.98	
8400										6.0
										2.0
										40.01

Notes: * deceleration rate on runway
 ** deceleration rate on exit path
 *** runway occupancy time
 **** the 40 sec cannot be achieved. The runway occupancy time jumps drastically from 38.06 to 41.42 sec for an exit location changing from 2357 to 2360 ft. This is due to the standard deviation of time which increases from 1.87 to 2.79 sec.

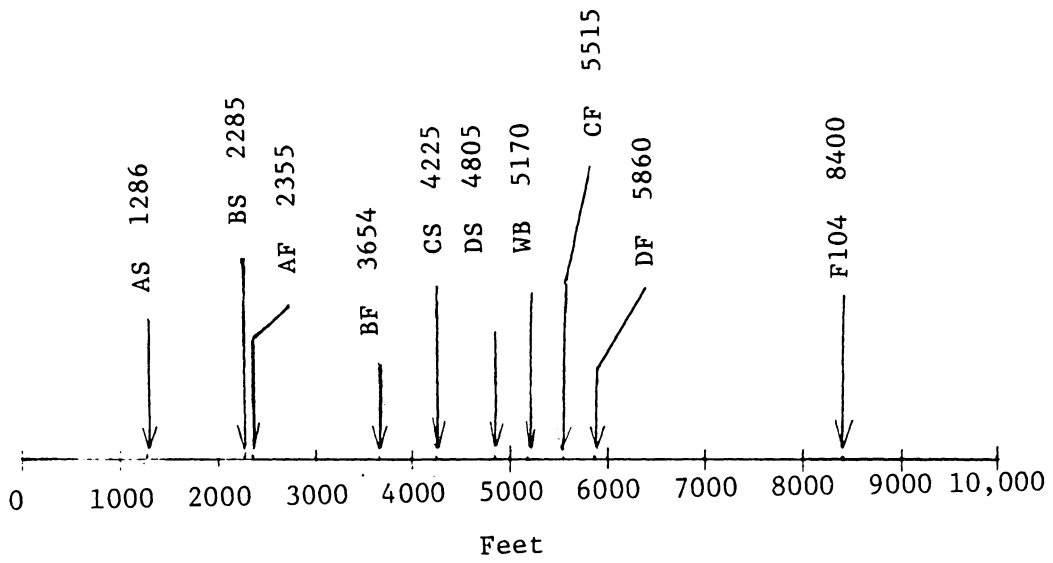


Figure 17. Optimal Exit Locations

Table 10. Exit Separations

Gener Airc	AS	BS	AF	BF	CS	DS	CF	DF
Exit locations	1286	2285	2355	3654	4225	4805	5515	5860
Exit separations	999	70	1299	571	580	710	345	

It is proposed in this research to minimize the number of exits and, at the same time, to accommodate the 8 generic aircrafts with regard to the following criteria:

5.2.1 Runway Occupancy Time

The maximum runway occupancy time remains 40 seconds for each generic aircraft.

5.2.2 Reliability

The 99.99 percent chance of exiting must also be achieved for every aircraft.

5.2.3 Exit Separation

The factors that control the exit separations are the avoidance of aircraft collision, FAA regulations and the aircraft cornering characteristics.

5.2.3.1 Aircraft Collision

Assuming that the critical wingtip is the longest aircraft wingtip, any distance from centerline to centerline of all consecutive exits should be greater than 207 ft. Adjustments are required to take into account the pilot's inability to follow a predetermined exit path at high speed.

5.2.3.2 FAA regulations

The minimum standard separation is 750 ft (16). It is easily noted that the FAA regulations satisfy already the above minimum.

5.2.3.3 Cornering Characteristics

To avoid much demand on the aircraft nose gear, an aircraft is not allowed to take an exit which is at least 750 earlier than its optimal exit. This is also correlated to the pilot's confidence, or lateral acceleration and jerk felt by the passengers.

5.3 SOLUTIONS

Abiding by the above criteria, it can be proved that an exit located 1286 ft is required and that the following pairs of exits are mutually exclusive: (2285, 2355); (3654, 4225); (4225, 4805); (4805, 5515) and (5515, 5860).

The second stage required additional computer runs in which some parameters are varied, sometimes to the limits. However the variable parameters leave few options. They are the deceleration rates before and after exit and the exit location. But beside the exit location, the model is only sensitive to the deceleration rate before turnoff, as can be seen in table 11. The deceleration rate on the exit path has very little effect on the runway occupancy time and the path profile.

Some possible solutions are presented in table 11 as follows.

A factor that needs to be considered is the effects of combining exit paths, in the same exit, on the probability of exiting and the runway occupancy time. A critical path is determined by choosing the aircraft which is the most constrained along the exit path. That aircraft tends to follow a path closer to the runway. It also has the largest turning radius. The problem may arise when another aircraft has to take the same exit and is not fast enough to clear the runway within 40 seconds. Fig 18 gives the picture of the problem.

5.3.1 exit location for AF and BS generic aircrafts

As discussed earlier, the runway occupancy time is very sensitive around the 2355 ft optimal exit location. A lateral displacement of only 5 ft along the exit centerline can result in the BS aircraft missing the 40 sec occupancy time. Besides the 2355 ft exit is not optimally located. These reasons lead to choose the 2285 ft exit to accommodate the AF and BS aircrafts.

5.3.2 exit location for BF and CS

Both exits meet the requirements at 3654 ft and 4225 ft. However if BF takes the 4225 ft exit, it would require a deceleration rate below 0.5

Table 11. Possible Bunching Solutions

Generic Aircraft	Exit locations				
	1286	2285	2355	3654	4225
AS	2.5 1.5 39.8				
AF		2.5 2.0 36.3	2.5 2.0 38.0		
BS		4.0 1.5 40.0	3.0 1.5 39.71		
BF					.5 1.5 39.5
				2.0 1.5 36.2	0.5 1.75 39.5
				4.0 1.5 39.99	
CS				5.0 1.0 33.39	2.0 1.75 32.03
					3.0 1.75 37.49
					4.0 1.0 38.47
					5.0 1.0 39.82
					5.0 1.75 39.95

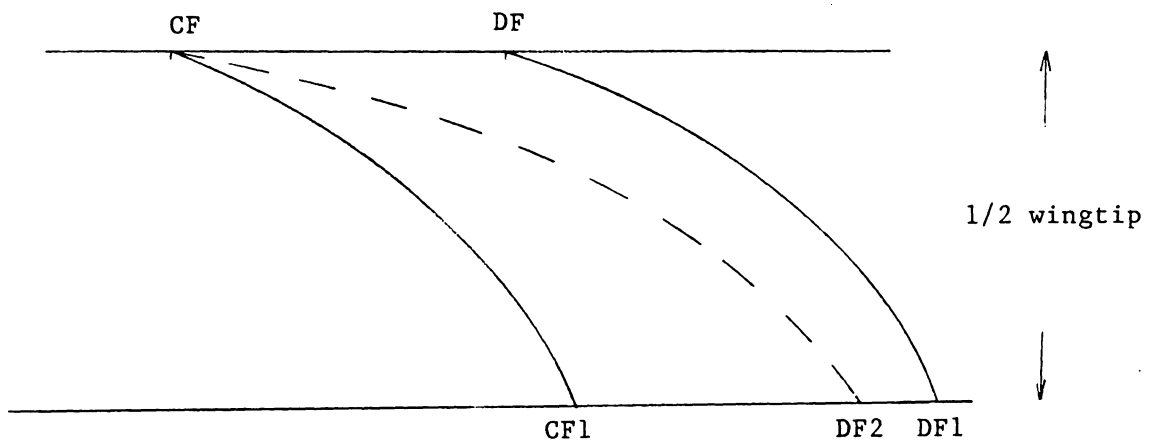


Figure 18. Bunching problem along an exit path

ft/sec**2 to follow the critical path and to be under the 40 seconds maximum runway occupancy time. Counting with drag and rolling friction, it seems risky to assume that this will be practically feasible. An exit at 3654 ft decreases the distance separation between the second and third exits from 1940 to 1369 ft. These factors lead to choose the 3654 ft exit for BS and CS.

5.3.3 Exit location for DS

An exit is required for DS at 4805 ft because it cannot take the following exit in the time limit, DF dictating the critical path.

5.3.4 Exit location for CF and DF

An exit located at 5515 ft would be too close to the 4805 ft exit. the 5860 ft exit is selected for CF and DF.

5.3.5 Final solution

Table 12 and figure 19 give the final solution, with 5 optimal exit locations for the 8 generic aircrafts. Another exit is proposed for the Lockheed F104 at 8400 ft. Similarly one or more exits may be required for aircrafts which characteristics are within the range of the generic aircraft DF and the Lockheed F 104.

The B 747 which optimal exit is located at 5170 ft cannot take any exit of the design because of its restraining cornering characteristics or the time constraint. Figure 19 also shows that the solution is unique. If the 5515 ft exit were chosen to accommodate CF and DF, the previous exit would be located at 4225 ft, and the 3654 ft exit will not exist. Then, at least, DS and/or CF would not meet the requirements.

Table 12. Final Solution

Exit locations	Generic aircrafts				CS	DS	CF	DF
	AS	BS	AF	BF				
1286	2.5 1.5 39.76							
2285		3.5 1.5 39.03	2.5 2.0 36.3					
3654				1.5 1.5 36.	5.0 1.75 33.4			
4805						5.0 1.75 39.96		
5860							.5 .5 37.4	5. 1.75 39.95

Figure 19. Final solution

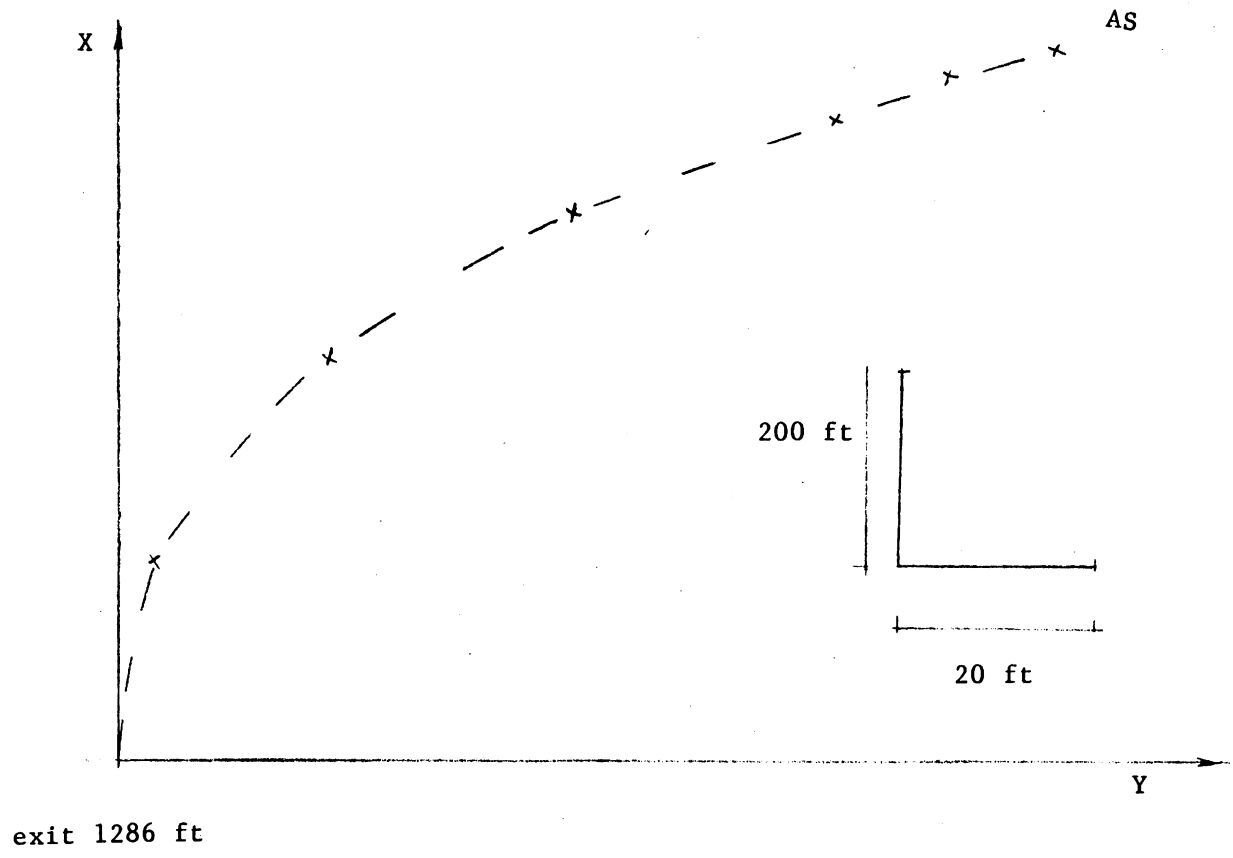


Figure 19. (continued)

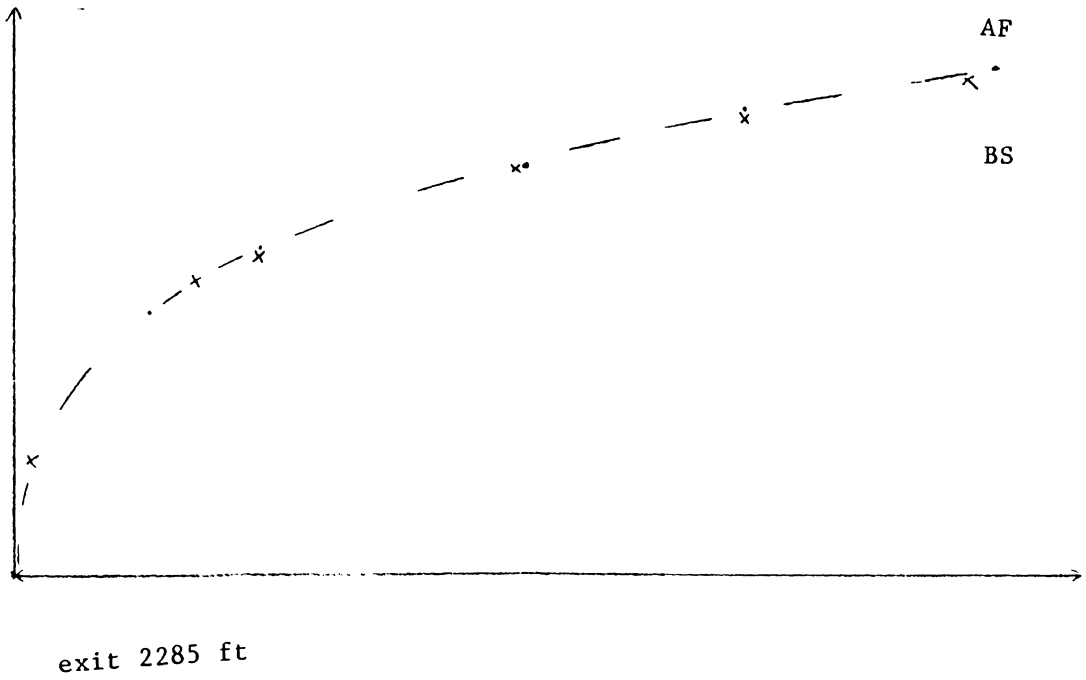
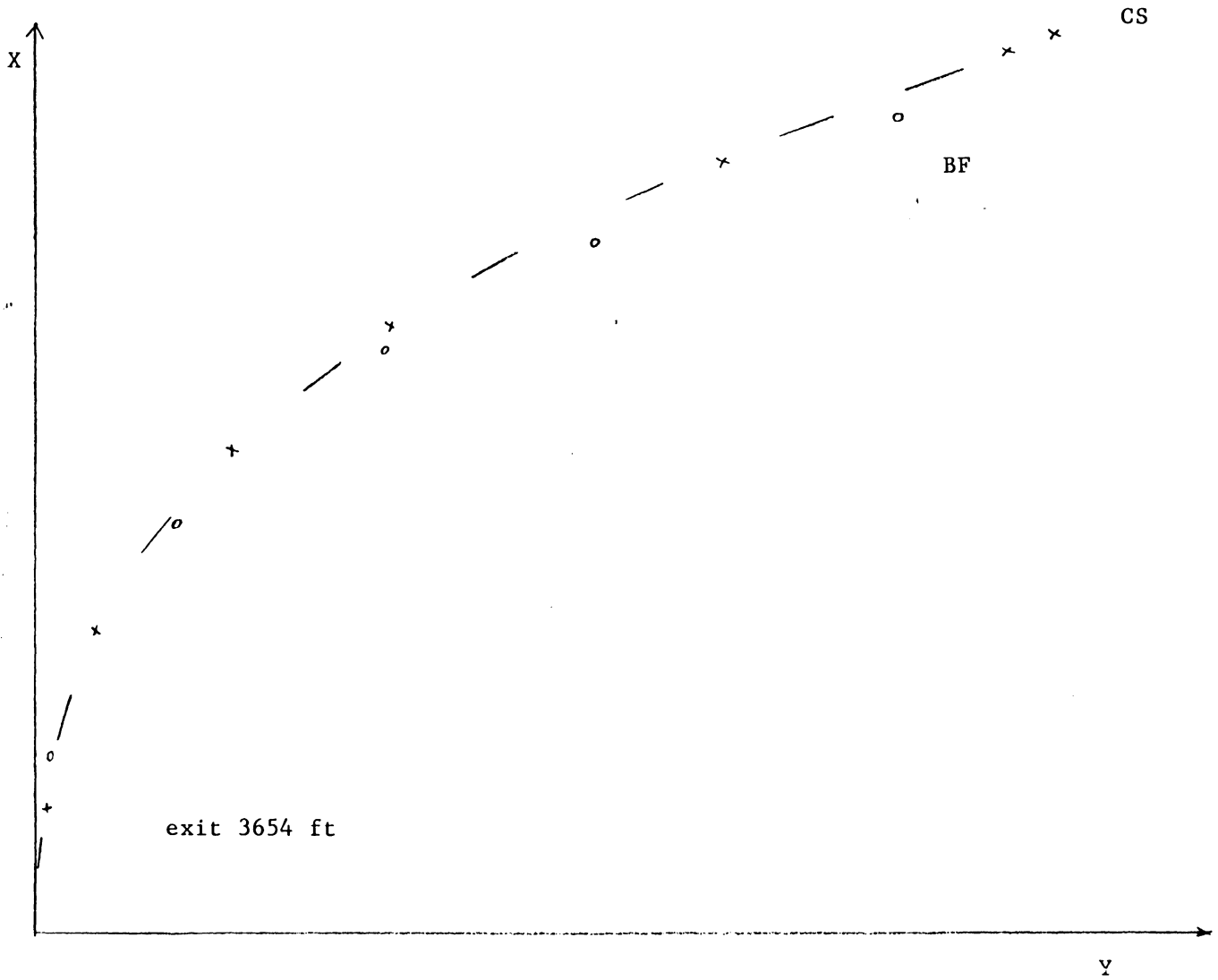


Figure 19. (continued)



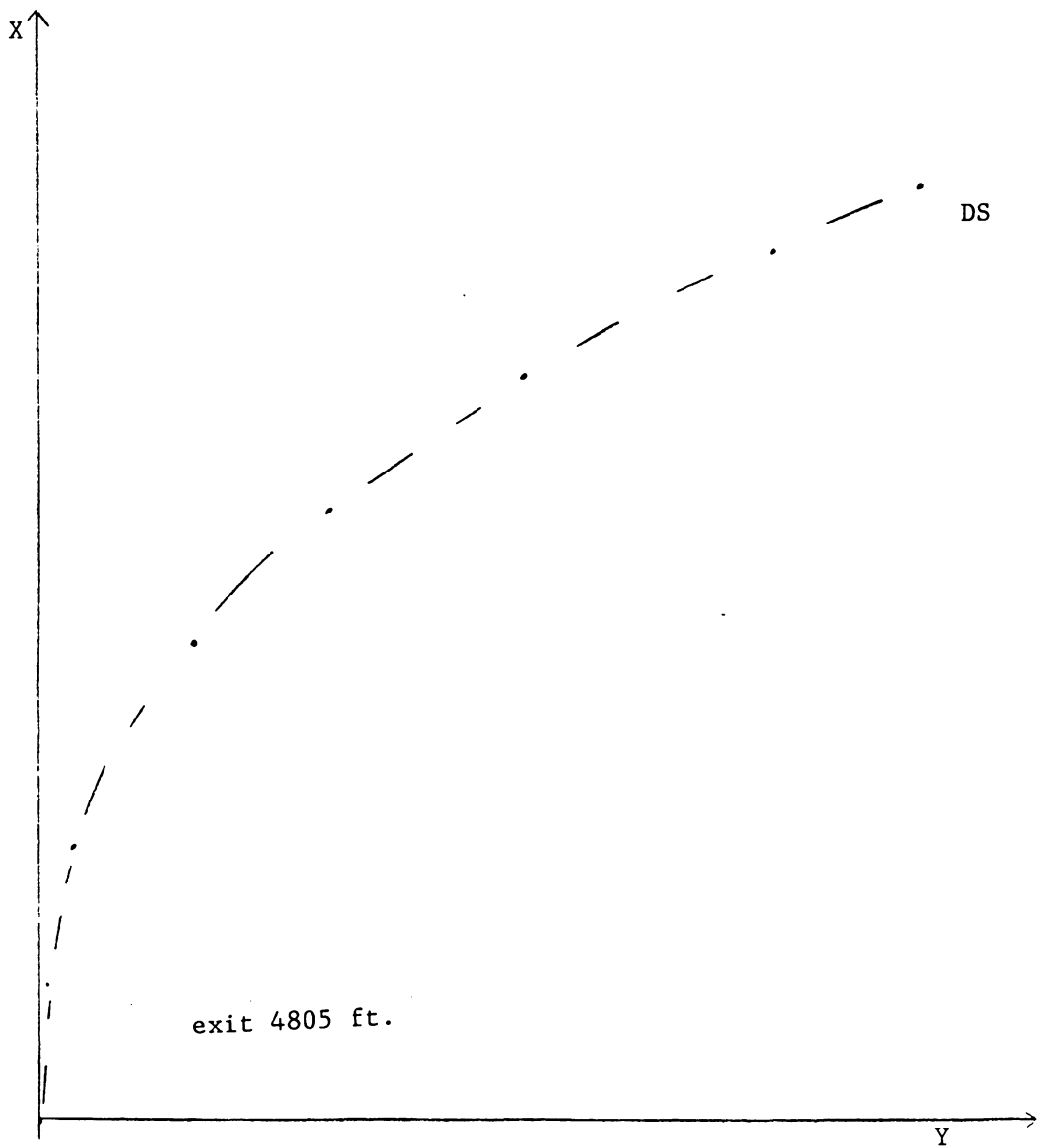


Figure 19. (continued)

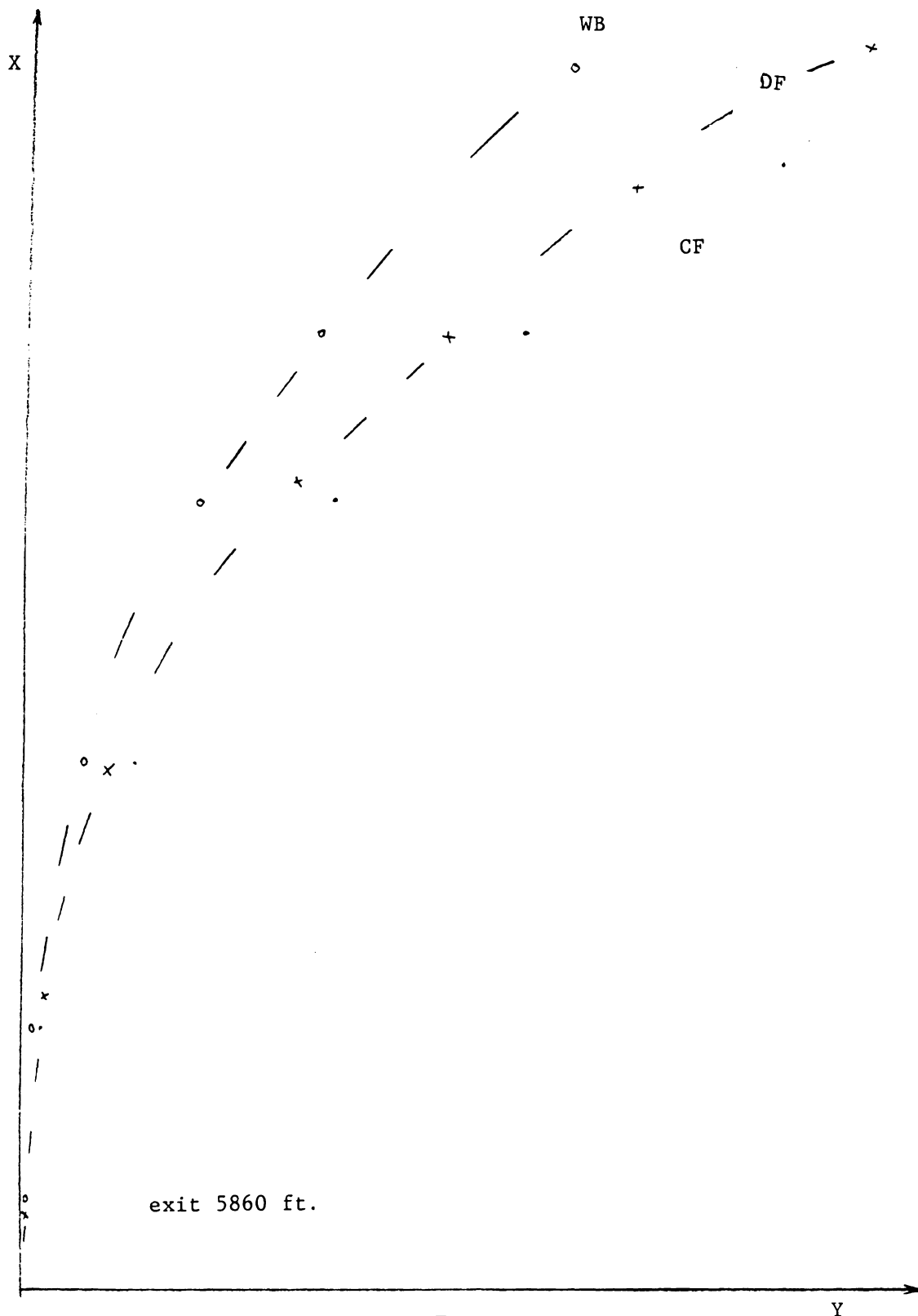
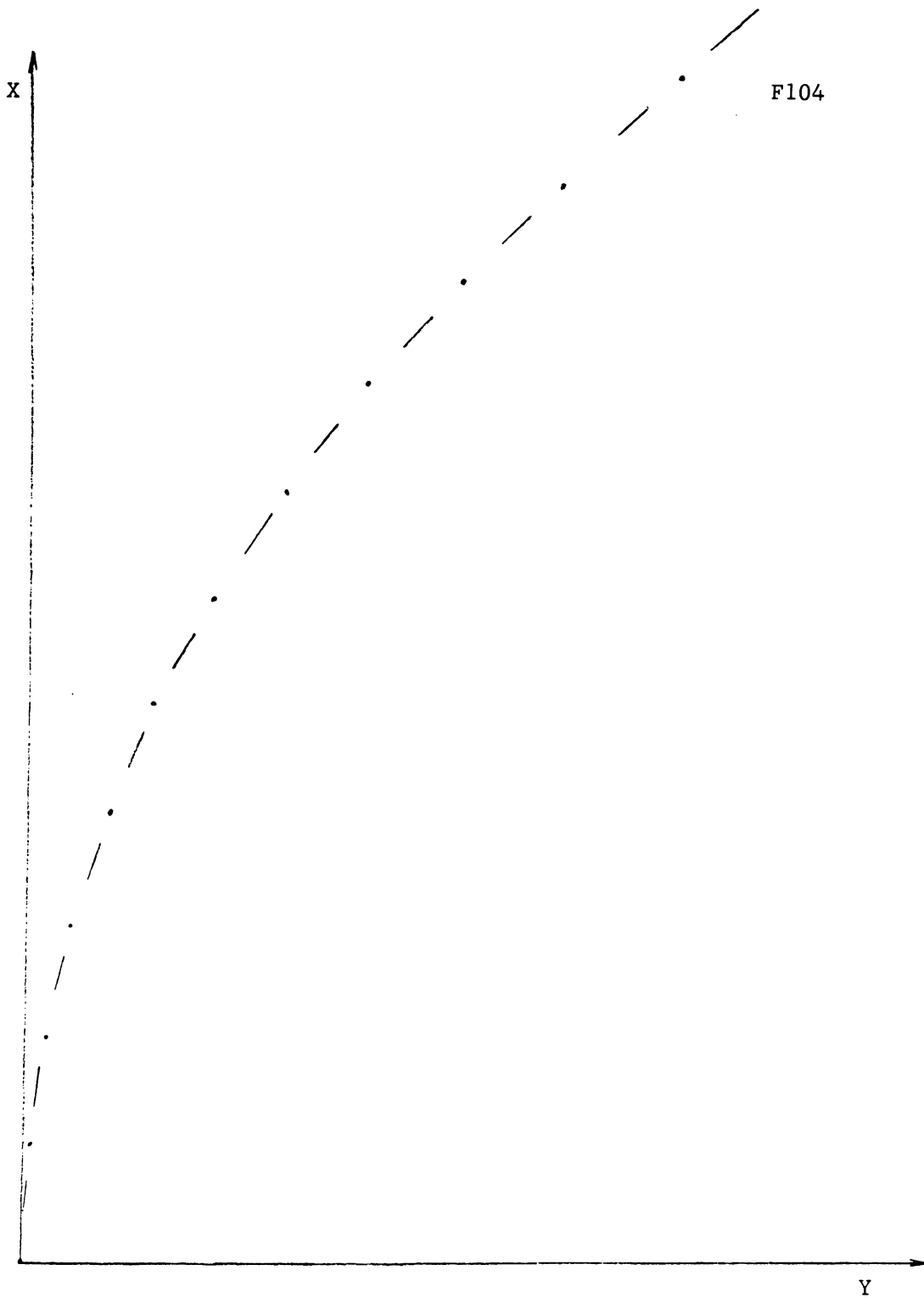
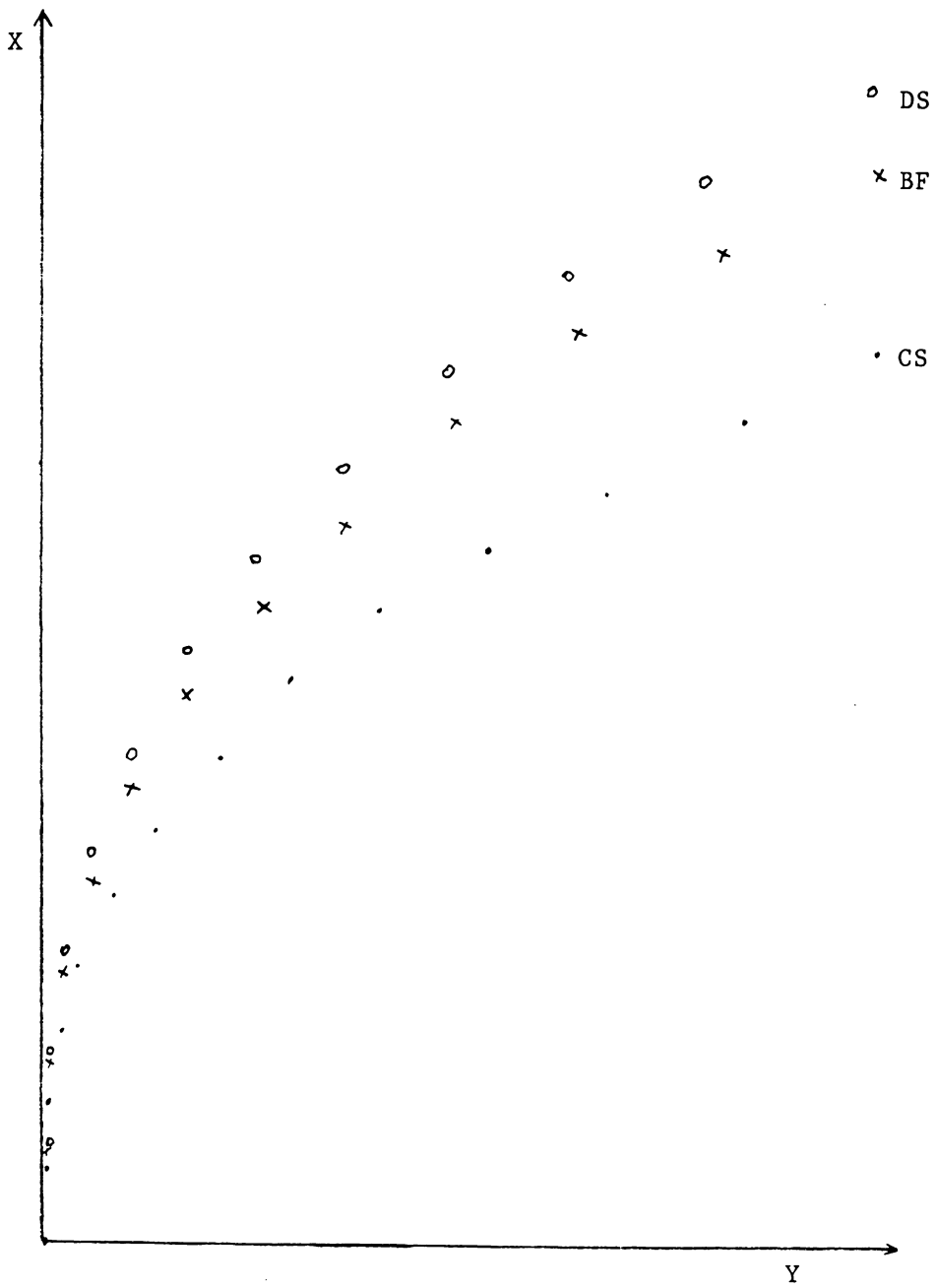


Figure 19. (continued)



exit 8400 ft.

Figure 19. (continued)



exit 4225 ft.

Figure 19. (continued)

CHAPTER 6 CONCLUSIONS AND RECOMMENDATIONS

As can be readily seen, the development of optimal high speed exits is very promising. It is relatively cheap compared to the Brandt Drift-off system or to the construction of a new runway and it can perform comparatively to them under certain conditions to accommodate efficiently the increasing demand of traffic (3).

Another attractiveness of the design is that it is not sensitive to aircraft mix and it is very reliable. It is not based on an average occupancy time, which makes it a better tool in the ultimate spacing of landing aircrafts.

However the Probabilistic Computer Model of Optimal Runway Turnoffs can be improved to include such factors as the temperature and the elevation variability. A subroutine can also be added to the model to ease the computational procedure of bunching of any particular aircraft in the proposed design. For the full use of the model further investigation needs to be performed to integrate the high speed runway exit maneuver smoothness. A more reasonable skewed curve would be preferred to the normal distribution assumed for the touchdown speed and the touchdown location.

The introduction of the MLS is essential in releasing delay in the landing process. It provides an approach curve path which alleviates the many

problems present in the ILS. An hypothetical example (1) shows the great role that the MLS plays in increasing capacity in an airport environment; considering an airport serves aircrafts which land at a speed of 165 mph with an average occupancy time of 25 sec, and an average spacing of 3 nautical miles; the minimum interarrival time is $(3 \times 6076 \times 3600 / 165 \times 5280)$, 75 sec, which corresponds to a maximum of 48 landings per hour, nearly half of the high speed exit design.

The automation of the system requires the introduction of filters and other navigational aids so that aircrafts can be directed efficiently from the terminal airspace to the taxiways. The advancement of the autobraking guidance laws , the use of a conservative deceleration rate and the airborne hardware/software packages makes the system more reliable.

The literature reviewed shows that the simulation runs and the field tests have been proved to be successful and feasible at speeds up to 150 mph. With the exit speeds obtained in the research further investigation is needed in the the areas of ride comfort, braking performance in all weather conditions, exit presignalization, and the aircraft cornering characteristics.

It is suggested that the development of high speed turnons be also incorporated in the design and that the effects of different runway configurations on the design be investigated. To allow landing from both sides of the runway, due to the variability of wind configurations, a

symmetrical design around the midpoint of the runway centerline is required.

APPENDIX A. PROBABILISTIC MODEL

MAIN PROGRAM

\$DEBUG

C\$JOB

C CHARACTER MS, MSP

REAL NTIP

REAL*4 NTITLE(20)

DIMENSION ARBS(16),DPX(16),P(16),DP(16)

DIMENSION SND(400)

DIMENSION ARBT(16),ARBI(15),DT(15)

DIMENSION PEX(16),ZROT(15),Z(16),ZEX(16)

OPEN(1,FILE='HISPEX.DAT')

OPEN(2,FILE='SND.DAT')

OPEN(3,FILE='SOLVIT.DAT',STATUS='NEW')

READ(1,11) (NTITLE(I),I=1,20)

11 FORMAT(20A4)

READ(1,10) UA, US, VA, VS, WA, WS

READ(1,10) XA, XS, YS, C, ZA, NTIP

10 FORMAT(6F5.0)

IBIRD=0

IFLAG=0

C

WRITE(*,125)

125 FORMAT('ENTER: 5 FOR TERMINAL PRINTOUT' /,

1 ' 6 FOR HARDCOPY PRINTOUT')

WRITE(*,126)

126 FORMAT(4X,'IF THE PROGRAM ASK ABOUT UNIT 5, ENTER CON: ',/4x,

1 'IF THE PROGRAM ASK ABOUT UNIT 6, ENTER LPT|:')


```

        READ(*,*)IWRT
        WRITE(*,139)
139  FORMAT(' ENTER: 1 FOR STANDARD PRINT ',/
1      '          2 FOR INTERMEDIATE VALUES',/
2      '          3 FOR FINAL VALUES ONLY')
        READ(*,*)IPRT
        WRITE(*,6)
6     FORMAT(' ENTER: 1 TO SOLVE FOR 40 SEC OCCUPANCY',/
1      '          2 TO SOLVE FOR MAXIMUM PROBABILITY',/
2      '          3 FOR USER ENTRY OF YA VALUE')
        READ(*,*)IYA
        WRITE(*,7)
7     FORMAT(' ENTER INITIAL YA SPEED')
        READ(*,*)YA
        IF(IPRT.EQ.3) GO TO 750
        WRITE(IWRT,3) (NTITLE(I),I=1,20)
3     FORMAT(29X,20A4/)
        WRITE(IWRT,1)
1     FORMAT(30X,' NASA HIGH SPEED ANALYSIS',/,
135X,' INPUT SUMMARY,'//,T35,'PROBABILISTIC MODEL',
2/T43,'AVERAGE   STD DEV   UNITS,')
        WRITE(IWRT,2)UA,US,VA,VS,WA,WS,XA,XS,YA,YS,C,ZA,NTIP
2     FORMAT(10X,'TOUCHDOWN LOCATION',T40,2F10.0,T65,'FEET',
1/10X,'TOUCHDOWN SPEED',T40,2F10.0,T65,'FT/SEC',
2/10X,'TIME-TOUCHDOWN TO DECEL',T40,2F10.0,T65,'SECONDS',
2/10X,'DECELERATION RATE',T40,2F10.2,T65,'FT/SEC**2',

```

```

3/10X, '50%PROBABILITY SPEED',T40,2F10.0,T65, 'FT/SEC',
3/10X, 'DIST: THRESHOLD-START OF TURN',T40,F10.0,T65, 'FEET',
4/10X, 'SPEED AT MAJOR DECEL REDUCE',T40,F10.0,T65, 'FT/SEC',
5/10X, 'NOSE-WINGTIP DIST',T40,F10.0,T65, 'FEET',//)
750  READ(2,20) SND
20   FORMAT(10F5.4)
      YAPERM = YA
C
C   CALCULATE DISTANCES
C
      A = UA + VA*WA
      B = A + (VA**2-ZA**2)/(2.*XA)
C
C   CALCULATE SPEEDS DURING LANDING
C
      ASB = (VA**2-2*XA*(B-A))**0.5
      IF(VA**2.GT.(2*XA*(C-A))) GO TO 825
      WRITE(IWRT,821)
821  FORMAT('  SPEED AT EXIT IS NEGATIVE')
      STOP
825  CONTINUE
      ICK=1
600  FORMAT(' AT POSITION ',I2)
      IF(IPRT.EQ.2)WRITE(5,600)ICK
      ICK=2
      ASC = (VA**2-2*XA*(C-A))**0.5

```

```

ASCSV = ASC
C
C CALL EXPATH TO DETERMINE EXIT PATH
C     TIME AND DISTANCE
C
C CALL EXPATH(ASC,PTIME,XDIST,IWRT,IPRT,IFLAG)
C
C UPON RETURNING FROM EXPATH,THE VALUE OF ASC
C (AVG SPEED AT START OF TURN)HAS BEEN REDIFIED
C TO SPEED AT END OF TURN.AFTER THIS POINT,
C AVG SPEED AT START OF TURN HAS BEEN REDIFIED AS 'ASCSV'
C
C TDIST= C + XDIST
500 CONTINUE
MS=0
MSP=1
ASC2=YAPERM-(1.5*YS)
IF(ASCSV.LT.ASC2)MS=1
IF(IPRT.EQ.2)WRITE(5,600) ICK
ICK = 3
C
C CALCULATE STANDARD DEVIATION
C
SDA= (VS**2+(US*XVA/VA)**2 + (WS*XVA)**2)**0.5
IF(IPRT.EQ.2)WRITE(5,600)ICK
ICK=4

```

```

SDB=(SDA**2 +( 2*XS*(B-A)/(VA+ZA))**2)**0.5
IF(IPRT.EQ.2)WRITE(5,600)ICK
ICK=5
SDC= (SDA**2 + (2*XS*(C-A)/(VA+ASCSV))**2)**0.5
IF(IPRT.EQ.2)WRITE(5,600)ICK
ICK=6

C
C   CALCULATE OCCUPANCY TIMES
c
ASA=VA
TA = ((UA+NTIP)/VA) + WA
IF(B.GT.C) GO TO 100
TB = TA + 2*(B-A)/(ASA+ASB)
TC = TB + 2*(C-B)/(ASB+ASCSV)
GO TO 110
100 TC = TA + 2*(C-A)/(ASA+ASCSV)
110 CONTINUE

C   CALCULATE DATA FOR AIRCRAFT TRAVELING
C   ONE STANDARD DEVIATION BELOW NORM
C
C   CALCULATE DISTANCES
C
AP = A
BP = AP + (B-A)*((ASA-SDA)-ZA)/((ASA-SDA)-(ZA-SDB))
CP = C

C

```

```

C      CALCULATE SPEEDS
C
      ASAP = ASA - SDA
      ASBP = ZA
      ASCP = ASCSV - SDC
      ASCP1 = YA - 1.5*YS
      IF(ASPC1.GT.ASCP)MSP=2
C
C      CALCULATE OCCUPANCY TIME
C
      TAP = 2*A/(VA-VS+ASAP)
      IF(BP.GT.CP) GO TO 120
      TBP = TAP + 2*(BP-AP)/(ASAP+ASBP)
      TCP = TBP + 2*(CP-BP)/(ASBP+ASCP)
      GO TO 130
120    TCP =TAP +2*(CP-AP)/(ASAP+ASCP)
130    SDOT = TCP - TC
      IF(SDOT.GT.0.) GO TO 900
      WRITE(*,901)
901    FORMAT('/STANDARD DEVIATION LESS THAN ZERO')
      STOP
900    CONTINUE
C
C
C      WRITE INTERMEDIATE VALUES FOR CHECKOUT
C

```

```

        IF(IPRT.NE.2) GO TO 138
        WRITE(IWRT,135)A,B,ASB,ASC,SDA,SDB,SDC,ASA,TA,TB,TC
135    FORMAT(' INTERMEDIATE RESULTS IN ORDER: '/,
        1' A,B,ASB,ASC,SDA,SDB,SDC,ASA,TA,TB,TC' /, ' AP,BP,CP,ASAP,ASBP, '
        2'ASCP,TAP TAP,TBP,TCP,SDOT' ,//11F8.2)
        WRITE(IWRT,136)AP,BP,CP,ASAP,ASBP,ASCP,TAP,TBP,TCP,SDOT
136    FORMAT(10F8.2)
C
C    CALCULATE PERCENT AIRCRAFT EXITING
C
C    SPECIFY ARBITRARY SPEED RANGE
C
138    CONTINUE
        ITEMP = ASCSV-3.
        ARBS(1) =ITEMP
        DO 140 I=2,16
140    ARBS(I) = ARBS(I-1) + 1.
C
C    CALCULATE PROBABILITY FOR SPEED RANGE
C
        DO 150 I=1,15
        Z(I)=(ARBS(I)-ASCSV)/SDC
        IF(ABS(Z(I)).GT.3.99)Z(I)=3.99
        ZZ=(ABS(Z(I))+0.01)*100.
        ICNT=ZZ
        P(I)=0.5+SND(ICNT)

```

```

        IF(Z(I).LT.0.)P(I)=0.5-SND(ICNT)
150    CONTINUE
C
C    CALCULATE DISCRETE INTERVALS
C
        DP(1) = P(1)
        TOT = P(1)
        DO 160 I=2,15
        DP(I) = P(I) - P(I-1)
160    TOT = TOT + DP(I)
        DP(16) =1.-TOT
C
C    CALCULATE PROBABILITY OF EXITING
C
        DO 170 I=1,16
        ZEX(I) = (YA-(ARBS(I)-0.5))/YS
        IF(ZEX(I).GT.3.99) ZEX(I)=3.99
        IF(ZEX(I).LT.-3.99) ZEX(I)=-3.99
        ZZ=(ABS(ZEX(I))+0.01)*100.
        ICNT=ZZ
        PEX(I)=0.5+SND(ICNT)
        IF(ZEX(I).LT.0.)PEX(I)=0.5-SND(ICNT)
170    CONTINUE
C
C    CALCULATE DISCRETE PROBABILITY AND SUM
C

```

```

PX = 0.
DO 180 I=1,16
DPX(I) = DP(I)*PEX(I)
180  PX = PX + DPX(I)
C
C  WRITE INTERMEDIATE VALUES
C
IF(IPRT.NE.2) GO TO 185
WRITE(IWRT,181)
181  FORMAT(/T10,' PERCENT AIRCRAT EXITING CALC'/, ' ARBS'
1,T13,'Z',T21,'P',T29,'DP',T37,'ZEX',T45,'PEX',T53,'DPX'/)
DO 184 I=1,16
WRITE(IWRT,183) DP(I),ZEX(I),PEX(I),DPX(I)
184  WRITE(IWRT,187)ARBS(I),Z(I),P(I)
183  FORMAT(24X,F8.4,F8.3,2F8.4)
187  FORMAT(F8.1,F8.3,F8.4)
WRITE(IWRT,188)PX
188  FORMAT(/T10,' PERCENT AIRCRAFT EXITING = ',T43,F10.4)
185  CONTINUE
C
C  CALCULATE MINIMUM OCCUPANCY TIME
C
PXC =ABS(PX-0.5)
DO 145 I=1,400
145  IF((PXC.GT.SND(I)).AND.(PXC.LE.SND(I+1))) GO TO 146
WRITE(*,147)

```



```

147  FORMAT('/PX VALUE NOT FOUND')
      STOP
146  BAN=I
      PXCH=BAN/100.
      OTMIN = TC-PXCH*SDOT
      IF(IPRT.EQ.2)WRITE(IWRT,191)OTMIN
191  FORMAT(T10,' MINIMUM OCCUPANCY TIME=',T43,F10.2,' SEC')
C
C  CALCULATE AVERAGE RUNWAY OCCUPANCY TIME
C
C
C  INITIALIZE ARBITRARY OCCUPANCY TIME
C
      ITMIN=OTMIN
      ARBT(1) = ITMIN
      DO 190 I=2,15
      ARBT(I) = ARBT(I-1) + 1.
190  CONTINUE
      ARBT(1)=OTMIN
C
C  COMPUTE Z VALUES
C
      DO 200 I=1,15
      ZROT(I) = (ARBT(I)-TC)/SDOT
      IF(ABS(ZROT(I)).GT.3.99) GO TO 201
      ZZ=(ABS(ZROT(I))+0.01)*100.

```

```

        ICNT=ZZ
        P(I)=0.5+SND(ICNT)
        IF(ZROT(I).LT.0.)P(I)=0.5-SND(ICNT)
200    CONTINUE
201    IBAN=I-1
C
C    CALCULATE INTERVALE MIDPOINTS
C
        ARBI(1) = (ARBT(1)+ARBT(2))/2.
        DO 210 I=2,IBAN
210    ARBI(I) = ARBT(I) + 0.5
C
C    CALCULATE DISCRETE PROBABILITY AND SUM
C
        PSUM=0.
        TSUM=0.
        P(IBAN+1)=1.
        DO 220 I=1,IBAN
        DP(I) = P(I+1) - P(I)
        DT(I) =DP(I)*ARBI(I)
        PSUM = DP(I) + PSUM
        TSUM = DT(I) + TSUM
220    CONTINUE
        AROTEX = TSUM /PSUM
C

```

```

C      WRITE FINAL PARAMETERS
C
      IF(IPRT.NE.2)GO TO 230
      WRITE(IWRT,231)
231    FORMAT(/ ' AVERAGE RUNWAY OCCUPANCY TIME CALC ',/,
1' ARBT',T12,'ZROT',T21,'P' ,T29,'ARBI',T37,'DP',T45,'DT'/)
      DO 232 I=1,IBAN
      WRITE(IWRT,233) ARBT(I),ZROT(I),P(I)
232    WRITE(IWRT,234)ARBI(I),DP(I),DT(I)
233    FORMAT(F8.2,F8.3,F8.4)
234    FORMAT(24X,F8.2,F8.4,F8.3)
      WRITE(IWRT,235)PSUM,TSUM
235    FORMAT(/' AREA SUM=',T20,F10.4,/' TIME SUM=',T20,F10.2)
      WRITE(IWRT,238)AROTEX
238    FORMAT(T10,' AVERAGE RUNWAY OCCUPANCY TIME=',T43,F10.2,'SEC')
230    CONTINUE
C
C      CALCULATE XTIME AND TTIME
C
      XTIME=AROTEX+3.9*SDOT
      TTIME=XTIME+PTIME
      IF(IPRT.EQ.2)WRITE(IWRT,651)SDOT
651    FORMAT(T10,' STANDARD DEVIATION=',T43,F10.2,' SEC')
      IF(IPRT.EQ.2)WRITE(IWRT,650)XTIME
650    FORMAT(T10' AVG TIME PLUS 3 STD DEV='T43,F10.2,'SEC')
      WRITE(3,700) PX,AROTEX,SDOT,XTIME,TTIME,YA,MS,MSP

```

```

      IF(IYA. EQ. 3) WRITE(*,827) PX
827  FORMAT(' PROB=' ,F7.4)
      IF((XTIME. LT. 39.99).OR. (XTIME. GT. 40.01)) GO TO 800
810  CONTINUE
      PXX=PX*100.
      WRITE(IWRT,853)PXX
853  FORMAT(/T10,' PERCENT AIRCRAFT EXITING= ',T43,F10.4)
      WRITE(IWRT,238)AROTEX
      WRITE(IWRT,651) SDOT
      WRITE(IWRT,650) XTIME
      WRITE(IWRT,850) YA
850  FORMAT(T10,' FINAL 50% PROBABILITY SPEED=' ,T43,F10.2,' M/SEC')
      WRITE(IWRT,852) ASCSV
852  FORMAT(T10,' AVERAGE SPEED At EXIT=' ,T43,F10.2,'M/SEC')
      WRITE(IWRT,851) IBIRD
851  FORMAT(T20,' PERFORMED IN ',I3,' ITERATIONS'/)
      GO TO 801
800  CONTINUE
      IF(IYA. EQ. 1) YA=YA*XTIME/40.
      IF(IYA. EQ. 2) YA=YA-1.
      IF(IYA. LT. 3) GO TO 824
      WRITE(*,823)
823  FORMAT('      ENTER NEW YA SPEED; 999 TO END')
      READ(*,*)YA
      IF(YA. EQ. 999.) GO TO 801
700  FORMAT(6F12.4,2A1)

```

```

824  IBIRD=IBIRD+1
      IF(IBIRD.LT.15) GO TO 500
801  CONTINUE
      WRITE(IWRT,820)
820  FORMAT(/'      CALCULATED RESULTS'/)
      WRITE(IWRT,822) ASCSV,ASC,PTIME,C,XDIST,TDIST
822  FORMAT(/'      CRITICAL VALUES: '/,T10,'ASCSV',T25,'ASC',T40,
1'PTIME',T55,'CDIST',T70,'XDIST',T85,'TDIST'/,T5,6(F10.2,5X))
      WRITE(IWRT,807)
807  FORMAT(//6X,'PROB',T18,'AVG TIME',T30,'STD DEV',T42,'XTIME',T54,
1'TTIME',T66,'YA'/)
      CLOSE(UNIT=3)
      OPEN(3,FILE='SOLVIT.DAT',STATUS='OLD')
803  READ(3,700,END=808)Q1,Q2,Q3,Q4,Q5,Q6,Q7,Q8
      WRITE(IWRT,700)Q1,Q2,Q3,Q4,Q5,Q6,Q7,Q8
      GO TO 803
808  WRITE(*,920)
920  FORMAT(/'      DO YOU WANT TO CONTINUE EXIT PATH TO TAXI-WAY '/
1'      1=YES, 2=NO.'')
      READ(*,*)INASA
      IF (INASA.EQ.2) STOP
      IFLAG=1
      CALL EXPATH(ASCSV,PTIME,XDIST,IWRT,IPRT,IFLAG)
      STOP

```

END

C\$ENTRY

C\$STOP

SUBROUTINE

‡DEBUG

C‡JOB

SUBROUTINE EXPATH(V,PTIME,XDIST,IWRT,IPRT,IFLAG)

DIMENSION RSCR(20), YMUSCR(20)

DIMENSION XP(100),YP(100)

INTEGER*4 IDO

REAL JMAX

OPEN(4,FILE='PATH.DAT')

C

C READ INPUT PARAMETERS

C

READ(4,10) WT,YAWI,WHLB,PCTM

READ(4,10) THETMX,YMUMAX,DECEL

READ(4,10) RWIDTH, WSP, TAXDIS

TWTH= (RWIDTH+WSP)/2.

10 FORMAT(4F12.3)

DO 20 I=1,20

20 READ(4,11,END=30) YMUSCR(I),RSCR(I)

11 FORMAT(F5.4,G10.1)

30 ICNT=I-1

REWIND 4

C CLOSE(UNIT=4)

IF(IPRT.EQ.3.OR.IFLAG.EQ.1) GO TO 37

WRITE(IWRT,35)

35 FORMAT(/T32,'AIRCRAFT TRACKING PROGRAM'//)

WRITE(IWRT,50) WT,YAWI,WHLB,PCTM


```

WRITE(IWRT,60) V, THETMX, YMUMAX,DECEL
WRITE(IWRT,75) RWIDTH,WSP,TWTH,TAXDIS
WRITE(IWRT,70)
WRITE(IWRT,80) YMUSCR(1),RSCR(1)
WRITE(IWRT,81) (YMUSCR(I),RSCR(I), I=2,ICNT)
50  FORMAT(T5,'AIRCRAFT CHARACTERISTICS'/,T10,'WEIGHT(LBS)',T25
1,'YAW INERTIA',T43,'WHEELBASE',T57,'% LOAD ON MAIN GEAR',/
2T10,4(F12.1,3X)/)
60  FORMAT('      FLIGHT CONDITIONAL PARAMETERS'/,T10,
1'EXIT VELOCITY',T25,'MAX EXIT ANGLE',T45,'MAX Y MU',
2T60,'DECEL RATE',/
2T10,4(F10.3,5X)/)
70  FORMAT('/'      SCRUB CHARACTERISTICS'/,T10,'Y MU',T20,'RADIUS'/)
75  FORMAT('      SYSTEM WIDTHS'/,T15,'RUNWAY',T28,'WINGSPAN',
1T42,'CLEAR DIST.',T61,'DIST TO TAXIWAY'/T10,3(F10.2,5X),T61,F10.2)
80  FORMAT(T5,F10.4,G10.1)
81  FORMAT(T5,F10.4,f10.1)
C
37  JMAX=10.0E20
    GMAX=10.0E20
C    INITIALIZE VARIABLES
C
85  CONTINUE
    IF(IFLAG.EQ.1) THETMX=180.
    IF(IFLAG.EQ.1) TWTH=TAXDIS
    G=0.000001

```

```

T=0.0
X=0.0
Y=0.0
THETA=0.0
R=100000.
IPRINT=10000
THETMX=THETMX*3.1416/180.
DT=0.001
C
C   CONSTANT NLG SIDE MU
C
ITR=2
IF(IPRT.EQ.3.OR.IFLAG.EQ.1) GO TO 810
WRITE(*,800)
800  FORMAT(/' ENTER: 1 TO PRINT TRACKINNG RESULTS TO RUNWAY EDGE ',/
1     '          2 TO WAIT FOR PRINT TO TAXIWAY EDGE')
READ(*,*) ITR
810  CONTINUE
IF(IFLAG.EQ.1) ITR=1
IF(ITR.EQ.1) WRITE(IWRT,8010)
IF(ITR.EQ.1) WRITE(IWRT,96)
IF(ITR.EQ.1) WRITE(IWRT,8011)
DO 200 IDO=1,60000
DO 90 J=2,ICNT
90   IF(R.GE.RSCR(J)) GO TO 92
92   JJ=J-1

```

```

      YMUSC=YMUSCR(JJ)+(YMUSCR(J)-YMUSCR(JJ))*(RSCR(JJ)-R)
1  /(RSCR(JJ)-RSCR(J))
      IF(RSCR(J).LE.0.) WRITE(IWRT,8001)
      IF(R.GT.RSCR(1)) WRITE(IWRT,8001)
      IF(RSCR(J).LE.0.OR.R.GT.RSCR(1)) STOP
      YMUC = V**2/(32.2*R)
      YMUI = YMUMAX-YMUSC-YMUC
      RD =-(YMUI*R**2/(YAWI*V))*WT*WHLB*(PCTM/100.)*(1.-PCTM/100.)
      G=V**2/(R*32.2)
      GDMX=JMAX*(1.-G/GMAX)
      RDMX =-32.2*R**2*GDMX/V**2
      IF(Y.GE.TWTH) GO TO 500
      IF(IPRINT.LT.500) GO TO 110
100  TH = THETA*180./3.1416
      IBC=IBC+1
      XP(IBC)=X
      YP(IBC)=Y
      IF(ITR.EQ.1) WRITE(IWRT,8000) T,X,Y,TH,R,RD,YMUSC,YMUC,YMUI,G,V
      IF(RD.EQ.RDMX) WRITE(IWRT,8002)
      IPRINT=0
110  CONTINUE
C
C      INTEGRATE
C
      T=T+DT
      V=V+DECEL*DT

```

```

IPRINT=IPRINT+1
X=X+V*DT*COS(THETA)
Y=Y+V*DT*SIN(THETA)
THETAD=V/R
THETA=THETA+THETAD*DT
R=R+RD*DT
200  CONTINUE
C
C  PRINT FINAL TIME VALUE
C
500  IF(THETA. LE. THETMX) GO TO 520
      WRITE(*,9000)
9000  FORMAT(//'  WARNING!!  WINTIP NOT CRITICAL POINT! '//)
      STOP
520  IF(ITR. EQ. 1) WRITE(IWRT,8600)
8600  FORMAT(//'    FINAL VALUES '//)
      IF(ITR. EQ. 1) WRITE(IWRT,8000)T,X,Y,TH,R,RD,YMUSC,YMUC,YMUI,G,V
      PTIME=T
      XDIST=X
C
C  FORMAT LIST
C
96   FORMAT('/  PASSENGER CONFORT IGNORED')
8000  FORMAT(4F10.3,2F12.2,5F10.3//)
8001  FORMAT(1H , '***OUT OF TABLE BOUND***')
8002  FORMAT(' LIMITED BY CONFORT')

```

```
8010  FORMAT(// '  CONSTANT NLG SIDE LOAD ANALYSIS')
8011  FORMAT(//T5,'TIME',T17,'X',T27,'Y',T35,'THETA',T46,'RADIUS',T58,
1'R RATE',T68,'MU SCRUB',T81,'MU CENT',T92,'MU I',T102,'G CENT'
1,T113,'VELOCITY'/)
      RETURN
      END
C$ENTRY
C$STOP
```

APPENDIX B. COMPUTER OUTPUTS

OPTIMAL EXIT LOCATIONS

COMPUTER OUTPUTS

OPTIMAL EXIT LOCATIONS

GENERIC AIRCRAFT AS

NASA HIGH SPEED ANALYSIS
INPUT SUMMARY,
PROBABILISTIC MODEL

	AVERAGE	STD DEV	UNITS,
TOUCHDOWN LOCATION	500.	10.	FEET
TOUCHDOWN SPEED	66.	5.	FT/SEC
TIME-TOUCHDOWN TO DECEL	3.	1.	SECONDS
DECELERATION RATE	2.50	1.00	FT/SEC**2
50%PROBABILITY SPEED	52.	1.	FT/SEC
DIST:THRESHOLD-START OF TURN	1286.		FEET
SPEED AT MAJOR DECEL REDUCE	55.		FT/SEC
NOSE-WINGTIP DIST	39.		FEET

AIRCRAFT TRACKING PROGRAM

AIRCRAFT CHARACTERISTICS

WEIGHT(LBS)	YAW INERTIA	WHEELBASE	% LOAD ON MAIN GEAR
2040.0	2310.0	5.3	72.0

FLIGHT CONDITIONAL PARAMETERS

EXIT VELOCITY	MAX EXIT ANGLE	MAX Y MU	DECEL RATE
37.630	90.000	.250	-1.500

SYSTEM WIDTHS

RUNWAY	WINGSPAN	CLEAR DIST.	DIST TO TAXIWAY
150.00	32.00	91.00	600.00

SCRUB CHARACTERISTICS

Y MU	RADIUS
.0000	.1E+32
.0200	50.0

CONSTANT NLG SIDE LOAD ANALYSIS

TIME	X	Y	THETA	RADUIS	R RATE	MU SCRUB	MUCENT	MUI	GCENT	VELOCITY
.000	.000	.000	.000	100000.00	-57563830.00	.020	.000	.230	.000	37.630
.500	18.626	.151	1.329	439.42	-661.36	.020	.096	.134	.096	36.880
1.000	36.855	1.036	4.474	274.66	-162.32	.020	.148	.082	.148	36.131
1.500	54.613	3.059	8.683	221.07	-70.58	.020	.176	.054	.176	35.381
2.000	71.786	6.415	13.542	194.62	-39.86	.020	.191	.039	.191	34.631
2.500	88.233	11.174	18.821	178.39	-26.72	.020	.200	.030	.200	33.882
3.000	103.807	17.331	24.392	166.81	-20.30	.020	.204	.026	.204	33.132
3.500	118.361	24.828	30.183	157.59	-16.89	.020	.207	.023	.207	32.383
4.000	131.755	33.572	36.156	149.67	-14.95	.020	.208	.022	.208	31.633
4.500	143.863	43.443	42.287	142.52	-13.75	.020	.208	.022	.208	30.883
5.000	154.568	54.299	48.568	135.85	-12.96	.020	.208	.022	.208	30.134
5.500	163.775	65.977	54.995	129.52	-12.38	.020	.207	.023	.207	29.384
6.000	171.404	78.304	61.566	123.45	-11.92	.020	.206	.024	.206	28.635
FINAL VALUES										
6.497	177.365	91.013	61.566	117.63	-11.53	.020	.205	.025	.205	27.890

CALCULATED RESULTS

CRITICAL VALUES:

ASCSV	ASC	PTIME	CDIST	XDIST	TDIST
37.63	27.89	6.50	1286.00	177.37	1463.37
PROB	AVG TIME	STD DEV	XTIME	TTIME	YA
1.0000	22.3087	2.8087	33.2626	39.7593	52.0000
.9987	22.5098	2.8087	33.4637	39.9604	51.0000

GENERIC AIRCRAFT AF

NASA HIGH SPEED ANALYSIS
INPUT SUMMARY,
PROBABILISTIC MODEL

	AVERAGE	STD DEV	UNITS,
TOUCHDOWN LOCATION	500.	10.	FEET
TOUCHDOWN SPEED	118.	5.	FT/SEC
TIME-TOUCHDOWN TO DECEL	3.	1.	SECONDS
DECELERATION RATE	2.50	1.00	FT/SEC**2
50%PROBABILITY SPEED	95.	1.	FT/SEC
DIST:THRESHOLD-START OF TURN	2355.		FEET
SPEED AT MAJOR DECEL REDUCE	55.		FT/SEC
NOSE-WINGTIP DIST	40.		FEET

AIRCRAFT TRACKING PROGRAM

AIRCRAFT CHARACTERISTICS

WEIGHT(LBS)	YAW INERTIA	WHEELBASE	% LOAD ON MAIN GEAR
24000.0	300000.0	23.0	93.0

FLIGHT CONDITIONAL PARAMETERS

EXIT VELOCITY	MAX EXIT ANGLE	MAX Y MU	DECEL RATE
80.119	41.000	.250	-2.000

SYSTEM WIDTHS

RUNWAY	WINGSPAN	CLEAR DIST.	DIST TO TAXIWAY
150.00	42.00	96.00	600.00

SCRUB CHARACTERISTICS

Y MU	RADIUS
.0000	.1E+32
.0200	50.0

CONSTANT NLG SIDE LOAD ANALYSIS

/ PASSENGER CONFORT IGNORED

TIME	X	Y	THETA	RADIUS	R RATE	MU SCRUB	MU CENT	MU I	G CENT	VELOCITY
.000	.000	.000	.000	100000.00	-3408886.00	.020	.002	.228	.002	80.119
.500	39.809	.051	.209	5870.30	-10271.80	.020	.033	.197	.033	79.119
1.000	79.117	.363	.754	3221.61	-2724.04	.020	.059	.171	.059	78.120
1.500	117.918	1.139	1.583	2303.77	-1235.06	.020	.080	.150	.080	77.120
2.000	156.202	2.543	2.659	1837.93	-702.15	.020	.098	.132	.098	76.121
2.500	193.949	4.708	3.946	1555.88	-453.01	.020	.113	.117	.113	75.121
3.000	231.135	7.741	5.416	1366.35	-317.16	.020	.125	.105	.125	74.122
3.500	267.728	11.727	7.046	1229.78	-235.29	.020	.135	.095	.135	73.123
4.000	303.691	16.728	8.817	1126.23	-182.35	.020	.143	.087	.143	72.123
4.500	338.984	22.792	10.710	1044.60	-146.30	.020	.150	.080	.150	71.124
5.000	373.560	29.951	12.713	978.17	-120.75	.020	.156	.074	.156	70.124
5.500	407.372	38.226	14.814	922.69	-102.05	.020	.161	.069	.161	69.125
6.000	440.370	47.623	17.002	875.33	-88.02	.020	.165	.065	.165	68.125
6.500	472.502	58.141	19.270	834.11	-77.27	.020	.168	.062	.168	67.126
7.000	503.717	69.768	21.611	797.66	-68.87	.020	.170	.060	.170	66.126
7.500	533.963	82.484	24.018	764.95	-62.21	.020	.172	.058	.172	65.127

FINAL VALUES

7.991	562.672	96.005	24.018	735.74	-56.93	.020	.174	.056	.174	64.145
-------	---------	--------	--------	--------	--------	------	------	------	------	--------

CALCULATED RESULTS

CRITICAL VALUES:

ASCSV	ASC	PTIME	CDIST	XDIST	TDIST
80.12	64.15	7.99	2355.00	562.67	2917.67

PROB	AVG TIME	STD DEV	XTIME	TTIME	YA
.9999	22.7291	1.8695	30.0200	38.0106	95.0000

GENERIC AIRCRAFT AF

NASA HIGH SPEED ANALYSIS
INPUT SUMMARY,
PROBABILISTIC MODEL

	AVERAGE	STD DEV	UNITS,
TOUCHDOWN LOCATION	500.	10.	FEET
TOUCHDOWN SPEED	118.	5.	FT/SEC
TIME-TOUCHDOWN TO DECEL	3.	1.	SECONDS
DECELERATION RATE	2.50	1.00	FT/SEC**2
50%PROBABILITY SPEED	94.	1.	FT/SEC
DIST:THRESHOLD-START OF TURN	2360.		FEET
SPEED AT MAJOR DECEL REDUCE	55.		FT/SEC
NOSE-WINGTIP DIST	40.		FEET

AIRCRAFT TRACKING PROGRAM

AIRCRAFT CHARACTERISTICS

WEIGHT(LBS)	YAW INERTIA	WHEELBASE	% LOAD ON MAIN GEAR
24000.0	300000.0	23.0	93.0

FLIGHT CONDITIONAL PARAMETERS

EXIT VELOCITY	MAX EXIT ANGLE	MAX Y MU	DECEL RATE
79.962	41.000	.250	-2.000

SYSTEM WIDTHS

RUNWAY	WINGSPAN	CLEAR DIST.	DIST TO TAXIWAY
150.00	42.00	96.00	600.00

SCRUB CHARACTERISTICS

Y MU	RADIUS
.0000	.1E+32
.0200	50.0

CONSTANT NLG SIDE LOAD ANALYSIS

/ PASSENGER CONFORT IGNORED

TIME	X	Y	THETA	RADIUS	R RATE	MU SCRUB	MU CENT	MU I	G CENT	VELOCITY
.000	.000	.000	.000	100000.00	-3415659.00	.020	.002	.228	.002	79.962
.500	39.731	.051	.209	5858.47	-10254.00	.020	.033	.197	.033	78.963
1.000	78.961	.363	.754	3214.48	-2719.10	.020	.059	.171	.059	77.964
1.500	117.684	1.137	1.584	2298.31	-1232.82	.020	.080	.150	.080	76.964
2.000	155.889	2.538	2.660	1833.32	-700.89	.020	.098	.132	.098	75.965
2.500	193.559	4.699	3.947	1551.77	-452.21	.020	.112	.118	.112	74.965
3.000	230.667	7.728	5.418	1362.57	-316.62	.020	.125	.105	.125	73.966
3.500	267.182	11.706	7.050	1226.23	-234.90	.020	.135	.095	.135	72.966
4.000	303.067	16.699	8.821	1122.86	-182.05	.020	.143	.087	.143	71.967
4.500	338.282	22.753	10.717	1041.35	-146.06	.020	.150	.080	.150	70.967
5.000	372.781	29.902	12.721	975.03	-120.56	.020	.156	.074	.156	69.968
5.500	406.516	38.163	14.824	919.64	-101.89	.020	.161	.069	.161	68.969
6.000	439.437	47.546	17.015	872.35	-87.89	.020	.164	.066	.164	67.969
6.500	471.492	58.047	19.286	831.20	-77.15	.020	.168	.062	.168	66.970
7.000	502.631	69.656	21.629	794.80	-68.76	.020	.170	.060	.170	65.970
7.500	532.800	82.353	24.039	762.14	-62.11	.020	.172	.058	.172	64.971

FINAL VALUES

7.997	561.778	96.024	24.039	732.64	-56.78	.020	.174	.056	.174	63.977
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CALCULATED RESULTS

CRITICAL VALUES:

ASCSV	ASC	PTIME	CDIST	XDIST	TDIST
79.96	63.98	8.00	2360.00	561.78	2921.78

PROB	AVG TIME	STD DEV	XTIME	TTIME	YA
.9999	22.5485	2.7898	33.4289	41.4255	94.0000

GENERIC AIRCRAFT BS

NASA HIGH SPEED ANALYSIS
INPUT SUMMARY,
PROBABILISTIC MODEL

	AVERAGE	STD DEV	UNITS,
TOUCHDOWN LOCATION	1000.	20.	FEET
TOUCHDOWN SPEED	110.	10.	FT/SEC
TIME-TOUCHDOWN TO DECEL	4.	1.	SECONDS
DECELERATION RATE	4.00	.50	FT/SEC**2
50%PROBABILITY SPEED	88.	1.	FT/SEC
DIST:THRESHOLD-START OF TURN	2285.		FEET
SPEED AT MAJOR DECEL REDUCE	90.		FT/SEC
NOSE-WINGTIP DIST	34.		FEET

AIRCRAFT TRACKING PROGRAM

AIRCRAFT CHARACTERISTICS

WEIGHT(LBS)	YAW INERTIA	WHEELBASE	% LOAD ON MAIN GEAR
24000.0	300000.0	23.0	93.0

FLIGHT CONDITIONAL PARAMETERS

EXIT VELOCITY	MAX EXIT ANGLE	MAX Y MU	DECEL RATE
73.075	38.000	.250	-1.500

SYSTEM WIDTHS

RUNWAY	WINGSPAN	CLEAR DIST.	DIST TO TAXIWAY
150.00	36.00	93.00	600.00

SCRUB CHARACTERISTICS

Y MU	RADIUS
.0000	.1E+32
.0230	50.0

CONSTANT NLG SIDE LOAD ANALYSIS

PASSENGER COMFORT IGNORED

TIME	X	Y	THETA	RADIUS	R RATE	MU SCRUB	MU CENT	MU I	G CENT	VELOCITY
.000	.000	.000	.000	100000.00	-3693768.00	.023	.002	.225	.002	73.075
.500	36.349	.046	.206	5415.26	-9568.13	.023	.030	.197	.030	72.324
1.000	72.322	.329	.748	2953.06	-2526.77	.023	.054	.173	.054	71.572
1.500	107.912	1.037	1.581	2102.48	-1143.27	.023	.074	.153	.074	70.821
2.000	143.110	2.329	2.666	1671.65	-648.67	.023	.091	.136	.091	70.069
2.500	177.898	4.334	3.972	1411.37	-417.44	.023	.106	.121	.106	69.318
3.000	212.252	7.161	5.471	1236.98	-291.28	.023	.118	.109	.118	68.566
3.500	246.140	10.896	7.140	1111.80	-215.15	.023	.128	.099	.128	67.815
4.000	279.527	15.608	8.959	1017.36	-165.84	.023	.137	.090	.137	67.063
4.500	312.370	21.353	10.912	943.34	-132.19	.023	.145	.082	.145	66.312
5.000	344.624	28.170	12.982	883.53	-108.28	.023	.151	.076	.151	65.560
5.500	376.238	36.086	15.159	833.98	-90.75	.023	.156	.071	.156	64.809
6.000	407.159	45.118	17.431	792.05	-77.55	.023	.161	.066	.161	64.057
6.500	437.335	55.273	19.790	755.91	-67.40	.023	.165	.062	.165	63.308
7.000	466.710	66.547	22.227	724.27	-59.46	.023	.168	.059	.168	62.558
7.500	495.226	78.929	24.736	696.18	-53.14	.023	.170	.057	.170	61.808
8.000	522.828	92.400	27.312	670.92	-48.06	.023	.173	.054	.173	61.059

FINAL VALUES

8.022	524.021	93.017	27.312	669.86	-47.86	.023	.173	.054	.173	61.026
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CALCULATED RESULTS

CRITICAL VALUES:

ASCSV	ASC	PTIME	CDIST	XDIST	TDIST
73.08	61.03	8.02	2285.00	524.02	2809.02
PROB	AVG TIME	STD DEV	XTIME	TTIME	YA
1.0000	22.6144	2.3934	31.9487	39.9703	88.0000
.9989	22.6391	2.3934	31.9733	39.9949	87.0000

NASA HIGH SPEED ANALYSIS
INPUT SUMMARY,
PROBABILISTIC MODEL

	AVERAGE	STD DEV	UNITS,
TOUCHDOWN LOCATION	1000.	20.	FEET
TOUCHDOWN SPEED	164.	10.	FT/SEC
TIME-TOUCHDOWN TO DECEL	4.	1.	SECONDS
DECELERATION RATE	4.00	.50	FT/SEC**2
50%PROBABILITY SPEED	119.	1.	FT/SEC
DIST:THRESHOLD-START OF TURN	3654.		FEET
SPEED AT MAJOR DECEL REDUCE	155.		FT/SEC
NOSE-WINGTIP DIST	56.		FEET

AIRCRAFT TRACKING PROGRAM

AIRCRAFT CHARACTERISTICS

WEIGHT(LBS)	YAW INERTIA	WHEELBASE	% LOAD ON MAIN GEAR
48000.0	800000.0	36.0	95.0

FLIGHT CONDITIONAL PARAMETERS

EXIT VELOCITY	MAX EXIT ANGLE	MAX Y MU	DECEL RATE
104.461	38.000	.250	-1.500

SYSTEM WIDTHS

RUNWAY	WINGSPAN	CLEAR DIST.	DIST TO TAXIWAY
150.00	49.00	99.50	600.00

SCRUB CHARACTERISTICS

Y MU	RADIUS
.0000	.1E+32
.0230	50.0

CONSTANT NLG SIDE LOAD ANALYSIS

/ PASSENGER CONFORT IGNORED

TIME	X	Y	THETA	RADIUS	R RATE	MU SCRUB	MU CENT	MU I	G CENT	VELOCITY
.000	.000	.000	.000	100000.00	-2196285.00	.023	.003	.224	.003	104.461
.500	52.042	.061	.186	8924.04	-14935.64	.023	.037	.190	.037	103.709
1.000	103.707	.418	.649	5023.10	-4059.80	.023	.066	.161	.066	102.958
1.500	154.990	1.294	1.347	3651.38	-1849.04	.023	.089	.138	.089	102.206
2.000	205.879	2.873	2.242	2954.43	-1048.71	.023	.108	.119	.108	101.455
2.500	256.359	5.306	3.305	2534.31	-672.23	.023	.124	.103	.124	100.703
3.000	306.406	8.713	4.510	2254.25	-466.17	.023	.138	.089	.138	99.952
3.500	355.990	13.193	5.838	2054.63	-341.69	.023	.149	.078	.149	99.200
4.000	405.078	18.824	7.271	1905.25	-261.09	.023	.158	.069	.158	98.449
4.500	453.633	25.668	8.794	1789.23	-206.19	.023	.166	.061	.166	97.697
5.000	501.612	33.772	10.396	1696.36	-167.32	.023	.172	.055	.172	96.946
5.500	548.972	43.169	12.066	1620.14	-138.94	.023	.177	.050	.177	96.194
6.000	595.665	53.882	13.795	1556.21	-117.71	.023	.182	.045	.182	95.443
6.500	641.645	65.927	15.577	1501.57	-101.52	.023	.185	.042	.185	94.691
7.000	686.862	79.308	17.406	1454.07	-88.96	.023	.188	.039	.188	93.940
7.500	731.267	94.024	19.277	1412.15	-79.09	.023	.191	.036	.191	93.188

FINAL VALUES

7.676	746.695	99.520	19.277	1398.50	-76.12	.023	.192	.035	.192	92.924
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CALCULATED RESULTS

CRITICAL VALUES:

ASCSV	ASC	PTIME	CDIST	XDIST	TDIST
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104.46	92.92	7.68	3654.00	746.69	4400.69
PROB	AVG TIME	STD DEV	XTIME	TTIME	YA
1.0000	25.3241	1.7919	32.3124	39.9880	119.0000
.9987	25.3320	1.7919	32.3202	39.9959	118.0000

NASA HIGH SPEED ANALYSIS
 INPUT SUMMARY,
 PROBABILISTIC MODEL

	AVERAGE	STD DEV	UNITS,
TOUCHDOWN LOCATION	1500.	30.	FEET
TOUCHDOWN SPEED	181.	10.	FT/SEC
TIME-TOUCHDOWN TO DECEL	5.	1.	SECONDS
DECELERATION RATE	5.00	.50	FT/SEC**2
50%PROBABILITY SPEED	135.	1.	FT/SEC
DIST:THRESHOLD-START OF TURN	4225.		FEET
SPEED AT MAJOR DECEL REDUCE	155.		FT/SEC
NOSE-WINGTIP DIST	48.		FEET

AIRCRAFT TRACKING PROGRAM

AIRCRAFT CHARACTERISTICS

WEIGHT(LBS)	YAW INERTIA	WHEELBASE	% LOAD ON MAIN GEAR
48000.0	800000.0	36.0	95.0

FLIGHT CONDITIONAL PARAMETERS

EXIT VELOCITY	MAX EXIT ANGLE	MAX Y MU	DECEL RATE
120.669	33.000	.250	-1.750

SYSTEM WIDTHS

RUNWAY	WINGSPAN	CLEAR DIST.	DIST TO TAXIWAY
150.00	85.00	117.50	600.00

SCRUB CHARACTERISTICS

Y MU	RADIUS
.0000	.1E+32
.0250	50.0

CONSTANT NLG SIDE LOAD ANALYSIS

PASSENGER CONFORT IGNORED

TIME	X	Y	THETA	RADIUS	R RATE	MU SCRUB	MU CENT	MU I	G CENT	VELOCITY
.000	.000	.000	.000	100000.00	-1874636.00	.025	.005	.220	.005	120.669
.500	60.116	.072	.187	10415.47	-16929.20	.025	.043	.182	.043	119.795
1.000	119.793	.481	.641	5968.18	-4652.88	.025	.074	.151	.074	118.922
1.500	179.026	1.474	1.314	4394.23	-2123.18	.025	.098	.127	.098	118.048
2.000	237.804	3.245	2.168	3594.17	-1203.11	.025	.119	.106	.119	117.175
2.500	296.109	5.951	3.172	3112.61	-769.61	.025	.135	.090	.135	116.301
3.000	353.918	9.715	4.301	2792.34	-532.40	.025	.148	.077	.148	115.428
3.500	411.201	14.633	5.534	2564.60	-389.34	.025	.159	.066	.159	114.554
4.000	467.926	20.781	6.855	2394.54	-297.00	.025	.168	.057	.168	113.680
4.500	524.055	28.216	8.250	2262.62	-234.38	.025	.175	.050	.175	112.807
5.000	579.551	36.977	9.708	2157.05	-190.28	.025	.180	.045	.180	111.933
5.500	634.371	47.096	11.220	2070.30	-158.30	.025	.185	.040	.185	111.060
6.000	688.473	58.589	12.779	1997.36	-134.57	.025	.189	.036	.189	110.186
6.500	741.813	71.468	14.379	1934.75	-116.63	.025	.192	.033	.192	109.313
7.000	794.346	85.732	16.015	1880.02	-102.85	.025	.194	.031	.194	108.439
7.500	846.029	101.379	17.683	1831.39	-92.12	.025	.196	.029	.196	107.565

FINAL VALUES

7.975	894.298	117.514	17.683	1789.61	-84.05	.025	.198	.027	.198	106.736
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CALCULATED RESULTS

CRITICAL VALUES:

ASCSV	ASC	PTIME	CDIST	XDIST	TDIST
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120.67	106.74	7.97	4225.00	894.30	5119.30
PROB	AVG TIME	STD DEV	XTIME	TTIME	YA
1.0000	25.6212	1.6276	31.9687	39.9433	135.0000
.9987	25.6285	1.6276	31.9760	39.9506	134.0000

GENERIC AIRCRAFT CF

NASA HIGH SPEED ANALYSIS
INPUT SUMMARY,
PROBABILISTIC MODEL

	AVERAGE	STD DEV	UNITS,
TOUCHDOWN LOCATION	1500.	30.	FEET
TOUCHDOWN SPEED	230.	10.	FT/SEC
TIME-TOUCHDOWN TO DECEL	5.	1.	SECONDS
DECELERATION RATE	5.00	.50	FT/SEC**2
50%PROBABILITY SPEED	170.	1.	FT/SEC
DIST:THRESHOLD-START OF TURN	5515.		FEET
SPEED AT MAJOR DECEL REDUCE	175.		FT/SEC
NOSE-WINGTIP DIST	103.		FEET

AIRCRAFT TRACKING PROGRAM

AIRCRAFT CHARACTERISTICS

WEIGHT(LBS)	YAW INERTIA	WHEELBASE	% LOAD ON MAIN GEAR
120000.0	4200000.0	61.0	95.0

FLIGHT CONDITIONAL PARAMETERS

EXIT VELOCITY	MAX EXIT ANGLE	MAX Y MU	DECEL RATE
155.724	39.000	.250	-1.750

SYSTEM WIDTHS

RUNWAY	WINGSPAN	CLEAR DIST.	DIST TO TAXIWAY
150.00	141.00	145.50	600.00

SCRUB CHARACTERISTICS

Y MU	RADIUS
.0000	.1E+32
.0250	50.0

CONSTANT NLG SIDE LOAD ANALYSIS

PASSENGER CONFORT IGNORED

TIME	X	Y	THETA	RADIUS	R RATE	MU SCRUB	MU CENT	MU I	G CENT	VELOCITY
.000	.000	.000	.000	100000.00	-1156104.00	.025	.008	.217	.008	155.724
.500	77.642	.085	.165	15935.32	-24202.22	.025	.047	.178	.047	154.847
1.000	154.844	.540	.542	9414.16	-6995.16	.025	.078	.147	.078	153.969
1.500	231.601	1.615	1.091	7028.21	-3243.73	.025	.104	.121	.104	153.092
2.000	307.904	3.511	1.780	5802.00	-1848.86	.025	.124	.101	.124	152.215
2.500	383.736	6.389	2.586	5061.43	-1183.78	.025	.141	.084	.141	151.337
3.000	459.079	10.375	3.487	4569.22	-817.14	.025	.154	.071	.154	150.460
3.500	533.908	15.568	4.468	4220.36	-594.93	.025	.165	.060	.165	149.582
4.000	608.196	22.046	5.514	3961.23	-451.04	.025	.173	.052	.173	148.705
4.500	681.914	29.871	6.615	3761.59	-353.25	.025	.180	.045	.180	147.828
5.000	755.028	39.086	7.763	3603.12	-284.32	.025	.186	.039	.186	146.950
5.500	827.506	49.726	8.950	3474.08	-234.34	.025	.191	.034	.191	146.073
6.000	899.311	61.813	10.170	3366.60	-197.27	.025	.194	.031	.194	145.196
6.500	970.407	75.363	11.419	3275.26	-169.30	.025	.197	.028	.197	144.318
7.000	1040.760	90.384	12.693	3196.19	-147.87	.025	.200	.025	.200	143.441
7.500	1110.330	106.879	13.990	3126.58	-131.25	.025	.202	.023	.202	142.563
8.000	1179.082	124.843	15.305	3064.33	-118.22	.025	.203	.022	.203	141.686
8.500	1246.979	144.272	16.638	3007.89	-107.92	.025	.205	.020	.205	140.809

FINAL VALUES

8.531 1251.159 145.524 16.638 3004.55 -107.36 .025 .205 .020 .205 140.754

CALCULATED RESULTS

CRITICAL VALUES:

ASCSV	ASC	PTIME	CDIST	XDIST	TDIST
155.72	140.75	8.53	5515.00	1251.16	6766.16
PROB	AVG TIME	STD DEV	XTIME	TTIME	YA
1.0000	26.8287	1.1898	31.4688	39.9996	170.0000
.9986	26.8346	1.1898	31.4747	40.0055	169.0000

GENERIC AIRCRAFT DS

NASA HIGH SPEED ANALYSIS
INPUT SUMMARY,
PROBABILISTIC MODEL

	AVERAGE	STD DEV	UNITS,
TOUCHDOWN LOCATION	1500.	30.	FEET
TOUCHDOWN SPEED	211.	15.	FT/SEC
TIME-TOUCHDOWN TO DECEL	5.	1.	SECONDS
DECELERATION RATE	5.00	.50	FT/SEC**2
50%PROBABILITY SPEED	163.	1.	FT/SEC
DIST:THRESHOLD-START OF TURN	4805.		FEET
SPEED AT MAJOR DECEL REDUCE	175.		FT/SEC
NOSE-WINGTIP DIST	87.		FEET

AIRCRAFT TRACKING PROGRAM

AIRCRAFT CHARACTERISTICS

WEIGHT(LBS)	YAW INERTIA	WHEELBASE	% LOAD ON MAIN GEAR
120000.0	4200000.0	61.0	95.0

FLIGHT CONDITIONAL PARAMETERS

EXIT VELOCITY	MAX EXIT ANGLE	MAX Y MU	DECEL RATE
148.395	37.000	.250	-1.750

SYSTEM WIDTHS

RUNWAY	WINGSPAN	CLEAR DIST.	DIST TO TAXIWAY
150.00	87.00	118.50	600.00

SCRUB CHARACTERISTICS

Y MU	RADIUS
.0000	.1E+32
.0100	5000.0
.0120	2000.0
.0180	1000.0
.0230	500.0
.0300	50.0

CONSTANT NLG SIDE LOAD ANALYSIS

PASSENGER CONFORT IGNORED

TIME	X	Y	THETA	RADIUS	R RATE	MU SCRUB	MU CENT	MU I	G CENT	VELOCITY
.000	.000	.000	.000	100000.00	-1300748.00	.010	.007	.233	.007	148.395
.500	73.978	.084	.172	14358.77	-22323.09	.010	.047	.193	.047	147.517
1.000	147.515	.540	.573	8385.23	-6365.42	.010	.080	.160	.080	146.640
1.500	220.607	1.627	1.162	6218.46	-2940.53	.010	.106	.134	.106	145.763
2.000	293.242	3.556	1.906	5107.44	-1674.74	.010	.128	.112	.128	144.885
2.500	365.404	6.494	2.779	4437.40	-1069.52	.010	.145	.094	.145	144.008
3.000	437.072	10.576	3.759	3992.93	-737.65	.011	.159	.080	.159	143.130
3.500	508.217	15.906	4.827	3677.96	-537.30	.011	.171	.068	.171	142.253
4.000	578.808	22.568	5.970	3443.81	-407.81	.011	.180	.059	.180	141.376
4.500	648.813	30.626	7.176	3263.19	-319.85	.011	.188	.051	.188	140.498
5.000	718.193	40.129	8.434	3119.59	-257.83	.011	.194	.045	.194	139.621
5.500	786.910	51.111	9.738	3002.49	-212.80	.011	.199	.040	.199	138.744
6.000	854.924	63.599	11.080	2904.84	-179.35	.011	.203	.035	.203	137.866
6.500	922.193	77.606	12.455	2821.76	-154.04	.011	.207	.032	.207	136.989
7.000	988.674	93.142	13.860	2749.80	-134.59	.012	.209	.029	.209	136.111
7.500	1054.327	110.207	15.290	2686.43	-119.46	.012	.211	.027	.211	135.234

FINAL VALUES

7.729 1084.107 118.533 15.290 2659.75 -113.66 .012 .212 .026 .212 134.832

CALCULATED RESULTS

CRITICAL VALUES:

ASCSV	ASC	PTIME	CDIST	XDIST	TDIST
148.39	134.83	7.73	4805.00	1084.11	5889.11
PROB	AVG TIME	STD DEV	XTIME	TTIME	YA
.9999	25.0418	1.8425	32.2276	39.9562	163.0000

GENERIC AIRCRAFT DF

NASA HIGH SPEED ANALYSIS
INPUT SUMMARY,
PROBABILISTIC MODEL

	AVERAGE	STD DEV	UNITS,
TOUCHDOWN LOCATION	1500.	30.	FEET
TOUCHDOWN SPEED	260.	15.	FT/SEC
TIME-TOUCHDOWN TO DECEL	5.	1.	SECONDS
DECELERATION RATE	5.00	.50	FT/SEC**2
50%PROBABILITY SPEED	207.	1.	FT/SEC
DIST:THRESHOLD-START OF TURN	5860.		FEET
SPEED AT MAJOR DECEL REDUCE	225.		FT/SEC
NOSE-WINGTIP DIST	150.		FEET

AIRCRAFT TRACKING PROGRAM

AIRCRAFT CHARACTERISTICS

WEIGHT(LBS)	YAW INERTIA	WHEELBASE	% LOAD ON MAIN GEAR
400000.0	40000000.0	84.0	96.0

FLIGHT CONDITIONAL PARAMETERS

EXIT VELOCITY	MAX EXIT ANGLE	MAX Y MU	DECEL RATE
192.354	45.000	.250	-1.750

SYSTEM WIDTHS

RUNWAY	WINGSPAN	CLEAR DIST.	DIST TO TAXIWAY
150.00	207.00	178.50	600.00

SCRUB CHARACTERISTICS

Y MU	RADIUS
.0000	.1E+32
.0100	5287.0
.0190	2638.0
.0390	1318.0
.0590	877.0
.0790	657.0
.0990	534.0

CONSTANT NLG SIDE LOAD ANALYSIS

PASSENGER CONFORT IGNORED

TIME	X	Y	THETA	RADIUS	R RATE	MU SCRUB	MU CENT	MU I	G CENT	VELOCITY
.000	.000	.000	.000	100000.00	-383189.50	.010	.011	.229	.011	192.354
.500	95.957	.075	.106	35269.88	-43528.70	.010	.032	.208	.032	191.476
1.000	191.475	.406	.308	22170.15	-15730.62	.010	.051	.189	.051	190.599
1.500	286.552	1.144	.596	16546.72	-8027.21	.010	.068	.172	.068	189.722
2.000	381.184	2.419	.962	13425.20	-4848.87	.010	.082	.158	.082	188.844
2.500	475.367	4.349	1.399	11442.87	-3238.13	.010	.096	.144	.096	187.967
3.000	569.091	7.040	1.901	10074.32	-2311.48	.010	.108	.132	.108	187.090
3.500	662.349	10.583	2.461	9073.95	-1730.38	.010	.119	.121	.119	186.212
4.000	755.127	15.060	3.075	8311.63	-1342.49	.010	.128	.112	.128	185.335
4.500	847.411	20.545	3.737	7711.91	-1071.04	.010	.137	.103	.137	184.457
5.000	939.185	27.101	4.444	7228.07	-873.90	.010	.145	.095	.145	183.580
5.500	1030.432	34.784	5.191	6829.61	-726.42	.010	.152	.088	.152	182.703
6.000	1121.131	43.644	5.975	6495.80	-613.37	.010	.158	.082	.158	181.825
6.500	1211.261	53.723	6.794	6212.05	-524.95	.010	.164	.076	.164	180.948
7.000	1300.800	65.058	7.643	5967.77	-454.61	.010	.169	.071	.169	180.071
7.500	1389.724	77.680	8.522	5755.12	-397.83	.010	.173	.067	.173	179.193
8.000	1478.006	91.617	9.427	5568.17	-351.42	.010	.177	.063	.177	178.316

8.500	1565.622	106.889	10.356	5402.32	-313.07	.010	.181	.059	.181	177.438
9.000	1652.544	123.516	11.308	5254.04	-280.52	.010	.184	.056	.184	176.561
9.500	1738.746	141.510	12.281	5121.19	-251.68	.011	.187	.052	.187	175.684
10.000	1824.198	160.884	13.273	5001.55	-227.53	.011	.190	.049	.190	174.806
FINAL VALUES										
10.428	1896.560	178.525	13.273	4908.23	-209.93	.011	.192	.047	.192	174.057

CALCULATED RESULTS

CRITICAL VALUES:

ASCSV	ASC	PTIME	CDIST	XDIST	TDIST
192.35	174.06	10.43	5860.00	1896.56	7756.56
PROB	AVG TIME	STD DEV	XTIME	TTIME	YA
.9999	24.8770	1.1902	29.5186	39.9462	207.0000

GENERIC AIRCRAFT WIDE BODY

NASA HIGH SPEED ANALYSIS
INPUT SUMMARY,
PROBABILISTIC MODEL

	AVERAGE	STD DEV	UNITS,
TOUCHDOWN LOCATION	1500.	30.	FEET
TOUCHDOWN SPEED	230.	10.	FT/SEC
TIME-TOUCHDOWN TO DECEL	5.	1.	SECONDS
DECELERATION RATE	5.00	1.00	FT/SEC**2
50%PROBABILITY SPEED	181.	1.	FT/SEC
DIST:THRESHOLD-START OF TURN	5170.		FEET
SPEED AT MAJOR DECEL REDUCE	190.		FT/SEC
NOSE-WINGTIP DIST	130.		FEET

AIRCRAFT TRACKING PROGRAM

AIRCRAFT CHARACTERISTICS

WEIGHT(LBS)	YAW INERTIA	WHEELBASE	% LOAD ON MAIN GEAR
400000.0	40000000.0	84.0	96.0

FLIGHT CONDITIONAL PARAMETERS

EXIT VELOCITY	MAX EXIT ANGLE	MAX Y MU	DECEL RATE
166.433	45.000	.250	-2.000

SYSTEM WIDTHS

RUNWAY	WINGSPAN	CLEAR DIST.	DIST TO TAXIWAY
150.00	207.00	178.50	600.00

SCRUB CHARACTERISTICS

Y MU	RADIUS
.0000	.1E+32
.0100	5287.0
.0190	2638.0
.0390	1318.0
.0590	877.0
.0790	657.0
.0990	534.0

CONSTANT NLG SIDE LOAD ANALYSIS

PASSENGER CONFORT IGNORED

TIME	X	Y	THETA	RADIUS	R RATE	MU SCRUB	MU CENT	MU I	G CENT	VELOCITY
.000	.000	.000	.000	100000.00	-448465.80	.010	.009	.231	.009	166.433
.500	82.966	.059	.099	31607.94	-41512.79	.010	.027	.213	.027	165.434
1.000	165.432	.333	.297	19351.20	-14442.17	.010	.043	.197	.043	164.434
1.500	247.397	.952	.584	14227.78	-7259.16	.010	.058	.182	.058	163.435
2.000	328.856	2.034	.952	11415.50	-4353.06	.010	.072	.168	.072	162.435
2.500	409.807	3.684	1.397	9639.21	-2896.76	.010	.084	.156	.084	161.436
3.000	490.241	5.996	1.910	8415.88	-2065.01	.010	.095	.145	.095	160.436
3.500	570.149	9.056	2.487	7522.24	-1546.02	.010	.105	.135	.105	159.437
4.000	649.522	12.936	3.123	6840.82	-1200.82	.010	.114	.126	.114	158.438
4.500	728.346	17.705	3.812	6303.92	-959.84	.010	.122	.118	.122	157.438
5.000	806.606	23.421	4.552	5869.80	-785.14	.010	.129	.111	.129	156.439
5.500	884.285	30.135	5.338	5511.31	-654.60	.010	.136	.104	.136	155.439
6.000	961.364	37.893	6.167	5210.12	-553.16	.010	.142	.098	.142	154.440
6.500	1037.823	46.735	7.035	4954.85	-471.22	.011	.148	.091	.148	153.440
7.000	1113.641	56.694	7.940	4735.91	-406.92	.012	.152	.086	.152	152.441
7.500	1188.794	67.799	8.878	4545.72	-355.60	.013	.157	.081	.157	151.441
8.000	1263.259	80.072	9.848	4378.65	-314.02	.013	.161	.076	.161	150.442

8.500	1337.010	93.533	10.846	4230.42	-279.91	.014	.164	.072	.164	149.443
9.000	1410.022	108.195	11.871	4097.75	-251.61	.014	.167	.069	.167	148.443
9.500	1482.269	124.069	12.921	3978.02	-227.91	.014	.170	.066	.170	147.444
10.000	1553.723	141.164	13.994	3869.20	-207.90	.015	.172	.063	.172	146.444
10.501	1624.357	159.481	15.089	3769.61	-190.87	.015	.174	.061	.174	145.445
FINAL VALUES										
10.989	1692.479	178.540	15.089	3680.03	-176.60	.015	.176	.058	.176	144.469

CALCULATED RESULTS

CRITICAL VALUES:

ASCSV	ASC	PTIME	CDIST	XDIST	TDIST
166.43	144.47	10.99	5170.00	1692.48	6862.48
PROB	AVG TIME	STD DEV	XTIME	TTIME	YA
.9999	24.7989	.9884	28.6537	39.6425	181.0000

NASA HIGH SPEED ANALYSIS
INPUT SUMMARY,
PROBABILISTIC MODEL

	AVERAGE	STD DEV	UNITS,
TOUCHDOWN LOCATION	1500.	30.	FEET
TOUCHDOWN SPEED	370.	25.	FT/SEC
TIME-TOUCHDOWN TO DECEL	5.	1.	SECONDS
DECELERATION RATE	6.00	2.00	FT/SEC**2
50%PROBABILITY SPEED	292.	1.	FT/SEC
DIST:THRESHOLD-START OF TURN	8400.		FEET
SPEED AT MAJOR DECEL REDUCE	150.		FT/SEC
NOSE-WINGTIP DIST	35.		FEET

AIRCRAFT TRACKING PROGRAM

AIRCRAFT CHARACTERISTICS

WEIGHT(LBS)	YAW INERTIA	WHEELBASE	% LOAD ON MAIN GEAR
22000.0	137776.0	15.0	92.3

FLIGHT CONDITIONAL PARAMETERS

EXIT VELOCITY	MAX EXIT ANGLE	MAX Y MU	DECEL RATE
276.225	20.000	.200	-2.000

SYSTEM WIDTHS

RUNWAY	WINGSPAN	CLEAR DIST.	DIST TO TAXIWAY
150.00	21.90	85.95	600.00

SCRUB CHARACTERISTICS

Y MU	RADIUS
.0000	.1E+32
.0200	50.0

CONSTANT NLG SIDE LOAD ANALYSIS

PASSENGER CONFORT IGNORED

TIME	X	Y	THETA	RADIUS	R RATE	MU SCRUB	MU CENT	MU I	G CENT	VELOCITY
.000	.000	.000	.000	100000.00	-963255.40	.020	.024	.156	.024	276.225
.500	137.860	.223	.231	22530.26	-23733.96	.020	.104	.076	.104	275.217
1.000	275.212	1.256	.654	16352.71	-6175.82	.020	.143	.037	.143	274.210
1.500	412.047	3.419	1.170	14383.35	-2428.62	.020	.161	.019	.161	273.203
2.000	548.353	6.862	1.731	13537.84	-1150.20	.020	.170	.010	.170	272.196
2.500	684.114	11.655	2.316	13111.48	-626.37	.020	.174	.006	.174	271.189
3.000	819.314	17.827	2.914	12864.03	-393.05	.020	.176	.004	.176	270.182
3.500	953.940	25.389	3.519	12697.89	-284.74	.020	.177	.003	.177	269.175
4.000	1087.976	34.344	4.128	12569.92	-233.25	.020	.178	.002	.178	268.168
4.500	1221.406	44.689	4.741	12460.26	-208.30	.020	.178	.002	.178	267.161
5.000	1354.217	56.419	5.356	12359.55	-195.94	.020	.178	.002	.178	266.154
5.500	1486.393	69.529	5.974	12263.33	-189.63	.020	.178	.002	.178	265.147
6.000	1617.918	84.012	6.595	12169.46	-186.20	.020	.178	.002	.178	264.140

FINAL VALUES

6.064	1634.705	85.965	6.595	12157.56	-185.88	.020	.178	.002	.178	264.011
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CALCULATED RESULTS

CRITICAL VALUES:

ASCSV	ASC	PTIME	CDIST	XDIST	TDIST
276.22	264.01	6.06	8400.00	1634.71	10034.71
PROB	AVG TIME	STD DEV	XTIME	TTIME	YA
1.0000	24.7617	2.3551	33.9466	40.0104	292.0000
.9999	24.7617	2.3551	33.9466	40.0104	291.0000

BUNCHING OF OPTIMAL EXIT LOCATIONS

GENERIC AIRCRAFT AF

NASA HIGH SPEED ANALYSIS
INPUT SUMMARY,
PROBABILISTIC MODEL

	AVERAGE	STD DEV	UNITS,
TOUCHDOWN LOCATION	500.	10.	FEET
TOUCHDOWN SPEED	118.	5.	FT/SEC
TIME-TOUCHDOWN TO DECEL	3.	1.	SECONDS
DECELERATION RATE	2.50	1.00	FT/SEC**2
50%PROBABILITY SPEED	97.	1.	FT/SEC
DIST:THRESHOLD-START OF TURN	2285.		FEET
SPEED AT MAJOR DECEL REDUCE	55.		FT/SEC
NOSE-WINGTIP DIST	40.		FEET

AIRCRAFT TRACKING PROGRAM

AIRCRAFT CHARACTERISTICS

WEIGHT(LBS)	YAW INERTIA	WHEELBASE	% LOAD ON MAIN GEAR
24000.0	300000.0	23.0	93.0

FLIGHT CONDITIONAL PARAMETERS

EXIT VELOCITY	MAX EXIT ANGLE	MAX Y MU	DECEL RATE
82.274	41.000	.250	-2.000

SYSTEM WIDTHS

RUNWAY	WINGSPAN	CLEAR DIST.	DIST TO TAXIWAY
150.00	42.00	96.00	600.00

SCRUB CHARACTERISTICS

Y MU	RADIUS
.0000	.1E+32
.0200	50.0

CONSTANT NLG SIDE LOAD ANALYSIS

/ PASSENGER CONFORT IGNORED

TIME	X	Y	THETA	RADIUS	R RATE	MU SCRUB	MU CENT	MU I	G CENT	VELOCITY
.000	.000	.000	.000	100000.00	-3318003.00	.020	.002	.228	.002	82.274
.500	40.887	.053	.210	6033.73	-10516.58	.020	.034	.196	.034	81.274
1.000	81.272	.373	.753	3320.30	-2792.04	.020	.060	.170	.060	80.275
1.500	121.151	1.169	1.579	2379.48	-1265.95	.020	.082	.148	.082	79.276
2.000	160.511	2.608	2.649	1902.06	-719.49	.020	.100	.130	.100	78.276
2.500	199.335	4.825	3.927	1613.10	-463.97	.020	.115	.115	.115	77.277
3.000	237.596	7.929	5.384	1419.03	-324.65	.020	.127	.103	.127	76.277
3.500	275.263	12.005	6.999	1279.28	-240.71	.020	.138	.092	.138	75.278
4.000	312.299	17.118	8.750	1173.38	-186.45	.020	.146	.084	.146	74.278
4.500	348.662	23.315	10.620	1089.92	-149.51	.020	.153	.077	.153	73.279
5.000	384.307	30.629	12.597	1022.05	-123.35	.020	.159	.071	.159	72.279
5.500	419.185	39.081	14.668	965.39	-104.23	.020	.163	.067	.163	71.280
6.000	453.246	48.678	16.824	917.01	-89.89	.020	.167	.063	.167	70.281
6.500	486.439	59.418	19.057	874.92	-78.91	.020	.170	.060	.170	69.281
7.000	518.713	71.290	21.359	837.69	-70.35	.020	.173	.057	.173	68.282
7.500	550.014	84.276	23.725	804.27	-63.57	.020	.175	.055	.175	67.282
FINAL VALUES										
7.920	575.518	96.025	23.725	778.57	-58.91	.020	.176	.054	.176	66.443

CALCULATED RESULTS

CRITICAL VALUES:

ASCSV	ASC	PTIME	CDIST	XDIST	TDIST
82.27	66.44	7.92	2285.00	575.52	2860.52
PROB	AVG TIME	STD DEV	XTIME	TTIME	YA
1.0000	21.8697	1.6699	28.3822	36.3018	97.0000
.9985	21.8781	1.6699	28.3905	36.3101	96.0000

NASA HIGH SPEED ANALYSIS
 INPUT SUMMARY,
 PROBABILISTIC MODEL

	AVERAGE	STD DEV	UNITS,
TOUCHDOWN LOCATION	1000.	20.	FEET
TOUCHDOWN SPEED	110.	10.	FT/SEC
TIME-TOUCHDOWN TO DECEL	4.	1.	SECONDS
DECELERATION RATE	3.50	.50	FT/SEC**2
50%PROBABILITY SPEED	93.	1.	FT/SEC
DIST:THRESHOLD-START OF TURN	2285.		FEET
SPEED AT MAJOR DECEL REDUCE	90.		FT/SEC
NOSE-WINGTIP DIST	34.		FEET

AIRCRAFT TRACKING PROGRAM

AIRCRAFT CHARACTERISTICS

WEIGHT(LBS)	YAM INERTIA	WHEELBASE	% LOAD ON MAIN GEAR
24000.0	300000.0	23.0	93.0

FLIGHT CONDITIONAL PARAMETERS

EXIT VELOCITY	MAX EXIT ANGLE	MAX Y MU	DECEL RATE
78.645	38.000	.250	-1.500

SYSTEM WIDTHS

RUNWAY	WINGSPAN	CLEAR DIST.	DIST TO TAXIWAY
150.00	36.00	93.00	600.00

SCRUB CHARACTERISTICS

Y MU	RADIUS
.0000	.1E+32
.0230	50.0

/ PASSENGER CONFORT IGNORED

TIME	X	Y	THETA	RADIUS	R RATE	MU SCRUB	MU CENT	MU I	G CENT	VELOCITY
.000	.000	.000	.000	100000.00	-3428186.00	.023	.002	.225	.002	78.645
.500	39.134	.050	.207	5841.02	-10217.21	.023	.032	.195	.032	77.893
1.000	77.891	.354	.746	3207.63	-2706.14	.023	.058	.169	.058	77.142
1.500	116.266	1.114	1.570	2296.50	-1224.64	.023	.079	.148	.079	76.390
2.000	154.247	2.496	2.639	1835.14	-694.29	.023	.097	.130	.097	75.639
2.500	191.816	4.637	3.921	1556.71	-446.23	.023	.112	.115	.112	74.887
3.000	228.949	7.649	5.387	1370.43	-310.88	.023	.125	.102	.125	74.136
3.500	265.613	11.622	7.013	1236.93	-229.24	.023	.135	.092	.135	73.384
4.000	301.770	16.627	8.779	1136.39	-176.40	.023	.144	.083	.144	72.633
4.500	337.379	22.721	10.669	1057.72	-140.37	.023	.152	.075	.152	71.881
5.000	372.392	29.945	12.668	994.26	-114.81	.023	.158	.069	.158	71.130
5.500	406.760	38.326	14.764	941.75	-96.10	.023	.163	.064	.163	70.378
6.000	440.429	47.881	16.947	897.37	-82.05	.023	.168	.059	.168	69.627
6.500	473.345	58.619	19.207	859.15	-71.28	.023	.171	.056	.171	68.875
7.000	505.452	70.535	21.538	825.69	-62.87	.023	.175	.052	.175	68.124
7.500	536.694	83.620	23.932	795.98	-56.22	.023	.177	.050	.177	67.372

FINAL VALUES

7.834	557.053	93.003	23.932	777.83	-52.52	.023	.179	.048	.179	66.870
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CALCULATED RESULTS

CRITICAL VALUES:

ASCSV	ASC	PTIME	CDIST	XDIST	TDIST
78.64	66.87	7.83	2285.00	557.05	2842.05
PROB	AVG TIME	STD DEV	XTIME	TTIME	YA

1.0000	22.3429	2.2708	31.1991	39.0327	93.0000
.9988	22.3605	2.2708	31.2167	39.0503	92.0000

NASA HIGH SPEED ANALYSIS
 INPUT SUMMARY,
 PROBABILISTIC MODEL

	AVERAGE	STD DEV	UNITS,
TOUCHDOWN LOCATION	1000.	20.	FEET
TOUCHDOWN SPEED	164.	10.	FT/SEC
TIME-TOUCHDOWN TO DECEL	4.	1.	SECONDS
DECELERATION RATE	1.00	.50	FT/SEC**2
50%PROBABILITY SPEED	166.	1.	FT/SEC
DIST:THRESHOLD-START OF TURN	3654.		FEET
SPEED AT MAJOR DECEL REDUCE	155.		FT/SEC
NOSE-WINGTIP DIST	56.		FEET

AIRCRAFT TRACKING PROGRAM

AIRCRAFT CHARACTERISTICS

WEIGHT(LBS)	YAW INERTIA	WHEELBASE	% LOAD ON MAIN GEAR
48000.0	800000.0	36.0	95.0

FLIGHT CONDITIONAL PARAMETERS

EXIT VELOCITY	MAX EXIT ANGLE	MAX Y MU	DECEL RATE
151.327	38.000	.250	-1.500

SYSTEM WIDTHS

RUNWAY	WINGSPAN	CLEAR DIST.	DIST TO TAXIWAY
150.00	49.00	99.50	600.00

SCRUB CHARACTERISTICS

Y MU	RADIUS
.0000	.1E+32
.0230	50.0

CONSTANT NLG SIDE LOAD ANALYSIS

/ PASSENGER CONFORT IGNORED

TIME	X	Y	THETA	RADIUS	R RATE	MU SCRUB	MU CENT	MU I	G CENT	VELOCITY
.000	.000	.000	.000	100000.00	-1490842.00	.023	.007	.220	.007	151.327
.500	75.476	.095	.193	13038.13	-20037.16	.023	.054	.173	.054	150.580
1.000	150.577	.616	.640	7728.14	-5594.11	.023	.090	.137	.090	149.832
1.500	225.295	1.853	1.287	5835.79	-2548.16	.023	.118	.109	.118	149.084
2.000	299.618	4.028	2.091	4878.94	-1431.42	.023	.140	.087	.140	148.337
2.500	373.525	7.313	3.019	4309.25	-903.87	.023	.157	.070	.157	147.589
3.000	446.992	11.837	4.046	3935.83	-615.44	.023	.170	.057	.170	146.841
3.500	519.989	17.699	5.151	3674.74	-442.15	.023	.180	.047	.180	146.094
4.000	592.484	24.972	6.319	3483.30	-331.06	.023	.188	.039	.188	145.346
4.500	664.440	33.709	7.538	3337.56	-256.45	.023	.195	.032	.195	144.598
5.000	735.819	43.948	8.799	3223.04	-204.57	.023	.199	.028	.199	143.851
5.500	806.584	55.716	10.093	3130.49	-167.54	.023	.203	.024	.203	143.103
6.000	876.694	69.027	11.416	3053.80	-140.56	.023	.206	.021	.206	142.355
6.500	946.109	83.890	12.763	2988.74	-120.59	.023	.208	.019	.208	141.608
FINAL VALUES										
6.977	1011.647	99.517	12.763	2934.80	-106.22	.023	.210	.017	.210	140.894

CALCULATED RESULTS

CRITICAL VALUES:

ASCSV	ASC	PTIME	CDIST	XDIST	TDIST
151.33	140.89	6.98	3654.00	1011.65	4665.65
PROB	AVG TIME	STD DEV	XTIME	YTIME	YA
1.0000	23.1106	1.2630	28.0362	35.0128	166.0000

.9988 23.1154 1.2630 28.0410 35.0177 165.0000

GENERIC AIRCRAFT BF

NASA HIGH SPEED ANALYSIS
INPUT SUMMARY,
PROBABILISTIC MODEL

	AVERAGE	STD DEV	UNITS,
TOUCHDOWN LOCATION	1000.	20.	FEET
TOUCHDOWN SPEED	164.	10.	FT/SEC
TIME-TOUCHDOWN TO DECEL	4.	1.	SECONDS
DECELERATION RATE	2.00	.50	FT/SEC**2
50%PROBABILITY SPEED	152.	1.	FT/SEC
DIST:THRESHOLD-START OF TURN	3654.		FEET
SPEED AT MAJOR DECEL REDUCE	155.		FT/SEC
NOSE-WINGTIP DIST	56.		FEET

AIRCRAFT TRACKING PROGRAM

AIRCRAFT CHARACTERISTICS

WEIGHT(LBS)	YAW INERTIA	WHEELBASE	% LOAD ON MAIN GEAR
48000.0	800000.0	36.0	95.0

FLIGHT CONDITIONAL PARAMETERS

EXIT VELOCITY	MAX EXIT ANGLE	MAX Y MU	DECEL RATE
137.492	38.000	.250	-1.500

SYSTEM WIDTHS

RUNWAY	WINGSPAN	CLEAR DIST.	DIST TO TAXIWAY
150.00	49.00	99.50	600.00

SCRUB CHARACTERISTICS

Y MU	RADIUS
.0000	.1E+32
.0230	50.0

CONSTANT NLG SIDE LOAD ANALYSIS

/ PASSENGER CONFORT IGNORED

TIME	X	Y	THETA	RADIUS	R RATE	MU SCRUB	MU CENT	MU I	G CENT	VELOCITY
.000	.000	.000	.000	100000.00	-1650124.00	.023	.006	.221	.006	137.492
.500	68.559	.085	.191	11814.30	-18625.16	.023	.049	.178	.049	136.744
1.000	136.742	.557	.643	6898.81	-5161.22	.023	.083	.144	.083	135.996
1.500	204.543	1.690	1.305	5153.14	-2352.08	.023	.110	.117	.110	135.249
2.000	271.949	3.697	2.134	4268.69	-1325.86	.023	.132	.095	.132	134.501
2.500	338.942	6.746	3.100	3739.82	-841.55	.023	.149	.078	.149	133.753
3.000	405.497	10.966	4.176	3391.16	-576.54	.023	.162	.065	.162	133.006
3.500	471.584	16.457	5.341	3145.80	-416.97	.023	.173	.054	.173	132.258
4.000	537.169	23.296	6.580	2964.71	-314.28	.023	.181	.046	.181	131.510
4.500	602.215	31.540	7.879	2825.94	-244.94	.023	.188	.039	.188	130.763
5.000	666.684	41.229	9.228	2716.27	-196.40	.023	.193	.034	.193	130.015
5.500	730.534	52.393	10.618	2627.24	-161.48	.023	.198	.029	.198	129.267
6.000	793.723	65.050	12.045	2553.23	-135.80	.023	.201	.026	.201	128.520
6.500	856.209	79.210	13.501	2490.35	-116.60	.023	.204	.023	.204	127.771
7.000	917.948	94.876	14.983	2435.83	-102.08	.023	.206	.021	.206	127.019

FINAL VALUES

7.140	935.095	99.532	14.983	2421.78	-98.66	.023	.206	.021	.206	126.809
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CALCULATED RESULTS

CRITICAL VALUES:

ASCSV	ASC	PTIME	CDIST	XDIST	TDIST
137.49	126.81	7.14	3654.00	935.10	4589.10
PROB	AVG TIME	STD DEV	XTIME	TTIME	YA

1.0000	23.6943	1.3833	29.0890	36.2287	152.0000
.9988	23.7003	1.3833	29.0950	36.2347	151.0000

GENERIC AIRCRAFT CS

NASA HIGH SPEED ANALYSIS
INPUT SUMMARY,
PROBABILISTIC MODEL

	AVERAGE	STD DEV	UNITS,
TOUCHDOWN LOCATION	1500.	30.	FEET
TOUCHDOWN SPEED	181.	10.	FT/SEC
TIME-TOUCHDOWN TO DECEL	5.	1.	SECONDS
DECELERATION RATE	5.00	.50	FT/SEC**2
50%PROBABILITY SPEED	157.	1.	FT/SEC
DIST:THRESHOLD-START OF TURN	3654.		FEET
SPEED AT MAJOR DECEL REDUCE	155.		FT/SEC
NOSE-WINGTIP DIST	48.		FEET

AIRCRAFT TRACKING PROGRAM

AIRCRAFT CHARACTERISTICS

WEIGHT(LBS)	YAW INERTIA	WHEELBASE	% LOAD ON MAIN GEAR
48000.0	800000.0	36.0	95.0

FLIGHT CONDITIONAL PARAMETERS

EXIT VELOCITY	MAX EXIT ANGLE	MAX Y MU	DECEL RATE
142.376	33.000	.250	-1.750

SYSTEM WIDTHS

RUNWAY	WINGSPAN	CLEAR DIST.	DIST TO TAXIWAY
150.00	85.00	117.50	600.00

SCRUB CHARACTERISTICS

Y MU	RADIUS
.0000	.1E+32
.0250	50.0

CONSTANT NLG SIDE LOAD ANALYSIS

/ PASSENGER CONFORT IGNORED

TIME	X	Y	THETA	RADIUS	R RATE	MU SCRUB	MU CENT	MU I	G CENT	VELOCITY
.000	.000	.000	.000	100000.00	-1576042.00	.025	.006	.219	.006	142.376
.500	70.968	.088	.190	12337.53	-19270.68	.025	.050	.175	.050	141.499
1.000	141.496	.573	.637	7240.80	-5362.63	.025	.085	.140	.085	140.622
1.500	211.577	1.729	1.287	5425.76	-2447.22	.025	.112	.113	.112	139.744
2.000	281.199	3.772	2.100	4505.18	-1380.65	.025	.133	.092	.133	138.867
2.500	350.343	6.864	3.043	3954.21	-877.21	.025	.150	.075	.150	137.989
3.000	418.984	11.132	4.092	3590.54	-601.92	.025	.163	.062	.163	137.112
3.500	487.094	16.672	5.225	3334.12	-436.36	.025	.173	.052	.173	136.235
4.000	554.641	23.557	6.428	3144.30	-330.03	.025	.181	.044	.181	135.357
4.500	621.588	31.838	7.688	2998.27	-258.42	.025	.187	.038	.187	134.480
5.000	687.898	41.554	8.995	2882.24	-208.43	.025	.192	.033	.192	133.602
5.500	753.533	52.730	10.341	2787.45	-172.59	.025	.196	.029	.196	132.725
6.000	818.454	65.381	11.721	2708.03	-146.33	.025	.199	.026	.199	131.848
6.500	882.618	79.513	13.129	2639.99	-126.75	.025	.202	.023	.202	130.970
7.000	945.987	95.127	14.562	2580.47	-111.95	.025	.204	.021	.204	130.093
7.500	1008.518	112.217	16.017	2527.44	-100.63	.025	.205	.020	.205	129.216

FINAL VALUES

7.647	1026.737	117.521	16.017	2512.86	-97.83	.025	.206	.019	.206	128.958
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CALCULATED RESULTS

CRITICAL VALUES:

ASCSV	ASC	PTIME	CDIST	XDIST	TDIST
142.38	128.96	7.65	3654.00	1026.74	4680.74

PROB	AVG TIME	STD DEV	XTIME	TTIME	YA
1.0000	21.2768	1.1700	25.8397	33.4863	157.0000
.9988	21.2816	1.1700	25.8445	33.4911	156.0000

GENERIC AIRCRAFT CF

NASA HIGH SPEED ANALYSIS
INPUT SUMMARY,
PROBABILISTIC MODEL

	AVERAGE	STD DEV	UNITS,
TOUCHDOWN LOCATION	1500.	30.	FEET
TOUCHDOWN SPEED	230.	10.	FT/SEC
TIME-TOUCHDOWN TO DECEL	5.	1.	SECONDS
DECELERATION RATE	.50	.50	FT/SEC**2
50%PROBABILITY SPEED	237.	1.	FT/SEC
DIST:THRESHOLD-START OF TURN	5860.		FEET
SPEED AT MAJOR DECEL REDUCE	175.		FT/SEC
NOSE-WINGTIP DIST	103.		FEET

AIRCRAFT TRACKING PROGRAM

AIRCRAFT CHARACTERISTICS

WEIGHT(LBS)	YAW INERTIA	WHEELBASE	% LOAD ON MAIN GEAR
120000.0	4200000.0	61.0	95.0

FLIGHT CONDITIONAL PARAMETERS

EXIT VELOCITY	MAX EXIT ANGLE	MAX Y MU	DECEL RATE
222.913	39.000	.250	-.500

SYSTEM WIDTHS

RUNWAY	WINGSPAN	CLEAR DIST.	DIST TO TAXIWAY
150.00	141.00	145.50	600.00

SCRUB CHARACTERISTICS

Y MU	RADIUS
.0000	.1E+32
.0250	50.0

CONSTANT NLG SIDE LOAD ANALYSIS

PASSENGER CONFORT IGNORED

TIME	X	Y	THETA	RADIUS	R RATE	MU SCRUB	MU CENT	MU I	G CENT	VELOCITY
.000	.000	.000	.000	100000.00	-778299.10	.025	.015	.210	.015	222.913
.500	111.393	.137	.177	22749.25	-30271.10	.025	.068	.157	.068	222.661
1.000	222.658	.809	.542	14399.43	-9131.32	.025	.107	.118	.107	222.409
1.500	333.789	2.331	1.048	11280.89	-4226.77	.025	.136	.089	.136	222.157
2.000	444.773	4.939	1.660	9696.01	-2359.71	.025	.158	.067	.158	221.905
2.500	555.595	8.808	2.352	8764.52	-1460.72	.025	.174	.051	.174	221.654
3.000	666.232	14.070	3.104	8169.12	-964.41	.025	.186	.039	.186	221.402
3.500	776.663	20.820	3.901	7767.39	-665.27	.025	.196	.029	.196	221.150
4.000	886.861	29.131	4.732	7485.87	-473.88	.025	.202	.023	.202	220.898
4.500	996.800	39.054	5.589	7282.84	-346.17	.025	.208	.017	.208	220.647
5.000	1106.450	50.627	6.466	7133.00	-258.34	.025	.211	.014	.211	220.395
5.500	1215.784	63.876	7.358	7020.12	-196.58	.025	.214	.011	.214	220.143
6.000	1324.771	78.821	8.261	6933.44	-152.45	.025	.217	.008	.217	219.891
6.500	1433.384	95.472	9.174	6865.60	-120.53	.025	.218	.007	.218	219.640
7.000	1541.592	113.838	10.094	6811.45	-97.22	.025	.219	.006	.219	219.388
7.500	1649.366	133.920	11.019	6767.33	-80.09	.025	.220	.005	.220	219.136

FINAL VALUES

7.771	1707.589	145.522	11.019	6746.64	-72.76	.025	.221	.004	.221	219.000
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CALCULATED RESULTS

CRITICAL VALUES:

ASCSV	ASC	PTIME	CDIST	XDIST	TDIST
222.91	219.00	7.77	5860.00	1707.59	7567.59

PROB	AVG TIME	STD DEV	XTIME	TTIME	YA
1.0000	26.1421	.8096	29.2997	37.0703	237.0000
.9987	26.1466	.8096	29.3041	37.0747	236.0000

GENERIC AIRCRAFT WIDE BODY

NASA HIGH SPEED ANALYSIS
INPUT SUMMARY,
PROBABILISTIC MODEL

	AVERAGE	STD DEV	UNITS,
TOUCHDOWN LOCATION	1500.	30.	FEET
TOUCHDOWN SPEED	230.	10.	FT/SEC
TIME-TOUCHDOWN TO DECEL	5.	1.	SECONDS
DECELERATION RATE	.50	1.00	FT/SEC**2
50%PROBABILITY SPEED	237.	1.	FT/SEC
DIST:THRESHOLD-START OF TURN	5860.		FEET
SPEED AT MAJOR DECEL REDUCE	190.		FT/SEC
NOSE-WINGTIP DIST	130.		FEET

AIRCRAFT TRACKING PROGRAM

AIRCRAFT CHARACTERISTICS

WEIGHT(LBS)	YAW INERTIA	WHEELBASE	% LOAD ON MAIN GEAR
400000.0	40000000.0	84.0	96.0

FLIGHT CONDITIONAL PARAMETERS

EXIT VELOCITY	MAX EXIT ANGLE	MAX Y MU	DECEL RATE
222.913	45.000	.250	-.500

SYSTEM WIDTHS

RUNWAY	WINGSPAN	CLEAR DIST.	DIST TO TAXIWAY
150.00	207.00	178.50	600.00

SCRUB CHARACTERISTICS

Y MU	RADIUS
.0000	.1E+32
.0100	5287.0
.0190	2638.0
.0390	1318.0
.0590	877.0
.0790	657.0
.0990	534.0

CONSTANT NLG SIDE LOAD ANALYSIS

/ PASSENGER CONFORT IGNORED

TIME	X	Y	THETA	RADIUS	R RATE	MU SCRUB	MU CENT	MU I	G CENT	VELOCITY
.000	.000	.000	.000	100000.00	-324956.00	.010	.015	.225	.015	222.913
.500	111.393	.094	.114	39349.85	-45058.04	.010	.039	.201	.039	222.661
1.000	222.660	.502	.321	25506.86	-16962.76	.010	.060	.180	.060	222.409
1.500	333.797	1.391	.610	19394.29	-8791.11	.010	.079	.161	.079	222.157
2.000	444.802	2.913	.974	15964.46	-5342.48	.010	.096	.144	.096	221.905
2.500	555.668	5.203	1.404	13778.60	-3571.28	.010	.111	.129	.111	221.654
3.000	666.386	8.380	1.893	12270.59	-2543.21	.010	.124	.116	.124	221.402
3.500	776.945	12.549	2.436	11172.33	-1894.35	.010	.136	.104	.136	221.150
4.000	887.331	17.806	3.026	10340.50	-1459.08	.010	.147	.093	.147	220.898
4.500	997.530	24.232	3.658	9691.49	-1153.27	.010	.156	.084	.156	220.647
5.000	1107.523	31.904	4.329	9173.22	-930.48	.010	.164	.076	.164	220.395
5.500	1217.290	40.885	5.033	8751.58	-763.38	.010	.172	.068	.172	220.143
6.000	1326.809	51.233	5.769	8403.26	-635.03	.010	.179	.061	.179	219.891
6.500	1436.060	62.999	6.532	8111.82	-534.48	.010	.185	.055	.185	219.640
7.000	1545.016	76.228	7.319	7865.30	-454.38	.010	.190	.050	.190	219.388
7.500	1653.651	90.957	8.129	7654.81	-389.67	.010	.195	.045	.195	219.136
8.000	1761.940	107.221	8.959	7473.61	-336.76	.010	.199	.041	.199	218.884

8.500	1869.856	125.048	9.806	7316.48	-293.04	.010	.203	.037	.203	218.632
9.000	1977.369	144.462	10.670	7179.32	-256.60	.010	.206	.034	.206	218.381
9.500	2084.452	165.485	11.548	7058.88	-225.97	.010	.209	.031	.209	218.129
FINAL VALUES										
9.792	2146.774	178.513	11.548	6995.21	-210.33	.010	.211	.029	.211	217.982

CALCULATED RESULTS

CRITICAL VALUES:

ASCSV	ASC	PTIME	CDIST	XDIST	TDIST
222.91	217.98	9.79	5860.00	2146.77	8006.77
PROB	AVG TIME	STD DEV	XTIME	TTIME	YA
.9999	26.2631	.8705	29.6578	39.4502	237.0000

NASA HIGH SPEED ANALYSIS
 INPUT SUMMARY,
 PROBABILISTIC MODEL

	AVERAGE	STD DEV	UNITS,
TOUCHDOWN LOCATION	1000.	20.	FEET
TOUCHDOWN SPEED	164.	10.	FT/SEC
TIME-TOUCHDOWN TO DECEL	4.	1.	SECONDS
DECELERATION RATE	.50	.50	FT/SEC**2
50%PROBABILITY SPEED	170.	1.	FT/SEC
DIST:THRESHOLD-START OF TURN	4225.		FEET
SPEED AT MAJOR DECEL REDUCE	155.		FT/SEC
NOSE-WINGTIP DIST	56.		FEET

AIRCRAFT TRACKING PROGRAM

AIRCRAFT CHARACTERISTICS

WEIGHT(LBS)	YAW INERTIA	WHEELBASE	% LOAD ON MAIN GEAR
48000.0	80000.0	36.0	95.0

FLIGHT CONDITIONAL PARAMETERS

EXIT VELOCITY	MAX EXIT ANGLE	MAX Y MU	DECEL RATE
155.971	38.000	.250	-1.500

SYSTEM WIDTHS

RUNWAY	WINGSPAN	CLEAR DIST.	DIST TO TAXINWAY
150.00	49.00	99.50	600.00

SCRUB CHARACTERISTICS

Y MU	RADIUS
.0000	.1E+32
.0230	50.0

CONSTANT NLG SIDE LOAD ANALYSIS

PASSENGER CONFORT IGNORED

TIME	X	Y	THETA	RADIUS	R RATE	MU SCRUB	MU CENT	MU I	G CENT	VELOCITY
.000	.000	.000	.000	100000.00	-1443540.00	.023	.008	.219	.008	155.971
.500	77.798	.099	.194	13450.86	-20493.91	.023	.056	.171	.056	155.223
1.000	155.220	.636	.639	8012.48	-5735.52	.023	.092	.135	.092	154.476
1.500	232.260	1.907	1.282	6072.28	-2611.91	.023	.121	.106	.121	153.728
2.000	308.904	4.137	2.077	5092.00	-1465.34	.023	.143	.084	.143	152.980
2.500	385.132	7.499	2.993	4509.28	-923.56	.023	.160	.067	.160	152.233
3.000	460.919	12.121	4.004	4128.10	-627.46	.023	.173	.054	.173	151.485
3.500	536.236	18.101	5.090	3862.20	-449.73	.023	.183	.044	.183	150.737
4.000	611.050	25.511	6.235	3667.71	-335.96	.023	.190	.037	.190	149.990
4.500	685.326	34.403	7.429	3519.96	-259.70	.023	.197	.030	.197	149.242
5.000	759.026	44.815	8.662	3404.08	-206.80	.023	.201	.026	.201	148.494
5.500	832.114	56.770	9.926	3310.59	-169.16	.023	.205	.022	.205	147.747
6.000	904.548	70.284	11.217	3233.18	-141.84	.023	.208	.019	.208	146.999
6.500	976.291	85.363	12.530	3167.54	-121.69	.023	.210	.017	.210	146.251
FINAL VALUES										
6.928	1037.124	99.516	12.530	3118.37	-108.55	.023	.211	.016	.211	145.611

CALCULATED RESULTS

CRITICAL VALUES:

ASCSV	ASC	PTIME	CDIST	XDIST	TDIST
155.97	145.61	6.93	4225.00	1037.12	5262.12
PROB	AVG TIME	STD DEV	XTIME	TTIME	YA

1.0000	26.4980	1.5457	32.5261	39.4538	170.0000
.9986	26.5044	1.5457	32.5325	39.4602	169.0000

GENERIC AIRCRAFT DS

NASA HIGH SPEED ANALYSIS
INPUT SUMMARY,
PROBABILISTIC MODEL

	AVERAGE	STD DEV	UNITS,
TOUCHDOWN LOCATION	1500.	30.	FEET
TOUCHDOWN SPEED	211.	15.	FT/SEC
TIME-TOUCHDOWN TO DECEL	5.	1.	SECONDS
DECELERATION RATE	.50	.50	FT/SEC**2
50%PROBABILITY SPEED	218.	1.	FT/SEC
DIST:THRESHOLD-START OF TURN	5515.		FEET
SPEED AT MAJOR DECEL REDUCE	175.		FT/SEC
NOSE-WINGTIP DIST	87.		FEET

AIRCRAFT TRACKING PROGRAM

AIRCRAFT CHARACTERISTICS

WEIGHT(LBS)	YAW INERTIA	WHEELBASE	% LOAD ON MAIN GEAR
120000.0	4200000.0	61.0	95.0

FLIGHT CONDITIONAL PARAMETERS

EXIT VELOCITY	MAX EXIT ANGLE	MAX Y MU	DECEL RATE
203.865	37.000	.250	-1.750

SYSTEM WIDTHS

RUNWAY	WINGSPAN	CLEAR DIST.	DIST TO TAXIWAY
150.00	87.00	118.50	600.00

SCRUB CHARACTERISTICS

Y MU	RADIUS
.0000	.1E+32
.0100	5000.0
.0120	2000.0
.0180	1000.0
.0230	500.0
.0300	50.0

CONSTANT NLG SIDE LOAD ANALYSIS

/ PASSENGER CONFORT IGNORED

TIME	X	Y	THETA	RADIUS	R RATE	MU SCRUB	MU CENT	MU I	G CENT	VELOCITY
.000	.000	.000	.000	100000.00	-922180.40	.010	.013	.227	.013	203.865
.500	101.713	.126	.182	19683.64	-27650.95	.010	.065	.175	.065	202.988
1.000	202.985	.765	.572	12138.82	-8177.81	.010	.105	.135	.105	202.110
1.500	303.809	2.234	1.122	9347.16	-3790.43	.010	.135	.105	.135	201.233
2.000	404.173	4.771	1.795	7919.60	-2140.26	.010	.157	.083	.157	200.356
2.500	504.058	8.558	2.563	7067.73	-1350.71	.010	.175	.065	.175	199.478
3.000	603.443	13.727	3.406	6510.56	-916.26	.010	.188	.052	.188	198.601
3.500	702.299	20.380	4.306	6122.82	-654.64	.010	.198	.042	.198	197.723
4.000	800.597	28.590	5.252	5840.24	-487.04	.010	.206	.034	.206	196.846
4.500	898.307	38.411	6.234	5626.51	-374.83	.010	.212	.028	.212	195.969
5.000	995.396	49.878	7.245	5459.60	-297.23	.010	.217	.023	.217	195.091
5.500	1091.829	63.019	8.280	5325.46	-242.24	.010	.220	.020	.220	194.214
6.000	1187.573	77.848	9.334	5214.78	-202.54	.010	.223	.017	.223	193.337
6.500	1282.594	94.373	10.403	5121.13	-173.46	.010	.225	.015	.225	192.459
7.000	1376.857	112.597	11.486	5040.04	-151.90	.010	.226	.014	.226	191.582
FINAL VALUES										
7.153	1405.544	118.513	11.486	5017.22	-146.47	.010	.227	.013	.227	191.313

CALCULATED RESULTS

CRITICAL VALUES:

ASCSV	ASC	PTIME	CDIST	XDIST	TDIST
203.87	191.31	7.15	5515.00	1405.54	6920.54
PROB	AVG TIME	STD DEV	XTIME	TTIME	YA
.9999	26.7904	1.6923	33.3903	40.5430	218.0000

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