



# 9th International Conference on **MANAGING PAVEMENT ASSETS (ICMPA9)**

## **A Framework for Developing Specifications and Performing Acceptance Testing of an Inertial Profiler**

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# Procedure for Purchasing an Inertial Profiler by an Agency

- **The specifications for the profiler are developed.**
- **Bid package developed and advertised.**
- **Typically the lowest bid is awarded the contract.**
- **It is important that specifications cover all details of the equipment to make sure you get what you want.**
- **The bid package must include an acceptance testing plan to check that the equipment can collect repeatable and accurate data before the equipment is accepted.**

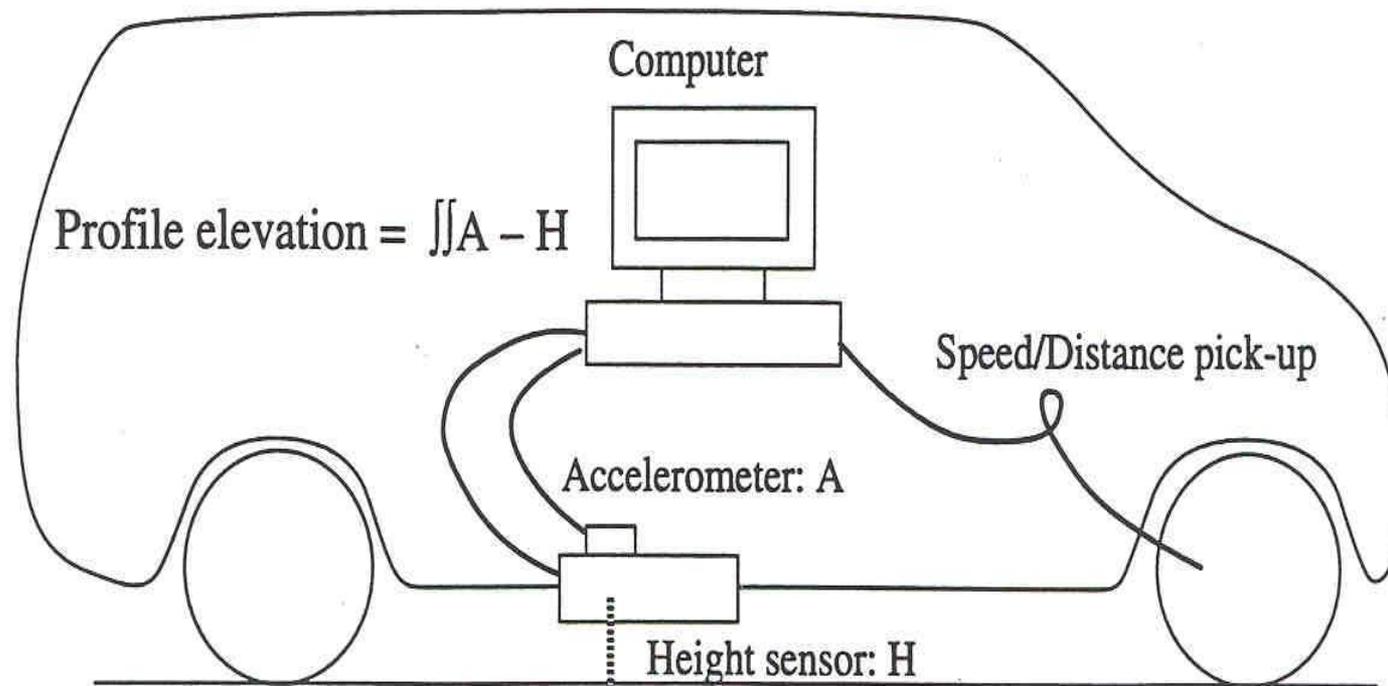
# SPECIFICATIONS FOR THE EQUIPMENT

# HOST VEHICLE AND SAFETY LIGHTING



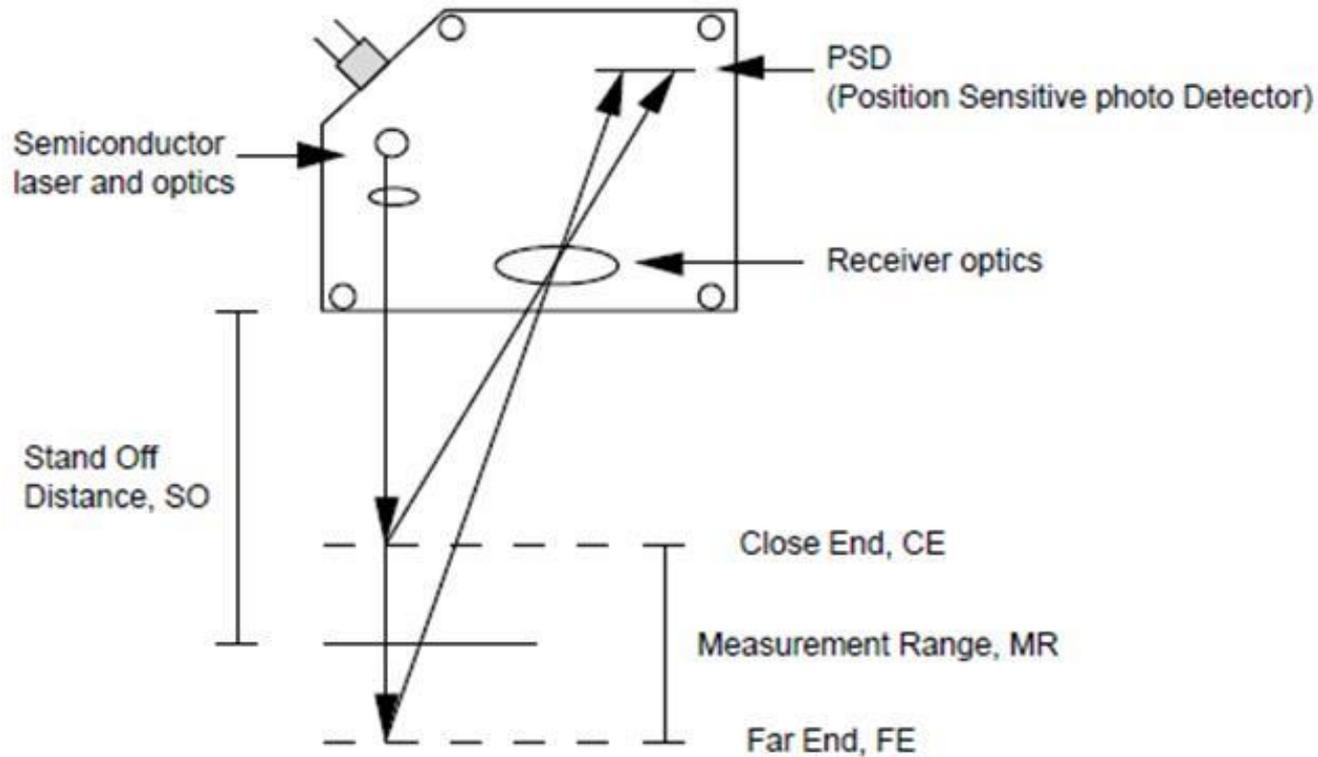
- **Strobe lights in front and rear vehicle lights.**
- **Security system for profiling bar.**

# Inertial Profiler



Karamihas, Little Book of Profiling

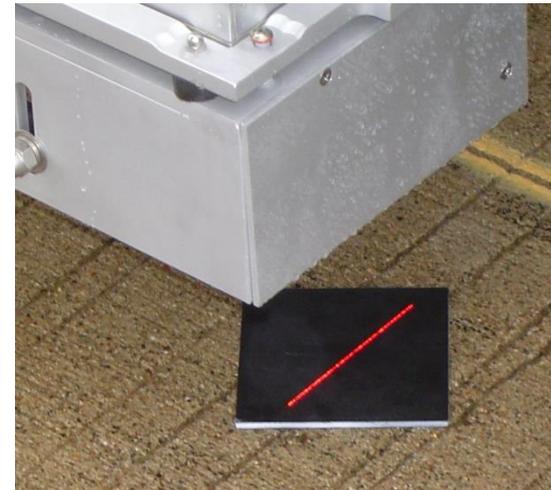
# Height Sensor - Laser



LMI Selcom

# Types of Height Sensors

- **Single Point Laser or Line Laser (4 in wide line).**



- One value generated per profile (acts as a single-point)
- 100+ points utilized in bridging function
- Software embedded inside sensor

# Height Sensor Type Effect on IRI

Surface Type	IRI (in/mi)	
	Single Point	Line Laser
Dense-Graded Asphalt Concrete	62	61
Stone Matrix Asphalt (SMA)	75	71
Open Graded Friction Course	70	63
Chip Seal	87	80
Concrete - Transverse Tining	72	72
Concrete - Longitudinal Tining	85	54
Concrete - Diamond Ground	108	72

**1 m/km = 63 in/mi**

# Accelerometer



- Range  $\pm 5g$  (NCHRP Report 434)

# Distance Measurement System (DMI)



- DMI should measure distance with an error of less than 0.15 percent (AASHTO M-328).

# Autotrigger (Photozell)



Vertical: Triggers off reflective tape placed on the pavement



Horizontal: Triggers off reflective mark on a cone placed on the shoulder

# Sensor Spacing



Sensor Spacing = Distance between left and right wheel path sensors

# Computer and Peripherals



# Calibration Blocks to Check Height Sensors

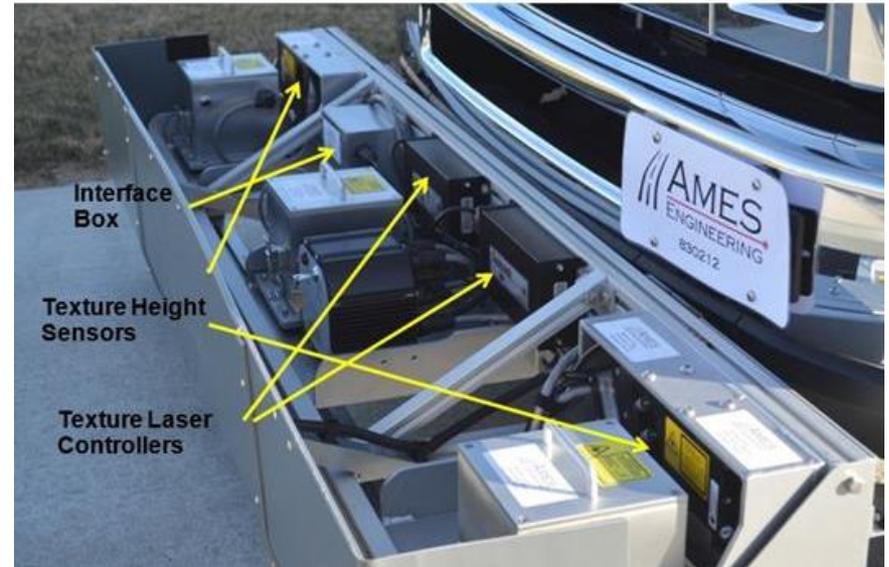


Block heights (typically 1" (25 mm), 2"  
(50 mm, 3" (75 mm)

# Additional Equipment



**GPS**



**Macrotexture: Texture Sensors**

# Additional Equipment (Temperature Sensors)

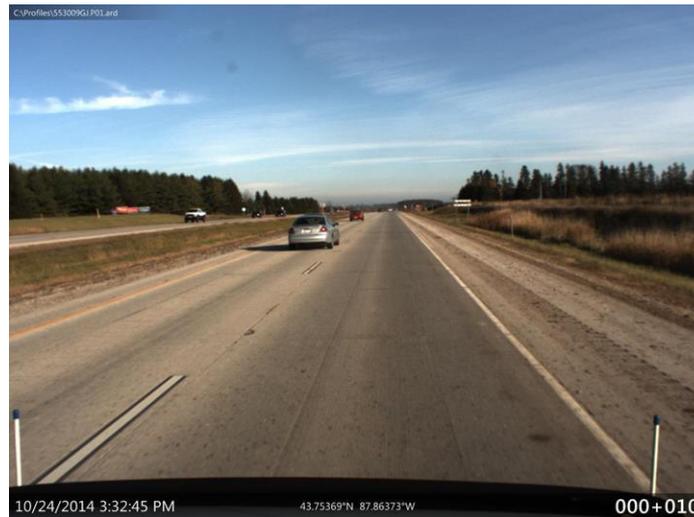


Ambient Temperature



Pavement Surface Temperature

# Additional Equipment (Camera)



# Data Requirements

- **Profile data recording interval.**
- **Data filtering: Upper wavelength cut-off filter to be applied to the data.**
- **Ability to automatically mark invalid data (i.e., when profiler collects data outside its operating speed range)**
- **Ability to manually add event marks during profiling (i.e., mark features such as start and end of a bridge).**

# Input Parameters (Header Information)

Ames Engineering - Header (Connected)

**Output File**

File name: 360000CA

Suffix:  None  Date 4/29/2015  Number 1 Next Increase 1

Full file path: C:\Profiles\360000CA.P01.ard

**Start/Stop**

Start Method: PHOTOCELL Stop Method: DISTANCE Stop Distance: 152.4 Units: Meters Direction:  Positive  Negative

Header Format: LTPP

**Site Identification**: 360000CA\_ **Operator and Driver**: JD/JD\_ **Vehicle Identification**: 830412\_

**Road Description**: I-990 **Lane Measured**: OUTSIDE **Travel Direction**: NORTH

**Horizontal Offset (m)**: 0. **Tape Width (mm)**: 50.8 **Beginning Description**: MP\_5.0

**Ending Description**: MP\_5.1 **Beginning Station**: 0. **Ending Station**: 152.4 **Surface Type**: P-CC

**Surface Condition**: FAIR **Cloud Conditions**: CLEAR **Other Weather Conditions**: STEADY CROSSWIND **Filter Wavelength (m)**: 100.0

**Spike Tolerance (mm)**: 5.0 **Air Temperature**: **Surface Temperature**:

# Software Requirements

- **Ability to perform calibration check of height sensors with calibration blocks.**
- **Ability to perform a bounce test (checks if accelerometer is cancelling out vehicle motion).**
- **Ability to perform real time quality control checks on the data (e.g., provide a warning if signals from height sensor are not being received).**
- **Ability to compute IRI at user specified intervals (e.g., 0.01 miles, 0.1 miles, 1 mile) and provide reports.**

# Reports and Output Files

- **Specify format for reports that are printed.**
- **Specify format for output files to be loaded to a Pavement Management system.**

# ACCEPTANCE TESTING OF PROFILERS

# Acceptance Testing

- **Static Sensor Check of Laser Sensors: Use calibration blocks (Meet criterion in AASHTO R 57).**
- **Bounce Test (Meet criterion in AASHTO R 57).**
- **Test on Autotrigger: When does sensor record first reading after being triggered?**
- **Check Accuracy of the Distance Measuring System: Error less than 0.15 percent.**

# Acceptance Testing

- **Establish test sections to evaluate repeatability and accuracy of data.**
- **Repeatability of IRI values: Look at standard deviation of IRI (must meet a specified criterion).**
- **Repeatability of IRI values: use cross-correlation analysis (meet AASHTO R 56).**

# Acceptance Testing

- **Accuracy of IRI Values: Compare IRI values with IRI from a reference device (must meet a specified criterion).**
- **Accuracy of IRI Values: Cross correlate IRI from profiler with IRI from a reference device (meet AASHTO R 56 criterion).**
- **Ability of profiler to collect accurate data within its operating speed: Collect data at different speeds and compare data and IRI.**