## Nomenclature

- A cell face area
- $\tilde{A}$  coefficient matrix
- *a* speed of sound
- *B* boundary condition state equation Bernstein polynomial
- *b* vector of Bezier control points
- C constraints
- $C_D$  coefficient of drag
- $C_L$  coefficient of lift
- $L/D, C_L/C_D$  lift-to-drag ratio
  - $C_p$  coefficient of pressure
    - *c* coordinates of the Bezier curve
    - D diagonal matrix
    - *E* inviscid flux vector
  - $e_o$  total energy per unit mass
  - *F* objective function
  - $\overline{\overline{I}}$  identity matrix
  - $I_A$  vector of active constraints
  - *K* global stiffness matrix
  - *k* grid adaptation spring stiffness number of GMRES restart cycles
  - *L* structural load vector
  - $M_n$  normal Mach number
  - *N* vector of direction cosines
  - *nbf* number of surface boundary faces
  - *nbface* total number of boundary faces

ncell	number of	unstructured	grid cells

- *ncon* number of constraints
- *ndv* number of design variables
  - *O* off-diagonal matrix
  - *p* static pressure parameter to control spring stiffness
  - *Q* aerodynamic state vector
  - *R* aerodynamic state equation
- $R^+, R^-$  one-dimensional Riemann invariants
  - $\overline{s}$  search direction vector
  - *u* computational arclength
  - *u*, *v*, *w* Cartesian velocities
    - V cell volume
    - w weighting factors
    - *X* vector of mesh points
  - x, y, z vector of discrete mesh points

## Greek Symbols

line search step length free-stream angle-of-attack

- vector of design variables
- ratio of specific heats
- *ij* Kronecker delta
  - normal velocity

feasible direction push-off factor trailing-edge included angle

adjoint vector Lagrange multipliers

direction cosine component

relaxation parameter

## **Subscripts**

- *b* boundary face value
- f value at the cell face

- *i* cell index
- *j* face index
- *k* design variable index
- *o* interior cell value
- TE trailing-edge

x, y, z physical coordinate direction

free-stream condition

## **Superscripts**

- *m* design cycle number subiteration number
- *n* nonlinear flow solution iteration number incremental iterative iteration number
- T transpose
- *x*, *y*, *z* physical coordinate direction
  - -1 inverse matrix
  - ± right and left states