

DESIGN OF A MICROCOMPUTER-BASED  
OPEN HEART SURGERY PATIENT MONITOR

by

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(ABSTRACT)

A patient monitor device for use during open heart surgery has been designed and constructed. The device uses a VIC 20 microcomputer along with some additional circuitry to monitor 3 separate functions. The first patient variable monitored is the blood flow rate through the extracorporeal blood circuit during surgery. The device also continuously monitors and displays 6 separate temperatures. Finally, 3 individual timers are monitored and displayed with the device. Both the hardware and the software used in the design are fully described.

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## TABLE OF CONTENTS

	<u>Page</u>
ABSTRACT . . . . .	ii
ACKNOWLEDGEMENTS . . . . .	iii
LIST OF FIGURES . . . . .	vi
LIST OF TABLES . . . . .	vii
I. INTRODUCTION . . . . .	1
Problem Overview . . . . .	1
Survey of Present Devices . . . . .	2
Principle of Problem Solution . . . . .	3
II. DESIGN OVERVIEW . . . . .	5
III. HARDWARE DESIGN . . . . .	7
Microcomputer Selection . . . . .	7
Microcomputer Overview . . . . .	8
VIC 20 System Review . . . . .	12
Power-up and Initialization . . . . .	13
Memory Expansion . . . . .	16
Interrupt Processing . . . . .	20
VIC 20 Interface Circuitry . . . . .	21
EPROM Circuitry . . . . .	21
RAM Circuitry . . . . .	24
Interface Devices . . . . .	27
Temperature Detection . . . . .	30
Pump Output Detection . . . . .	32
Power Supply . . . . .	33
IV. SOFTWARE DESIGN . . . . .	34
Program Languages . . . . .	34
Initialization . . . . .	35
Input Section . . . . .	38
Monitor and Display Loop . . . . .	50
Assembly Language Subroutines . . . . .	56
Video Display . . . . .	57
Keyboard Input . . . . .	58

TABLE OF CONTENTS (continued)

	<u>Page</u>
Temperature Update . . . . .	60
Interrupt Processing . . . . .	61
V.    SYSTEM EVALUATION . . . . .	67
Electrical System . . . . .	67
Software System . . . . .	70
VI.   RECOMMENDATIONS AND CONCLUSIONS . . . . .	76
REFERENCES . . . . .	77
APPENDICES . . . . .	78
A    Software Listing . . . . .	78
B    Video Screen Displays . . . . .	153
C    VIC 20 Initialization Routine . . . . .	157
D    Construction Details . . . . .	158
E    VIC 20 Schematic . . . . .	160
VITA . . . . .	162

## LIST OF FIGURES

<u>Figure</u>		<u>Page</u>
1	Open Heart Surgery Patient Monitor Device . . . . .	6
2	Microcomputer Block Diagram . . . . .	9
3	Timing Diagram . . . . .	11
4	VIC 20 Memory Map . . . . .	14
5	Location and Type of Pins on the Memory Expansion Connector . . . . .	17
6	Buffer Circuitry . . . . .	22
7	EPROM Circuitry . . . . .	23
8	RAM Circuitry . . . . .	26
9	Interface Devices . . . . .	28
10	Initialization Routine Flowchart . . . . .	36
11	Input Section Flowchart . . . . .	39
12	Monitor and Display Flowchart . . . . .	51
13	Interrupt Flowchart . . . . .	62
14	Accuracy of Temperature and Centrifugal Flow Probes . . . . .	69
B1	Title Screen Display after SCREN1 Subroutine Call . . . . .	155
B2	Monitor Screen Display after SCREN2 Subroutine Call . . . . .	156
D1	Interface Circuit Board Layout . . . . .	159
E1	VIC 20 Schematic . . . . .	161

LIST OF TABLES

<u>Table</u>		<u>Page</u>
1	Memory Expansion Connector Pin Functions . .	18
2	EPROM Address Range versus $\overline{\text{BLK}}$ Enabling Range . . . . .	25
3	Verification of Analog Switches . . . . .	68
4	Verification of Pulse Counter . . . . .	71
5	Roller Pump Output . . . . .	72
6	Pulsatile Pump Output . . . . .	73
7	Patient Data Calculations . . . . .	74

## I. INTRODUCTION

### Problem Overview

A microcomputer-based patient monitoring device has been developed for use during open heart surgery. The device has three separate functions: (1) monitor and display the blood flow rate through the patient, (2) monitor and display six different temperatures, and (3) display three individual timers.

The blood flow rate is found using a noninvasive technique which calculates the blood pump's output, then normalizes the output for the patient's size in two ways. One flowrate is found by dividing the blood pump output by the patient's weight, the other is found by dividing by the patient's total body surface area. Three types of blood pumps can be used with this device: (1) centrifugal, (2) roller, and (3) pulsatile. The centrifugal pump is a turbo-machine which pumps the blood using a rotor. The rotor transfers its rotational energy to the blood by centrifugal forces which move the blood from the center of the rotor to the outer casing. The roller pump has rollers on the end of arms attached at their other end to a rotating shaft. The rollers pinch tubing filled with blood against the outer casing. As the rollers move the blood is pushed along in the direction of rotation. The pulsatile pump consists of a

reciprocating piston which pushes a hydraulic fluid against a flexible diaphragm. The diaphragm expands into a spherical cavity filled with blood. As the diaphragm expands, the blood is squeezed out of the cavity. Two check valves, one above and below the cavity, move the blood along in only one direction.

Six different temperature measurements are needed in order to fully monitor the patient's skin and core temperature, the temperature entering and leaving the heat exchanger water bath, as well as the temperature of the blood entering and leaving the blood oxygenator.

Two of the three individual timers can be used to time the total perfusion time, the amount of time the blood is being oxygenated, or the cross-clamping of the aorta. Finally, the remaining timer can be used to obtain the time for each individual distal anastomosis. A distal anastomosis is a surgical connection between two blood vessels.

### Survey of Present Devices

The idea for the patient monitor device was given to Dr. Leon Arp by Mr. Edward C. Berger, a retired perfusionist [1]. A perfusionist runs the blood pump and oxygenator during the open heart surgery. According to Mr. Berger, the existing devices used to monitor blood flow need more flexibility in the patient input data as well as in the output display.

With both the Sarns and the Cobe-Stoekert units, either the patient weight or the body surface area are input, then the perfusionist is stuck with that flow index, either ml/min/kg or ml/min/m<sup>2</sup>. With the monitor designed in this thesis, just the patient height and weight are input, then the body surface area is calculated using the Dubois formula [2]. This simplifies the patient input data as well as adds the flexibility of having both flow indexes displayed continuously.

Most of the existing temperature monitors have only four inputs where one or two more are often needed. Also, many of these devices display only one temperature, chosen by a switch. With the device described in this thesis, all six temperatures are displayed continuously, eliminating the confusion of switching from one temperature to another.

The timing module described in this thesis is comparable with the available devices. The advantage of incorporating the timing module with the temperature and flow index modules is the elimination of three separate devices.

### Principle of Problem Solution

A dedicated microcomputer is used to monitor and display the various parameters because it is a flexible and efficient system. The system can be used with any of the three types of blood pumps now available: the centrifugal, the roller, and the pulsatile pump. Also, the inputs can be in a variety

of units, such as kilograms or pounds, which eliminates the chance of conversion errors.

## II. DESIGN OVERVIEW

The patient monitor device, as shown in Fig. 1, consists of a VIC 20 microcomputer and keyboard, a television set and an interface circuit board.

The patient information is input to the microprocessor through the keyboard. The input data includes the patient's name, height, and weight; the type of blood pump; the stroke volume if a pulsatile pump is used; the number of rollers, the tubing diameter and arc length if a roller pump is used; the labels for the six temperature probes and three timers; as well as the units for the height, weight and pump data.

Also input to the microcomputer, through the interface circuit board, are the six temperature values in either Fahrenheit or Celsius, selectable by a switch on the front panel, the tachometer information from the roller or pulsatile pump, and a voltage representing the flowrate through the centrifugal pump.

Software, consisting of both BASIC and assembly language programs, calculates the patient body surface area, the blood pump output and the normalized blood flow rate using consistent units. This information along with the patient's name, height, and weight, the six temperatures, the three timers, as well as the current time of day are then displayed on the television set. The program continues to display and monitor the parameters until the power is turned off, or the input parameters need to be changed.

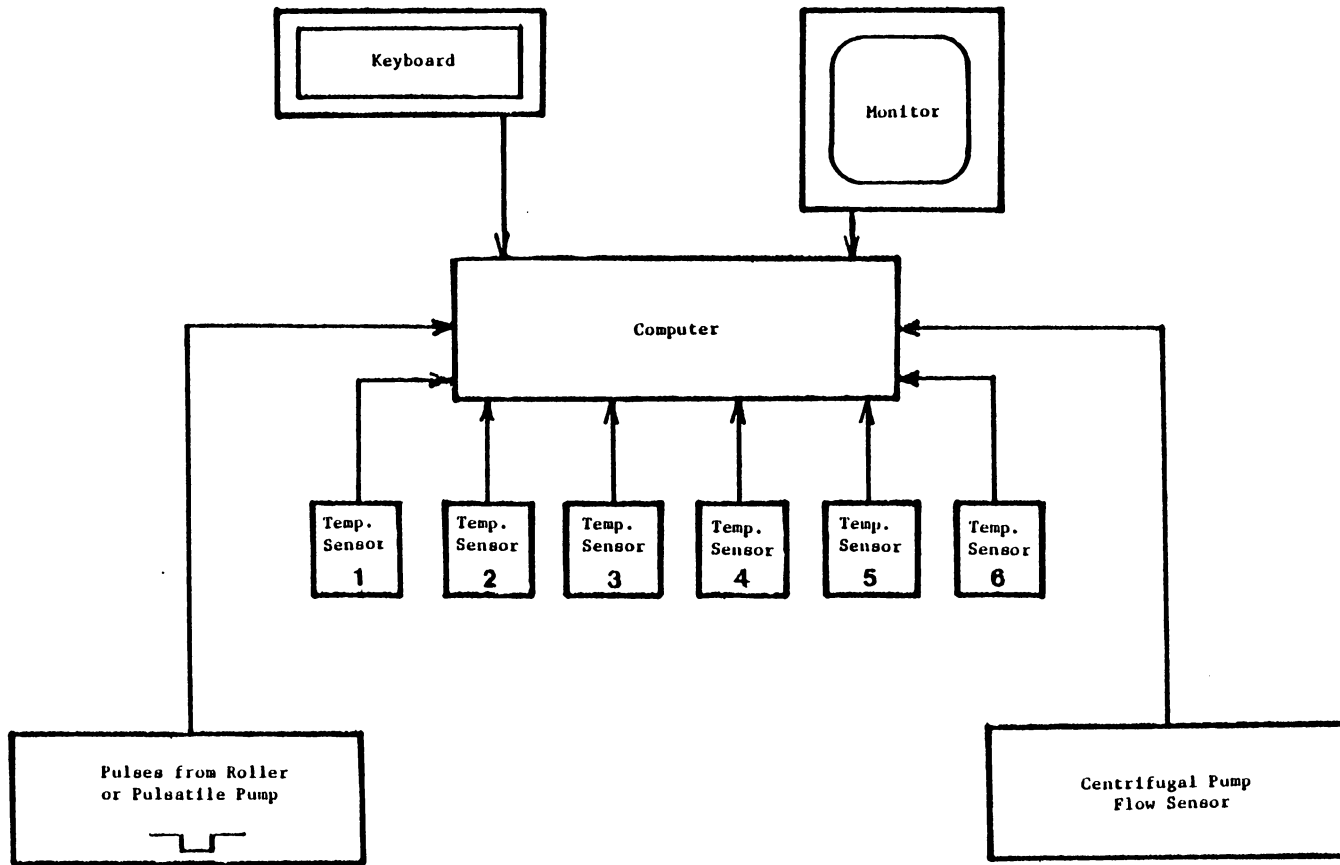


Figure 1. Open Heart Surgery Patient Monitor Device

### III. HARDWARE DESIGN

#### Microcomputer Selection

For the design of the patient monitor a VIC 20 microcomputer was used. The design could have been implemented with dedicated circuitry, however, since the VIC 20 was available it was used because of its following advantages. The VIC 20 uses a 6502 microprocessor, contains a keyboard, a video interface chip (6560), as well as user callable machine language subroutines which input keyboard information and output characters to the video display.

Since the VIC 20 uses a 6502 microprocessor, it is compatible with the AIM 65 Advanced Interactive Microcomputer. This allows machine language subroutines to be programmed onto Electrically Programmable Read Only Memory (EPROM) chips, using the AIM 65. These programs can then be run on the VIC 20 using the memory expansion port to access the address, data and control lines from the microprocessor.

Getting information into the microprocessor is simple using the VIC 20 keyboard and input subroutines, as well as the BASIC input statement. Displaying information from the microcomputer is also easy, using the VIC 20 video interface chip and output subroutines, as well as the BASIC print statement [3,4].

As shown in the VIC 20 schematic in Appendix E, memory expansion is easily accomplished, since the VIC 20 hardware has already decoded the six most significant address lines. Therefore, only the ten least significant address lines need to be decoded when adding memory or interfacing devices. For the EPROM chips, these ten least significant address lines are inputs to the chip, eliminating any further decoding.

The VIC 20 also has an assembly language programming cartridge, the VIC MON<sup>®</sup>, which will assemble, disassemble and run assembly language programs. This helped with debugging assembly language subroutines, as well as enabled the disassembly of some of the VIC 20 assembly language subroutines.

### Microcomputer Overview

The VIC 20 system along with the added memory and interface circuitry is outlined in Fig. 2. The Motorola 6502A microprocessor uses a 16-bit address bus, and an 8-bit data bus to communicate with memory and interface devices. The address bus contains the location that the data is to be sent to or received from. All devices that the microprocessor communicates with have an address, such as added memory or peripheral devices. The direction of data transfer is determined by the READ/WRITE signal from the 6502A. If the signal is high, then data is being read into the microprocessor. If

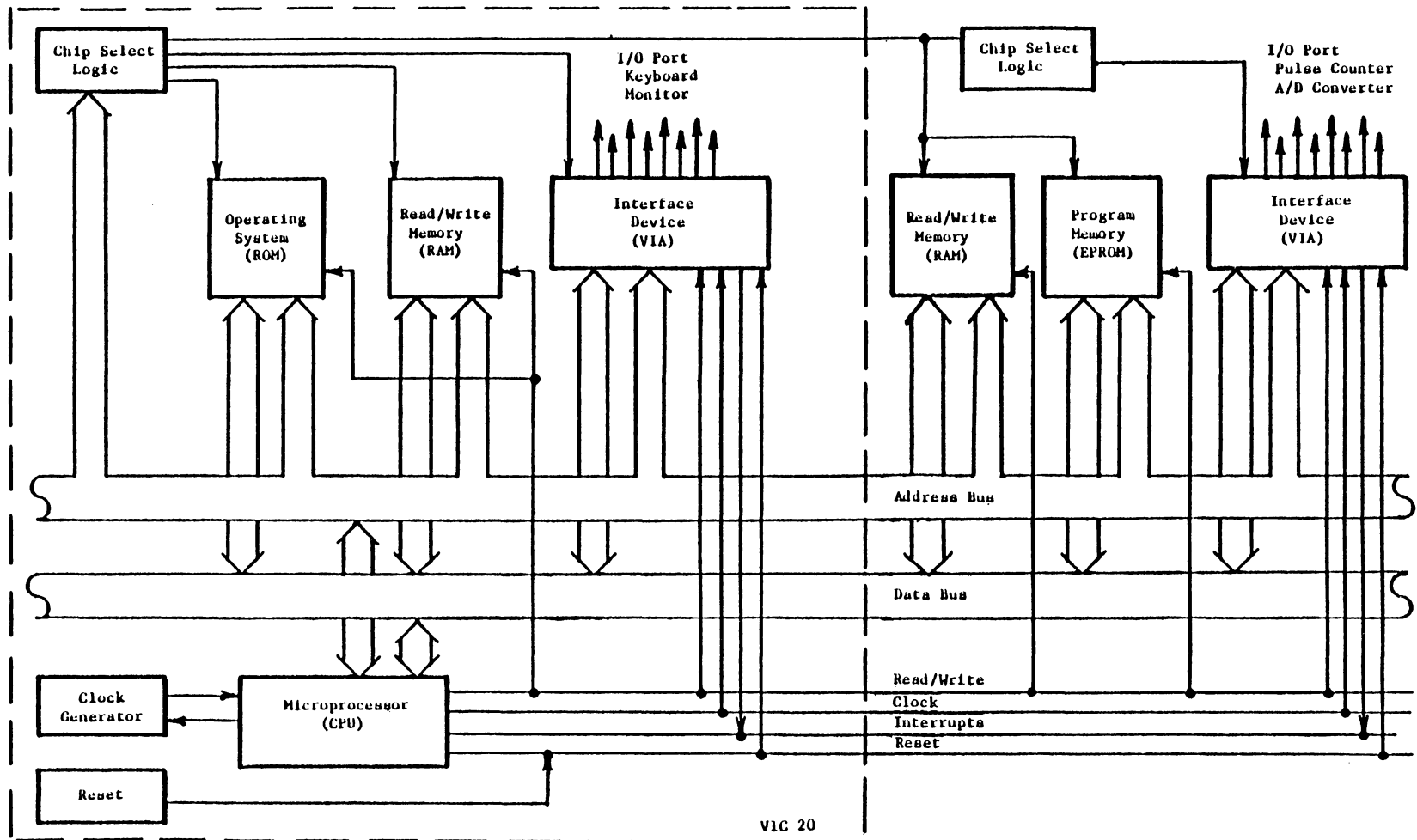


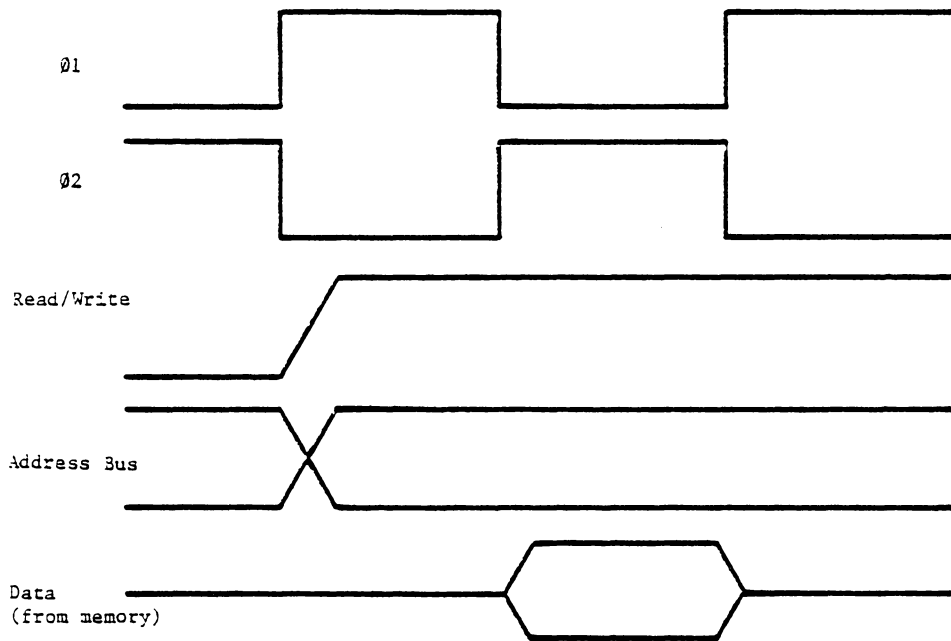
Figure 2. Microcomputer Block Diagram

the signal is low, then data is being written into memory or a peripheral device.

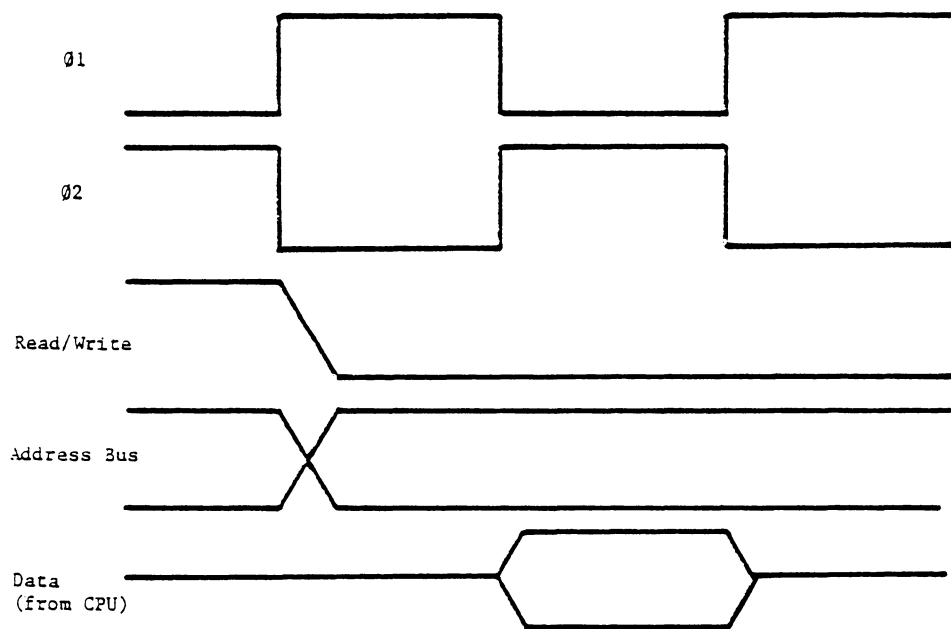
The timing which the microprocessor follows when sending or receiving data is shown in Fig. 3. As shown in the schematic, the microprocessor clocks,  $\phi 1$  and  $\phi 2$ , control the timing of the data transfers. During the high portion of  $\phi 1$ , the  $\overline{\text{READ/WRITE}}$  line and the address lines stabilize. The data is then sent or received during the high portion of  $\phi 2$ . This ensures that the correct data is sent to or received by the correct address [5].

To ensure correct operation at power-up, the VIC 20 contains reset hardware. This hardware delays the system operation until all of the supply voltages and clock cycles are stabilized.

Also available with this microprocessor is the ability to interrupt. An interrupt causes the microprocessor to finish executing the current instruction, service an interrupt routine, then return to the main program. For example, if an alarm condition occurred, the microprocessor could be interrupted, then the interrupt routine would stop execution of the main program and sound an alarm. Without the ability to interrupt, the microprocessor would have to periodically check to see if an alarm condition had occurred. This would increase the main program length, as well as, possibly, not recognize the alarm condition as quickly.



a) Memory Read Operation



b) Memory Write Operation

Figure 3. Timing Diagram for Data Transfer Between Memory and 6502A Microprocessor

## VIC 20 System Review

The VIC 20 schematic is shown in Appendix E. As shown in the schematic, the VIC 20 contains reset hardware, a clock generator, random access memory, read only memory, interface devices, and chip select logic.

The reset hardware consists of a 555 timer chip which at power up pulses the reset line low. This causes the microprocessor to wait to start executing instructions until the supply voltages and clock signals have stabilized. Also, the reset signal places the interface devices in the input mode, and disables the timers, interrupts, and shift registers.

The clock generator for the microprocessor is a 14.31818 MHz quartz crystal oscillator. Its output is used to clock the 6560 video interface chip which controls the television screen input and output (I/O). The  $\phi 1$  and  $\phi 2$  clock signals are also generated by the oscillator using a 1.000 MHz signal.

There is 6K (6143 bytes) of random access memory available on the unexpanded VIC 20. This memory is used for temporary storage of variables used by the VIC 20 operating system, temporary storage of user programs, and storage of the characters and colors to be displayed on the screen.

The unexpanded VIC 20 contains 20K (20,479) of read only memory. This memory contains the KERNAL machine language subroutines, the BASIC interpreter program and the character

generator information. The addresses for both the read only memory and the random access memory are shown in Fig. 4. A hexadecimal number is noted by the dollar sign prefix, \$. If there is no prefix, then a decimal number is indicated.

The interface devices contained in the unexpanded VIC 20 are a 6560 video interface device, and two 6522 versatile interface adapters. The 6560 can control the video display, sound generation, a light pen and a joystick. The 6522's perform the following I/O functions: the cassette deck, the user port, the keyboard input, the RESTORE key, the interrupt request (IRQ) timing for the real time clock and scanning the keyboard, the light pen control, and the joystick.

The chip select logic determines which chip is accessed, such as read only memory or random access memory or an interface device. This is accomplished on the VIC 20 by three 74LS138 integrated circuit chips. These chips are 3 to 8 line decoders which take an input address and output a low-going pulse on a separate line for each separate address. These pulses are sent to the different chips to enable them when their address is on the address bus.

#### Power-up and Initialization

When the power is turned on, after the reset line returns to the high state, the microprocessor delays 6 ns, then executes the initialization routine starting with the

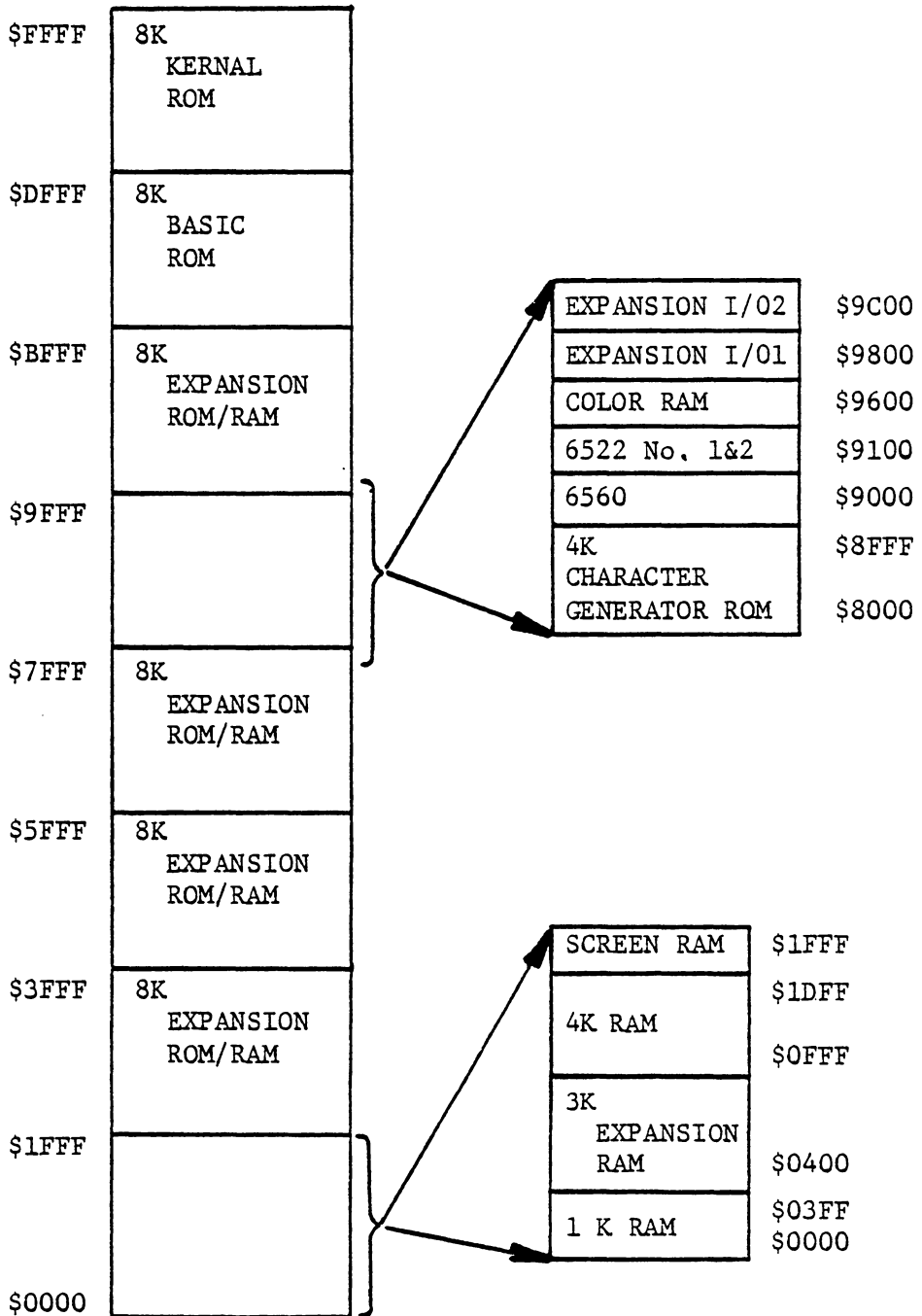


Figure 4. VIC 20 Memory Map

instruction located at address \$FD22. This initialization routine is listed in Appendix C.

First, the interrupts are disabled until the initialization sequence has finished. The stack pointer is then set at \$00FF. The stack pointer contains the address of the current value in the stack register. The stack register is a last-in-first-out (LIFO) register used to temporarily store variables.

Next, address \$A000 is checked for the presence of ROM. If the auto-start ROM sequence:

Address - \$A004	Contents - \$41
\$A005	\$30
\$A006	\$C3
\$A007	\$C2
\$A008	\$CD

is found, then the program counter high byte is loaded with the contents of address \$A001, and the program counter low byte is loaded with the contents of address \$A000. The microprocessor then executes the instructions starting at the program counter address. If the auto-start sequence is not found then the normal initialization routine is continued, executing the instructions starting at address \$FD2F.

The above instructions clear and test the RAM, initialize all of the indirect jump vectors, the I/O, and the video chip. Next, the interrupts are enabled since the

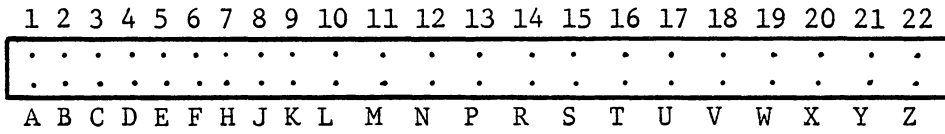
system is fully initialized. Finally, the processor jumps to the BASIC interpreter, turning control over to the user. For proper operation of the VIC 20 system, the programmer should include these instructions in his initialization routine if they are bypassed by the auto-start sequence.

### Memory Expansion

The memory expansion connector located on the back of the VIC 20 is used to expand the microcomputer by adding memory or interface devices. As shown in Fig. 5, the female edge connector has 44-pins. Fig. 5 shows the location and the type of pins on the memory expansion connector. Table 1 gives brief explanations of the functions of each pin. A more detailed description follows.

Eight of the pins, CD0-CD7, are the data lines from the microprocessor. These lines are used to transfer data between the microprocessor and memory or interface devices. Fourteen of the pins, CA0-CA13, are the 14 least significant address lines from the microprocessor. These lines are used to direct the data to and from the correct chip. The 2 most significant address lines are not needed since the VIC 20 chip select logic has already decoded these lines for the block select signals.

The block select signals use 9 of the pins on the memory expansion connector. Four of these lines,  $\overline{\text{BLK1}}$ ,  $\overline{\text{BLK2}}$ ,  $\overline{\text{BLK3}}$ ,



Pin #	Type
1	GND
2	CDO
3	CD1
4	CD2
5	CD3
6	CD4
7	CD5
8	CD6
9	CD7
10	$\overline{\text{BLK1}}$
11	$\overline{\text{BLK2}}$

Pin #	Type
12	$\overline{\text{BLK3}}$
13	$\overline{\text{BLK5}}$
14	$\overline{\text{RAM1}}$
15	$\overline{\text{RAM2}}$
16	$\overline{\text{RAM3}}$
17	VR/W
18	CR/W
19	$\overline{\text{IRQ}}$
20	NC
21	+5V
22	GND

Pin #	Type
A	GND
B	CA0
C	CA1
D	CA2
E	CA3
F	CA4
H	CA5
J	CA6
K	CA7
L	CA8
M	CA9

Pin #	Type
N	CA10
P	CA11
R	CA12
S	CA13
T	$\overline{\text{I/O2}}$
U	$\overline{\text{I/O3}}$
V	S02
W	$\overline{\text{NMI}}$
X	RESET
Y	NC
Z	GND

Figure 5 . Location and Type of Pins on the Memory Expansion Connector

Table 1. Memory Expansion Connector Pin Functions

<u>Type</u>	<u>Pin #</u>	<u>Description</u>
GND	1	System Ground
(CD0-CD7)	2-9	Data bus lines 0-7
BLK1	10	8 K decoded RAM/ROM block 1, starting at \$2000 (active low)
BLK2	11	8 K decoded RAM/ROM block 2, starting at \$4000 (active low)
BLK3	12	8 K decoded RAM/ROM block 3, starting at \$6000 (active low)
BLK5	13	8 K decoded RAM/ROM block 5, starting at \$A000 (active low)
RAM1	14	1 K decoded RAM at \$0400 (active low)
RAM2	15	1 K decoded RAM at \$0800 (active low)
RAM3	16	1 K decoded RAM at \$0C00 (active low)
VR/W	17	Read/Write line from buffer chip, (1=read, 0=write)
CR/W	18	Read/Write line from CPU, (1=read, 0=write)
IRQ	19	6502A Interrupt request line (active low)
(NC)	20	No connection
+5V	21	+5 volt power
GND	22	System Ground
GND	A	System Ground
CA0-CA13	B-S	Address bus lines 0-13
I/O1	T	Decoded I/O block 1, starting at \$9800
I/O2	U	Decoded I/O block 2, starting at \$9C00
SØ2	V	Phase 2 system clock
NMI	W	6502A non-maskable interrupt (active low)
RESET	X	6502A reset line (active low)
(NC)	Y	No connection
GND	Z	System Ground

and  $\overline{\text{BLK5}}$ , go from high to low, respectively, when addresses, \$2000 - \$3FFF, \$4000 - \$5FFF, \$6000 - \$7FFF, and \$A000 - \$BFFF are accessed. These signals are used to enable a RAM or a ROM chip.

Three of the block select signals,  $\overline{\text{RAM1}}$ ,  $\overline{\text{RAM2}}$ , and  $\overline{\text{RAM3}}$ , go from high to low, respectively, when addresses, \$0400 - \$07FF, \$0800 - \$0BFF, and \$0C00 - \$0FFF are accessed. These signals are used to enable a RAM chip.

The last two block select signals,  $\overline{\text{I/O1}}$  and  $\overline{\text{I/O2}}$ , go from high to low, respectively, when addresses, \$9800 - \$9BFF and \$9C00 - \$9FFF are accessed. These signals are used to enable interface devices.

The remaining lines on the memory expansion port are used for power and for microprocessor control. The power lines consist of a system ground and a +5 supply voltage with a current rating of approximately 750 ma. The control lines consist of the  $\emptyset 2$  microprocessor clock, the reset line, two  $\overline{\text{READ/WRITE}}$  lines, and two interrupt lines. The  $\emptyset 2$  clock controls the timing of data transfers between the microprocessor and memory or interface devices. The reset line when pulled low, halts the microprocessor operation until 6 clock cycles after the line returns high. The processor then executes the instruction found at address \$FD22. The first  $\overline{\text{READ/WRITE}}$  line, the CR/W, is directly connected to the microprocessor. This line is used for

memory and interface device timing. The second  $\overline{\text{READ/WRITE}}$  line, the VR/W, is the buffered CR/W line. This signal is used by the video interface chip, the 6560. The two interrupt lines,  $\overline{\text{IRQ}}$  and  $\overline{\text{NMI}}$ , when brought low, cause the microprocessor to finish executing the current instruction, then go to an interrupt service routine. The difference between the two lines is that the  $\overline{\text{IRQ}}$  signal can be ignored by the processor by setting the interrupt disable bit.

### Interrupt Processing

The VIC 20 uses the  $\overline{\text{IRQ}}$  line to interrupt the microprocessor every 1/60 of a second. When the  $\overline{\text{IRQ}}$  signal goes low, providing the interrupt disable bit is 0, the microprocessor transfers execution to the VIC 20 interrupt service routine located at address \$FF72. This routine starts with a subroutine which saves the processor registers on the stack. Next program control jumps to the address pointed at by addresses \$0314 (low byte) and \$0315 (high byte). This address is set to \$EABF by the VIC 20 initialization routine. This routine scans the keyboard for a pressed key and updates the system clock. If the programmer wants to bypass this routine, then the starting address of the new interrupt routine should be placed at addresses \$0314 and \$0315. The return from interrupt instruction (RTI) returns program control to the

instruction following the instruction that was being executed when the  $\overline{\text{IRQ}}$  line went low.

### VIC 20 Interface Circuitry

The interface circuitry used in this thesis to connect the VIC 20 with the added memory and interface devices is described in this section. The circuitry is based on the design used in Browning's thesis "Design of a Microcomputer-Based Microporous Membrane Process Controller" [6]. All the lines from the memory expansion port are buffered using four 74245 buffers as shown in Fig. 6. These chips can transfer data in one of two directions as chosen by the DIR input. Their outputs are 3-state with a typical propagation delay time from input to output of 8 ns. As shown in Fig. 6, 74245-3 is only enabled when either  $\overline{\text{BLK1}}$ ,  $\overline{\text{BLK2}}$ ,  $\overline{\text{BLK5}}$ ,  $\overline{\text{RAM3}}$ , or  $\overline{\text{I/O2}}$  is low and  $\text{S02}$  is high. This makes sure that the data bus is only enabled when added memory or interface devices are accessed. This enabling is accomplished using a 7430 8-input nand gate in combination with a 7420 dual input nand gate as shown in Fig. 6.

### EPROM Circuitry

Fig. 7 shows the EPROM circuitry used in this thesis, based on the design described in Browning's thesis [6]. The assembly language software for the patient monitor device is



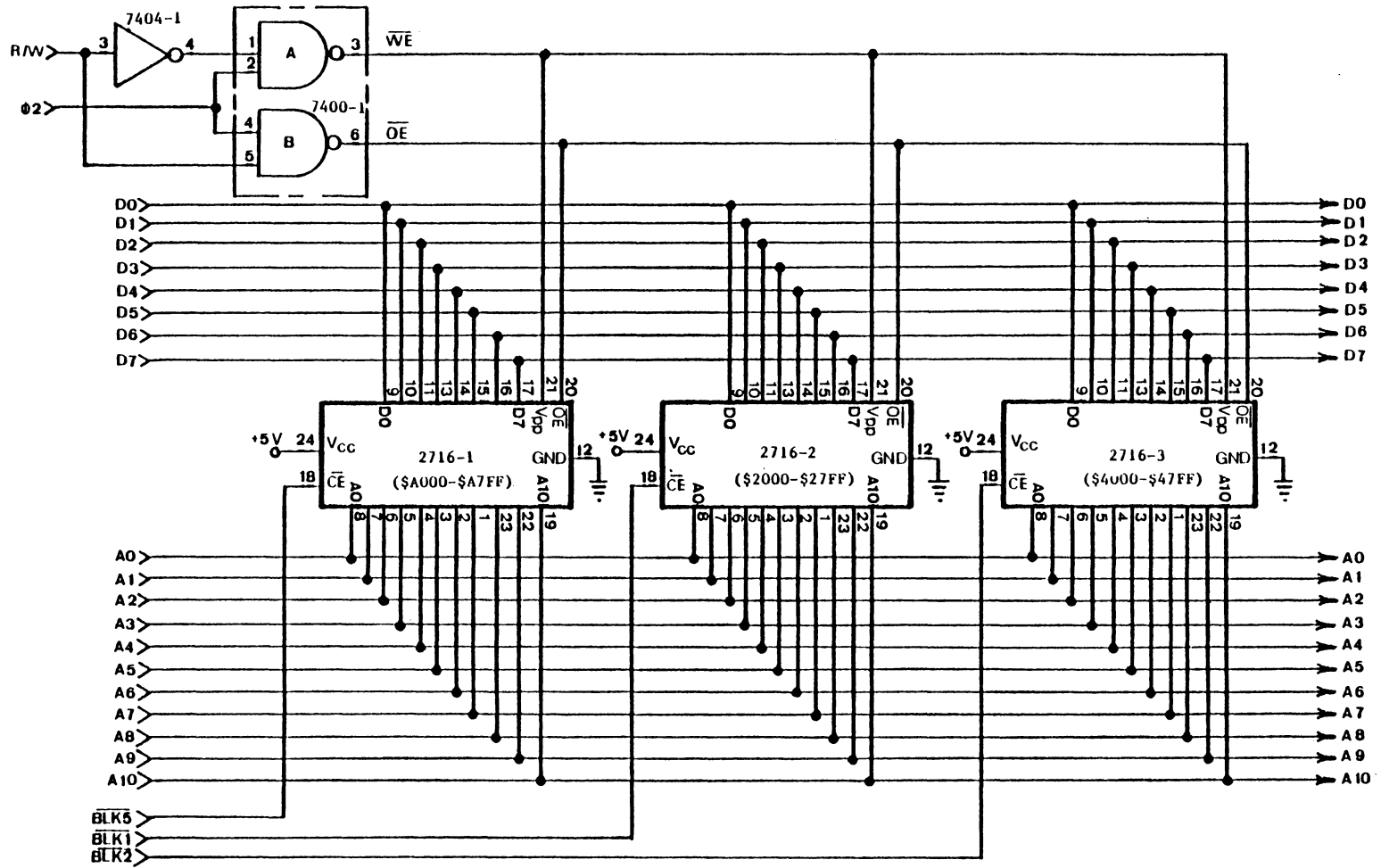


Figure 7. EPROM Circuitry

contained in these three memory chips. Each of the three 2716 EPROM chips are enabled using chip select pulses accessed directly at the memory expansion port. The chip select pulses,  $\overline{\text{BLK1}}$ ,  $\overline{\text{BLK2}}$ , and  $\overline{\text{BLK5}}$ , each enable a separate EPROM chip. Each chip contains only 2K (2048) bytes of read only memory, while each of the chip select pulses enables 8K (8192) bytes of memory. Therefore, 6K (6144) of the addressable memory for each of the chip select pulses cannot be used with this circuitry. Table 2 shows the addresses used by the EPROM chips as well as the enabling range for the  $\overline{\text{BLK}}$  signals.

Also shown in Fig. 7 is the circuitry required to achieve the correct timing of data transfers between the microprocessor and the EPROM chips. This is accomplished by logically gating the  $\overline{\text{READ/WRITE}}$  signal with the  $\phi 2$  clock signal. This must be added since the EPROM chip does not have a clock input to synchronize data transfers with the microprocessor.

### RAM Circuitry

In order to have enough memory to hold the BASIC program and the variables used by the assembly language program, random access memory (RAM) was added. The circuitry used is shown in Fig. 8. The 2114 RAM chips each hold 1K (1024) of addressable memory locations. However only 4 bits of data

Table 2. EPROM Address Range versus  $\overline{\text{BLK}}$  Enabling Range

<u>EPROM</u>	<u>EPROM Range</u>	<u><math>\overline{\text{BLK}}</math></u>	<u><math>\overline{\text{BLK}}</math> Range</u>
2716-2	\$2000-\$27FF	$\overline{\text{BLK1}}$	\$2000-\$3FFF
2716-3	\$4000-\$47FF	$\overline{\text{BLK2}}$	\$4000-\$5FFF
2716-1	\$A000-\$A7FF	$\overline{\text{BLK5}}$	\$A000-\$BFFF

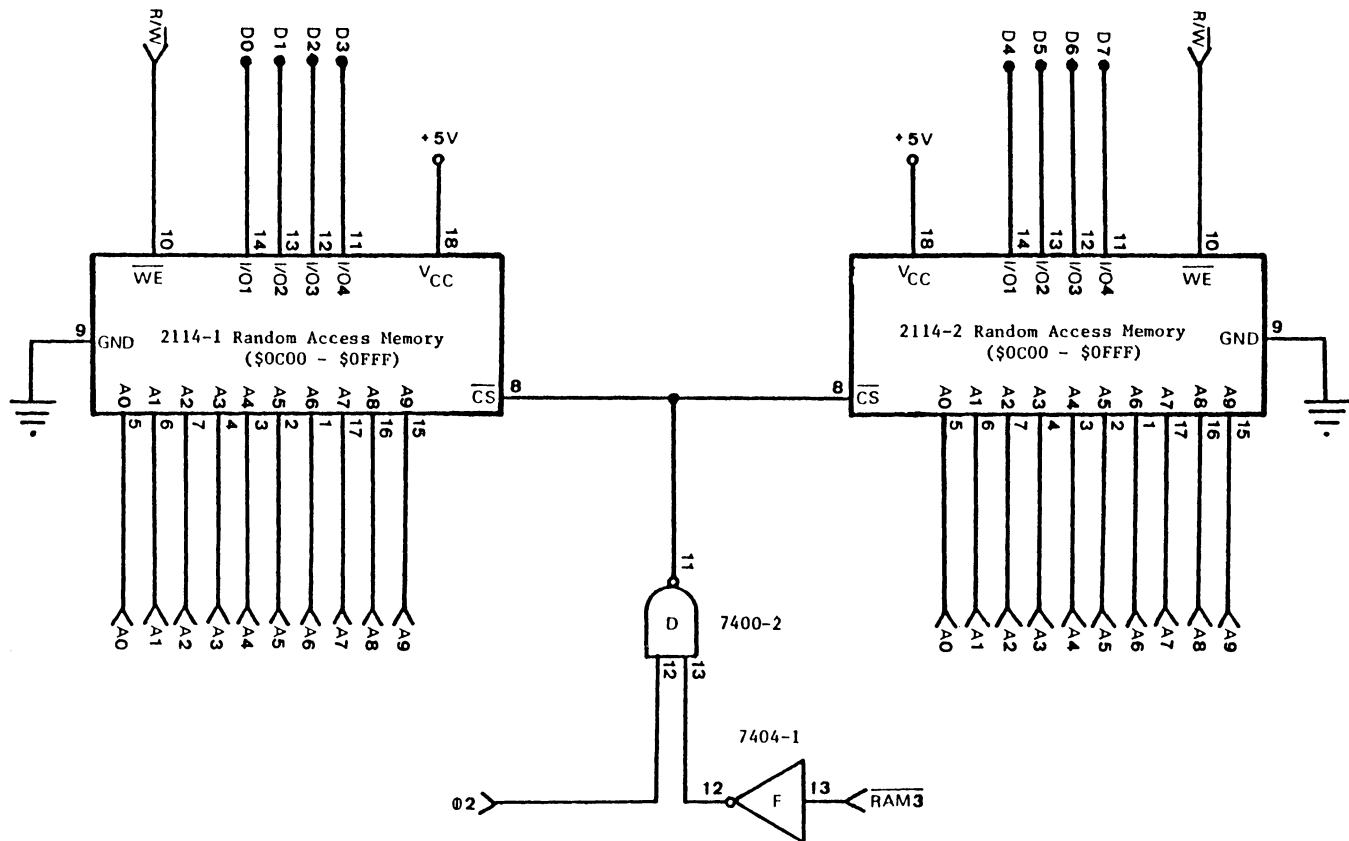


Figure 8. RAM Circuitry

are available in each chip. In order to hold the necessary 8 bits of data, two RAM chips are enabled with the same chip select pulse while the 4 least significant data bits are stored in 2114-1 and the 4 most significant data bits are stored in 2114-2.

Both the chip select logic and the correct data transfer timing is accomplished using the logic circuitry shown in Fig. 8. The  $\overline{\text{RAM3}}$  chip select signal from the memory expansion port pulses low whenever a memory location at addresses \$0C00 - \$0FFF is accessed. This signal gated with the system clock,  $\phi_2$ , enables the RAM chips at the correct time for data transfers with the desired address. The RAM is added at these locations since the BASIC interpreter program needs a continuous block of memory to run a BASIC program.

### Interface Devices

In order to monitor six temperatures and the blood pump output, the circuitry shown in Fig. 9 was used. Two of the chips, the 6520-1 peripheral interface adapter, and the 6522-1 versatile interface adapter are used to interface the signals from the temperature sensors and the blood pump with the microcomputer.

The 6520 peripheral interface adapter has two bi-directional peripheral data ports which perform the following functions. Port A is configured as an input port to accept



the temperature information from the A/D converter. The 7 most significant data lines of port B are outputs that select which temperature probe is connected to the temperature board. The least significant data bit of port B is an input from a switch that selects the temperature degree unit, either Fahrenheit or Celsius.

In order to enable the 6520 for addresses \$9A00 - \$9A03, the chip select logic shown in Fig. 9 was used. The 74154-1 is a 4 - 16 line decoder with two enabling inputs. Inputting the  $\overline{I/O2}$  signal from the memory expansion port along with the address lines, A5 through A9, to the 74154-1 decoder, produces a chip select pulse at pin 3 of the decoder for addresses \$9A00 - \$9A1F. The 6520-1, however, only uses addresses \$9A00 - \$9A03. Therefore, the address lines A2, A3 and A4 were decoded using the logic gates as shown in Fig. 9, to enable the 6520-1 only when addresses \$9A00 - \$9A03 are accessed.

The other interface device, the 6522-1, also has two bi-directional peripheral data ports in addition to two interval timers and a serial-parallel/parallel-serial shift register. For this project, the 6522-1's interval timer in connection with port B's input line 6 was used to count the low-going pulses from either the roller pump or the pulsatile pump. These pulses indicate either the revolutions per minute for

the roller pump, or the pulses per minute for the pulsatile pump.

The chip select logic for the 6522-1, as shown in Fig. 9, was accomplished using the 74154-1 decoder [6]. Using the  $\overline{I/O2}$  signal from the memory expansion port along with address lines 5 through 9 as inputs to the decoder, gives a low going pulse at pin 1 of the decoder for addresses \$9800 - \$981F. In order to enable the 6522-1 only when addresses \$9800-\$980F are accessed, address line 4 is gated as shown in Fig. 9.

### Temperature Detection

The temperature detection scheme used in this thesis is based on the design used in Mears' thesis "A Microcomputer-Based Temperature and Humidity Control System for Respiratory Therapy" [7].

Each temperature sensor is input to the temperature board which outputs a voltage signal proportional to the temperature. The voltages range from 0.000 to 1.999, where 0.010 V is equivalent to either 1.0 C or 1.0 F. The degree unit, C or F, is chosen by a switch connected to the temperature board.

The temperature probes are multiplexed, as shown in Fig. 9, using 6 analog switches. The integrated circuits, 4016-1 and 4016-2, each contain 4 analog switches which will

close when their respective enabling line goes high. These switches are opened and closed using the 6520-1, which is controlled by software.

The output of the 6 analog switches are input to the temperature board. The output of the temperature board is input to the analog-to-digital (A/D) converter, the MC14433-1. This is a dual slope A/D converter which outputs a number from 0 to 1999 for inputs ranging from 0.000 V to either 1.999 V or 199.9 mV [8]. The two voltage ranges are chosen by the input to the reference voltage, pin 2 on the MC14433-1. If the reference voltage is 2.000 V then the 1.999 V range is chosen. If the reference voltage is 200.0 mV then the 199.9 mV range is used. In this design, a reference voltage of 2.000 V is provided using a LM336 2.5 Voltage reference connected with a 10K trim potentiometer [9]. The accuracy of the A/D is  $\pm 0.05\%$  of reading +1 count.

The MC14433-1 makes up to 25 conversions per second, depending upon the resistor value connected to pins 10 and 11. This resistor changes the A/D converter's internal clock frequency. The conversion rate is then equal to the clock frequency divided by 16,400. In this design, as shown in Fig. 9, the A/D makes roughly 8 conversions/sec due to the 150 K resistor, R3.

The A/D converter's data outputs are connected to port A of the peripheral interface adapter, the 6520-1. These out-

puts are DS1 through DS4 and Q0 through Q3. The digit select lines, DS1 through DS4, pulse high when the most significant digit, DS1, through the least significant digit, DS4 has data on the data lines, Q0 - Q3. These data lines contain binary coded decimal (BCD) data, where Q0 is the least significant bit and Q3 is the most significant bit. Since both the data and digit select lines are read at the same time by the microprocessor through port A, the correct data is read for the desired digit. The MC14433 outputs a high going pulse at pin 14, to signal the end-of-conversion (EOC). This signal is connected to CB1 of 6520-1 which sets a flag in an internal register of the 6520-1 when an EOC pulse occurs. This flag is then monitored by software.

The MC14433 A/D converter works fine when the capacitors, C2 and C3, are mylar capacitors. If the capacitors are not mylar, then the A/D does not track the voltages correctly.

### Pump Output Detection

In order to calculate the pump output both the 6520-1 and the 6522-1 are used as shown in Fig. 9. For the centrifugal blood pump, a voltage signal representing the flow through the pump is sent to the A/D converter (MC14433-1) through a switch in the 4016-2. This voltage is in the range of 0.000 V to 1.999 V which converts to 0. to 1999. ml/min.

Both the roller pump and the pulsatile pump have pick-up devices which produce 100 low-going pulses per revolution of the roller and 1 low-going pulse per pulse of the diaphragm. These pulses are input to line 6 of port B on the 6522-1. The 6522-1 interval timer counts these pulses, then the pump output is calculated using software.

### Power Supply

The circuitry for this design is powered by the VIC 20 power supply and a commercially available negative power supply. A common ground between the circuitry, the two power supplies and the VIC 20 memory expansion port is connected. In order to avoid ground loops, each chip's ground is connected to the same point on the circuit board. When the grounds are not connected in this way, each chip draws a small amount of current at the ground input. This causes each ground to be at a slightly different potential causing circuit operation problems.

#### IV. SOFTWARE DESIGN

##### Program Languages

The software used in this design consists of both BASIC and assembly language programs which monitor and display the various parameters. The BASIC program contains the main program loop, the initial input section, the calculation of pump output and blood flow rate, as well as some of the display routines. These sections were written in BASIC since it is a higher level language, which greatly simplifies the programming.

The assembly language software consists of a power up initialization routine, an interrupt servicing routine, as well as display and monitor subroutines. The power up initialization routine was written in assembly language since the only way to bypass the VIC 20 initialization routine is to store the signature bytes, as described in the VIC 20 Review section, on an EPROM starting at the hexadecimal address A000. Similarly, in order to bypass the VIC 20 interrupt service routine, a machine code program must be used. The display and monitor subroutines were written in assembly language in order to operate at the fastest speed possible. Both the BASIC and assembly language programs are listed in Appendix A.

In the software discussion, the following prefixes indicate the base of the number. The dollar sign, \$, indicates that a hexadecimal number follows. The per cent sign, %, indicates that a binary number follows. No prefix indicates a decimal number.

### Initialization

When the VIC 20 is turned on it follows the initialization routine shown in Appendix C. The routine checks for an auto-start sequence as explained in the VIC 20 Review section. When the signature bytes are found at addresses \$A004 through \$A008, the VIC 20 routine jumps to the user's initialization routine at the address indicated by \$A000 (low byte) and \$A001 (high byte). In this design the initialization routine begins at \$A009.

The initialization routine flowchart is shown in Fig. 10. First, the peripheral interface devices are configured such that the temperature and centrifugal flow probes are not connected to the A/D converter, and the pulse counter is disabled. In order to configure the PIA's, the ports must be made either outputs or inputs.

Setting the peripheral port pins to be outputs or inputs is accomplished by writing either a 1 or a 0 into the appropriate bit in the Data Direction Register (DDR). For example, if bit 7 of a port is to be an input while bits 0

SA009

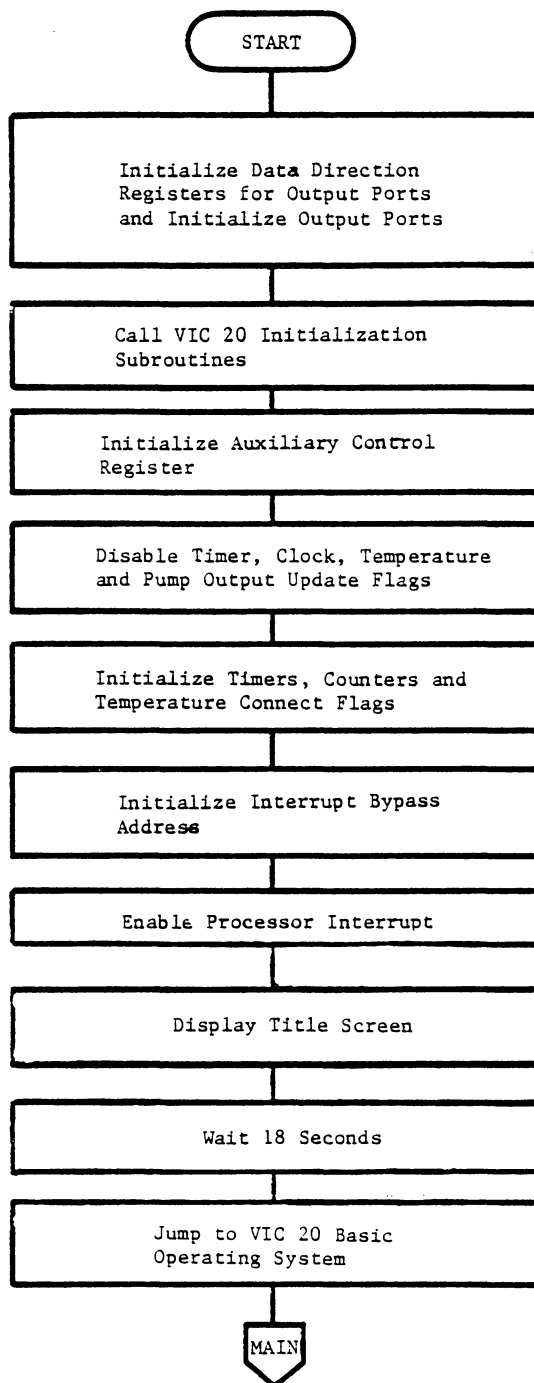


Figure 10. Initialization Routine Flowchart

through 6 are to be outputs, then %01111111 is stored in the DDR. The reset pulse at power up causes all the ports to be inputs, therefore only the output ports need to be initialized.

Once the output ports have been configured, the initial state of the pins is determined simply by writing a value to the output data register. The 6520 peripheral interface uses the same address for both the data direction register and the output register. When bit 2 in the control register is a 0, the data direction register is being accessed. When bit 2 in the control register is a 1, the output data register is being accessed. Therefore, after the data direction has been set, the data output register must be accessed to set the initial output values. These outputs are set to 0, which disconnects the probes from the A/D converter.

Once the temperature and centrifugal probes have been disabled, the routine calls subroutines which finish initializing the VIC 20 for operation. These routines clear and check the random access memory (RAM), set the VIC 20 vectors, and initialize the VIC 20 I/O and screen. Next the 6522 Versatile Interface Adapter (VIA) is configured.

In order to initialize the VIA, only the Auxiliary Control Register which controls the timers' modes of operation, and the Peripheral Control Register which determines the conditions for an interrupt to occur, need to be set.

The data direction register has already been set as inputs by the reset pulse and there are no outputs to initialize.

Following the initialization of the VIA, all of the flags are disabled and the variables are initialized. Then the interrupt by-pass address is specified and interrupts allowed. Next the title screen is displayed for 18 seconds, then the routine jumps to the BASIC operating system.

In order to use part of the RAM for storage of machine language variables, the top of BASIC memory is set below the highest RAM address. Unfortunately, this cannot be set in the initialization sequence since the BASIC operating system resets it to the highest RAM address. Therefore, the top of BASIC memory is set by the user after the initialization sequence, before the BASIC program is loaded. After the title screen goes blank, the user presses the CTRL and 2 keys simultaneously, then types in:

```
poke56,29:poke55,196:poke52,29:poke51,196
```

then hits the RETURN key. The user then fully rewinds the tape, then presses the SHIFT and RUN keys simultaneously.

### Input Section

The BASIC input section is flowcharted in Fig. 11. The first section inputs all of the patient information: the patient's name; height, in either cm or in; and weight, in either kg or lb. Throughout the inputs, the user is asked if

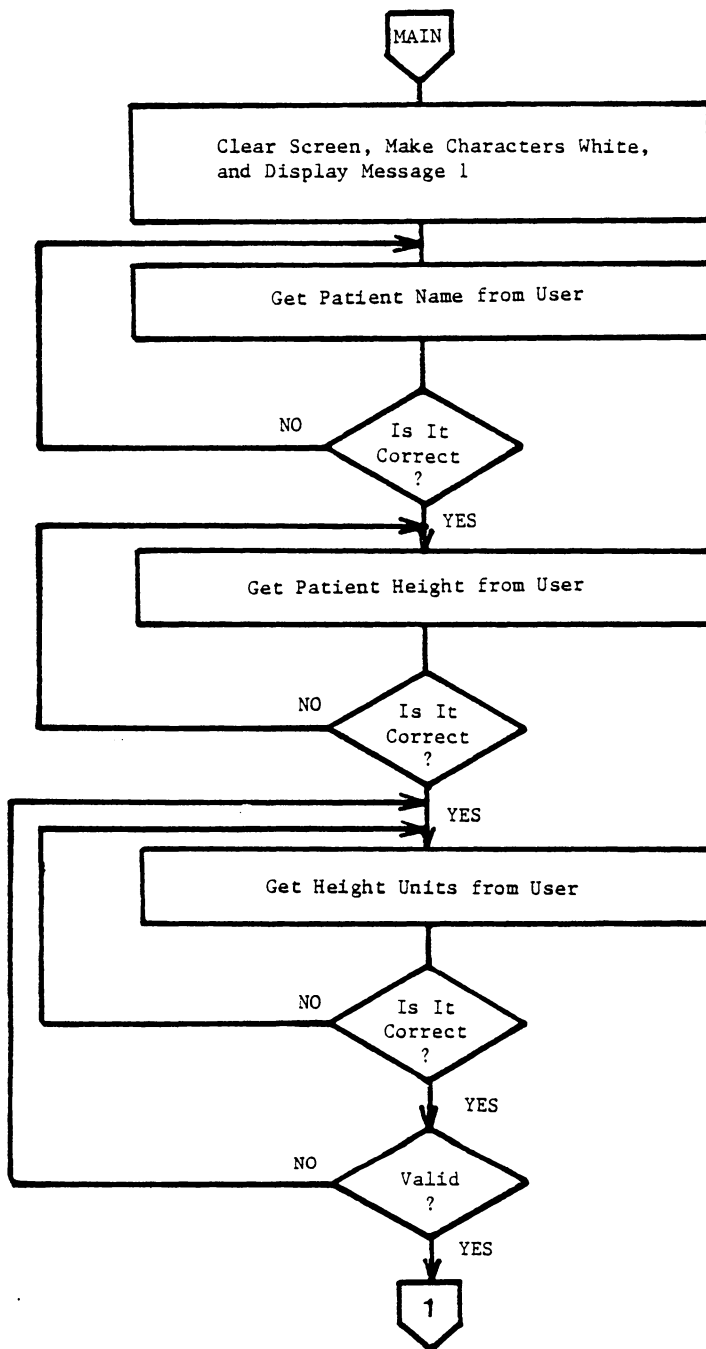


Figure 11 a. Input Section Flowchart

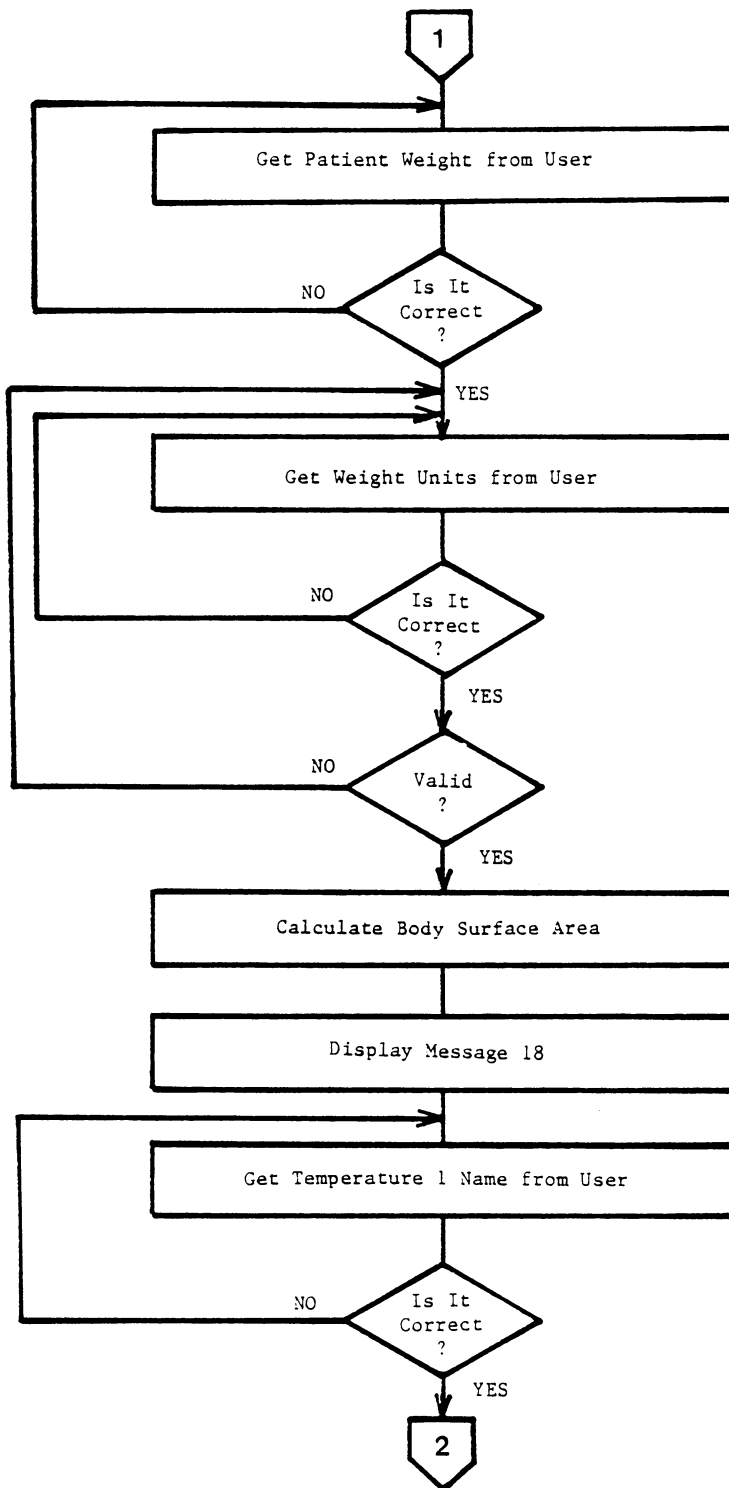


Figure 11 b. Input Section Flowchart

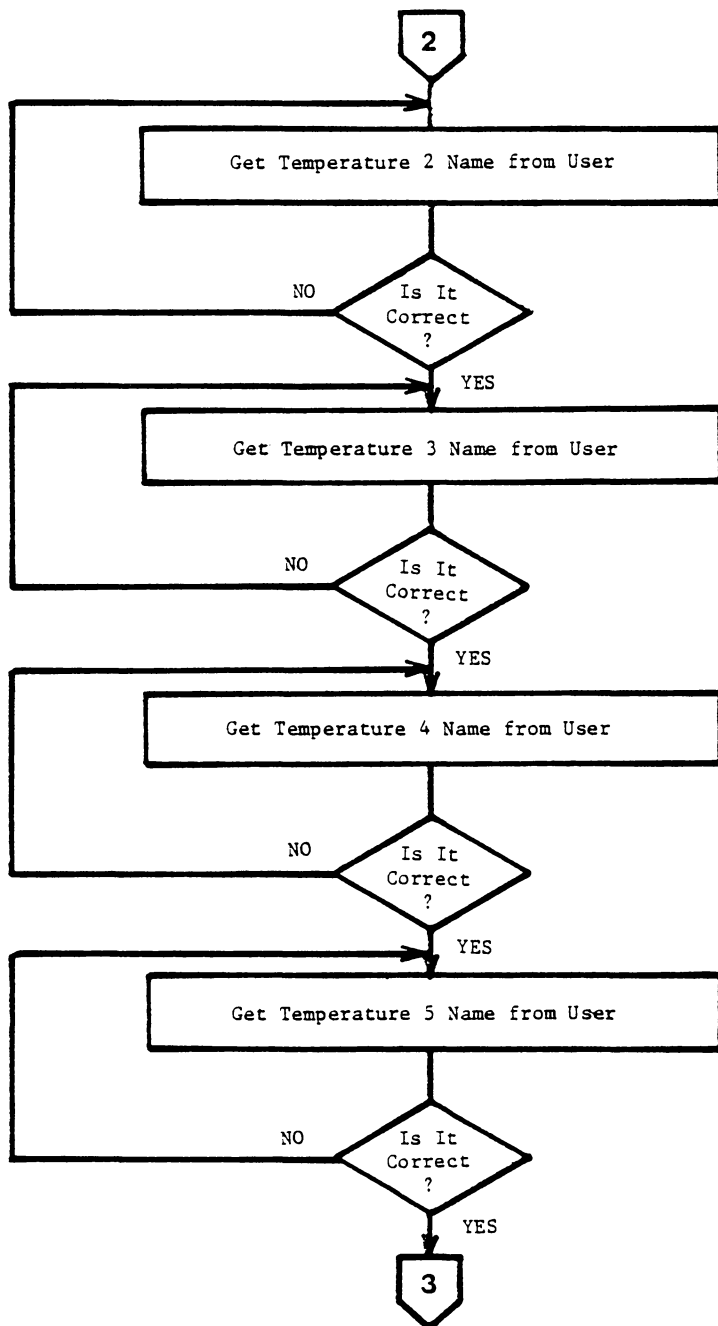


Figure 11 c. Input Section Flowchart

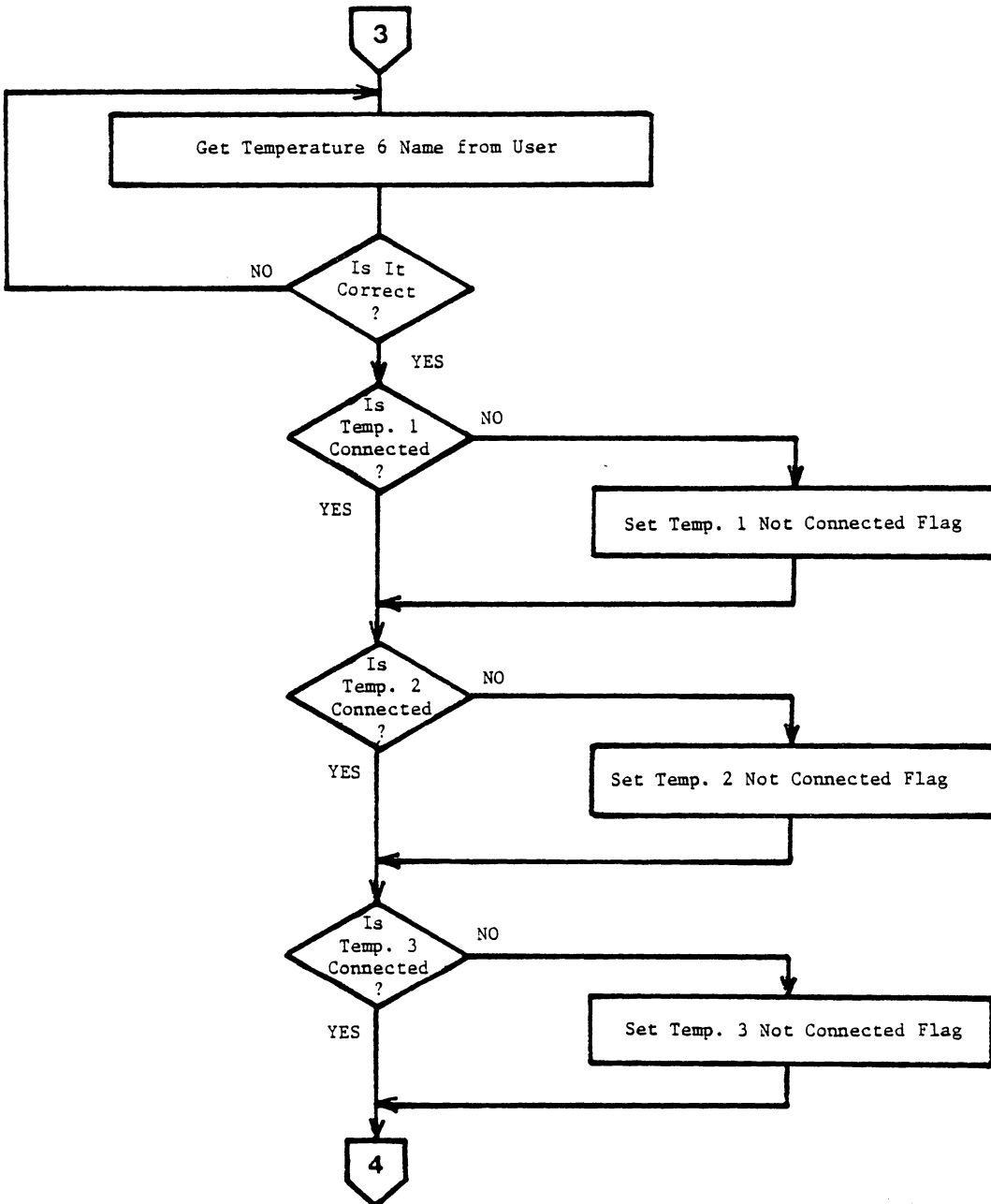


Figure 11 d. Input Section Flowchart .

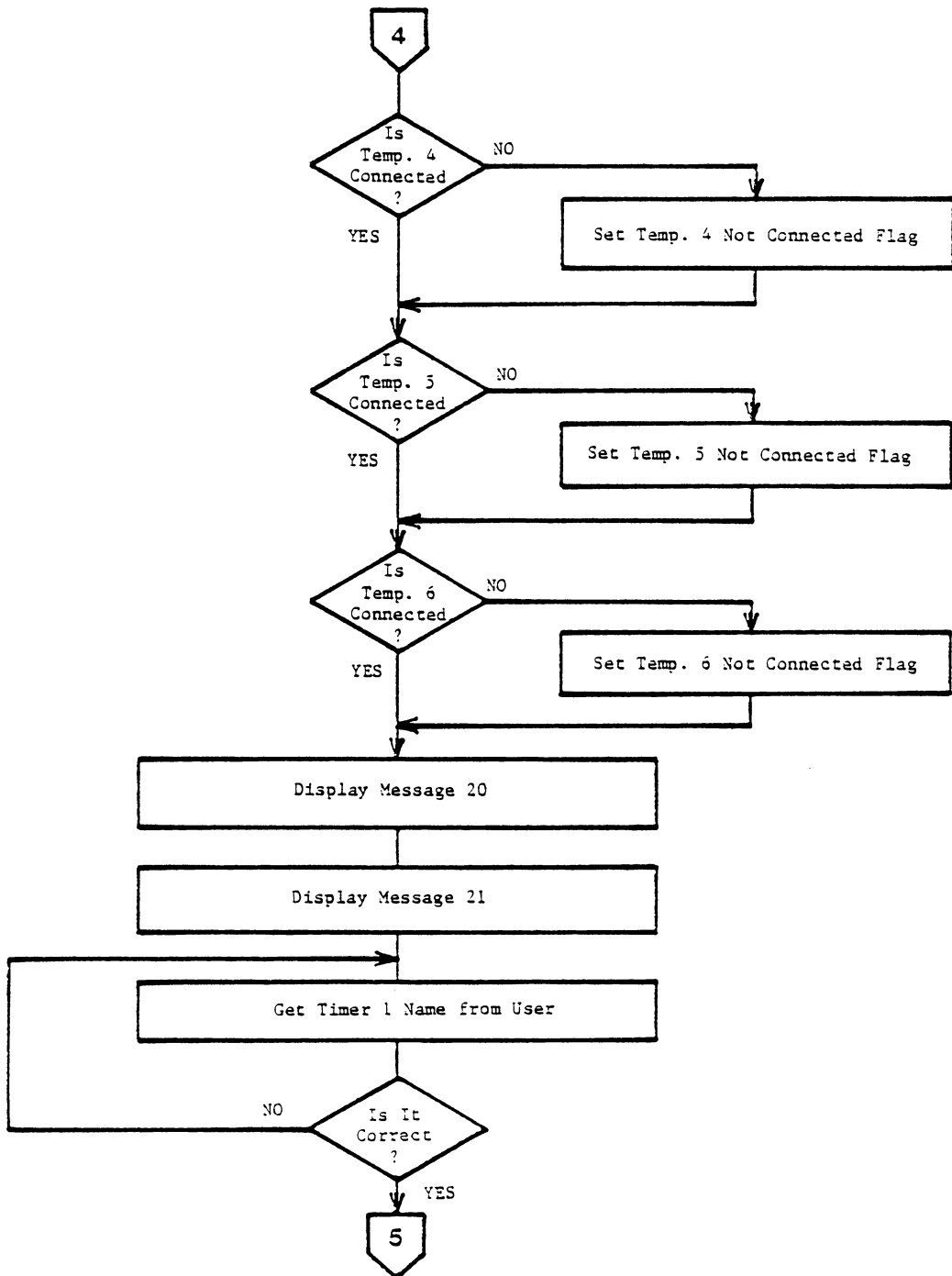


Figure 11 e. Input Section Flowchart

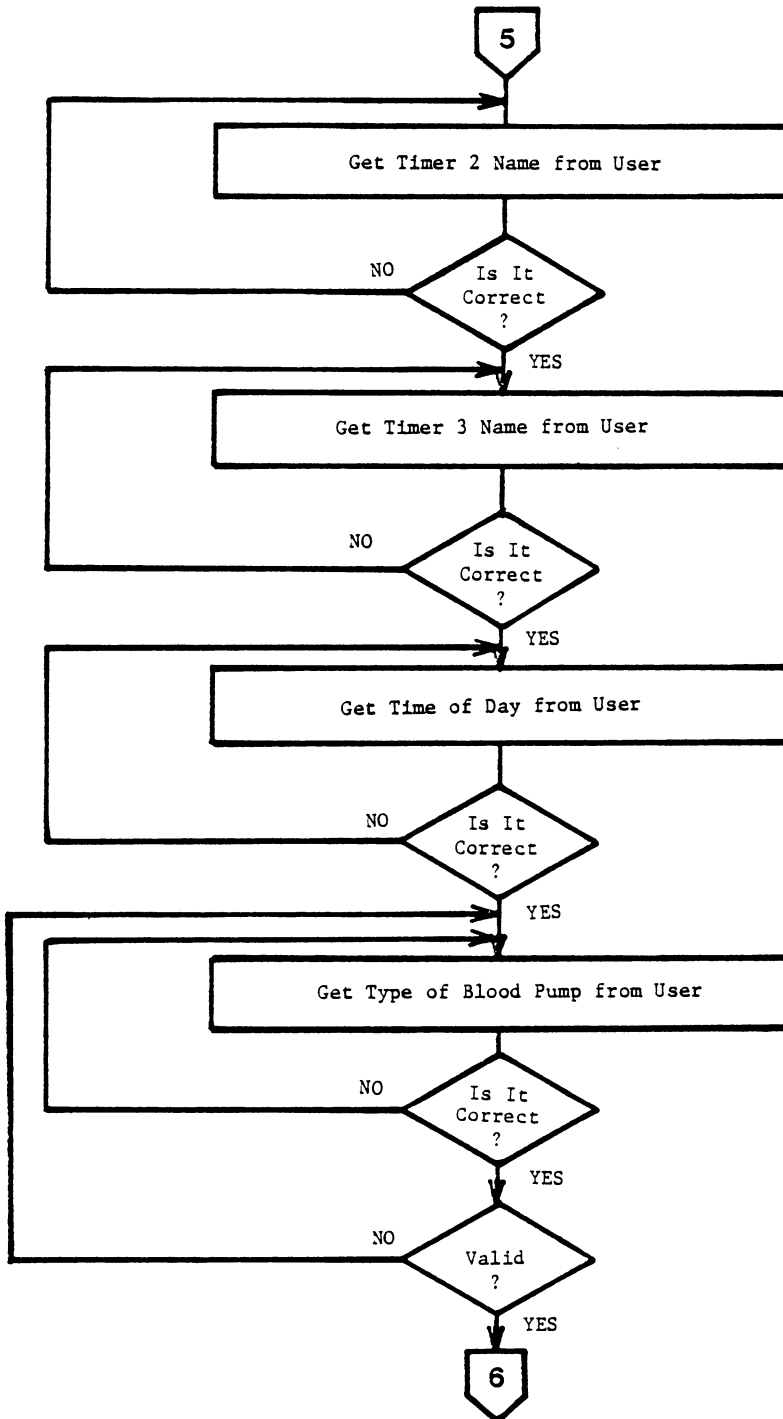


Figure 11 f. Input Section Flowchart

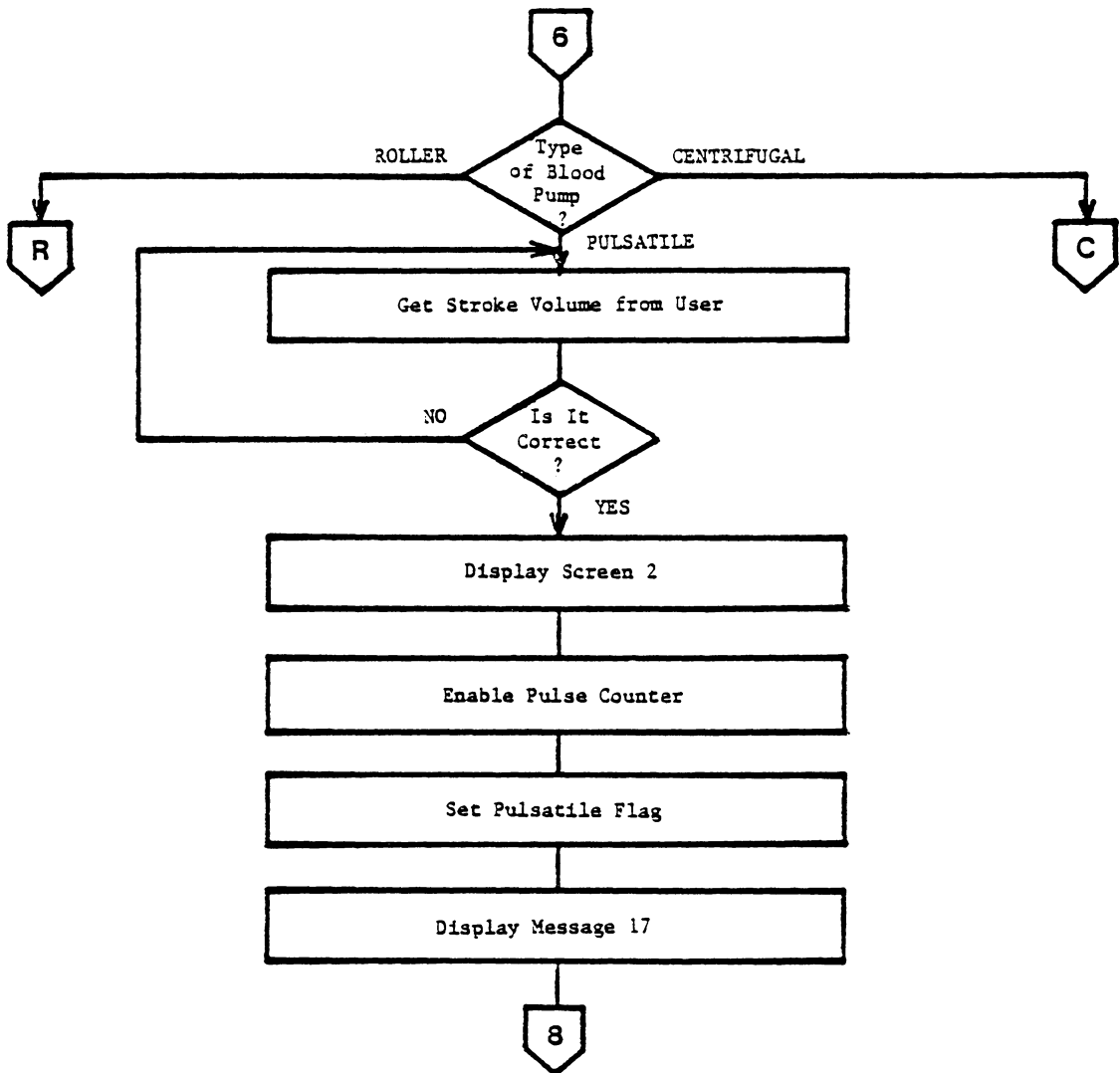


Figure 11 g. Input Section Flowchart

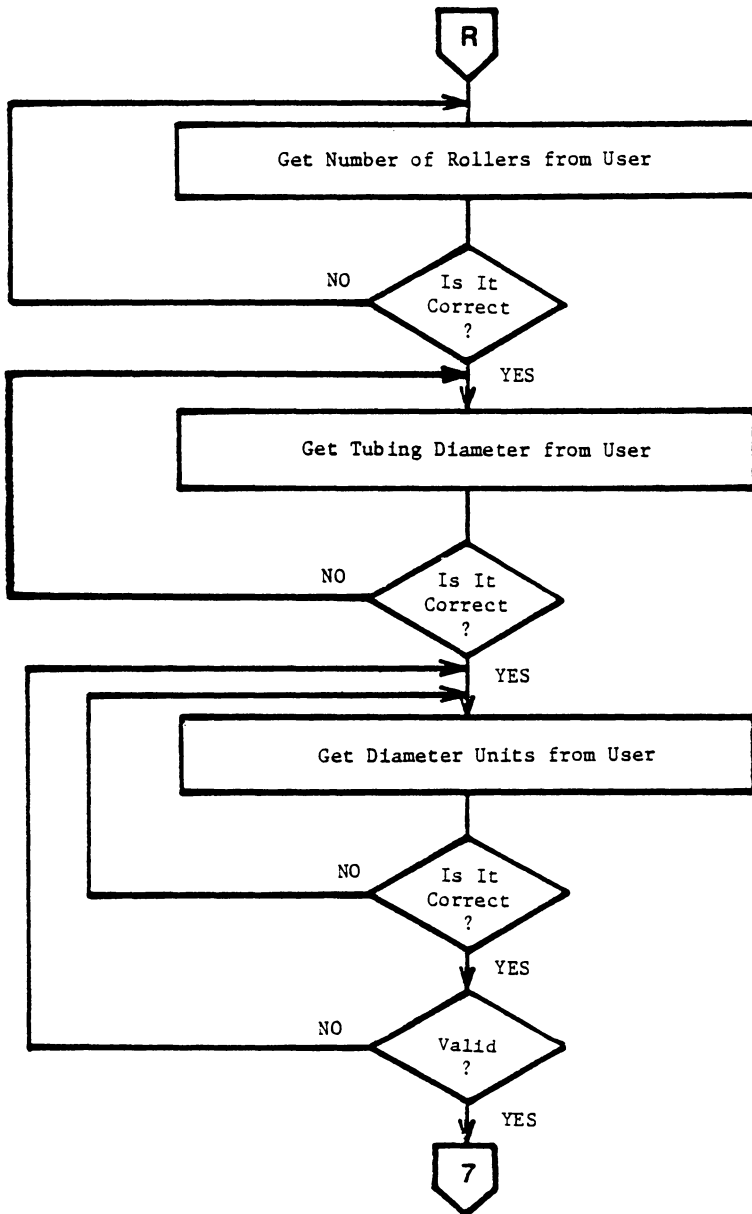


Figure 11 h. Input Section Flowchart

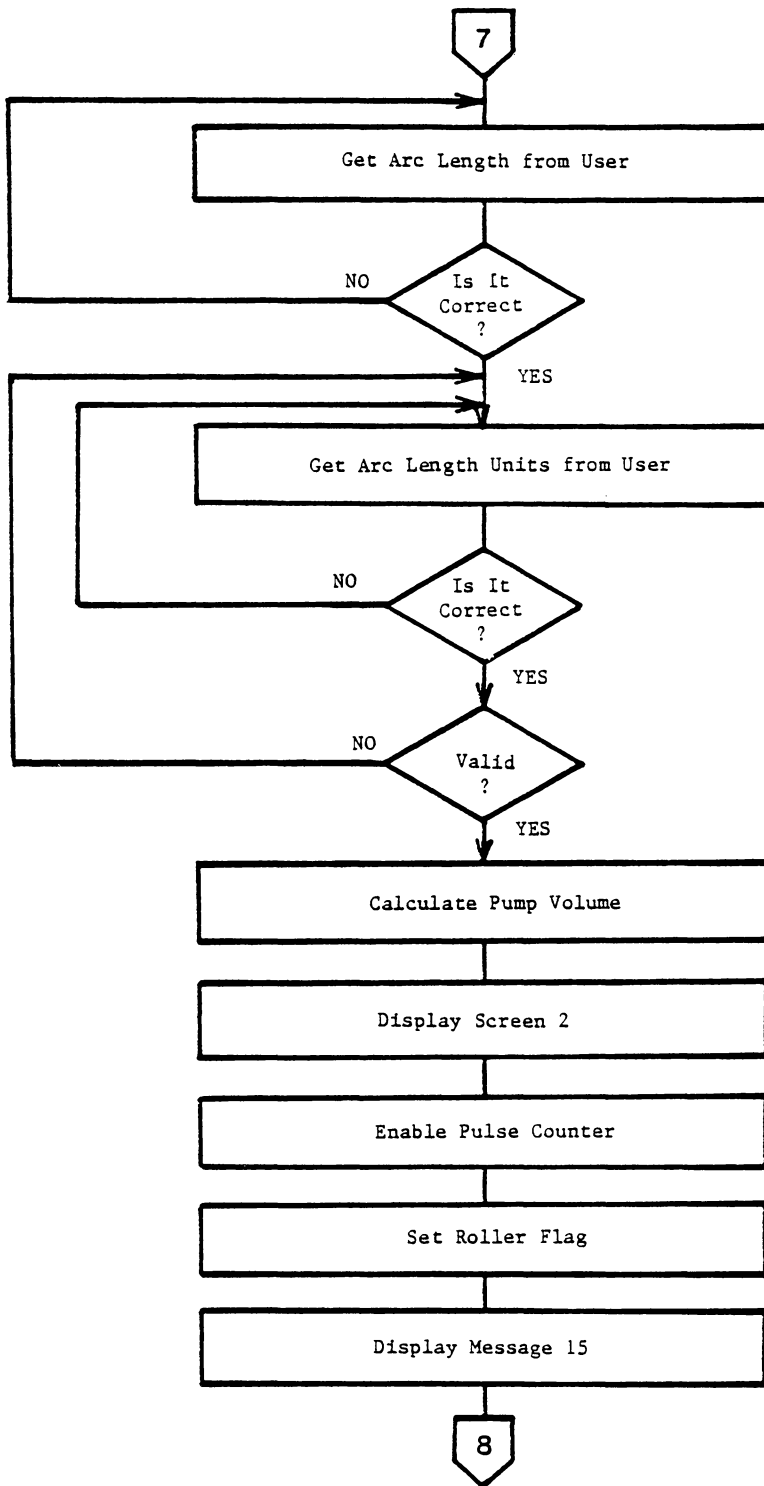


Figure 11 i. Input Section Flowchart

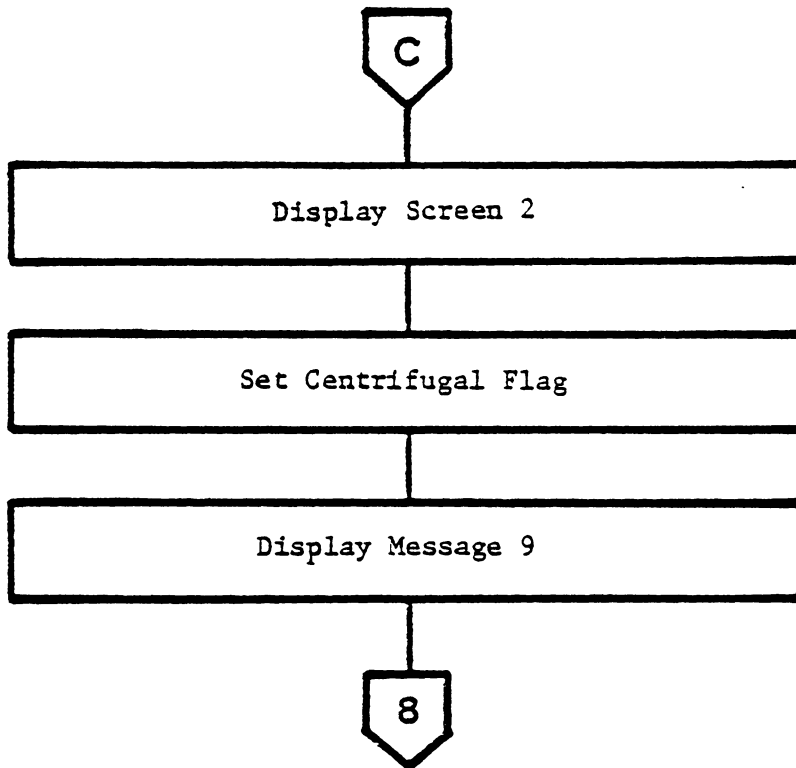


Figure 11 j. Input Section Flowchart

the entry is correct and is able to change the entry if needed. If an invalid entry is made, such as kd instead of kg, for kilograms, the program displays a message to the user to input the entry again.

Next, the temperature information is input. Labels for each of the six temperature probes are entered with a chance for correction if needed. If a temperature probe is not being used, then the user names the probe "N/C" for not connected. The program then checks for unconnected probes and sets the appropriate flags.

The third input section accepts the timer labels. Again the entries can be changed if needed. The current time is also input at this time.

Finally, the pump information is entered. First, the type of blood pump is input, either centrifugal, roller or pulsatile. Next, depending on the type of pump various parameters need to be entered.

If the centrifugal pump is being used, then screen 2 is displayed by an assembly language subroutine. Screen 2 is the monitor display as shown in Appendix B. Next the centrifugal flag is set and message 9, CENTRIFUGAL PUMP, is displayed in the correct location on the monitor screen.

If the roller pump is being used, then the user inputs the following information: the number of rollers, the tubing diameter and units, and the arc length and units. The

program checks for valid units and allows the user to correct any of the inputs if necessary. Next, the roller pump volume, PV, in ml, is calculated using the following formula:

$$PV = NR*AL*3.1416*(TD**2)/4$$

where NR is the number of rollers, AL is the arc length in cm, and TD is the tubing diameter in cm. The program then displays screen 2, the monitor screen, as shown in Appendix B. Next, the revolutions per minute pulse counter on the 6522-1 versatile interface adapter is enabled and cleared. The roller flag is then set and message 15, ROLLER PUMP, is displayed in the correct spot on the screen.

If a pulsatile pump is being used, then the user is asked to input the stroke volume of the pump in cc. Again, the user can correct his response if necessary. The monitor screen, screen 2, is then displayed, as shown in Appendix B. The pulse counter on the versatile interface adapter is then cleared and enabled, the pulsatile flag set, and message 17, PULSATILE PUMP, is displayed at the correct screen location.

### Monitor and Display Loop

Next, the program displays all of the patient monitor information as flowcharted in Fig. 12. First, the names of the patient, the timers, and the temperatures are displayed on the screen. The program then prints the initial timer values of 00:00:00 (hours:minutes:seconds). Next, the

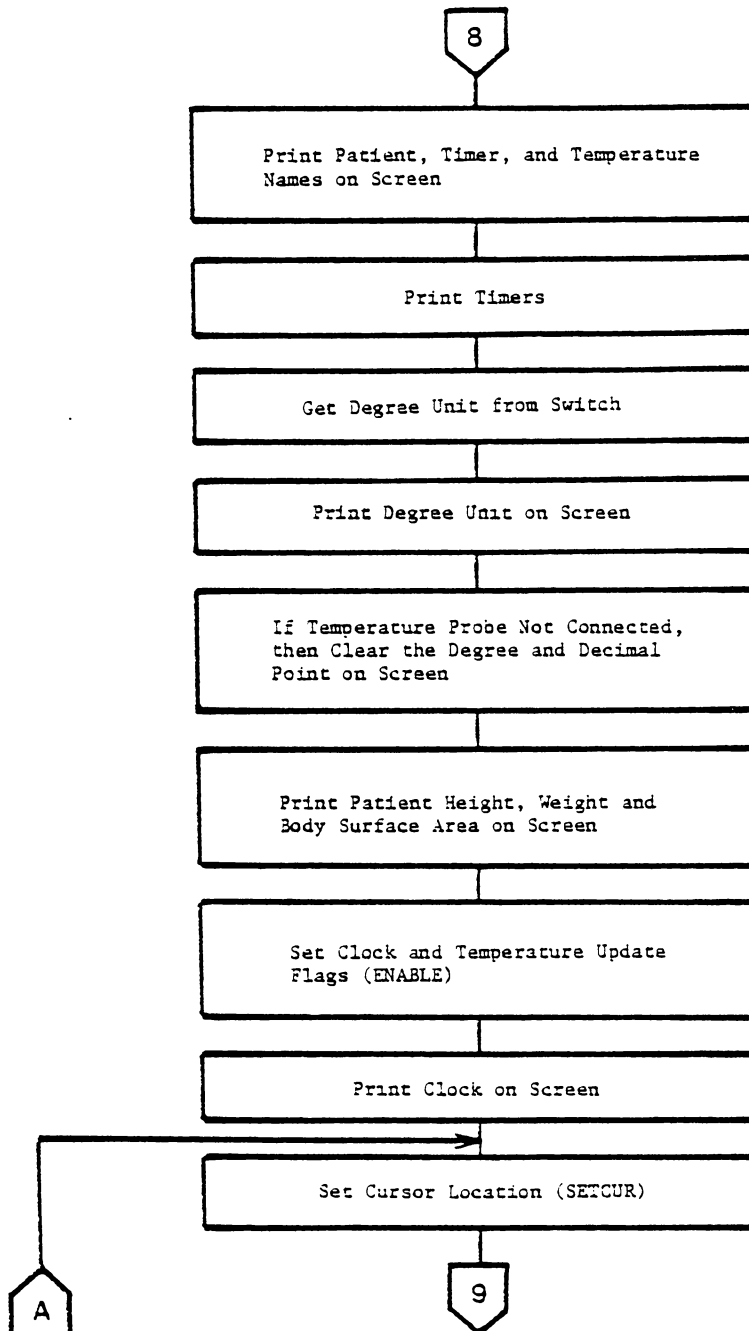


Figure 12 a. Monitor and Display Flowchart

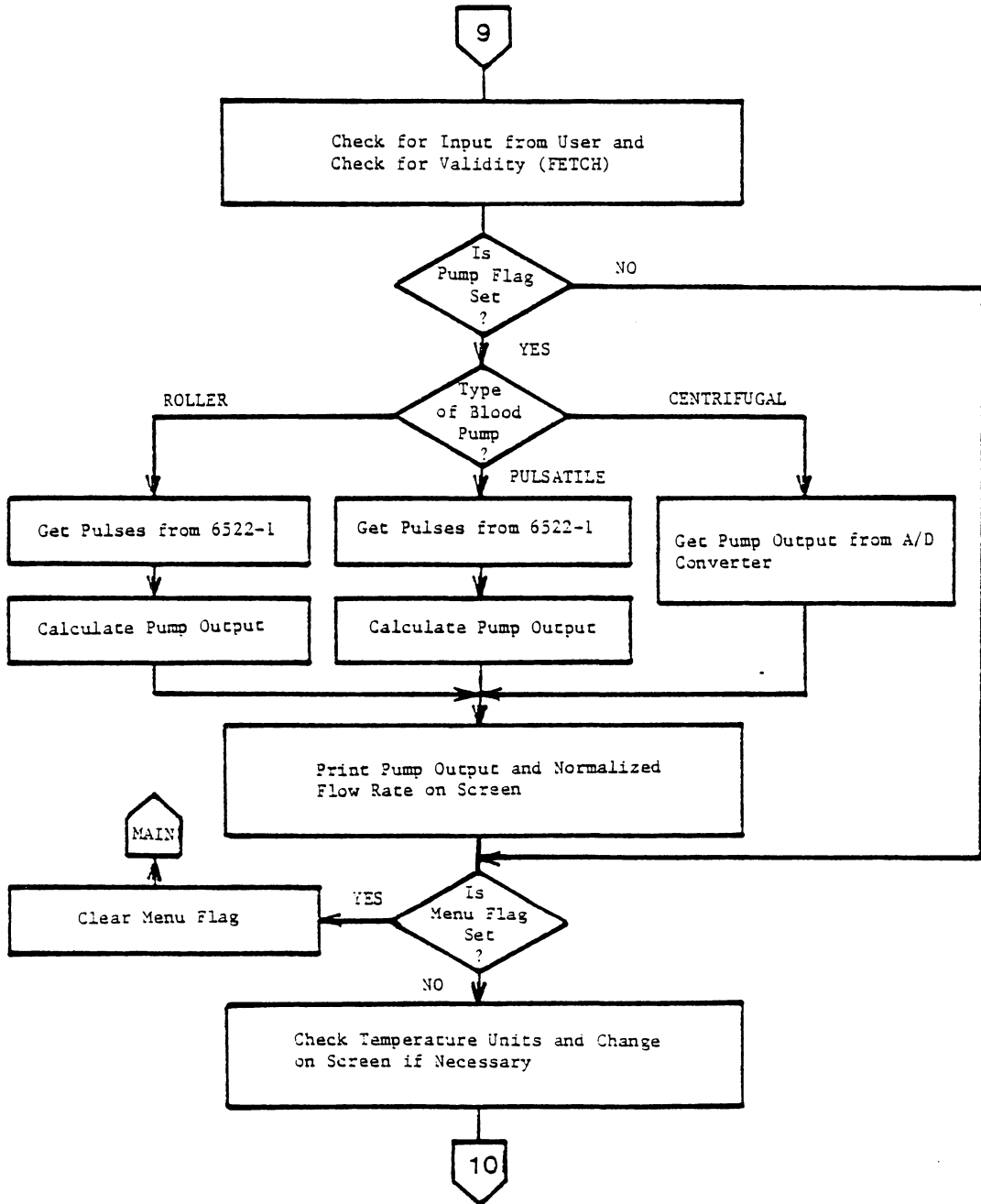


Figure 12 b. Monitor and Display Flowchart

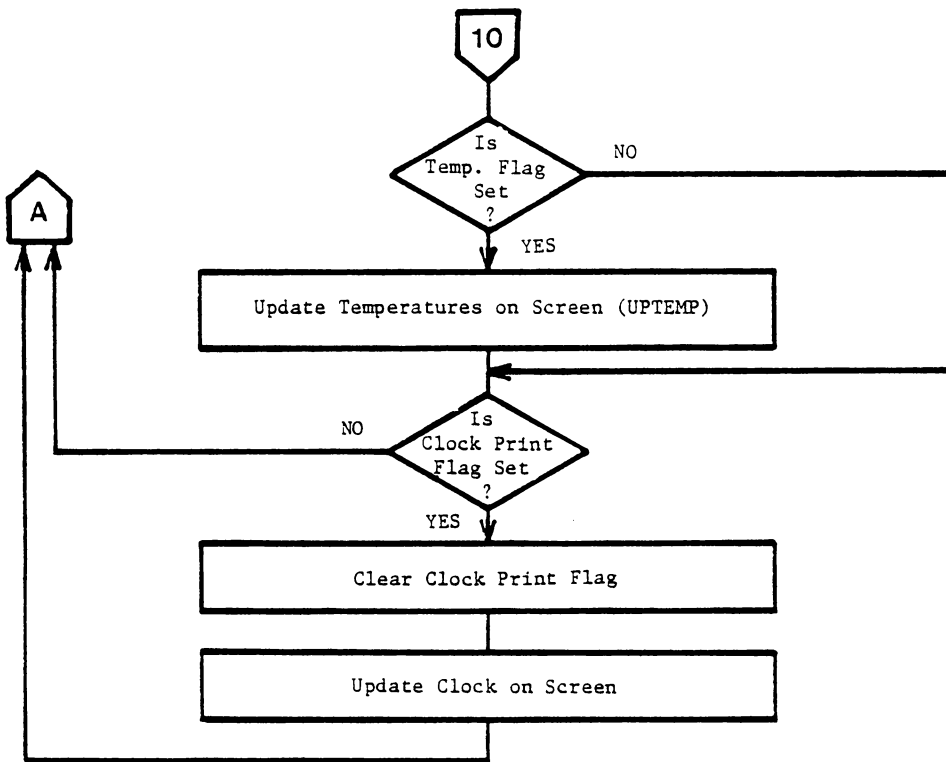


Figure 12 c. Monitor and Display Flowchart

temperature degree unit is input from the peripheral interface adapter and printed on the screen. Then, the degree unit and the decimal point are cleared on the screen, if the corresponding temperature probe is not being used. The patient's height, weight and surface area are printed next. Finally, the clock and temperature update flags are set, then the clock is printed on the screen.

The next section described is the software loop that the computer stays in while monitoring the patient information. First, software sets the cursor location for the display of the timer commands, such as s1 which starts timer 1. A machine language subroutine, SETCUR, uses a VIC 20 subroutine to set the cursor location on the screen. Then, using the machine language subroutine, FETCH, based on a subroutine described in Browning's thesis, "Design of a Microcomputer-Based Microporous Membrane Process Controller" [6], the program checks for any keyboard input from the user and checks its validity. If a valid input is found then the input is printed on the screen at the cursor location and the command is implemented. For example, an input of s1 would cause timer 1 to start and s1 would be printed on the screen. If an invalid input is found then the timer command is cleared from the screen and the program execution continues.

Next, the program checks to see if it is time to update the pump output by checking the pump update flag. If the

flag is set, then the program checks for the type of blood pump being used, either centrifugal, roller, or pulsatile.

If the centrifugal flag is set, then the program gets the pump output from the A/D converter using the machine language subroutine, TNEW, based on the subroutine described in Mears' thesis, "A Microcomputer-Based Temperature and Humidity Control System for Respiratory Therapy" [7].

If the roller flag is set, then the program takes the number of pulses from the 6522-1 and calculates the pump output, PO, in ml/min using the following formula:

$$PO = \text{Pump Volume} * \text{Number of Pulses} * 1.2$$

where the pump volume is in ml, and the pulses are counted for 1/2 sec with 100 pulses being generated per revolution.

When the pulsatile flag is set, the number of pulses from the 6522-1 is read and the pump output in ml/min is calculated using the following equation:

$$\text{Pump Output} = \text{Stroke Volume} * \text{Number of Pulses} * 120$$

where the stroke volume is in cc, and the pulses are counted for 1/2 sec.

The pump output and the two normalized blood flow rates are then printed on the screen. If the pump flag was not set then the pump output is not updated on the screen and the program continues to determine whether or not the user wants to return to the input section by checking the menu flag.

If the menu flag is set, then the program returns to the beginning of the input section. If the menu flag is not set, then the program checks to see if the operator has changed the temperature degree units to be displayed on the screen. The degree units are then changed on the screen if necessary.

Next, the program checks the temperature update flag. If the flag is set, then it is time to update the temperatures. The program updates the temperatures using the machine language subroutine, UPTEMP. If the temperature update flag is not set, then the program does not update the temperatures and continues to check the clock print flag.

When the clock print flag is set, the program reads the time of day using the VIC 20 BASIC command, TI\$ [3]. This value is then displayed on the screen and the flag is cleared. The program then goes back to setting the cursor location and checking for user input. If the clock print flag was not set, then the program returns to setting the cursor and checking for keyboard input. The program continues to repeat this loop until the power is turned off.

### Assembly Language Subroutines

In the following discussion of the assembly language subroutines, the starting address of the subroutine is given in parentheses after the subroutine name.

## Video Display

The title and monitor screens, as shown in Appendix B, are displayed using subroutines SCREN1 (\$A47E) and SCREN2 (\$226A) respectively. These routines use a series of load and store commands which load a number into the processor accumulator then store the value at a memory location. Characters are displayed on the VIC 20 by storing an ASCII value in the screen memory. The screen memory starts at address \$1E00 and continues to address \$1FF9. These addresses describe a character grid of 22 columns by 23 rows, where \$1E00 is the location of the character to be displayed in the top left corner, and \$1FF9 is the location of the character to be displayed at the bottom right corner of the screen [3].

Similarly, each character has a color determined by a value placed in the color memory which starts at address \$9600 and ends at address \$97F9. Seven character colors can be used, black, white, red, cyan, purple, green, blue, and yellow. These colors are displayed, respectively, by storing a number from 0 to 7 at the address corresponding to the desired screen location.

All of the printed messages on the screen are accomplished using one of two subroutines, DISPLY and MSGE. Both of these subroutines are based on routines described in

Browning's thesis "Design of a Microcomputer-Based Microporous Membrane Process Controller" [6].

The first routine, DISPLY (\$A38A), takes a string of ASCII values in memory and outputs them one at a time to the screen using the VIC 20 subroutine, CHROUT (\$FFD2). This routine takes the ASCII value in the accumulator and displays it on the screen at the current cursor location. The routine, DISPLY, simply needs the starting address of the string of ASCII values as well as the number of characters to be displayed.

The second display routine, MSGE (\$A398), stores a string of ASCII values at a certain location in screen memory. This routine needs, in addition to the starting address and the length of the character string, the starting address of the screen memory where the character string is to be displayed.

### Keyboard Input

During the monitoring loop, the operator can start, stop, or reset any of the three timers, as well as return to the patient input section. Two subroutines, SETCUR and FETCH, get the user input from the keyboard then display and implement any valid commands.

SETCUR (\$A20C) uses a VIC 20 subroutine, PLOT (\$FFF0), which when the accumulator carry flag is clear, positions the

cursor to the column (0-21) indicated by the Y register and the row (0-22) indicated by the X register. In SETCUR, the cursor is positioned at column 18 and row 2 for display of the valid commands.

FETCH (\$A215 checks to see if any keyboard entry has been made, using the VIC 20 subroutine, GETIN (\$FFE4), which removes one character from the keyboard queue. If the queue is empty then after returning from subroutine, GETIN, the accumulator will be zero. If there is an entry, then FETCH checks it for validity. There are 10 valid entries:

s1 - starts timer 1

s2 - starts timer 2

s3 - starts timer 3

e1 - stops timer 1

e2 - stops timer 2

e3 - stops timer 3

r1 - resets timer 1

r2 - resets timer 2

r3 - resets timer 3

m - returns to input section

The user must press the RETURN key after each of the above entries. If one of these entries is found, it is displayed on the screen and its function is implemented. If none of these entries are recognized, then the display is cleared and program execution continues.

## Temperature Update

In order to update the temperatures, a subroutine called UPTEMP (\$4000), is called. This subroutine first checks for an unconnected temperature probe by looking at the respective temperature connect flag. If the flag is set, then the temperature probe is not being used and the program continues to check the next flag. If the flag is not set, then the routine closes the switch connecting that probe to the temperature board while at the same time opening all of the other probes' switches. This is accomplished by writing, to port B of the 6520-1, a 1 in the bit position connected to the switch enable line of the temperature to be updated, while storing zeros at all other bit positions.

Once the correct probe is connected to the temperature board, the output of the A/D converter is read using the subroutine, TNEW (\$A423). This routine delays for 1/2 sec to make sure the converter is displaying the correct value. This delay is needed since the converter has a long recovery time from an underrange condition, i.e., any voltage under 0.180 V. After the time delay, the routine waits for an end-of-conversion pulse by monitoring the B control register of the 6520-1. When the pulse occurs, bit 7 of the B control register is set to a 1. Next, the routine monitors port A or the 6520-1 to wait for digit select 1, DS1, to go high. When DS1 goes high, the value at port A is stored in memory. Both

the digit select lines and the binary coded decimal data lines are connected to port A of the 6520-1. Therefore, when port A is read the data for digit 1 is on the lines when the digit select 1 line is high. This eliminates the possibility of reading the wrong data for the desired digit. Similarly, the program reads and stores the second through the fourth digit, then returns to the routine UPTEMP.

### Interrupt Processing

The VIC 20 generates an interrupt request signal every 1/60 sec. This signal causes program execution to jump to a VIC 20 interrupt servicing routine which is used to update the system clock as well as check to see if any keyboard entries have been made. This interrupt routine is easily bypassed simply by storing the address of the programmer's routine at addresses \$0314 (low byte) and \$0315 (high byte) in the initialization routine.

In this design, the VIC 20 routine is bypassed and the routine flowcharted in Fig. 13 is used. As shown in Fig. 13, the routine first checks to see if the roller pump is being used. If it is then the pump output update counter is incremented and compared with 30. Since the interrupt is generated every 1/60 sec, a count of 30 is equivalent to 1/2 sec. If the counter has reached 30, then the pump output update flag is set. The routine then reads the number of

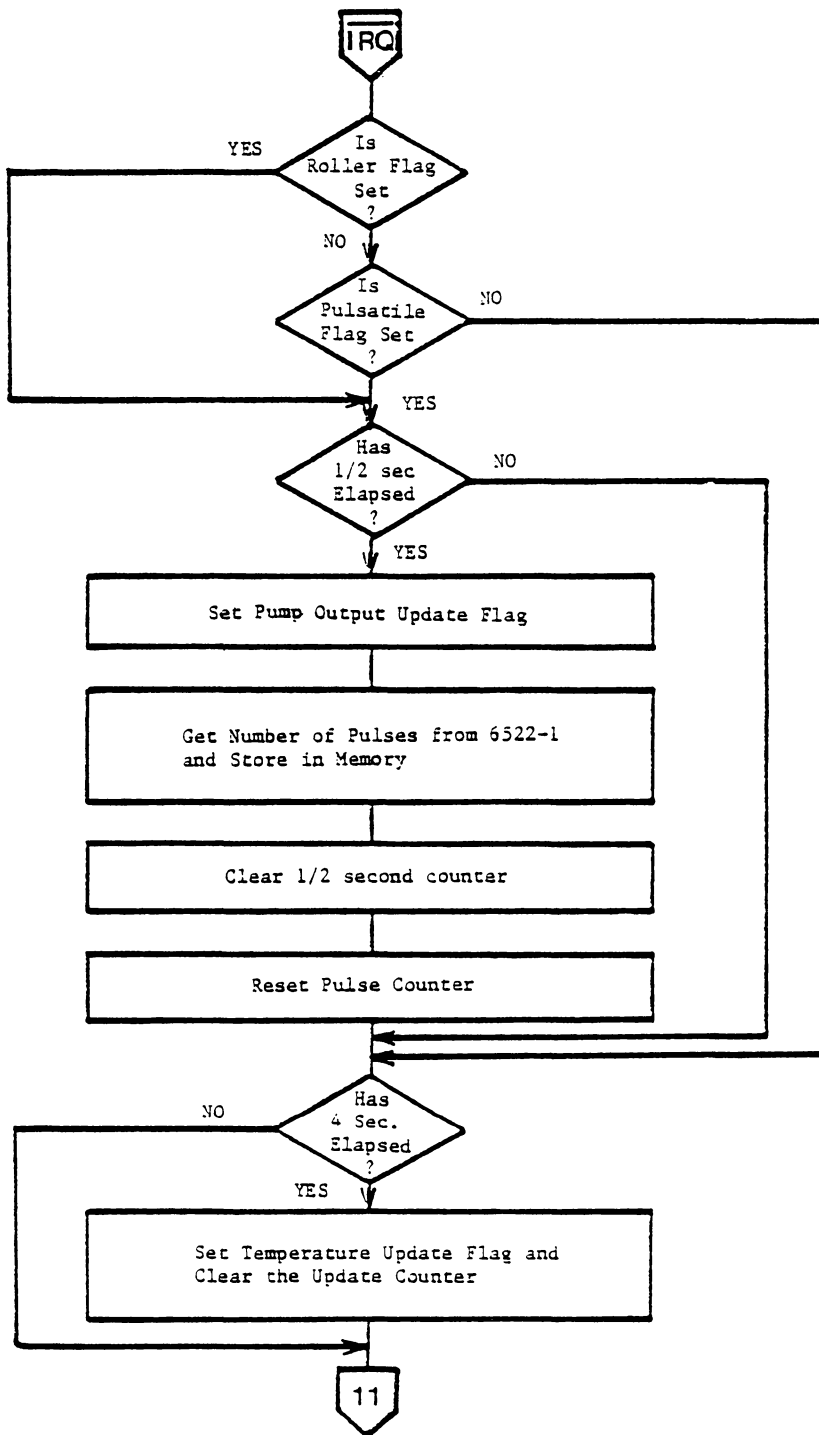


Figure 13 a. Interrupt Routine Flowchart

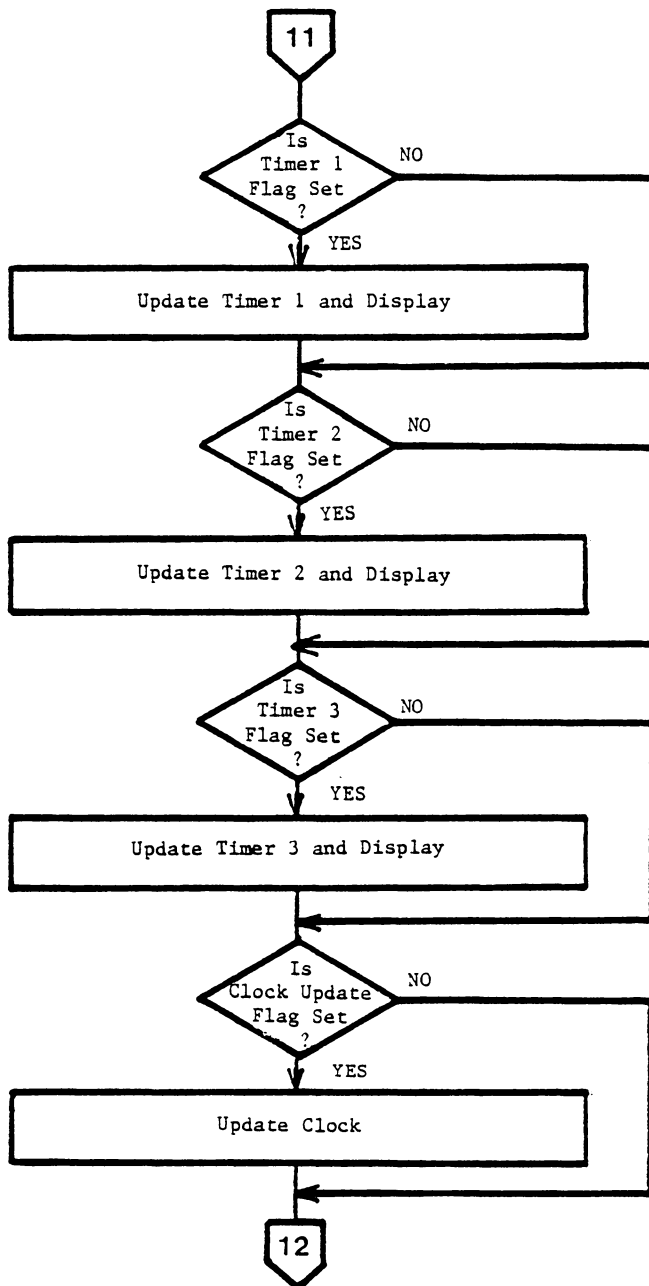


Figure 13 b. Interrupt Routine Flowchart

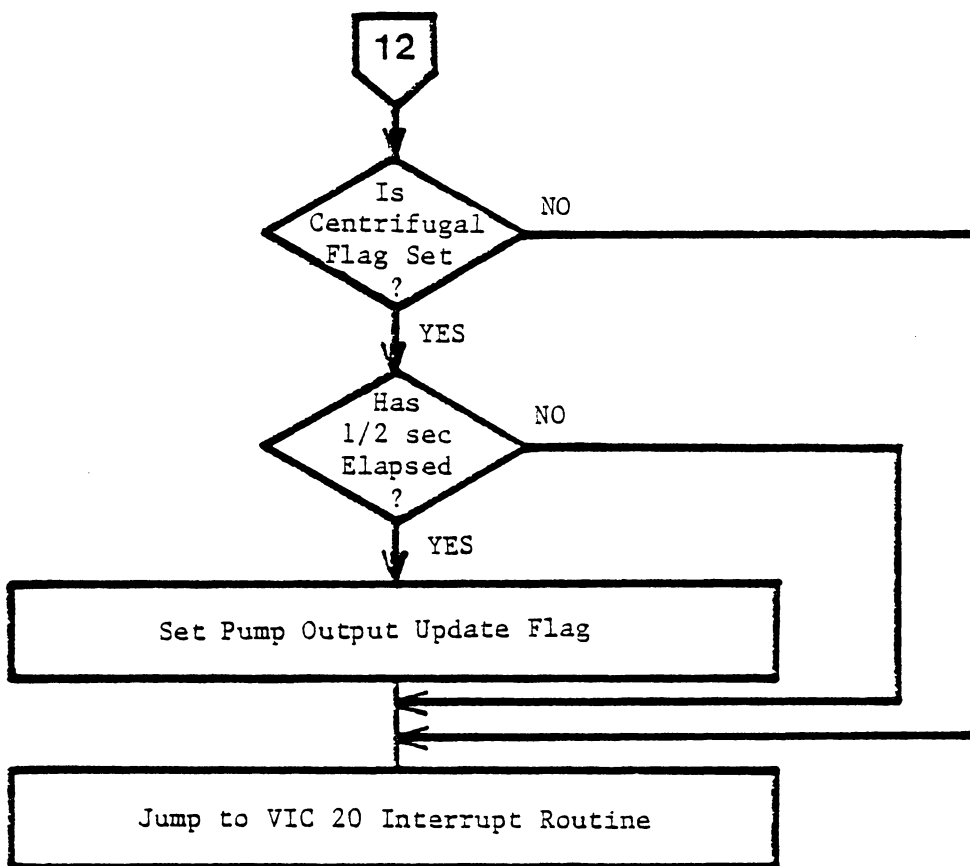


Figure 13 c. Interrupt Routine Flowchart

pulses counted by the 6522-1, the versatile interface adapter, and stores the value in memory. The pump output update counter is then cleared along with the pulse counter on the 6522-1.

If the roller pump is not being used, then the program checks for a pulsatile pump. If the pulsatile pump is being used, then the program increments the pump output update counter, compares it to 30 and sets the pump output update flag if 1/2 sec has elapsed. Then, just as if the roller pump was being used, the pulse counter is read and stored in memory, and the pump output update counter along with the pulse counter are cleared.

If neither the roller or the pulsatile pump is being used, or if 1/2 sec has not elapsed, then the program jumps to the next portion of the interrupt service routine as shown in Fig. 13.

This section increments the temperature update counter and compares it to 240 (4 sec). If 4 sec has elapsed, then the temperature update flag is set, the counter is cleared, and program execution continues to the timer update section. If 4 sec has not gone by, then the program jumps to the timer update section.

In the timer update section, first the timer 1 flag is read. If the flag is set then the timer 1 counter is incremented, stored in memory, and displayed on the screen if

1 sec has elapsed (60 counts). The program execution then continues to check the timer 2 flag. If the timer 1 flag is not set then the program branches to check the timer 2 flag. Timers 2 and 3 are checked and updated similarly to the timer 1 routine.

After checking timer 3, the program checks the clock update flag. If the flag is set then a counter is incremented and compared with 60. If the counter is equal to 60 (1 sec), then the clock print flag is set, the counter is cleared, and program execution continues to check for a centrifugal pump. If the clock update flag is not set, or if the counter has not reached 1 sec, then the program branches to the centrifugal pump routine.

If the centrifugal flag is set, then a pump update counter is incremented and compared to 30. If 1/2 sec has elapsed then the pump output update flag is set, the counter is cleared, and the program jumps to the VIC 20 interrupt service routine. If either the centrifugal pump is not being used or the 1/2 sec has not elapsed, then the program jumps to the VIC 20 interrupt routine.

## V. SYSTEM EVALUATION

### Electrical System

The electrical system worked as expected. The time of day clock worked perfectly, as compared with a timex quartz watch. When the clock was synchronized with the watch, after 3 hours the clock still agreed with the watch. Also, all three of the timers ran for 3 hours keeping perfect time.

As shown in Table 3, the switches to connect the 6 temperature probes and the centrifugal flow probe worked perfectly. To show this, different voltages were connected to the probes and the screen displayed the correct voltages for the corresponding probes.

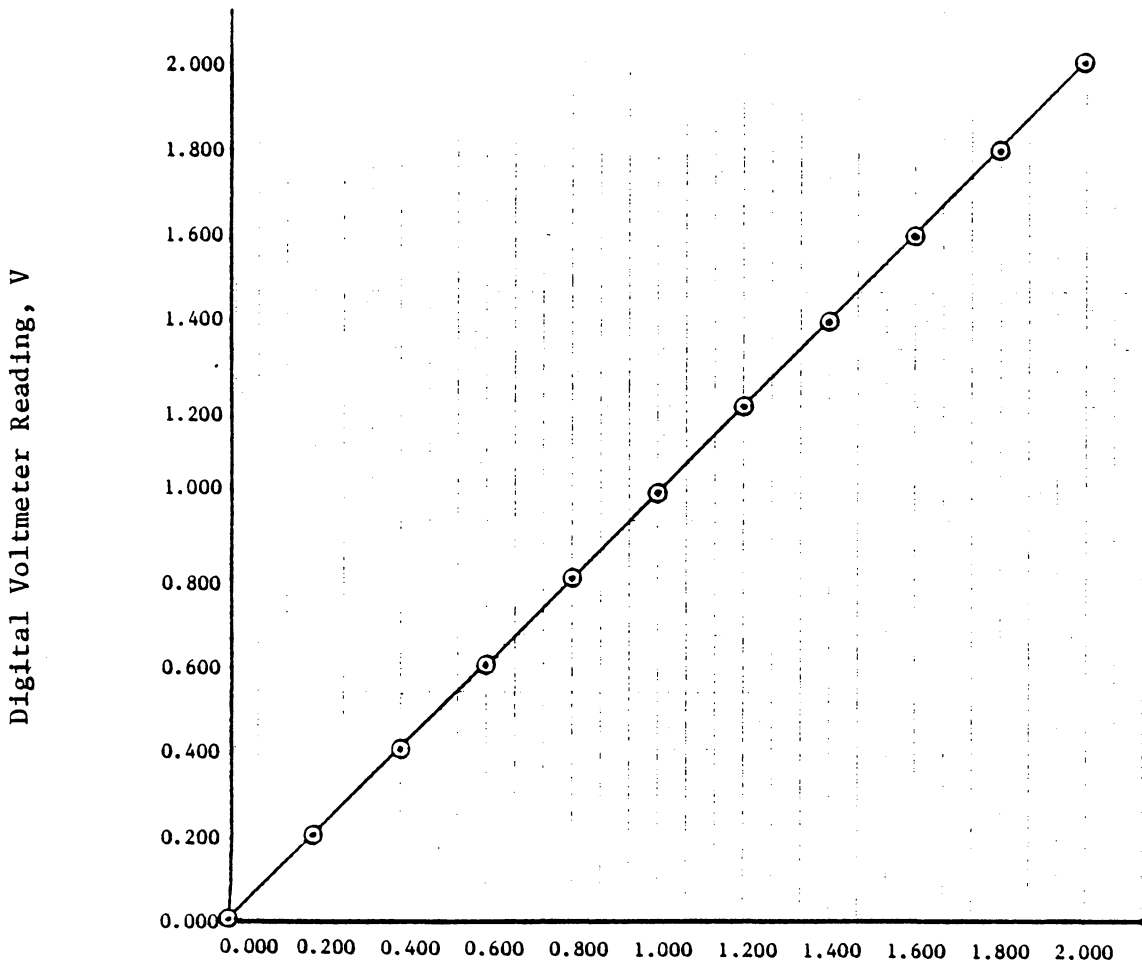
In order to verify that the A/D converter worked correctly, 11 voltages ranging from 0.000 to 2.000 were input through all of the temperature probes and the centrifugal flow probe. As shown in Fig. 14, the input voltages, as measured with a digital voltmeter (DVM), compared within a millivolt to the values displayed on the patient monitor screen.

To prove that the pulse counter on the versatile interface adapter was working correctly, square waves with varying frequencies were input to the interface board using a 555 timer integrated circuit. The square waves were monitored on an oscilloscope to compare with the values

Table 3. Verification of Analog Switches

<u>Probe</u>	<u>Input, V *</u>	<u>Screen Display</u>
Temp. 1	0.020	2.3
	1.999	199.9
Temp. 2	0.667	67.0
	0.020	2.3
Temp. 3	0.930	93.2
	1.615	161.4
Temp. 4	1.267	126.8
	0.930	93.2
Temp. 5	1.615	161.4
	0.668	67.0
Temp. 6	1.797	179.7
	1.268	126.8
Centrifugal Flow	0.668	670.
	0.020	2.

\*As measured by a digital voltmeter, Fluke model 8050A,  
SN 3016073, on 8/20/85



Temperature Probes 1-6,  $\times 10^2$   
Centrifugal Flow Probe,  $\times 10^3$

Figure 14. Accuracy of Temperature and Centrifugal Flow Probes

counted by the 6522-1. The pulses counted were calculated, for the roller pump, by dividing the displayed pump output by 1.2 times the pump volume. For the pulsatile pump, the pulses were calculated by dividing the displayed pump output by 120 times the stroke volume. Table 4 shows the pulses counted by the 6522-1 versus the oscilloscope readings for both the roller and the pulsatile pump. This table shows a slight discrepancy, at the most 13 pulses, between the oscilloscope reading and the number of pulses counted by the 6522-1. This is due to the fact that the oscilloscope cannot be read with the accuracy and precision necessary to compare with the pulse counter. For all of the data points the pulse counter predicted a reading which agreed with the oscilloscope within  $\pm 2$  small divisions.

### Software System

The software worked as expected, with all calculations checked using a Hewlett-Packard 15C calculator. As shown in Tables 5 and 6, the calculated and displayed pump output for both the roller pump and the pulsatile pump agreed exactly, within the significant figures displayed on the screen.

To make sure that the calculations involving the patient data were correct, data values as shown in Table 7 were input and the displayed outputs compared with the calculated values using the hp 15C. The calculator predicted exactly the values

Table 4. Verification of Pulse Counter

Oscilloscope *			Monitor Screen		
<u>No. of Divisions</u>	<u>Time Scale/Div.</u>	<u>Pulses Counted</u>	<u>No. of Divisions</u>	<u>Time Scale/Div.</u>	<u>Pulses Counted</u>
4.3	10 ms	11.6	4.5/4.1	10 ms	11/12
4.8	5 ms	20.8	5.0	5 ms	20/21
4.1	5 ms	24.3	4.2	5 ms	24
4.2	1 ms	119.0	4.4	1 ms	113/114
4.5	0.5 ms	222.2	4.6	0.5 ms	216/217
4.0	0.5 ms	250.0	4.2	0.5 ms	237/238

\* Hitachi, V-152F 15 MHz, SN 430024, used on 8/21/85

Table 5. Roller Pump Output

<u>Pulses/ 1/2 sec</u>	<u>No. of Rollers</u>	<u>Inputs</u>		<u>Calculated and Displayed Pump Output, ml/min</u>
		<u>Tubing Diameter</u>	<u>Arc Length</u>	
11/12	2	0.5 in.	3 in.	255/278
11/12	2	1 cm	6 cm	124/136
20/21	2	1 cm	6 cm	226/238
20/21	2	0.5 in.	3 in.	463/487
216/217	2	0.5 in.	3 in.	5004/5027
216/217	2	1 cm	6 cm	2443/2454
237/238	2	1 cm	6 cm	2680/2692
237/238	2	0.5 in.	3 in.	5491/5514

Table 6. Pulsatile Pump Output

<u>Inputs</u>		<u>Calculated and Displayed Pump Output, ml/min</u>
<u>Pulses/1/2 sec</u>	<u>Stroke Volume, cc</u>	
11	0.1	132.
11	1.0	1320.
12	0.1	144.
12	1.0	1440.
24	0.1	288.
24	1.0	2880.
113	0.05	678.
113	0.1	1356.
114	0.05	684.
114	0.1	1368.
216	0.05	1296.
216	0.1	2592.
217	0.05	1302.
217	0.1	2604.

Table 7. Patient Data Calculations

Inputs		Calculated and Displayed Outputs				
Height	Weight	Height	Weight	Surface	*	*
				Area, m <sup>2</sup>	ml/min/kg	ml/min/m <sup>2</sup>
24 in.	10 lb	61 cm	5 kg	0.27	439.	7400.
36 in.	20 lb	91 cm	9 kg	0.48	219.	4108.
48 in.	50 lb	122 cm	23 kg	0.88	88.	2259.
52 in.	75 lb	132 cm	34 kg	1.11	58.	1794.
60 in.	100 lb	152 cm	45 kg	1.39	44.	1431.
66 in.	150 lb	168 cm	68 kg	1.77	29.	1124.
72 in.	200 lb	183 cm	91 kg	2.13	22.	934.
78 in.	250 lb	198 cm	113 kg	2.48	18.	802.
84 in.	300 lb	213 cm	136 kg	2.83	15.	703.
90 in.	320 lb	229 cm	145 kg	3.06	14.	651.
70 cm	10 kg	28 in.	22 lb	0.42	199.	4784.
80 cm	12 kg	31 in.	26 lb	0.50	166.	4019.
100 cm	15 kg	39 in.	33 lb	0.64	133.	3109.
110 cm	20 kg	43 in.	44 lb	0.78	100.	2568.
130 cm	30 kg	51 in.	66 lb	1.04	66.	1915.
140 cm	40 kg	55 in.	88 lb	1.24	50.	1606.
160 cm	50 kg	63 in.	110 lb	1.50	40.	1326.
170 cm	80 kg	67 in.	176 lb	1.92	25.	1039.
190 cm	100 kg	75 in.	220 lb	2.28	20.	872.
200 cm	120 kg	79 in.	265 lb	2.56	17.	777.

\*NOTE: All blood flows calculated using a pump output of 1990. ml/min

displayed on the screen, within the significant figures displayed.

## VI. RECOMMENDATIONS AND CONCLUSIONS

The system described in this thesis works perfectly. However, before using the system in the operating room, shielded cable should be added to connect the temperature board with the interface circuit board and the temperature probes. Also, shielded cable should be used to connect the pulse generator and the centrifugal flow probe with the interface circuit board.

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APPENDIX A

Software Listing

This appendix lists both the BASIC and the assembly language programs used in the patient monitor device.

Basic Program

In the listing of the BASIC program, the statements are listed in the left column separated by colons. In the right column, comments are written, separated by colons, to help explain the BASIC statements.

The symbols and abbreviations used in this listing follow.

?	= BASIC keyword for PRINT
sys XXXX	= BASIC command which jumps to a machine language subroutine at address XXXX
↑	= BASIC exponent operator
pn\$	= Patient's name
ph	= Patient's height
hu\$	= Height unit, either cm or in.
pw	= Patient's weight
wu\$	= Weight unit, either kg or lb
sa	= Patient's body surface area
t1\$	= Temperature 1 name
t2\$	= Temperature 2 name
t3\$	= Temperature 3 name
t4\$	= Temperature 4 name
t5\$	= Temperature 5 name
t6\$	= Temperature 6 name
tw\$	= Timer 1 name
tt\$	= Timer 2 name
th\$	= Timer 3 name
ti\$	= Time of day (HHMMSS)
pt\$	= Type of blood pump, either centrifugal or roller or pulsatile
nr	= Number of rollers
td	= Tubing diameter
du\$	= Tubing diameter units, either cm or in.

al = Tubing arc length  
 au\$ = Tubing arc length units, either cm or in.  
 pv = Pump volume in ml  
 sv = Stoke volume in cc  
 z = Variable screen location  
 x\$ = Variable character string  
 x = Length of character string  
 u = maximum length of character string

## Listing

1	print"☺":sys 41056:?	Clears the screen and makes the characters white:Displays message 1 on the screen:Prints a carriage return.
2	sys 41107:?:input"name";pn\$:gosub500	Displays message 4 on the screen:Prints a carriage return:Inputs the patient's name:Asks if the answer is correct.
3	if y\$="n" then 2	If the answer is no, then inputs the name again.
4	if y\$="y" then 6	If the answer is yes, then inputs the patient's height.
5	gosub600:go to 3	The answer is invalid, so asks again if the answer is correct:Checks the validity of the response.
6	sys 41107:?:input"height";ph:gosub 500	Displays message 4:Prints a carriage return:Inputs the patient's height:Asks if the answer is correct.
7	if y\$="n" then 6	If the answer is no, then inputs the height again.
8	if y\$="y" then 10	If the answer is yes, then inputs the height unit.
9	gosub600:goto 7	The answer is invalid, so asks again if the answer is correct:Checks the validity of the response.
10	sys 41124:?:input"or in";hu\$:gosub500	Displays message 5:Prints a carriage return:Inputs the height unit:Asks if the answer is correct.
11	if y\$="n" then 10	If the answer is no, then inputs the height unit again

12 if y\$="y" then 14	If the answer is yes, then inputs the weight.
13 gosub 600:goto 11	The answer is invalid, so asks again if the answer is correct:Checks the validity of the response.
14 gosub 700	Checks for a valid height unit, and inputs again if invalid.
15 sys 41107:?:input"weight";pw: gosub 500	Displays message 4:Prints a carriage return:Inputs the patient's weight:Asks if the answer is correct.
16 if y\$="n" then 15	If the answer is no, then inputs the weight again.
17 if y\$="y" then 19	If the answer is yes, then inputs the weight unit.
18 gosub 600:goto 16	The answer is invalid, so asks again if the answer is correct:Checks the validity of the response.
19 sys 41141:?:input"or lb";wu\$: gosub 500	Displays message 6:Prints a carriage return:Inputs the weight unit:Asks if the answer is correct.
20 if y\$="n" then 19	If the answer is no, then inputs the weight unit again.
21 if y\$="y" then 23	If the answer is yes, then checks the validity of the weight unit entered.
22 gosub 600:goto 20	The answer is invalid, so asks again if the answer is correct:Checks the validity of the response.
23 if wu\$="kg" then 27	If the weight unit is kg, then calculates the body surface area.
24 if wu\$="lb" then 26	If the weight unit is lb, then converts the weight to kg.
25 sys 41090:?:input"in kg or lb";wu\$:goto 23	Displays message 3:Prints a carriage return:Inputs the weight unit again:Checks its validity.
26 pw=pw*0.45359237	Converts the weight to kg.
27 sa=pw <sup>↑</sup> 0.425*ph <sup>↑</sup> 0.725*0.007184	Calculates the body surface area using the Dubois formula.
28 sys 41390:?	Displays message 18:Prints a carriage return.

29 sys 41407?:input"1  
measuring";t1\$:gosub 500

Displays message 19:Prints a carriage return:Inputs the name of temperature 1: Asks if the answer is correct.

30 if y\$="y" then 33

If the answer is yes, then inputs the name of temperature 2.

31 if y\$="n" then 29

If the answer is no, then inputs the name of temperature 1 again.

32 gosub 600:goto 30

The answer is invalid, so asks again if the answer is correct:Checks the validity of the response.

33 sys 41407?:input"2  
measuring";t2\$:gosub 500

Displays message 19:Prints a carriage return:Inputs the name of temperature 2: Asks if the answer is correct.

34 if y\$="y" then 37

If the answer is yes, then inputs the name of temperature 3.

35 if y\$="n" then 33

If the answer is no, then inputs the name of temperature 2 again.

36 gosub 600:goto 34

The answer is invalid, so asks again if the answer is correct:Checks the validity of the response.

37 sys 41407?:input"3  
measuring";t3\$:gosub 500

Displays message 19:Prints a carriage return:Inputs the name of temperature 3: Asks if the answer is correct.

38 if y\$="y" then 41

If the answer is yes, then inputs the name of temperature 4.

39 if y\$="n" then 37

If the answer is no, then inputs the name of temperature 3 again.

40 gosub 600:goto 38

The answer is invalid, so asks again if the answer is correct:Checks the validity of the response.

41 sys 41407?:input"4  
measuring";t4\$:gosub 500

Displays message 19:Prints a carriage return:Inputs the name of temperature 4: Asks if the answer is correct.

```

42 if y$="y" then 45
43 if y$="n" then 41
44 gosub 600:goto 42

45 sys 41407?:input"5
   measuring";t5$:gosub 500

46 if y$="y" then 49
47 if y$="n" then 45
48 gosub 600:goto 46

49 sys 41407?:input"6
   measuring";t6$:gosub 500

50 if y$="y" then 53
51 if y$="n" then 49
52 gosub 600:goto 50

53 if t1$="N/C" then poke
   7656,255

54 if t4$="N/C" then poke
   7659,255

```

If the answer is yes, then inputs the name of temperature 5.

If the answer is no, then inputs the name of temperature 4 again.

The answer is invalid, so asks again if the answer is correct:Checks the validity of the response.

Displays message 19:Prints a carriage return:Inputs the name of temperature 5: Asks if the answer is correct.

If the answer is yes, then inputs the name of temperature 6.

If the answer is no, then inputs the name of temperature 5 again.

The answer is invalid, so asks again if the answer is correct:Checks the validity of the response.

Displays message 19:Prints a carriage return:Inputs the name of temperature 6: Asks if the answer is correct.

If the answer is yes, then checks to see if temperature 1 is connected.

If the answer is no, then inputs the name of temperature 6 again.

The answer is invalid, so asks again if the answer is correct:Checks the validity of the response.

If temperature 1 is not connected, then sets the temperature 1 not connected flag.

If temperature 4 is not connected, then sets the temperature 4 not connected flag.

```
55 sys 41424?:sys 41441?:
   if t2$="N/C" then poke
   7657,255
```

Displays message 20:Prints a carriage return:Displays message 21:Prints a carriage return:If temperature 2 is not connected, then sets the temperature 2 not connected flag.

```
56 sys 41458?:input"1
   measuring";tw$:gosub 500:
   if t3$="N/C" then poke
   7658,255
```

Displays message 22:Prints a carriage return:Inputs the name of timer 1:Asks if the answer is correct:If temperature 3 is not connected, then sets the temperature 3 not connected flag.

```
57 if y$="y" then 60
```

If the answer is yes, then inputs the name of timer 2. If the answer is no, then inputs the name of timer 1 again.

```
58 if y$="n" then 56
```

```
59 gosub 600:goto 57
```

The answer is invalid, so asks again if the answer is correct:Checks the validity of the response.

```
60 sys 41458?:input"2
   measuring";tt$:gosub 500:
   if t5$="N/C" then poke
   7660,255
```

Displays message 22:Prints a carriage return:Inputs the name of timer 2:Asks if the answer is correct:If temperature 5 is not connected, then sets the temperature 5 not connected flag.

```
61 if y$="y" then 64
```

If the answer is yes, then inputs the name of timer 3. If the answer is no, then inputs the name of timer 2 again.

```
62 if y$="n" then 60
```

```
63 gosub 600:goto 61
```

The answer is invalid, so asks again if the answer is correct:Checks the validity of the response.

```
64 sys 41458?:input"3
   measuring";th$:gosub 500:
   if t6$="N/C" then poke
   7661,255
```

Displays message 22:Prints a carriage return:Inputs the name of timer 3:Asks if the answer is correct:If temperature 6 is not connected, then sets the temperature 6 not connected flag.

65 if y\$="y" then 68	If the answer is yes, then inputs the time of day.
66 if y\$="n" then 64	If the answer is no, then inputs the name of timer 3 again.
67 gosub 600:goto 65	The answer is invalid, so asks again if the answer is correct:Checks the validity of the response.
68 sys 41852?:input"time (HHMMSS)";ti\$:goto 132	Displays message 23:Prints a carriage return:Inputs the time of day:Asks if the answer is correct.
69 sys 41158?:input"pump being used";pt\$:gosub 500	Displays message 7:Prints a carriage return:Inputs the type of blood pump being used:Asks if the answer is correct.
70 if y\$="y" then 73	If the answer is yes, then checks for a centrifugal pump being used.
71 if y\$="n" then 69	If the answer is no, then inputs the type of blood pump again.
72 gosub 600:goto 70	The answer is invalid, so asks again if the answer is correct:Checks the validity of the response.
73 if pt\$="centrifugal" then 75	If a centrifugal pump is being used, then sets the centrifugal flag, and displays the monitor screen with CENTRIFUGAL PUMP displayed in the right location.
74 goto 76	Check for a roller pump being used.
75 sys 8810:sys 41192:goto 111	Displays the monitor screen:Sets the centrifugal flag and displays message 9:Prints the patient's and timers' names.
76 if pt\$="roller" then 79	If the roller pump is being used, then inputs roller pump data.
77 if pt\$="pulsatile" then 106	If the pulsatile pump is being used, then inputs pulsatile pump data.

<pre> 78 sys 41090:?:sys 41175:?:   input"roller, or pulsatile";   pt\$:goto 73 </pre>	<p>Displays message 3:Prints a carriage return:Displays message 8:Prints a carriage return:Inputs the pump type again:Checks the validity of the response.</p>
<pre> 79 sys 41222:?:input"are there"   ;nr:gosub 500 </pre>	<p>Displays message 10:Prints a carriage return:Inputs the number of rollers:Asks if the answer is correct. If the answer is yes, then inputs the tubing diameter If the answer is no, then inputs the number of rollers again.</p>
<pre> 80 if y\$="y" then 83 </pre>	<p>The answer is invalid, so asks again if the answer is correct:Checks the validity of the response.</p>
<pre> 81 if y\$="n" then 79 </pre>	<p>Displays message 11:Prints a carriage return:Inputs the tubing diameter:Asks if the answer is correct.</p>
<pre> 82 gosub 600:goto 80 </pre>	<p>If the answer is yes, then inputs the tubing diameter unit.</p>
<pre> 83 sys 41239:?:input"diameter"   ;td:gosub 500 </pre>	<p>If the answer is no, then inputs the tubing diameter again.</p>
<pre> 84 if y\$="y" then 87 </pre>	<p>The answer is invalid, so asks again if the answer is correct:Checks the validity of the response.</p>
<pre> 85 if y\$="n" then 83 </pre>	<p>Displays message 12:Prints a carriage return:Inputs the diameter unit:Asks if the answer is correct.</p>
<pre> 86 gosub 600:goto 84 </pre>	<p>If the answer is yes, then checks the validity of the diameter unit.</p>
<pre> 87 sys 41256:?:input"cm or in"   ;du\$:gosub 500 </pre>	<p>If the answer is no, then inputs the diameter unit again.</p>
<pre> 88 if y\$="y" then 91 </pre>	<p>The answer is invalid, so asks again if the answer is correct:Checks the validity of the response.</p>
<pre> 89 if y\$="n" then 87 </pre>	<p>If the diameter unit is cm, then inputs the arc length.</p>
<pre> 90 gosub 600:goto 88 </pre>	
<pre> 91 if du\$="cm" then 94 </pre>	

92 if du\$="in" then td=td*2.54: goto 94	If the diameter unit is in, then converts the diameter to cm and inputs the arc length.
93 sys 41090:?:input"in cm or in";du\$:goto 91	Displays message 3:Prints a carriage return:Inputs the diameter unit again:Checks the validity of the response.
94 sys 41273:?:input"length"; al:gosub 500	Displays message 13:Prints a carriage return:Asks if the answer is correct.
95 if y\$="y" then 98	If the answer is yes, then inputs the arc length unit.
96 if y\$="n" then 94	If the answer is no, then inputs the arc length again.
97 gosub 600:goto 95	The answer is invalid, so asks again if the answer is correct:Checks the validity of the response.
98 sys 41290:?:input"in cm or in";au\$:gosub 500	Displays message 14:Prints a carriage return:Inputs the arc length unit:Asks if the answer is correct.
99 if y\$="y" then 102	If the answer is yes, then checks for a valid unit.
100 if y\$="n" then 98	If the answer is no, then inputs the arc length unit again.
101 gosub 600:goto 99	The answer is invalid, so asks again if the answer is correct:Checks the validity of the response.
102 if au\$="cm" then 105	If the arc length is in cm, then calculates the pump volume.
103 if au\$="in" then al=al*2.54: goto 105	If the arc length is in inches, then convert the arc length to cm:Calculates the pump volume.
104 sys 41090:?:input"in cm or in";au\$:goto 102	Displays message 3:Prints a carriage return:Inputs the arc length unit again: Checks the validity of the response.

<pre> 105 pv=nr*al*3.1416*(td^2)/4:     sys 8810:sys 41307:goto 111 </pre>	<p>Calculates the pump volume: Displays the monitor screen:Sets the roller pump flag, displays message 15, and enables the pulse counter on the 6522-1: Prints the patient and timer names.</p>
<pre> 106 sys 41340?:input"volume in     cc";sv:gosub 500 </pre>	<p>Displays message 16:Prints a carriage return:Inputs the stroke volume:Asks if the answer is correct.</p>
<pre> 107 if y\$="y" then 110 </pre>	<p>If the answer is yes, then displays the monitor screen and message 17, sets the pulsatile flag and enables the pulse counter on the 6522-1.</p>
<pre> 108 if y\$="n" then 106 </pre>	<p>If the answer is no, then inputs the stroke volume again.</p>
<pre> 109 gosub 600:goto 107 </pre>	<p>The answer is invalid, so asks again if the answer is correct:Checks the validity of the response.</p>
<pre> 110 sys 8810:sys 41357 </pre>	<p>Displays the monitor screen:Displays message 17, sets the pulsatile flag and enables the pulse counter on the 6522-1.</p>
<pre> 111 x\$=pn\$:z=7680:u=21:gosub     800:x\$=tw\$:z=8120:u=6:     gosub 800:x\$=tt\$:z=8142:     gosub 800 </pre>	<p>:::Displays the patient name on the monitor screen: :::Displays the name of timer 1:::Displays the name of timer 2.</p>
<pre> 112 x\$=th\$:z=8164:gosub 800:     x\$=t1\$:z=7968:u=8:gosub     800:x\$=t2\$:z=7979:gosub     800:x\$=t3\$ </pre>	<p>:::Displays the name of timer 3:::Displays the name of temperature 1::: Displays the name of temperature 2:</p>
<pre> 113 z=8012:gosub 800:x\$=t4\$:     z=8023:gosub 800:x\$=t5\$:     z=8056:gosub 800:x\$=t6\$:     z=8067:gosub 800 </pre>	<p>:Displays the name of temperature 3:::Displays the name of temperature 4::: Displays the name of temperature 5:::Displays the name of temperature 6.</p>

<pre> 114 sys 41902:sys 41942:sys     41982:sys 8682:x=ph:z=7711:     gosub 900:x=ph/2.54:z=7733:     gosub 900 </pre>	<p>Displays timer 1:Displays timer 2:Displays timer 3: Prints the temperature degree unit and clears the display for unconnected temperature probes:Displays the patient's height in cm: Displays the patient's height in inches.</p>
<pre> 115 x=pw:z=7755:gosub 900:x=pw/     0.45359237:z=7777:gosub 900:     u=int(sa):poke 7822,u+48 </pre>	<p>::Displays the patient's weight in kg::Displays the weight in lb:Gets the unit's place of the surface area:Displays it.</p>
<pre> 116 t=int((sa-u)*10):poke 7824,     t+48:h=int((sa-u-t/10)*100):     poke 7825,h+48 </pre>	<p>Gets the tenth's digit of the surface area:Prints it: Gets the hundredth's digit of the surface area:Prints it.</p>
<pre> 117 if (sa-u-t/10-h/100)&lt;0.005     then 122 </pre>	<p>If the thousandth's digit is less than 5, then enables the clock and temperature update flags.</p>
<pre> 118 h=h+1:if h&lt;10 then 121 </pre>	<p>The thousandth's digit is greater than 5, so increments the hundredth's digit:if the hundredth's digit is less than 10, then updates the surface area display.</p>
<pre> 119 h=0:t=t+1:if t&lt;10 then 121 </pre>	<p>The hundredth's digit was ten, so clears the digit: Increments the tenth's digit:If the tenth's digit is less than 10, then updates the surface area display.</p>
<pre> 120 t=0:u=u+1 </pre>	<p>The tenth's digit was 10, so clears the digit:Increments the unit's digit.</p>
<pre> 121 poke 7822,u+48:poke 7824,     t+48:poke7825,h+48 </pre>	<p>Displays the unit's digit of the surface area:Displays the tenth's digit of the surface area:Displays the hundredth's digit of the surface area.</p>
<pre> 122 sys 41475:gosub 913 </pre>	<p>Enables the clock and temperature update flags: Displays the clock.</p>

123 sys 41484:sys 41493:if peek(7621)=0 then 128	Sets the cursor location: If the pump output update flag is not set, then checks the menu flag.
124 poke 7621,0:if peek(7622) =255 then gosub 920	Clears the pump output up- date flag:If the roller flag is set then updates the roller pump output and displays.
125 if peek(7623)=255 then gosub 930	If the pulsatile flag is set, then updates the puls- atile pump output and dis- plays.
126 if peek(7624)=255 then gosub 940	If the centrifugal flag is set, then updates and dis- plays the centrifugal pump output.
127 x=po:z=7866:gosub 900: x=po/pw:z=7904:gosub 900: x=po/sa:z=7926:gosub 900	::Displays the pump output: ::Displays the blood flow rate in ml/min/kg:: Displays the blood flow rate in ml/min/m**2.
128 if peek(7662)=0 then 130	If the menu flag is not set then checks the temperature degree units and the temp- erature and print clock up- date flags.
129 poke 7662,0:goto 1	The menu flag is set so clears the flag:Returns to the input section.
130 sys 41807:sys 16384:if peek(7650)=0 then 123	Checks the temperature de- gree units and updates them if changed:Checks the temp- erature update flag and up- dates the temperatures if it set:If the print clock flag is not set then returns to statement 123 to set the position of the cursor.
131 poke 7650,0:gosub 913: goto 123	The print clock flag is set so clears the flag:Updates the clock on the screen: Returns to statement 123 to set the cursor location.
132 gosub 500	Asks if the the answer is correct.
133 if y\$="y" then 69	If the answer is yes, then inputs the type of blood pump.

134 if y\$="n" then 68	If the answer is no, then inputs the time of day again.
135 gosub 600:goto 133	The answer is invalid, so asks again if the answer is correct:Checks the validity of the response.

### Subroutines

400 if th=0 then poke z,32:goto 402	If the most significant digit is 0 then clears the digit on the screen:Checks the second most significant digit.
401 poke z,th+48	Displays the most significant digit.
402 if h=0 and th=0 then poke z+1,32:goto 404	If both the most and the next most significant digits are zero, then clears the next most significant digit on the screen: Checks the third most significant digit.
403 poke z+1,h+48	Displays the next most significant digit.
404 if t=0 and th=0 and h=0 then poke z+2,32:goto 406	If the 3 most significant are zero, then clears the third most significant digit:Displays then least significant digit.
405 poke z+2,t+48	Displays the third most significant digit.
406 poke z+3,u+48:return	Displays the least significant digit:Returns from subroutine.
500 sys 41073:?:input"(y/n)"; y\$:return	Displays message 2:Prints a carriage return:Inputs the answer to "Is this correct?":Returns from subroutine.
600 sys 41090:?:input"in y or n";y\$:return	Displays message 3:Prints a carriage return:Inputs the answer to "Invalid entry, type in y or n?":Returns from subroutine.

700 if hu\$="cm" then return	If the height unit is cm then returns from subroutine.
710 if hu\$="in" then 740	If the height unit is in, then converts the height to cm and returns from subroutine.
720 sys 41090?:input"in cm or in";hu\$:goto 700	Displays message 3:Prints a carriage return:Inputs the height unit:Checks the validity of the response.
800 y=1:x=len(x\$):if x>u then x=u	Sets the pointer, y, to the first character:Calculates the length of the character string:If the string is too long, then resets the string length.
801 w=asc(mid\$(x\$,y,l))-64:if w<0 then w=w+64	Calculates the screen code for a character:Converts the screen code if necessary.
802 if w>128 then w=w-64	Converts the screen code if necessary.
803 poke z+y,w:y=y+1:x=x-1:if x>0 then 801	Displays a character on the screen:Increments the character pointer:Decrements the length of the string:Displays another character if not through with string.
804 return	Returns from subroutine.
900 th=int(x/1000):h=int((x-th*1000)/100):t=int((x-th*1000-h*100)/10)	Gets the thousand's digit: Gets the hundred's digit: Gets the ten's digit.
901 u=int(x-th*1000-h*100-t*10)	Gets the unit's digit.
902 if (x-th*1000-h*100-t*10-u)<0.5 then 907	If the tenth's digit is less than 5 then, displays the number on the screen.
903 u=u+1:if u<10 then 907	The tenth's digit is more than 5 so increments the unit's digit:If the unit's digit is less than 10 then displays the number.
904 t=t+1:u=0:if t<10 then 907	Increments the ten's digit:Clears the unit's digit:If the ten's digit is less than 10 then displays the number.

905	h=h+1:t=0:ifh<10 then 907	Increments the hundred's digit:Clears the ten's digit:If the hundred's digit is less than 10 then displays the number.
906	th=th+1:h=0	Increments the thousand's digit:Clears the hundred's digit.
907	gosub 400:return	Displays the number:Returns from the subroutine.
913	poke 8112,asc(mid\$(ti\$,1,1): poke 8113,asc(mid\$(ti\$,2,1): poke 8115,asc(mid\$(ti\$,3,1):	Displays the high byte of the clock hours:Displays the low byte of the clock hours:Displays the high byte of the clock minutes.
914	poke 8116,asc(mid\$(ti\$,4,1): poke 8118,asc(mid\$(ti\$,5,1): poke 8119,asc(mid\$(ti\$,6,1)	Displays the low byte of the clock minutes:Displays the high byte of the clock seconds:Displays the low byte of the clock seconds.
915	return	Returns from subroutine.
920	po=pv*peek(7653)*1.2:return	Calculates roller pump output:Returns from subroutine.
930	po=sv*peek(7653)*120:return	Calculates pulsatile pump output:Returns from subroutine.
940	poke39426,128:sys42022	Enables centrifugal flow probe:Gets value from A/D converter.
941	po=(peek(7667)-48)*1000+ (peek(7669)-48)*100+(peek (7669)-48)*10+(peek(7670)- 48)	Calculates centrifugal pump output
942	return	Returns from subroutine

### Assembly Language Listing

In the following listing, the hexadecimal address, XXXX, of the upcoming machine code byte is noted by ==XXXX. The hexadecimal machine code is shown in the left hand column. The assembly language mnemonic and operand are shown in the middle column and comments are listed following a semicolon in the right hand column. The assembler directive, \*=\$XXXX, causes the assembled program's machine code to start at



```

==A000    TMP2NC=$1DE9    ; Temperature 2 flag
==A000    TMP3NC=$1DEA    ; Temperature 3 flag
==A000    TMP4NC=$1DEB    ; Temperature 4 flag
==A000    TMP5NC=$1DEC    ; Temperature 5 flag
==A000    TMP6NC=$1DED    ; Temperature 6 flag
==A000    MENFLG=$1DEE    ; Menu flag
                                0 = don't return to input
                                $FF = return to input
==A000    DEGUNT=$1DEF    ; Temperature degree unit
                                0 = C / $FF = F
==A000    MSGADL=$FB      ; Low byte of starting address of
                                message to be displayed
==A000    MSGADH=$FC      ; High byte of starting address of
                                message to be displayed
==A000    NOCHAR=$1DF0    ; Number of characters in message
==A000    MSGPRL=$FD      ; Low byte of starting screen loca-
                                tion of message
==A000    MSGPRH=$FE      ; High byte of starting screen loca-
                                tion of message
==A000    CHRCNT=$1DF9    ; Character counter for input
==A000    MEMORY=$1DFB    ; Temporary storage of input char-
                                acters
==A000    HALFCT=$1DF1    ; 1/2 sec counter for pulse counter
==A000    IOLACR=$980B    ; 6522-1 Auxilliary control register
==A000    IOLIFR=$980D    ; 6522-1 Interrupt flag register
==A000    IOLIER=$980E    ; 6522-1 Interrupt enable register
==A000    IOL2L=$9808    ; 6522-1 Timer 2 low byte latch
==A000    IOL2H=$9809    ; 6522-1 Timer 2 high byte latch
==A000    INTH=$20        ; Interrupt bypass address-high byte
==A000    INTL=$00        ; Interrupt bypass address-low byte
==A000    M1L=$F5         ; Message 1 starting address, LB
==A000    M1H=$24         ; Message 1 starting address, HB
==A000    M2L=$50         ; Message 2 starting address, LB
==A000    M2H=$25         ; Message 2 starting address, HB
==A000    M3L=$5F         ; Message 3 starting address, LB
==A000    M3H=$25         ; Message 3 starting address, HB
==A000    M4L=$72         ; Message 4 starting address, LB
==A000    M4H=$25         ; Message 4 starting address, HB
==A000    M5L=$87         ; Message 5 starting address, LB
==A000    M5H=$25         ; Message 5 starting address, HB
==A000    M6L=$9A         ; Message 6 starting address, LB
==A000    M6H=$25         ; Message 6 starting address, HB
==A000    M7L=$AD         ; Message 7 starting address, LB
==A000    M7H=$25         ; Message 7 starting address, HB
==A000    M8L=$D1         ; Message 8 starting address, LB
==A000    M8H=$25         ; Message 8 starting address, HB
==A000    M9L=$E0         ; Message 9 starting address, LB
==A000    M9H=$25         ; Message 9 starting address, HB
==A000    M10L=$F0        ; Message 10 starting address, LB
==A000    M10H=$25        ; Message 10 starting address, HB

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==A000 M11L=$00 ; Message 11 starting address, LB
==A000 M11H=$26 ; Message 11 starting address, HB
==A000 M12L=$12 ; Message 12 starting address, LB
==A000 M12H=$26 ; Message 12 starting address, HB
==A000 M13L=$24 ; Message 13 starting address, LB
==A000 M13H=$26 ; Message 13 starting address, HB
==A000 M14L=$33 ; Message 14 starting address, LB
==A000 M14H=$26 ; Message 14 starting address, HB
==A000 M15L=$44 ; Message 15 starting address, LB
==A000 M15H=$26 ; Message 15 starting address, HB
==A000 M16L=$4F ; Message 16 starting address, LB
==A000 M16H=$26 ; Message 16 starting address, HB
==A000 M17L=$61 ; Message 17 starting address, LB
==A000 M17H=$26 ; Message 17 starting address, HB
==A000 M18L=$6F ; Message 18 starting address, LB
==A000 M18H=$26 ; Message 18 starting address, HB
==A000 M19L=$32 ; Message 19 starting address, LB
==A000 M19H=$27 ; Message 19 starting address, HB
==A000 M20L=$45 ; Message 20 starting address, LB
==A000 M20H=$27 ; Message 20 starting address, HB
==A000 M21L=$88 ; Message 21 starting address, LB
==A000 M21H=$27 ; Message 21 starting address, HB
==A000 M22L=$D5 ; Message 22 starting address, LB
==A000 M22H=$27 ; Message 22 starting address, HB
==A000 M23L=$E2 ; Message 23 starting address, LB
==A000 M23H=$27 ; Message 23 starting address, HB
==A000 DIGSEL=$1DF2 ; Selects digit during A/D conver-
sion
==A000 TEMPH=$1DF3 ; Temperature - hundred's digit
==A000 TEMPT=$1DF4 ; Temperature - ten's digit
==A000 TEMPU=$1DF5 ; Temperature - unit's digit
==A000 TEMPTH=$1DF6 ; Temperature - tenth's digit
==A000 COUNT=$1DF7 ; Counter used in subroutine SCREN1
==A000 CNT=$1DF8 ; Counter used in subroutine SCREN2
;INITIALIZATION ROUTINE
09 .BYT 09,$A0,0 ; Auto-start sequence
9,$A0,$41,$30,$C3,$C
2,$CD
A0
09 ; Start of program - LB
A0 ; Start of program - HB
41 ; Signature bytes
30
C3
C2
CD
A902 LDA #02 ; Accesses DDRB on 6520-1
8D039A STA $9A03 ; Control register B on 6520-1
A9FE LDA #$FE ; All bits outputs except bit 0

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==A010
8D029A   STA $9A02       ; DDRB on 6520-1
A906     LDA #06       ; Accesses port B on 6520-1
8D039A   STA $9A03       ; Control register B on 6520-1
A900     LDA #00       ; Initializes outputs to zero
8D029A   STA $9A02
208DFD   JSR $FD8D       ; RAM clear and memory check
==A020
2052FD   JSR $FD52       ; Sets VIC 20 vectors
20F9FD   JSR $FDF9       ; Initializes VIC 20 I/O
2018E5   JSR $E518       ; Initializes screen
A920     LDA #$20       ; Initializes 6522-1 ACR
8D0B98   STA IO1ACR
A904     LDA #04       ; Accesses port A on 6520-1
==A030
8D019A   STA $9A01       ; Control register A on 6520-1
A9FF     LDA #$FF       ; Initializes low byte of timer 2
8D0898   STA IO1T2L       latch
20BA40   JSR DISABL       ; Disables all flags, initializes
                                constants
A920     LDA #INTH       ; Sets interrupt bypass address
8D1503   STA $0315
==A040
A900     LDA #INTL
8D1403   STA $0314
58       CLI           ; Allows interrupts
2081A4   JSR $A481       ; Displays title screen (SCREEN1)
A930     LDA #$30       ; 18 sec time delay
8DFAD1D  STA $1DFA
==A04E   DCRM
A2FF     LDX #$FF
==A050   DCRX
A0FF     LDY #$FF
==A052   DCRY
88       DEY
D0FD     BNE DCRY
CA       DEX
D0F8     BNE DCRX
CEFA1D   DEC $1DFA
D0F1     BNE DCRM
6C00C0   JMP ($C000)       ; Jumps to basic
==A060   MSG1           ; Prints first message
A9F5     LDA #M1L       ; Sets starting address, LB
85FB     STA MSGADL
A924     LDA #M1H       ; Sets starting address, HB
85FC     STA MSGADH
A95B     LDA #$5B       ; Sets number of characters
8DF01D   STA NOCHAR
208DA3   JSR $A38D       ; Displays message (DISPLY)

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==A070
60      RTS      ; Returns from subroutine
==A071  MSG2     ; Prints second message
A950   LDA #M2L ; Sets starting address, LB
85FB   STA MSGADL
A925   LDA #M2H ; Sets starting address, HB
85FC   STA MSGADH
A90F   LDA # $0F ; Sets number of characters
8DF01D STA NOCHAR
208DA3 JSR $A38D ; Displays message (DISPLY)
==A081
60      RTS      ; Returns from subroutine
==A082  MSG3     ; Prints third message
A95F   LDA #M3L ; Sets starting address, LB
85FB   STA MSGADL
A925   LDA #M3H ; Sets starting address, HB
85FC   STA MSGADH
A913   LDA # $13 ; Sets number of characters
8DF01D STA NOCHAR
208DA3 JSR $A38D ; Displays message (DISPLY)
==A092
60      RTS      ; Returns from subroutine
==A093  MSG4     ; Prints fourth message
A972   LDA #M4L ; Sets starting address, LB
85FB   STA MSGADL
A925   LDA #M4H ; Sets starting address, HB
85FC   STA MSGADH
A915   LDA # $15 ; Sets number of characters
8DF01D STA NOCHAR
208DA3 JSR $A38D ; Displays message (DISPLY)
==A0A3
60      RTS      ; Returns from subroutine
==A0A4  MSG5     ; Prints fifth message
A987   LDA #M5L ; Sets starting address, LB
85FB   STA MSGADL
A925   LDA #M5H ; Sets starting address, HB
85FC   STA MSGADH
A913   LDA # $13 ; Sets number of characters
8DF01D STA NOCHAR
208DA3 JSR $A38D ; Displays message (DISPLY)
==A0B4
60      RTS      ; Returns from subroutine
==A0B5  MSG6     ; Prints sixth message
A99A   LDA #M6L ; Sets starting address, LB
85FB   STA MSGADL
A925   LDA #M6H ; Sets starting address, HB
85FC   STA MSGADH
A913   LDA # $13 ; Sets number of characters
8DF01D STA NOCHAR
208DA3 JSR $A38D ; Displays message (DISPLY)

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==A0C5
60      RTS                ; Returns from subroutine
==A0C6
MSG7    ; Prints seventh message
A9AD    LDA #M7L          ; Sets starting address, LB
85FB    STA MSGADL
A925    LDA #M7H          ; Sets starting address, HB
85FC    STA MSGADH
A924    LDA #$24          ; Sets number of characters
8DF01D  STA NOCHAR
208DA3  JSR $A38D        ; Displays message (DISPLY)
==A0D6
60      RTS                ; Returns from subroutine
==A0D7
MSG8    ; Prints eighth message
A9D1    LDA #M8L          ; Sets starting address, LB
85FB    STA MSGADL
A925    LDA #M8H          ; Sets starting address, HB
85FC    STA MSGADH
A90F    LDA #$0F          ; Sets number of characters
8DF01D  STA NOCHAR
208DA3  JSR $A38D        ; Displays message (DISPLY)
==A0E7
60      RTS                ; Returns from subroutine
==A0E8
CENPMP  ; Centrifugal pump being used

A9FF    LDA #$FF          ; Sets centrifugal flag
8DC81D  STA CENFLG
A9E0    LDA #M9L          ; Sets starting address for message
                        9, LB
85FB    STA MSGADL
A925    LDA #M9H          ; Sets starting address, HB
85FC    STA MSGADH
A99B    LDA #$9B          ; Sets starting screen location, LB
85FD    STA MSGPRL
==A0F9
A91E    LDA #$1E          ; Sets starting screen location, HB
85FE    STA MSGPRH
A910    LDA #$10          ; Sets number of characters
8DF01D  STA NOCHAR
209BA3  JSR $A39B        ; Displays message (MSGE)
60      RTS                ; Returns from subroutine
==A106
MSG10   ; Prints tenth message
A9F0    LDA #M10L         ; Sets starting address, LB
85FB    STA MSGADL
A925    LDA #M10H         ; Sets starting address, HB
85FC    STA MSGADH
A910    LDA #$10          ; Sets number of characters
8DF01D  STA NOCHAR
208DA3  JSR $A38D        ; Displays message (DISPLY)
==A116
60      RTS                ; Returns from subroutine

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==A117    MSG11          ; Prints eleventh message
A900     LDA #M11L      ; Sets starting address, LB
85FB     STA MSGADL
A926     LDA #M11H      ; Sets starting address, HB
85FC     STA MSGADH
A912     LDA #$12       ; Sets number of characters
8DF01D   STA NOCHAR
208DA3   JSR $A38D     ; Displays message (DISPLY)
==A127
60       RTS           ; Returns from subroutine
==A128    MSG12          ; Prints twelfth message
A912     LDA #M12L      ; Sets starting address, LB
85FB     STA MSGADL
A926     LDA #M12H      ; Sets starting address, HB
85FC     STA MSGADH
A912     LDA #$12       ; Sets number of characters
8DF01D   STA NOCHAR
208DA3   JSR $A38D     ; Displays message (DISPLY)
==A138
60       RTS           ; Returns from subroutine
==A139    MSG13          ; Prints thirteenth message
A924     LDA #M13L      ; Sets starting address, LB
85FB     STA MSGADL
A926     LDA #M13H      ; Sets starting address, HB
85FC     STA MSGADH
A90F     LDA #$0F       ; Sets number of characters
8DF01D   STA NOCHAR
208DA3   JSR $A38D     ; Displays message (DISPLY)
==A149
60       RTS           ; Returns from subroutine
==A14A    MSG14          ; Prints fourteenth message
A933     LDA #M14L      ; Sets starting address, LB
85FB     STA MSGADL
A926     LDA #M14H      ; Sets starting address, HB
85FC     STA MSGADH
A911     LDA #$11       ; Sets number of characters
8DF01D   STA NOCHAR
208DA3   JSR $A38D     ; Displays message (DISPLY)
==A15A
60       RTS           ; Returns from subroutine
==A15B    MSG15          ; Prints fifteenth message
A944     LDA #M15L      ; Sets starting address, LB
85FB     STA MSGADL
A926     LDA #M15H      ; Sets starting address, HB
85FC     STA MSGADH
A90B     LDA #$0B       ; Sets number of characters
8DF01D   STA NOCHAR
A99B     LDA #$9B       ; Sets starting screen location, LB
85FD     STA MSGPRL

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==A16C
A91E    LDA #$1E    ; Sets starting screen location, HB
85FE    STA MSGPRH
209BA3  JSR $A39B    ; Displays message (MSGE)
A9FF    LDA #$FF    ; Sets roller flag
8DC61D  STA ROLFLG
20A8A3  JSR $A3A8    ; Enables pulse counter (PULSE)
60      RTS        ; Returns from subroutine
==A17C
MSG16
A94F    LDA #M16L    ; Sets starting address, LB
85FB    STA MSGADL
A926    LDA #M16H    ; Sets starting address, HB
85FC    STA MSGADH
A912    LDA #$12    ; Sets number of characters
8DF01D  STA NOCHAR
208DA3  JSR $A38D    ; Displays message (DISPLY)
==A18C
60      RTS        ; Returns from subroutine
==A18D
MSG17
20A8A3  JSR $A3A8    ; Enables pulse counter (PULSE)
A9FF    LDA #$FF    ; Sets pulsatile flag
8DC71D  STA PULFLG
A961    LDA #M17L    ; Sets starting address, LB
85FB    STA MSGADL
A926    LDA #M17H    ; Sets starting address, HB
85FC    STA MSGADH
==A19D
A90E    LDA #$0E    ; Sets number of characters
8DF01D  STA NOCHAR
A99B    LDA #$9B    ; Sets starting screen location, LB
85FD    STA MSGPRL
A91E    LDA #$1E    ; Sets starting screen location, HB
85FE    STA MSGPRH
209BA3  JSR $A39B    ; Displays message (MSGE)
==A1AD
60      RTS        ; Returns from subroutine
==A1AE
MSG18
A96F    LDA #M18L    ; Sets starting address, LB
85FB    STA MSGADL
A926    LDA #M18H    ; Sets starting address, HB
85FC    STA MSGADH
A9C3    LDA #$C3    ; Sets number of characters
8DF01D  STA NOCHAR
208DA3  JSR $A38D    ; Displays message (DISPLY)
==A1BE
60      RTS        ; Returns from subroutine
==A1BF
MSG19
A932    LDA #M19L    ; Sets starting address, LB
85FB    STA MSGADL
A927    LDA #M19H    ; Sets starting address, HB

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85FC      STA MSGADH
A913      LDA #$13      ; Sets number of characters
8DF01D    STA NOCHAR
208DA3    JSR $A38D    ; Displays message (DISPLY)
==A1CF
60        RTS          ; Returns from subroutine
==A1D0    MSG20        ; Prints twentieth message
A943      LDA #$43      ; Sets number of characters
8DF01D    STA NOCHAR
A945      LDA #M20L     ; Sets starting address, LB
85FB      STA MSGADL
A927      LDA #M20H     ; Sets starting address, HB
85FC      STA MSGADH
208DA3    JSR $A38D    ; Displays message (DISPLY)
==A1E0
60        RTS          ; Returns from subroutine
==A1E1    MSG21        ; Prints twenty-first message
A988      LDA #M21L     ; Sets starting address, LB
85FB      STA MSGADL
A927      LDA #M21H     ; Sets starting address, HB
85FC      STA MSGADH
A94D      LDA #$4D      ; Sets number of characters
8DF01D    STA NOCHAR
208DA3    JSR $A38D    ; Displays message (DISPLY)
==A1F1
60        RTS          ; Returns from subroutine
==A1F2    MSG22        ; Prints twenty-second message
A9D5      LDA #M22L     ; Sets starting address, LB
85FB      STA MSGADL
A927      LDA #M22H     ; Sets starting address, HB
85FC      STA MSGADH
A90D      LDA #$0D      ; Sets number of characters
8DF01D    STA NOCHAR
208DA3    JSR $A38D    ; Displays message (DISPLY)
==A202
60        RTS          ; Returns from subroutine
==A203    ENABLE       ; Enables clock and temperature up-
                        ; date flags

A9FF      LDA #$FF
8DE31D    STA CLKFLG
8DE61D    STA TMPFLG
60        RTS          ; Returns from subroutine
==A20C    SETCUR       ; Sets the cursor location
18        CLC
A202      LDX #02       ; Sets row to 2
A012      LDY #$12     ; Sets column to 18
20F0FF    JSR $FFFO    ; Sets the cursor location
60        RTS          ; Returns from subroutine

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==A215    FETCH                ; Checks for keyboard input and if
                                ; any checks its validity
A900      LDA #00              ; Initializes character counter
8DF91D    STA CHRCNT
==A21A    LOOP1
20E4FF    JSR $FFE4           ; Gets character from keyboard queue
C900      CMP #00             ; Is it empty?
D00A      BNE STORE          ; It isn't so branches
ADF91D    LDA CHRCNT         ; It is so checks if character
                                ; counter is greater than or equal
                                ; to 1
C900      CMP #00
F04C      BEQ RETURN         ; No characters so returns from sub-
                                ; routine
4C1AA2    JMP $A21A          ; Is a character so loops and waits
==A22B    STORE
ACF91D    LDY CHRCNT         ; Restores character counter
99FB1D    STA MEMORY,Y      ; Stores character counter in memory
C8        INY                ; Increments character counter
8CF91D    STY CHRCNT        ; Saves character counter
C90D      CMP #$0D           ; Carriage return?
F003      BEQ PRCHK         ; If so, prints first 2 characters
                                ; and checks validity
4C1AA2    JMP $A21A          ; If not, gets another character
==A23C    PRCHK
ADFB1D    LDA MEMORY         ; Gets first character
20D2FF    JSR $FFD2         ; Prints it
ADFC1D    LDA MEMORY+1     ; Gets second character
20D2FF    JSR $FFD2         ; Prints it
A901      LDA #01           ; Colors the characters white
8D3E96    STA 38462
==A24D
8D3F96    STA 38463
ADFB1D    LDA MEMORY         ; Gets first character
C953      CMP #$53          ; Is it a s?
F01E      BEQ STRTIM        ; It is so branches to start a timer
C952      CMP #$52          ; Is it a r?
F03F      BEQ RESTIM        ; It is so branches to reset a timer
C945      CMP #$45          ; Is it an e?
==A25D
D003      BNE LOOP4         ; If it's not checks for a m
4C16A3    JMP $A316         ; It is so jumps to end a timer
==A262    LOOP4
C94D      CMP #$4D          ; Is it a m?
D003      BNE CLRCOD        ; If it's not clears the screen
4C3BA3    JMP $A33B         ; It is so jumps to set menu flag
==A269    CLRCOD           ; Clears the invalid command on the
                                ; screen
200CA2    JSR $A20C         ; Sets cursor position
A920      LDA #$20          ; Spaces over code

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```

20D2FF JSR $FFD2
20D2FF JSR $FFD2
==A274 RETURN
60 RTS ; Returns from subroutine
==A275 STRTIM ; Starts a timer
ADFC1D LDA MEMORY+1 ; Gets timer number
C931 CMP #$31 ; Is it 1?
F00C BEQ TIMER1 ; If it is branches to start timer 1
C932 CMP #$32 ; Is it 2?
F00E BEQ TIMER2 ; If it is branches to start timer 2
C933 CMP #$33 ; Is it 3?
F010 BEQ TIMER3 ; If it is branches to start timer 3
2069A2 JSR $A269 ; Invalid timer number, so jumps to
clear code

==A287
60 RTS ; Returns from subroutine
==A288 TIMER1 ; Starts timer 1
A9FF LDA #$FF ; Sets timer 1 flag
8DCA1D STA TM1FLG
60 RTS ; Returns from subroutine
==A28E TIMER2 ; Starts timer 2
A9FF LDA #$FF ; Sets timer 2 flag
8DD21D STA TM2FLG
60 RTS ; Returns from subroutine
==A294 TIMER3 ; Starts timer 3
A9FF LDA #$FF ; Sets timer 3 flag
8DDA1D STA TM3FLG
60 RTS ; Returns from subroutine
==A29A RESTIM ; Resets a timer
ADFC1D LDA MEMORY+1 ; Gets timer number
C931 CMP #$31 ; Is it a 1?
F00C BEQ RT1 ; If it is branches to reset timer 1
C932 CMP #$32 ; Is it a 2?
F02B BEQ RT2 ; If it is branches to reset timer 2
C933 CMP #$33 ; Is it a 3?
F04A BEQ RT3 ; If it is branches to reset timer 3
2069A2 JSR $A269 ; Invalid timer numer, so jumps to
clear code

==A2AC
60 RTS ; Returns from subroutine
==A2AD RT1 ; Resets timer 1
A900 LDA #00 ; Clears timer 1 flag and sets timer
1 to zero

8DCA1D STA TM1FLG
8DD11D STA TMR1JF
A930 LDA #$30 ; ASCII code for zero
8DCB1D STA TMR1HH
8DCC1D STA TMR1HL
==A2BD
8DCD1D STA TMR1MH

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8DCE1D   STA TMR1ML
8DCF1D   STA TMR1SH
8DD01D   STA TMR1SL
20AEA3   JSR $A3AE           ; Prints timer 1
200CA2   JSR $A20C           ; Sets cursor location
==A2CF
60        RTS                ; Returns from subroutine
==A2D0   RT2                 ; Resets timer 2
A900     LDA #00             ; Clears timer 2 flag and sets timer
                                2 to zero

8DD21D   STA TM2FLG
8DD91D   STA TMR2JF
A930     LDA #$30           ; ASCII code for zero
8DD31D   STA TMR2HH
8DD41D   STA TMR2HL
==A2E0
8DD51D   STA TMR2MH
8DD61D   STA TMR2ML
8DD71D   STA TMR2SH
8DD81D   STA TMR2SL
20D6A3   JSR $A3D6           ; Prints timer 2
200CA2   JSR $A20C           ; Sets cursor location
==A2F2
60        RTS                ; Returns from subroutine
==A2F3   RT3                 ; Resets timer 3
A900     LDA #00             ; Clears timer 3 flag and sets timer
                                3 to zero

8DDA1D   STA TM3FLG
8DE11D   STA TMR3JF
A930     LDA #$30           ; ASCII code for zero
8DDB1D   STA TMR3HH
8DDC1D   STA TMR3HL
==A303
8DDD1D   STA TMR3MH
8DDE1D   STA TMR3ML
8DDF1D   STA TMR3SH
8DE01D   STA TMR3SL
20FEA3   JSR $A3FE           ; Prints timer 3
200CA2   JSR $A20C           ; Sets cursor location
==A315
60        RTS                ; Returns from subroutine
==A316   ENDTIM             ; Stops a timer
ADFC1D   LDA MEMORY+1       ; Gets timer number
C931     CMP #$31           ; Is it timer 1?
F00C     BEQ ET1            ; If it is, branches to stop timer 1
C932     CMP #$32           ; Is it timer 2?
F00E     BEQ ET2            ; If it is, branches to stop timer 2
C933     CMP #$33           ; Is it timer 3?
F010     BEQ ET3            ; If it is, branches to stop timer 3

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2069A2 JSR $A269 ; Invalid timer number so clears
           code on screen
==A328
60 RTS ; Returns from subroutine
==A329 ET1 ; Stops timer 1
A900 LDA #00 ; Clears timer 1 flag
8DCA1D STA TM1FLG
60 RTS ; Returns from subroutine
==A32F ET2 ; Stops timer 2
A900 LDA #00 ; Clears timer 2 flag
8DD21D STA TM2FLG
60 RTS ; Returns from subroutine
==A335 ET3 ; Stops timer 3
A900 LDA #00 ; Clears timer 3 flag
8DDA1D STA TM3FLG
60 RTS ; Returns from subroutine
==A33B MENU ; Returns to input section
20BA40 JSR DISABL ; Disables all flags, clears all
           constants
A9FF LDA #$FF ; Sets menu flag
8DEE1D STA MENFLG
60 RTS ; Returns from subroutine
ADE61D LDA TMPFLG ; Gets temperature flag
C9FF CMP #$FF ; Is it set?
D003 BNE RETRN ; If it's not returns from subrou-
           tine
==A34B
200040 JSR UPTEMP ; It is set, so updates temperatures
==A34E RETRN
60 RTS ; Returns from subroutine
AD029A LDA $9A02 ; Gets the temperature degree unit
           from the 6520-1
2901 AND #01 ; Masks off other bits
CDEF1D CMP DEGUNT ; Compares with the previous unit
F0F5 BEQ RETRN ; If the same returns from subrou-
           tine
8DEF1D STA DEGUNT ; Saves the degree unit
C901 CMP #01 ; It's not the same so is it F?
==A35E
F004 BEQ F ; If it is branches to print F
A943 LDA #$43 ; It's not F so gets screen code for
           C
D002 BNE POKE ; Branches to print C
==A364 F ; Prints F
A946 LDA #$46 ; Screen code for F
==A366 POKE ; Prints degree units
8D3D1F STA 7997
8D481F STA 8008
8D691F STA 8041
8D741F STA 8052

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8D951F   STA 8085
8DA01F   STA 8096
==A378
200F22   JSR $220F           ; Clears the degree unit if the
                                temperature probe is not connected
60       RTS           ; Returns from subroutine
==A37C   MSG23           ; Prints message 23
A9E2     LDA #M23L     ; Sets starting address, LB
85FB     STA MSGADL
A927     LDA #M23H     ; Sets starting address, HB
85FC     STA MSGADH
A913     LDA #$13      ; Sets number of characters
8DF01D   STA NOCHAR
208DA3   JSR $A38D     ; Displays message (DISPLY)
==A38C
60       RTS           ; Returns from subroutine
==A38D   DISPLY        ; Displays a message to the screen
                                at the current cursor location
A000     LDY #00       ; Clears the character counter
==A38F   MOREC
B1FB     LDA (MSGADL),Y ; Gets a character
20D2FF   JSR $FFD2     ; Displays it
C8       INY           ; Increments character counter
CCF01D   CPY NOCHAR   ; Finished message?
D0F5     BNE MOREC    ; If not gets another character
60       RTS           ; Returns from subroutine
==A39B   MSGE         ; Displays a message at a specified
                                screen location
A000     LDY #00       ; Clears character counter
==A39D   MORECH
B1FB     LDA (MSGADL),Y ; Gets a character
91FD     STA (MSGPRL),Y ; Displays it
C8       INY           ; Increments character counter
CCF01D   CPY NOCHAR   ; Finished message?
D0F6     BNE MORECH   ; If not gets another character
60       RTS           ; Returns from subroutine
==A3A8   PULSE        ; Enables pulse counter on 6522-1
A900     LDA #00
8D0998   STA IO1T2H   ; Starts counting pulses
60       RTS           ; Returns from subroutine
==A3AE   PRTIM1       ; Prints timer 1
ADCB1D   LDA TMR1HH   ; Gets timer 1 hours HB
8DC61F   STA 8134     ; Prints it
ADCC1D   LDA TMR1HL   ; Gets timer 1 hours LB
8DC71F   STA 8135     ; Prints it
ADCD1D   LDA TMR1MH   ; Gets timer 1 minutes HB
8DC91F   STA 8137     ; Prints it
==A3C0
ADCE1D   LDA TMR1ML   ; Gets timer 1 minutes LB
8DCA1F   STA 8138     ; Prints it

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ADCF1D   LDA TMR1SH   ; Gets timer 1 seconds HB
8DCC1F   STA 8140     ; Prints it
ADD01D   LDA TMR1SL   ; Gets timer 1 seconds LB
8DCD1F   STA 8141     ; Prints it
==A3D2
200CA2   JSR $A20C    ; Sets cursor location
60       RTS         ; Returns from subroutine
==A3D6   PRTIM2      ; Prints timer 2
ADD31D   LDA TMR2HH   ; Gets timer 2 hours HB
8DDC1F   STA 8156     ; Prints it
ADD41D   LDA TMR2HL   ; Gets timer 2 hours LB
8DDD1F   STA 8157     ; Prints it
ADD51D   LDA TMR2MH   ; Gets timer 2 minutes HB
8DDF1F   STA 8159     ; Prints it
==A3E8
ADD61D   LDA TMR2ML   ; Gets timer 2 minutes LB
8DE01F   STA 8160     ; Prints it
ADD71D   LDA TMR2SH   ; Gets timer 2 seconds HB
8DE21F   STA 8162     ; Prints it
ADD81D   LDA TMR2SL   ; Gets timer 2 seconds LB
8DE31F   STA 8163     ; Prints it
==A3FA
200CA2   JSR $A20C    ; Sets cursor location
60       RTS         ; Returns from subroutine
==A3FE   PRTIM3      ; Prints timer 3
ADDB1D   LDA TMR3HH   ; Gets timer 3 hours HB
8DF21F   STA 8178     ; Prints it
ADDC1D   LDA TMR3HL   ; Gets timer 3 hours LB
8DF31F   STA 8179     ; Prints it
ADDD1D   LDA TMR3MH   ; Gets timer 3 minutes HB
8DF51F   STA 8181     ; Prints it
==A410
ADDE1D   LDA TMR3ML   ; Gets timer 3 minutes LB
8DF61F   STA 8182     ; Prints it
ADDF1D   LDA TMR3SH   ; Gets timer 3 seconds HB
8DF81F   STA 8184     ; Prints it
ADE01D   LDA TMR3SL   ; Gets timer 3 seconds LB
8DF91F   STA 8185     ; Prints it
==A422
200CA2   JSR $A20C    ; Sets cursor location
60       RTS         ; Returns from subroutine
==A426   TNEW        ; Gets temperature from A/D convert-
                    er
202CA6   JSR $A62C    ; Time delay (DELAY)
A980     LDA #$80     ; Initializes test byte (first
                    digit)
8DF21D   STA DIGSEL
AD029A   LDA $9A02    ; Resets EOC flag in 6520-1 CRB
==A431   NEOC
2C039A   BIT $9A03    ; Has EOC occurred?

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10FB      BPL  NECC      ; Loops until EOC flag set
==A436    DS1
AD009A    LDA  $9A00    ; Loads digit select
2CF21D    BIT  DIGSEL   ; Compares with test byte
F0F8      BEQ  DS1      ; Loops until first digit
2908      AND  #08      ; Isolates first digit
4908      EOR  #08
4A        LSR  A
4A        LSR  A
4A        LSR  A
0930      ORA  #$30     ; Makes it ASCII
==A447
8DF31D    STA  TEMPH    ; Stores hundred's digit
4EF21D    LSR  DIGSEL   ; Shifts test byte
==A44D    DS2
AD009A    LDA  $9A00    ; Loads digit select byte
2CF21D    BIT  DIGSEL   ; Compares with test byte
F0F8      BEQ  DS2      ; Loops until second digit
290F      AND  #$0F     ; Removes digit select bits
0930      ORA  #$30     ; Makes it ASCII
8DF41D    STA  TEMPT    ; Stores ten's digit
4EF21D    LSR  DIGSEL   ; Shifts test byte
==A45F    DS3
AD009A    LDA  $9A00    ; Loads digit select byte
2CF21D    BIT  DIGSEL   ; Compares with test byte
F0F8      BEQ  DS3      ; Loops until third digit
290F      AND  #$0F     ; Removes digit select bits
0930      ORA  #$30     ; Makes it ASCII
8DF51D    STA  TEMPU    ; Stores unit's digit
4EF21D    LSR  DIGSEL   ; Shifts test byte
==A471    DS4
AD009A    LDA  $9A00    ; Loads digit select byte
2CF21D    BIT  DIGSEL   ; Compares with test byte
F0F8      BEQ  DS4      ; Loops until fourth digit
290F      AND  #$0F     ; Removes digit select bits
0930      ORA  #$30     ; Makes it ASCII
8DF61D    STA  TEMPTH   ; Store tenth's digit
60        RTS          ; Returns from subroutine
==A481    SCREEN1      ; Displays title screen
2018E5    JSR  $E518    ; Clears the screen
18        CLC          ; Clears the carry bit
A9F2      LDA  #242     ; Sets upper and lower case
8D0590    STA  $9005
A200      LDX  #00      ; Prints 22 cyan asterisks in two
                                rows
A000      LDY  #00
A916      LDA  #22
8DF71D    STA  COUNT
==A493    HERE
A92A      LDA  #42      ; Gets screen code for asterisk

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9D161E    STA 7702,X    ; Prints first row
9D4A1F    STA 8010,X    ; Prints second row
E8        INX
A903      LDA #03    ; Gets screen code for cyan char-
           acter
991696    STA 38422,Y ; Colors first row
994A97    STA 38730,Y ; Colors second row
==A4A4
C8        INY
CEF71D    DEC COUNT
DOE9      BNE HERE
A200      LDX #00    ; Prints 2 columns of 11 cyan aster-
           isks
A000      LDY #00
A90B      LDA #11
8DF71D    STA COUNT
==A4B3    COL
A92A      LDA #42    ; Screen code for asterisk
9D2C1E    STA 7724,X ; Prints first column
9D411E    STA 7745,X ; Prints second column
A903      LDA #03    ; Gets screen code for cyan char-
           acter
992C96    STA 38444,Y ; Colors first column
994196    STA 38465,Y ; Colors second column
==A4C3
8A        TXA
6916      ADC #22
AA        TAX
98        TYA
6916      ADC #22
A8        TAY
CEF71D    DEC COUNT
DOE3      BNE COL
A92A      LDA #42    ; Gets screen code for asterisk
8D1E1F    STA 7966    ; Prints first asterisk
==A4D5
8D341F    STA 7988    ; Prints second asterisk
8D331F    STA 7987    ; Prints third asterisk
8D491F    STA 8009    ; Prints fourth asterisk
A903      LDA #C3    ; Gets screen code for cyan char-
           acter
8D1E97    STA 38686    ; Colors first asterisk
8D3497    STA 38708    ; Colors second asterisk
==A4E6
8D3397    STA 38707    ; Colors third asterisk
8D4997    STA 38729    ; Colors fourth asterisk
A94F      LDA #79    ; Gets screen code for O
8D441E    STA 7748    ; Prints first O
8D7B1E    STA 7803    ; Prints second O
8D7F1E    STA 7807    ; Prints third O

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==A4F7
8DB61E STA 7862 ; Prints fourth O
8DB71E STA 7863 ; Prints fifth O
8DBC1E STA 7868 ; Prints sixth O
8D121F STA 7954 ; Prints seventh O
A950 LDA #80 ; Gets screen code for P
8D451E STA 7749 ; Prints first P
==A508
8D721E STA 7794 ; Prints second P
8DE71E STA 7911 ; Prints third P
8D131F STA 7955 ; Prints fourth P
A945 LDA #69 ; Gets screen code for E
8D461E STA 7750 ; Prints first E
8D4A1E STA 7754 ; Prints second E
==A519
8D531E STA 7763 ; Prints third E
8D761E STA 7798 ; Prints fourth E
8DC21E STA 7874 ; Prints fifth E
8DE51E STA 7909 ; Prints sixth E
8DE81E STA 7912 ; Prints seventh E
8DEE1E STA 7918 ; Prints eighth E
==A52B
8D0F1F STA 7951 ; Prints ninth E
8D101F STA 7952 ; Prints tenth E
8D141F STA 7956 ; Prints eleventh E
8D291F STA 7977 ; Prints twelfth E
A94E LDA #78 ; Gets screen code for N
8D471E STA 7751 ; Prints first N
==A53C
8D771E STA 7799 ; Prints second N
8D7C1E STA 7804 ; Prints third N
8D191F STA 7961 ; Prints fourth N
A948 LDA #72 ; Gets screen code for H
8D491E STA 7753 ; Prints first H
8D0D1F STA 7949 ; Prints second H
==A54D
A941 LDA #65 ; Gets screen code for A
8D4B1E STA 7755 ; Prints first A
8D731E STA 7795 ; Prints second A
8DC01E STA 7872 ; Prints third A
8DEA1E STA 7914 ; Prints fourth A
8D161F STA 7958 ; Prints fifth A
==A55E
A952 LDA #82 ; Gets screen code for R
8D4C1E STA 7756 ; Prints first R
8D511E STA 7761 ; Prints second R
8D541E STA 7764 ; Prints third R
8D801E STA 7808 ; Prints fourth R
8DBF1E STA 7871 ; Prints fifth R

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==A56F
8DE91E STA 7913 ; Prints sixth R
8DED1E STA 7917 ; Prints seventh R
8D0E1F STA 7950 ; Prints eighth R
8D151F STA 7957 ; Prints ninth R
A954 LDA #84 ; Gets screen code for T
8D4D1E STA 7757 ; Prints first T
==A580
8D741E STA 7796 ; Prints second T
8D781E STA 7800 ; Prints third T
8D7E1E STA 7806 ; Prints fourth T
8DC11E STA 7873 ; Prints fifth T
8DE41E STA 7908 ; Prints sixth T
8DEB1E STA 7915 ; Prints seventh T
==A592
8D0C1F STA 7948 ; Prints eighth T
8D171F STA 7959 ; Prints ninth T
8D261F STA 7974 ; Prints tenth T
A953 LDA #83 ; Gets screen code for S
8D4F1E STA 7759 ; Prints first S
8DE01E STA 7904 ; Prints second S
==A5A3
8DEF1E STA 7919 ; Prints third S
8D2A1F STA 7978 ; Prints fourth S
A955 LDA #85 ; Gets screen code for U
8D501E STA 7760 ; Prints first U
8DEC1E STA 7916 ; Prints second U
A947 LDA #71 ; Gets screen code for G
==A5B3
8D521E STA 7762 ; Prints first G
8D1A1F STA 7962 ; Prints second G
A959 LDA #89 ; Gets screen code for Y
8D551E STA 7765 ; Prints first Y
A949 LDA #73 ; Gets screen code for I
8D751E STA 7797 ; Prints first I
==A5C3
8D7D1E STA 7805 ; Prints second I
8DE11E STA 7905 ; Prints third I
8D181F STA 7960 ; Prints fourth I
8D271F STA 7975 ; Prints fifth I
A94D LDA #77 ; Gets screen code for M
8D7A1E STA 7802 ; Prints first M
==A5D4
8DE61E STA 7910 ; Prints second M
8D281F STA 7976 ; Prints third M
A95E LDA #94 ; Gets screen code for a bullet
8DB21E STA 7858 ; Prints first bullet
8DDE1E STA 7902 ; Prints second bullet
8D0A1F STA 7946 ; Prints third bullet

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==A5E5
A942      LDA #66           ; Gets screen code for B
8DB41E    STA 7860        ; Prints first B
A94C      LDA #76           ; Gets screen code for L
8DB51E    STA 7861        ; Prints first L
8DBB1E    STA 7867        ; Prints second L
A944      LDA #68           ; Gets screen code for D
8DB81E    STA 7864        ; Prints first D
==A5F7
A946      LDA #70           ; Gets screen code for F
8DBA1E    STA 7866        ; Prints first F
A957      LDA #87           ; Gets screen code for W
8DBD1E    STA 7869        ; Prints first W
A958      LDA #88           ; Gets screen code for X
8DE21E    STA 7906        ; Prints first X
A96E      LDA #110         ; Gets screen code for blue back-
                                ground
==A608
8D0F90    STA 36879        ; Colors the background blue
A200      LDX #00
A90B      LDA #11           ; 11 rows of white characters
8DF81D    STA CNT
==A612    THERE
A912      LDA #18           ; 18 characters in a row
8DF71D    STA COUNT
==A617    LOOP
A901      LDA #01           ; Gets screen code for white charac-
                                ters
9D4496    STA 38468,X      ; Colors a row
E8        INX
CEF71D    DEC COUNT
D0F5      BNE LOOP
8A        TXA
6904      ADC #04
AA        TAX
CEF81D    DEC CNT
==A629
D0E7      BNE THERE
60        RTS              ; Returns from subroutine
==A62C    DELAY            ; Delays for roughly 1/2 sec
A200      LDX #00
A000      LDY #00
==A630    COMPY
C00A      CPY #10
F06B      BEQ RET          ; Branches to return from subroutine
                                if finished with delay
==A634    COMPX
E0FF      CPX #255
F063      BEQ CONT

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EA      NOP
E8      INX
4C34A6  JMP $A634      ; Repeats loop
==A69B  CONT
C8      INY
4C30A6  JMP $A630      ; Repeats loop
==A69F  RET
60      RTS           ; Returns from subroutine
; INTERRUPT ROUTINE
*=$2000

==2000
ADC61D  LDA ROLFLG     ; Gets roller flag
C9FF    CMP #$FF      ; Is it set?
F007    BEQ GETRPM    ; If it is then updates pump output
ADC71D  LDA PULFLG    ; Gets pulsatile flag
C9FF    CMP #$FF      ; Is it set?
D01E    BNE NEXT      ; If it's not then updates tempera-
                        ; ture update counter
==200E  GETRPM        ; Updates roller or pulsatile pump
                        ; output
ACF11D  LDY HALFCT     ; Gets update counter
C8      INY           ; Increments update counter
8CF11D  STY HALFCT     ; Stores update counter
C01E    CPY #30        ; Is it 1/2 sec yet?
D013    BNE NEXT      ; If it isn't then updates tempera-
                        ; ture update counter
A9FF    LDA #$FF      ; Sets pump output update flag
8DC51D  STA PMPFLG     ; Sets pump output update flag
==201E
ED0898  SBC IO1T2L     ; Gets number of pulses counted
8DE51D  STA PULSES     ; Stores number of pulses counted
A900    LDA #00        ; Clears 1/2 sec counter
8DF11D  STA HALFCT     ; Resets pulse counter
8D0998  STA IO1T2H     ; Resets pulse counter
==202C  NEXT
ACE71D  LDY TPCNT      ; Gets temperature update counter
C8      INY           ; Increments it
8CE71D  STY TPCNT      ; Stores it
C0FF    CPY #$FF      ; Has it been 4 sec?
D00A    BNE TM1UPD     ; If it hasn't branches to check
                        ; timer 1
A9FF    LDA #$FF      ; It has so sets temperature update
8DE61D  STA TMPFLG     ; flag
==203C
A900    LDA #00        ; Clears temperature update counter
8DE71D  STA TPCNT      ; Updates timer 1 if necessary
==2041  TM1UPD
ADCA1D  LDA TM1FLG     ; Gets timer 1 flag
C9FF    CMP #$FF      ; Is it set?

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D073      BNE  TM2UPD      ; If it isn't branches to check
                                timer 2
ACD11D    LDY  TMR1JF      ; Gets timer 1 jiffy counter (1/60
                                sec)
C8        INY              ; Increments it
8CD11D    STY  TMR1JF      ; Stores it
C03C      CPY  #60         ; Has it been 1 sec?
==2051
D068      BNE  TM2UPD      ; If it hasn't branches to check
                                timer 2

A900      LDA  #00         ;
8DD11D    STA  TMR1JF      ; It has so clears jiffy counter
ACD01D    LDY  TMR1SL      ; Gets timer 1 seconds LB
C8        INY              ; Increments it
8CD01D    STY  TMR1SL      ; Stores it
C03A      CPY  #$3A       ; Has it been 10 sec?
==2061
D055      BNE  PTIMR1      ; If it hasn't then branches to
                                print timer 1

A930      LDA  #$30        ;
8DD01D    STA  TMR1SL      ; It has so clears timer 1 sec LB
ACCF1D    LDY  TMR1SH      ; Gets timer 1 seconds HB
C8        INY              ; Increments it
8CCF1D    STY  TMR1SH      ; Stores it
C036      CPY  #$36       ; Has it been 60 seconds?
==2071
D045      BNE  PTIMR1      ; If it hasn't branches to print
                                timer 1

A930      LDA  #$30        ;
8DCF1D    STA  TMR1SH      ; It has so clears timer 1 sec HB
ACCE1D    LDY  TMR1ML      ; Gets timer 1 minutes LB
C8        INY              ; Increments it
8CCE1D    STY  TMR1ML      ; Stores it
C03A      CPY  #$3A       ; Has it been 10 minutes?
==2081
D035      BNE  PTIMR1      ; If it hasn't branches to print
                                timer 1

A930      LDA  #$30        ;
8DCE1D    STA  TMR1ML      ; It has so clears timer 1 min LB
ACCD1D    LDY  TMR1MH      ; Gets timer 1 minutes HB
C8        INY              ; Increments it
8CCD1D    STY  TMR1MH      ; Stores it
C036      CPY  #$36       ; Has it been 60 minutes?
==2091
D025      BNE  PTIMR1      ; If it hasn't branches to print
                                timer 1

A930      LDA  #$30        ;
8DCD1D    STA  TMR1MH      ; It has so clears timer 1 min HB
ACCC1D    LDY  TMR1HL      ; Gets timer 1 hours LB
C8        INY              ; Increments it

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8CCC1D  STY TMR1HL      ; Stores it
C03A    CPY #$3A      ; Has it been 10 hours?
==20A1
D015    BNE PTIMR1    ; If it hasn't branches to print
                    ; timer 1

A930    LDA #$30
8DCC1D  STA TMR1HL    ; It has so clears timer 1 hours LB
ACCB1D  LDY TMR1HH    ; Gets timer 1 hours HB
C8      INY          ; Increments it
8CCB1D  STY TMR1HH    ; Stores it
C036    CPY #$36      ; Has it been 60 hours?
==20B1
D005    BNE PTIMR1    ; If it hasn't branches to print
                    ; timer 1

A930    LDA #$30
8DCB1D  STA TMR1HH    ; It has so clears timer 1 hours HB
==20B8  PTIMR1        ; Prints timer 1
20AEA3  JSR PRTIM1
==20BB  TM2UPD        ; Checks timer 2
ADD21D  LDA TM2FLG    ; Gets timer 2 flag
C9FF    CMP #$FF      ; Is it set?
D073    BNE TM3UPD    ; If it isn't branches to check
                    ; timer 3

ACD91D  LDY TMR2JF    ; Gets timer 2 jiffy counter
C8      INY          ; Increments it
8CD91D  STY TMR2JF    ; Stores it
C03C    CPY #60       ; Has it been 1 sec?
==20CB  D068        ; If it hasn't branches to check
                    ; timer 3

A900    LDA #00
8DD91D  STA TMR2JF    ; It has so clears timer 2 jiffy
                    ; counter

ACD81D  LDY TMR2SL    ; Gets timer 2 seconds LB
C8      INY          ; Increments it
8CD81D  STY TMR2SL    ; Stores it
C03A    CPY #$3A      ; Has it been 10 seconds?
==20DB  D055        ; If it hasn't branches to print
                    ; timer 2

A930    LDA #$30
8DD81D  STA TMR2SL    ; It has so clears timer 2 sec LB
ACD71D  LDY TMR2SH    ; Gets timer 2 seconds HB
C8      INY          ; Increments it
8CD71D  STY TMR2SH    ; Stores it
C036    CPY #$36      ; Has it been 60 seconds?
==20EB  D045        ; If it hasn't branches to print
                    ; timer 2

A930    LDA #$30

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8DD71D   STA TMR2SH   ; It has so clears timer 2 sec HB
ACD61D   LDY TMR2ML  ; Gets timer 2 minutes LB
C8       INY      ; Increments it
8CD61D   STY TMR2ML  ; Stores it
C03A     CPY #\$3A  ; Has it been 10 minutes?
==20FB
D035     BNE PTIMR2 ; If it hasn't branches to print
                    timer 2

A930     LDA #\$30
8DD61D   STA TMR2ML  ; It has so clears timer 2 min LB
ACD51D   LDY TMR2MH  ; Gets timer 2 minutes HB
C8       INY      ; Increments it
8CD51D   STY TMR2MH  ; Stores it
C036     CPY #\$36  ; Has it been 60 minutes?
=210B
D025     BNE PTIMR2 ; If it hasn't branches to print
                    timer 2

A930     LDA #\$30
8DD51D   STA TMR2MH  ; It has so clears timer 2 min HB
ACD41D   LDY TMR2HL  ; Gets timer 2 hours LB
C8       INY      ; Increments it
8CD41D   STY TMR2HL  ; Stores it
C03A     CPY #\$3A  ; Has it been 10 hours?
==211B
D015     BNE PTIMR2 ; If it hasn't branches to print
                    timer 2

A930     LDA #\$30
8DD41D   STA TMR2HL  ; It has so clears timer 2 hours LB
ACD31D   LDY TMR2HH  ; Gets timer 2 hours HB
C8       INY      ; Increments it
8CD31D   STY TMR2HH  ; Stores it
C036     CPY #\$36  ; Has it been 60 hours?
==212B
D005     BNE PTIMR2 ; If it hasn't branches to print
                    timer 2

A930     LDA #\$30
8DD31D   STA TMR2HH  ; It has so clears timer 2 hours HB
==2132   PTIMR2    ; Prints timer 2
20D6A3   JSR PRTIM2
==2135   TM3UPD    ; Checks timer 3
ADDA1D   LDA TM3FLG  ; Gets timer 3 flag
C9FF     CMP #\$FF   ; Is it set?
D073     BNE CLKUPD  ; If it isn't branches to check
                    clock
ACE11D   LDY TMR3JF  ; It is so gets timer 3 jiffy
                    counter
C8       INY      ; Increments it
8CE11D   STY TMR3JF  ; Stores it
C03C     CPY #60     ; Has it been 1 sec?

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8DDC1D  STA TMR3HL      ; It has so clears timer 3 hours LB
ACDB1D  LDY TMR3HE      ; Gets timer 3 hours HB
C8      INY          ; Increments it
8CDB1D  STY TMR3HH      ; Stores it
C036    CPY #\$36     ; Has it been 60 hours?
==21A5
D005    BNE PTIMR3    ; If it hasn't branches to print
                    timer 3

A930    LDA #\$30
8DDB1D  STA TMR3HH      ; It has so clears timer 3 hours HB
==21AC  PTIMR3        ; Prints timer 3
20FEA3  JSR PRTIM3
==21AF  CLKUPD        ; Checks clock
ADE31D  LDA CLKFLG     ; Gets clock update flag
C9FF    CMP #\$FF      ; Is it set?
D015    BNE CENTRF    ; If it isn't branches to check cen-
                    trifugal pump output update

ACE41D  LDY CLKJIF     ; It is so gets clock jiffy counter
C8      INY          ; Increments it
8CE41D  STY CLKJIF     ; Stores it
C03C    CPY #60       ; Has it been a second?
==21BF
D00A    BNE CENTRF    ; If it hasn't branches to check
                    centrifugal pump update

A900    LDA #00
8DE41D  STA CLKJIF     ; It has so clears clock jiffy
                    counter

A9FF    LDA #\$FF
8DE21D  STA PRCLKF     ; Sets print clock flag
==21CB  CENTRF        ; Checks centrifugal pump update
ADC81D  LDA CENFLG     ; Gets centrifugal update flag
C9FF    CMP #\$FF      ; Is it set?
D015    BNE VICINT    ; If it isn't branches to VIC 20
                    interrupt routine

ACC91D  LDY CENCNT     ; Gets centrifugal update counter
C8      INY          ; Increments it
8CC91D  STY CENCNT     ; Stores it
C01E    CPY #\$1E     ; Has it been 1/2 second?
==21DB
D00A    BNE VICINT    ; If it hasn't branches to VIC 20
                    interrupt routine

A900    LDA #00
8DC91D  STA CENCNT     ; It has so clears centrifugal up-
                    date counter

A9FF    LDA #\$FF
8DC51D  STA PMPFLG     ; Sets pump output update flag
==21E7  VICINT        ; Jumps to VIC 20 interrupt routine
4CBFEA  JMP \$EABF

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## ;SUBROUTINES

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==21EA    CONTMP          ; Prints temperature degree units
                                and check for unconnected probes
AD029A    LDA $9A02      ; Gets degree unit
2901      AND #$01       ; Masks off other bits
8DEF1D    STA DEGUNT     ; Stores it
C901      CMP #$01       ; Is it degree F?
D005      BNE DEGC       ; If it isn't branches to degree C
A946      LDA #70        ; Gets screen code for F
4CFD21    JMP $21FD      ; Prints the degree units
==21FB    DEGC
A943      LDA #67        ; Gets screen code for C
==21FD    PRDEG          ; Prints the degree units
8D3D1F    STA 7997
8D481F    STA 8008
8D691F    STA 8041
8D741F    STA 8052
8D951F    STA 8085
8DA01F    STA 8096
==220F
ADE81D    LDA TMP1NC     ; Gets temperature 1 flag
C900      CMP #00        ; Is it connected?
F008      BEQ CKTMP2     ; If it is branches to check temp-
                                erature 2
A920      LDA #$20       ; It isn't so clears its display
8D3A1F    STA 7994
8D3D1F    STA 7997
==221E    CKTMP2        ; Checks temperature 2
ADE91D    LDA TMP2NC     ; Gets temperature 2 flag
C900      CMP #00        ; Is it connected?
F008      BEQ CKTMP3     ; If it is branches to check temp-
                                erature 3
A920      LDA #$20       ; It isn't so clears its display
8D481F    STA 8008
8D451F    STA 8005
==222D    CKTMP3        ; Checks temperature 3
ADEA1D    LDA TMP3NC     ; Gets temperature 3 flag
C900      CMP #00        ; Is it connected?
F008      BEQ CKTMP4     ; If it is branches to check temp-
                                erature 4
A920      LDA #$20       ; It isn't so clears its display
8D691F    STA 8041
8D661F    STA 8038
==223C    CKTMP4        ; Checks temperature 4
ADEB1D    LDA TMP4NC     ; Gets temperature 4 flag
C900      CMP #00        ; Is it connected?
F008      BEQ CKTMP5     ; If it is branches to check temp-
                                erature 5
A920      LDA #$20       ; It isn't so clears its display
8D741F    STA 8052

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8D711F   STA 8049
==224B   CKTMP5           ; Checks temperature 5
ADEC1D   LDA TMP5NC     ; Gets temperature 5 flag
C900     CMP #00        ; Is it connected?
F008     BEQ CKTMP6     ; If it is branches to check temp-
                                     erature 6

A920     LDA #$20       ; It isn't so clears its display
8D951F   STA 8085
8D921F   STA 8082
==225A   CKTMP6           ; Checks temperature 6
ADED1D   LDA TMP6NC     ; Gets temperature 6 flag
C900     CMP #00        ; Is it connected?
F008     BEQ RETURN     ; If it is branches to return from
                                     subroutine

A920     LDA #$20       ; It isn't so clears its display
8DA01F   STA 8096
8D9D1F   STA 8093
==2269   RETURN
60       RTS           ; Returns from subroutine
==226A   SCREN2         ; Displays monitor screen
2018E5   JSR $E518     ; Clears the screen
18       CLC           ; Clears the carry bit
A92E     LDA #$2E       ; Gets screen code for .
8D9D1F   STA 8093       ; Prints first .
A948     LDA #72        ; Gets screen code for H
8D171E   STA 7703       ; Prints first H
8D1B1E   STA 7707       ; Prints second H
==227B   STA 7751       ; Prints third H
A945     LDA #69        ; Gets screen code for E
8D441E   STA 7748       ; Prints first E
8D181E   STA 7704       ; Prints second E
8D7A1E   STA 7802       ; Prints third E
8D7E1E   STA 7806       ; Prints fourth E
==228C   STA 7893       ; Prints fifth E
8D0E1F   STA 7950       ; Prints sixth E
8D111F   STA 7953       ; Prints seventh E
8D171F   STA 7959       ; Prints eighth E
8DA71F   STA 8103       ; Prints ninth E
8DAE1F   STA 8110       ; Prints tenth E
==229E   STA 8131       ; Prints eleventh E
8DD91F   STA 8153       ; Prints twelfth E
8DEF1F   STA 8175       ; Prints thirteenth E
A949     LDA #73        ; Gets screen code for I
8D191E   STA 7705       ; Prints first I
8D451E   STA 7749       ; Prints second I
==22AF   STA 8108       ; Prints third I
8DAC1F

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8DC11F   STA 8129           ; Prints fourth I
8DD71F   STA 8151           ; Prints fifth I
8DED1F   STA 8173           ; Prints sixth I
A909     LDA #09           ; Gets screen code for i
8D3B1E   STA 7739           ; Prints first i
==22C0
8DC41E   STA 7876           ; Prints second i
8DEA1E   STA 7914           ; Prints third i
8D001F   STA 7936           ; Prints fourth i
A947     LDA #71           ; Gets screen code for G
8D1A1E   STA 7706           ; Prints first G
8D461E   STA 7750           ; Prints second G
==22D1
A907     LDA #07           ; Gets screen code for g
8D521E   STA 7762           ; Prints first g
8DEE1E   STA 7918           ; Prints second g
A954     LDA #84           ; Gets screen code for T
8D1C1E   STA 7708           ; Prints first T
8D481E   STA 7752           ; Prints second T
==22E1
8DB31E   STA 7859           ; Prints third T
8DB61E   STA 7862           ; Prints fourth T
8DD41E   STA 7892           ; Prints fifth T
8D0D1F   STA 7949           ; Prints sixth T
8D141F   STA 7956           ; Prints seventh T
8DA91F   STA 8105           ; Prints eighth T
==22F3
8DAB1F   STA 8107           ; Prints ninth T
8DC01F   STA 8128           ; Prints tenth T
8DD61F   STA 8150           ; Prints eleventh T
8DEC1F   STA 8172           ; Prints twelfth T
A93D     LDA #61           ; Gets screen code for =
8D1E1E   STA 7710           ; Prints first =
==2304
8D341E   STA 7732           ; Prints second =
8D4A1E   STA 7754           ; Prints third =
8D601E   STA 7776           ; Prints fourth =
8D8C1E   STA 7820           ; Prints fifth =
8DB81E   STA 7864           ; Prints sixth =
8DDE1E   STA 7902           ; Prints seventh =
==2316
8DF41E   STA 7924           ; Prints eighth =
A903     LDA #03           ; Gets screen code for c
8D251E   STA 7717           ; Prints first c
A943     LDA #67           ; Gets screen code for C
8D791E   STA 7801           ; Prints first C
8DA31F   STA 8099           ; Prints second C
==2326
A90D     LDA #13           ; Gets screen code for m
8D261E   STA 7718           ; Prints first m

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8D931E   STA 7827   ; Prints second m
8DC01E   STA 7872   ; Prints third m
8DC31E   STA 7875   ; Prints fourth m
8DE61E   STA 7910   ; Prints fifth m
==2337
8DE91E   STA 7913   ; Prints sixth m
8DFC1E   STA 7932   ; Prints seventh m
8DFF1E   STA 7935   ; Prints eighth m
8D031F   STA 7939   ; Prints ninth m
A94D     LDA #77     ; Gets screen code for M
8DAD1F   STA 8109   ; Prints first M
==2348
8D0F1F   STA 7951   ; Prints second M
8DC21F   STA 8130   ; Prints third M
8DD81F   STA 8152   ; Prints fourth M
8DEE1F   STA 8174   ; Prints fifth M
A90E     LDA #14     ; Gets screen code for n
8D3C1E   STA 7740   ; Prints first n
==2359
8DC51E   STA 7877   ; Prints second n
8DEB1E   STA 7915   ; Prints third n
8D011F   STA 7937   ; Prints fourth n
A94E     LDA #78     ; Gets screen code for N
8DA81F   STA 8104   ; Prints first N
A957     LDA #87     ; Gets screen code for W
==2369
8D431E   STA 7747   ; Prints first W
8DD01E   STA 7888   ; Prints second W
A90B     LDA #11     ; Gets screen code for k
8D511E   STA 7761   ; Prints first k
8DED1E   STA 7917   ; Prints second k
A90C     LDA #12     ; Gets screen code for l
==2379
8D671E   STA 7783   ; Prints first l
8DC11E   STA 7873   ; Prints second l
8DE71E   STA 7911   ; Prints third l
8DFD1E   STA 7933   ; Prints fourth l
A94C     LDA #76     ; Gets screen code for L
8DC81E   STA 7880   ; Prints first L
==238A
8DCE1E   STA 7886   ; Prints second L
A902     LDA #02     ; Gets screen code for b
8D681E   STA 7784   ; Prints first b
A942     LDA #66     ; Gets screen code for B
8D6F1E   STA 7791   ; Prints first B
8DC71E   STA 7879   ; Prints second B
==239A
A94F     LDA #79     ; Gets screen code for O
8D701E   STA 7792   ; Prints first O
8DB11E   STA 7857   ; Prints second O

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8DC91E   STA 7881   ; Prints third O
8DCA1E   STA 7882   ; Prints fourth O
8DCF1E   STA 7887   ; Prints fifth O
==23AB
A944     LDA #68     ; Gets screen code for D
8D711E   STA 7793   ; Prints first D
8DCB1E   STA 7883   ; Prints second D
A959     LDA #89     ; Gets screen code for Y
8D721E   STA 7794   ; Prints first Y
A953     LDA #83     ; Gets screen code for S
8D741E   STA 7796   ; Prints first S
==23BD
8D181F   STA 7960   ; Prints second S
A955     LDA #85     ; Gets screen code for U
8D751E   STA 7797   ; Prints first U
8DB21E   STA 7858   ; Prints second U
8DB51E   STA 7861   ; Prints third U
8D151F   STA 7957   ; Prints fourth U
==23CE
8DA41F   STA 8100   ; Prints fifth U
A952     LDA #82     ; Gets screen code for R
8D761E   STA 7798   ; Prints first R
8D7D1E   STA 7805   ; Prints second R
8DD21E   STA 7890   ; Prints third R
8D121F   STA 7954   ; Prints fourth R
==23DF
8D161F   STA 7958   ; Prints fifth R
8DA51F   STA 8101   ; Prints sixth R
8DA61F   STA 8102   ; Prints seventh R
A946     LDA #70     ; Gets screen code for F
8D771E   STA 7799   ; Prints first F
8DCD1E   STA 7885   ; Prints second F
==23F0
A941     LDA #65     ; Gets screen code for A
8D781E   STA 7800   ; Prints first A
8D7C1E   STA 7804   ; Prints second A
8D7F1E   STA 7807   ; Prints third A
8DD31E   STA 7891   ; Prints fourth A
8D131F   STA 7955   ; Prints fifth A
==2401
A92A     LDA #42     ; Gets screen code for *
8D941E   STA 7828   ; Prints first *
8D951E   STA 7829   ; Prints second *
8D041F   STA 7940   ; Prints third *
8D051F   STA 7941   ; Prints fourth *
A92E     LDA #46     ; Gets screen code for .
==2411
8D231E   STA 7715   ; Prints first .
8D391E   STA 7737   ; Prints second .
8D4F1E   STA 7759   ; Prints third .

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8D651E   STA 7781   ; Prints fourth .
8D8F1E   STA 7823   ; Prints fifth .
8DBE1E   STA 7870   ; Prints sixth .
==2423
8DE41E   STA 7908   ; Prints seventh .
8DFA1E   STA 7930   ; Prints eighth .
A932     LDA #50     ; Gets screen code for 2
8D961E   STA 7830   ; Prints first 2
8D061F   STA 7942   ; Prints second 2
8D2A1F   STA 7978   ; Prints third 2
==2434
8DDA1F   STA 8154   ; Prints fourth 2
A950     LDA #80     ; Gets screen code for P
8DB41E   STA 7860   ; Prints first P
8D101F   STA 7952   ; Prints second P
A92F     LDA #47     ; Gets screen code for /
8DC21E   STA 7874   ; Prints first /
==2444
8DE81E   STA 7912   ; Prints second /
8DEC1E   STA 7916   ; Prints third /
8DFE1E   STA 7934   ; Prints fourth /
8D021F   STA 7938   ; Prints fifth /
A92E     LDA #$2E   ; Gets screen code for .
8D3A1F   STA 7994   ; Prints first .
==2455
8D451F   STA 8005   ; Prints second .
8D661F   STA 8038   ; Prints third .
8D711F   STA 8049   ; Prints fourth .
8D921F   STA 8082   ; Prints fifth .
A92D     LDA #45     ; Gets screen code for -
8D201F   STA 7968   ; Prints first -
==2466
8D2B1F   STA 7979   ; Prints second -
8D4C1F   STA 8012   ; Prints third -
8D571F   STA 8023   ; Prints fourth -
8D781F   STA 8056   ; Prints fifth -
8D831F   STA 8067   ; Prints sixth -
A93A     LDA #58     ; Gets screen code for :
==2477
8DB21F   STA 8114   ; Prints first :
8DB51F   STA 8117   ; Prints second :
8DC81F   STA 8136   ; Prints third :
8DCB1F   STA 8139   ; Prints fourth :
8DDE1F   STA 8158   ; Prints fifth :
8DE11F   STA 8161   ; Prints sixth :
==2489
8DF41F   STA 8180   ; Prints seventh :
8DF71F   STA 8183   ; Prints eighth :
A931     LDA #49     ; Gets screen code for l
8D1F1F   STA 7967   ; Prints first l

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8DC41F   STA 8132           ; Prints second 1
A933     LDA #51          ; Gets screen code for 3
==2499
8D4B1F   STA 8011           ; Prints first 3
8DF01F   STA 8176           ; Prints second 3
A934     LDA #52          ; Gets screen code for 4
8D561F   STA 8022           ; Prints first 4
A935     LDA #53          ; Gets screen code for 5
8D771F   STA 8055           ; Prints first 5
==24A9
A936     LDA #54          ; Gets screen code for 6
8D821F   STA 8066           ; Prints first 6
A96E     LDA #110         ; Gets screen code for blue back-
                        ; ground
8D0F90   STA 36879         ; Colors background
A200     LDX #00
==24B5   ROW
A907     LDA #07          ; Gets screen code for yellow
9D0096   STA 38400,X      ; Colors first row yellow
E8       INX
E016     CPX #22
D0F6     BNE ROW
A200     LDX #00
==24C1   ROW1
A903     LDA #03          ; Gets screen code for cyan
9D1696   STA 38422,X      ; Colors second - ninth row cyan
E8       INX
E0B0     CPX #176
D0F6     BNE ROW1
A200     LDX #00
==24CD   ROW2
A907     LDA #07          ; Gets screen code for yellow
9DC696   STA 38598,X      ; Colors tenth - twelfth row yellow
E8       INX
E042     CPX #66
D0F6     BNE ROW2
A200     LDX #00
==24D9   ROW3
A901     LDA #01          ; Gets screen code for white
9D0897   STA 38664,X      ; Colors thirteenth - nineteenth row
                        ; white
E8       INX
E09A     CPX #154
D0F6     BNE ROW3
A200     LDX #00
==24E5   ROW4
A903     LDA #03          ; Gets screen code for cyan
9DA297   STA 38818,X      ; Colors twentieth - twenty-third
                        ; row cyan
E8       INX

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E058      CPX #88
D0F6      BNE ROW4
A9F2      LDA #242      ; Sets upper and lower case
8D0590    STA $9005
60        RTS          ; Returns from subroutine
==24F5    MSG1         ; Message 1
C6        .BYT $C6,$4F, ; F
          $52,$20,$54,$48,$45,
          $20,$46,$4F,$4C,$4C,
4F        ; o
52        ; r
20        ; space
54        ; t
48        ; h
45        ; e
20        ; space
46        ; f
4F        ; o
4C        ; l
4C        ; l
4F        .BYT $4F,$57, ; o
          $49,$4E,$47,$0D,$49,
          $4E,$50,$55,$54,$53,
          $2C,$20
57        ; w
49        ; i
4E        ; n
==2505
47        ; g
0D        ; carriage return
49        ; i
4E        ; n
50        ; p
55        ; u
54        ; t
53        ; s
2C        ; ,
20        ; space
41        .BYT $41,$46, ; a
          $54,$45,$52,$20,$54,
          $48,$45,$0D,$41,$4E,
          $53,$57
46        ; f
54        ; t
45        ; e
52        ; r
20        ; space
==2515
54        ; t
48        ; h

```

```

45 ; e
0D ; carriage return
41 ; a
4E ; n
53 ; s
57 ; w
45 ; e
    .BYT $45,$52,
    $20,$54,$4F,$20,$54,
    $48,$45,$0D,$51,$55,
    $45,$53
52 ; r
20 ; space
54 ; t
4F ; o
20 ; space
54 ; t
48 ; h
==2525
45 ; e
0D ; carriage return
51 ; q
55 ; u
45 ; e
53 ; s
54 ; t
    .BYT $54,$49,
    $4F,$4E,$20,$49,$53,
    $20,$54,$59,$50,$45,
    $44,$20
49 ; i
4F ; o
4E ; n
20 ; space
49 ; i
53 ; s
20 ; space
54 ; t
59 ; y
==2535
50 ; p
45 ; e
44 ; d
20 ; space
49 ; i
    .BYT $49,$4E,
    $2C,$20,$48,$49,$54,
    $20,$54,$48,$45,$20,
    $D2,$C5
4E ; n
2C ; ,
20 ; space
48 ; h

```

```

49          ; i
54          ; t
20          ; space
54          ; t
48          ; h
45          ; e
20          ; space
==2545
D2          ; R
C5          ; E
D4          ; T
           .BYT $D4,$D5,
           $D2,$CE,$20,$4B,$45,
           $59,$2E
D5          ; U
D2          ; R
CE          ; N
20          ; space
4B          ; k
45          ; e
59          ; y
2E          ; .
==2550    MSG2          ; Message 2
C9          ; I
           .BYT $C9,$53,
           $20,$54,$48,$49,$53,
           $20,$43,$4F,$52,$52
53          ; s
20          ; space
54          ; t
48          ; h
49          ; i
53          ; s
20          ; space
43          ; c
4F          ; o
52          ; r
52          ; r
45          ; e
           .BYT $45,$43,
           $54
43          ; c
54          ; t
==255F    MSG3          ; Message 3
C9          ; I
           .BYT $C9,$4E,
           $56,$41,$4C,$49,$44,
           $20,$45,$4E,$54,$52
4E          ; n
56          ; v
41          ; a
4C          ; l
49          ; i
44          ; d

```

```

20      ; space
45      ; e
4E      ; n
54      ; t
52      ; r
59      ; y
      .BYT $59,$2C,
$20,$54,$59,$50,$45
2C      ; ,
20      ; space
54      ; t
==256F
59      ; y
50      ; p
45      ; e
==2572  MSG 4      ; Message 4
D7      ; W
      .BYT $D7,$48,
$41,$54,$20,$49,$53,
$20,$54,$48,$45,$20
48      ; h
41      ; a
54      ; t
20      ; space
49      ; i
53      ; s
20      ; space
54      ; t
48      ; h
45      ; e
20      ; space
50      ; p
      .BYT $50,$41,
$54,$49,$45,$4E,$54,
$27,$53
41      ; a
54      ; t
49      ; i
==2582
45      ; e
4E      ; n
54      ; t
27      ; '
53      ; s
==2587  MSG5      ; Message 5
C9      ; I
      .BYT $C9,$53,
$20,$54,$48,$45,$20,
$48,$45,$49,$47,$48
53      ; s
20      ; space
54      ; t
48      ; h
45      ; e

```

```

20 ; space
48 ; h
45 ; e
49 ; i
47 ; g
48 ; h
54 ; t
    .BYT $54,$20,
    $49,$4E,$20,$43,$4D
20 ; space
49 ; i
4E ; n
==2597
20 ; space
43 ; c
4D ; m
==259A MSG6 ; Message 6
C9 ; I
    .BYT $C9,$53,
    $20,$54,$48,$45,$20,
    $57,$45,$49,$47,$48
53 ; s
20 ; space
54 ; t
48 ; h
45 ; e
20 ; space
57 ; w
45 ; e
49 ; i
47 ; g
48 ; h
54 ; t
    .BYT $54,$20,
    $49,$4E,$20,$4B,$47
20 ; space
49 ; i
4E ; n
==25AA
20 ; space
4B ; k
47 ; g
==25AD MSG7 ; Message 7
C9 ; I
    .BYT $C9,$53,
    $20,$41,$20,$43,$45,
    $4E,$54,$52,$49,$46
53 ; s
20 ; space
41 ; a
20 ; space
43 ; c
45 ; e
4E ; n

```

```

54 ; t
52 ; r
49 ; i
46 ; f
55 ; u
    .BYT $55,$47,
    $41,$4C,$0D,$52,$4F,
    $4C,$4C,$45,$52,$20,
    $4F,$52
47 ; g
41 ; a
4C ; l
==25BD
0D ; carriage return
52 ; r
4F ; o
4C ; l
4C ; l
45 ; e
52 ; r
20 ; space
4F ; o
52 ; r
20 ; space
    .BYT $20,$50,
    $55,$4C,$53,$41,$54,
    $49,$4C,$45
50 ; p
55 ; u
4C ; l
53 ; s
41 ; a
==25CD
54 ; t
49 ; i
4C ; l
45 ; e
==25D1 MSG8 ; Message 8
49 ; i
    .BYT $49,$4E,
    $20,$43,$45,$4E,$54,
    $52,$49,$46,$55,$47
4E ; n
20 ; space
43 ; c
45 ; e
4E ; n
54 ; t
52 ; r
49 ; i
46 ; f
55 ; u
47 ; g

```

```

41      .BYT $41,$4C, ; a
  $2C
4C      ; l
2C      ; ,
==25E0  MSG9        ; Message 9
43      .BYT $43,$45, ; C
  $4E,$54,$52,$49,$46,
  $55,$47,$41,$4C,$20
45      ; E
4E      ; N
54      ; T
52      ; R
49      ; I
46      ; F
55      ; U
47      ; G
41      ; A
4C      ; L
20      ; space
50      .BYT $50,$55, ; P
  $4D,$50
55      ; U
4D      ; M
50      ; P
==25F0  MSG10       ; Message 10
C8      .BYT $C8,$4F, ; H
  $57,$20,$4D,$41,$4E,
  $59,$20,$52,$4F,$4C
4F      ; o
57      ; w
20      ; space
4D      ; m
41      ; a
4E      ; n
59      ; y
20      ; space
52      ; r
4F      ; o
4C      ; l
4C      .BYT $4C,$45, ; l
  $52,$53
45      ; e
52      ; r
53      ; s
==2600  MSG11       ; Message 11
D7      .BYT $D7,$48, ; W
  $41,$54,$20,$49,$53,
  $20,$54,$48,$45,$20
48      ; h
41      ; a

```

```

54 ; t
20 ; space
49 ; i
53 ; s
20 ; space
54 ; t
48 ; h
45 ; e
20 ; space
54 .BYT $54,$55, ; t
    $42,$49,$4E,$47
55 ; u
42 ; b
49 ; i
==2610
4E ; n
47 ; g
==2612 MSG12 ; Message 12
C9 .BYT $C9,$53, ; I
    $20,$54,$48,$45,$20,
    $44,$49,$41,$4D,$45
53 ; s
20 ; space
54 ; t
48 ; h
45 ; e
20 ; space
44 ; d
49 ; i
41 ; a
4D ; m
45 ; e
54 .BYT $54,$45, ; t
    $52,$20,$49,$4E
45 ; e
52 ; r
20 ; space
==2622
49 ; i
4E ; n
==2624 MSG13 ; Message 13
D7 .BYT $D7,$48, ; W
    $41,$54,$20,$49,$53,
    $20,$54,$48,$45,$20
48 ; h
41 ; a
54 ; t
20 ; space
49 ; i
53 ; s

```

```

20 ; space
54 ; t
48 ; h
45 ; e
20 ; space
41 .BYT $41,$52, ; a
  $43
52 ; r
43 ; c
==2633 MSG14 ; Message 14
C9 .BYT $C9,$53, ; I
  $20,$54,$48,$45,$20,
  $41,$52,$43,$20,$4C
53 ; s
20 ; space
54 ; t
48 ; h
45 ; e
20 ; space
41 ; a
52 ; r
43 ; c
20 ; space
4C ; l
45 .BYT $45,$4E, ; e
  $47,$54,$48
4E ; n
47 ; g
54 ; t
==2643
48 ; h
==2644 MSG15 ; Message 15
52 .BYT $52,$4F, ; R
  $4C,$4C,$45,$52,$20,
  $50,$55,$4D,$50
4F ; O
4C ; L
4C ; L
45 ; E
52 ; R
20 ; space
50 ; P
55 ; U
4D ; M
50 ; P
==264F MSG16 ; Message 16
D7 .BYT $D7,$48, ; W
  $41,$54,$20,$49,$53,
  $20,$54,$48,$45,$20
48 ; h

```

```

41 ; a
54 ; t
20 ; space
49 ; i
53 ; s
20 ; space
54 ; t
48 ; h
45 ; e
20 ; space
53 .BYT $53,$54, ; s
    $52,$4F,$4B,$45
54 ; t
52 ; r
4F ; o
==265F
4B ; k
45 ; e
==2661 MSG17 ; Message 17
50 .BYT $50,$55, ; P
    $4C,$53,$41,$54,$49,
    $4C,$45,$20,$50,$55
55 ; U
4C ; L
53 ; S
41 ; A
54 ; T
49 ; I
4C ; L
45 ; E
20 ; space
50 ; P
55 ; U
4D .BYT $4D,$50 ; M
50 ; P
==266F MSG18 ; Message 18
C6 .BYT $C6,$4F, ; F
    $52,$20,$54,$48,$45,
    $20,$46,$4F,$4C,$4C
4F ; o
52 ; r
20 ; space
54 ; t
48 ; h
45 ; e
20 ; space
46 ; f
4F ; o
4C ; l
4C ; l

```

```

4F      .BYT $4F,$57, ; o
      $49,$4E,$47,$0D,$51,
      $55,$45,$53,$54,$49,
      $4F,$4E
57      ; w
49      ; i
4E      ; n
==267F
47      ; g
0D      ; carriage return
51      ; q
55      ; u
45      ; e
53      ; s
54      ; t
49      ; i
4F      ; o
4E      ; n
53      .BYT $53,$2C, ; s
      $20,$54,$48,$45,$0D,
      $54,$45,$4D,$50,$45,
      $52,$41
2C      ; ,
20      ; space
54      ; t
48      ; h
45      ; e
==268F
0D      ; carriage return
54      ; t
45      ; e
4D      ; m
50      ; p
45      ; e
52      ; r
41      ; a
54      .BYT $54,$55, ; t
      $52,$45,$53,$20,$42,
      $45,$49,$4E,$47,$0D,
      $4D,$45
55      ; u
52      ; r
45      ; e
53      ; s
20      ; space
42      ; b
45      ; e
==269F
49      ; i
4E      ; n

```

```

47          ; g
0D         ; carriage return
4D         ; m
45         ; e
41         ; a
           .BYT $41,$53,
           $55,$52,$45,$44,$20,
           $53,$48,$4F,$55,$4C,
           $44,$20
53         ; s
55         ; u
52         ; r
45         ; e
44         ; d
20         ; space
53         ; s
48         ; h
4F         ; o
==26AF
55         ; u
4C         ; l
44         ; d
20         ; space
42         ; b
           .BYT $42,$45,
           $0D,$4E,$41,$4D,$45,
           $44,$20,$49,$4E,$20,
           $38,$20
45         ; e
0D         ; carriage return
4E         ; n
41         ; a
4D         ; m
45         ; e
44         ; d
20         ; space
49         ; i
4E         ; n
20         ; space
==26BF
38         ; 8
20         ; space
43         ; c
           .BYT $43,$48,
           $41,$52,$41,$43,$54,
           $45,$52,$53,$20,$4F,
           $52,$20
48         ; h
41         ; a
52         ; r
41         ; a
43         ; c
54         ; t

```

```

45 ; e
52 ; r
53 ; s
20 ; space
4F ; o
52 ; r
20 ; space
==26CF
4C .BYT $4C,$45, ; l
    $53,$53,$2E,$20,$20,
    $C9,$46,$20,$41,$0D,
    $54,$45
45 ; e
53 ; s
53 ; s
2E ; .
20 ; space
20 ; space
C9 ; I
46 ; f
20 ; space
41 ; a
0D ; carriage return
54 ; t
45 ; e
4D .BYT $4D,$50, ; m
    $45,$52,$41,$54,$55,
    $52,$45,$20,$50,$52,
    $4F,$42
50 ; p
==26DF
45 ; e
52 ; r
41 ; a
54 ; t
55 ; u
52 ; r
45 ; e
20 ; space
50 ; p
52 ; r
4F ; o
42 ; b
45 .BYT $45,$20, ; e
    $49,$53,$20,$20,$4E,
    $4F,$54,$20,$42,$45,
    $49,$4E
20 ; space
49 ; i
53 ; s

```

==26EF

```

20 ; space
20 ; space
4E ; n
4F ; o
54 ; t
20 ; space
42 ; b
45 ; e
49 ; i
4E ; n
47 ; g
    .BYT $47,$20,
    $55,$53,$45,$44,$2C,
    $20,$54,$48,$45,$4E,
    $20,$20

```

```

20 ; space
55 ; u
53 ; s
45 ; e
44 ; d

```

==26FF

```

2C ; ,
20 ; space
54 ; t
48 ; h
45 ; e
4E ; n
20 ; space
20 ; space
4E ; n
    .BYT $4E,$41,
    $4D,$45,$20,$54,$48,
    $45,$20,$54,$45,$4D,
    $50,$45

```

```

41 ; a
4D ; m
45 ; e
20 ; space
54 ; t
48 ; h
45 ; e

```

==270F

```

20 ; space
54 ; t
45 ; e
4D ; m
50 ; p
45 ; e
52 ; r
    .BYT $52,$41,
    $54,$55,$52,$45,$20,
    $20,$CE,$2F,$C3,$20,

```

```

$46,$4F
41 ; a
54 ; t
55 ; u
52 ; r
45 ; e
20 ; space
20 ; space
CE ; N
2F ; /
==271F
C3 ; C
20 ; space
46 ; f
4F ; o
52 ; r
    .BYT $52,$20,
    $4E,$4F,$54,$20,$43,
    $4F,$4E,$4E,$45,$43,
    $54,$45
20 ; space
4E ; n
4F ; o
54 ; t
20 ; space
43 ; c
4F ; o
4E ; n
4E ; n
45 ; e
43 ; c
==272F
54 ; t
45 ; e
44 ; d
    .BYT $44
==2732 MSG19 ; Message 19
D7 ; W
    .BYT $D7,$48,
    $41,$54,$20,$49,$53,
    $20,$54,$45,$4D,$50
48 ; h
41 ; a
54 ; t
20 ; space
49 ; i
53 ; s
20 ; space
54 ; t
45 ; e
4D ; m
50 ; p
45 ; e
    .BYT $45,$52,

```

```

    $41,$54,$55,$52,$45
52      ; r
41      ; a
54      ; t
==2742
55      ; u
52      ; r
45      ; e
==2745  MSG20      ; Message 20
C6      .BYT $C6,$4F, ; F
        $52,$20,$54,$48,$45,
        $20,$54,$45,$4D,$50
4F      ; o
52      ; r
20      ; space
54      ; t
48      ; h
45      ; e
20      ; space
54      ; t
45      ; e
4D      ; m
50      ; p
45      .BYT $45,$52, ; e
        $41,$54,$55,$52,$45,
        $0D,$44,$49,$53,$50,
        $4C,$41
52      ; r
41      ; a
54      ; t
==2755
55      ; u
52      ; r
45      ; e
0D      ; carriage return
44      ; d
49      ; i
53      ; s
50      ; p
4C      ; l
41      ; a
59      .BYT $59,$2C, ; y
        $20,$53,$45,$4C,$45,
        $43,$54,$0D,$45,$49,
        $54,$48
2C      ; ,
20      ; space
53      ; s
45      ; e
4C      ; l

```

```

==2765
45 ; e
43 ; c
54 ; t
0D ; carriage return
45 ; e
49 ; i
54 ; t
48 ; h
45 ; e
    .BYT $45,$52,
    $20,$C6,$41,$52,$45,
    $4E,$48,$45,$49,$54,
    $0D,$4F
52 ; r
20 ; space
C6 ; F
41 ; a
52 ; r
45 ; e
4E ; n
==2775
48 ; h
45 ; e
49 ; i
54 ; t
0D ; carriage return
4F ; o
52 ; r
    .BYT $52,$20,
    $C3,$45,$4C,$53,$49,
    $55,$53,$2E,$20,$20,
    $20
20 ; space
C3 ; C
45 ; e
4C ; l
53 ; s
49 ; i
55 ; u
53 ; s
2E ; .
==2785
20 ; space
20 ; space
20 ; space
==2788 MSG21 ; Message 21
C6 ; F
    .BYT $C6,$4F,
    $52,$20,$54,$48,$45,
    $20,$46,$4F,$4C,$4C
4F ; o
52 ; r

```

```

20 ; space
54 ; t
48 ; h
45 ; e
20 ; space
46 ; f
4F ; o
4C ; l
4C ; l
4F ; o
    .BYT $4F,$57,
    $49,$4E,$47,$0D,$51,
    $55,$45,$53,$54,$49,
    $4F,$4E
57 ; w
49 ; i
4E ; n
==2798
47 ; g
0D ; carriage return
51 ; q
55 ; u
45 ; e
53 ; s
54 ; t
49 ; i
4F ; o
4E ; n
53 ; s
    .BYT $53,$2C,
    $20,$54,$48,$45,$0D,
    $54,$49,$4D,$45,$52,
    $53,$20
2C ; ,
20 ; space
54 ; t
48 ; h
45 ; e
==27A8
0D ; carriage return
54 ; t
49 ; i
4D ; m
45 ; e
52 ; r
53 ; s
20 ; space
4E ; n
    .BYT $4E,$41,
    $4D,$45,$53,$20,$53,
    $48,$4F,$55,$4C,$44,
    $0D,$42
41 ; a

```

```

4D           ; m
45           ; e
53           ; s
20           ; space
53           ; s
48           ; h
==27B8
4F           ; o
55           ; u
4C           ; l
44           ; d
0D           ; carriage return
42           ; b
45           ; e
           .BYT $45,$20,
           $36,$20,$43,$48,$41,
           $52,$41,$43,$54,$45,
           $52,$53
20           ; space
36           ; 6
20           ; space
43           ; c
48           ; h
41           ; a
52           ; r
41           ; a
43           ; c
==27C8
54           ; t
45           ; e
52           ; r
53           ; s
20           ; space
           .BYT $20,$4F,
           $52,$0D,$4C,$45,$53,
           $53,$2E
4F           ; o
52           ; r
0D           ; carriage return
4C           ; l
45           ; e
53           ; s
53           ; s
2E           ; .
==27D5      MSG22      ; Message 22
D7           ; W
           .BYT $D7,$48,
           $41,$54,$20,$49,$53,
           $20,$54,$49,$4D,$45
48           ; h
41           ; a
54           ; t
20           ; space

```

```

49 ; i
53 ; s
20 ; space
54 ; t
49 ; i
4D ; m
45 ; e
52 ; r
==27E2 MSG23 ; Message 23
D7 .BYT $D7,$48, ; W
    $41,$54,$20,$49,$53,
    $20,$54,$48,$45,$20
48 ; h
41 ; a
54 ; t
20 ; space
49 ; i
53 ; s
20 ; space
54 ; t
48 ; h
45 ; e
20 ; space
43 .BYT $43,$55, ; c
    $52,$52,$45,$4E,$54
55 ; u
52 ; r
52 ; r
==27F2
45 ; e
4E ; n
54 ; t

*=4000
==4000 UPTMP ; Updates the temperatures
ADE61D LDA TMPFLG ; Gets temperature update flag
C9FF CMP #$FF ; Is it set?
D07D BNE RTURN ; If it isn't branches to return
                    from subroutine

A900 LDA #00
8DE61D STA TMPFLG ; It is so clears update flag
ADE81D LDA TMP1NC
C900 CMP #00 ; Is temperature 1 connected?
==4011
D00D BNE CHKTM2 ; If it isn't branches to check
                    temperature 2
A902 LDA #02 ; It is connected, so enables temp.
                    probe 1

8D029A STA $9A02
2026A4 JSR TNEW ; Gets ASCII value from A/D
A000 LDY #00 ; Sets screen location

```

```

208540 JSR PRTEMP ; Prints temperature 1
==4020 CHKTM2 ; Checks temperature 2
ADE91D LDA TMP2NC
C900 CMP #00 ; Is temperature 2 connected?
D00D BNE CHKTM3 ; If it isn't branches to check
temperature 3
A904 LDA #04 ; It is so enables temp. probe 2
8D029A STA $9A02
2026A4 JSR TNEW ; Gets ASCII value from A/D
A00B LDY #11 ; Sets screen location
==4031
208540 JSR PRTEMP ; Prints temperature 2
==4034 CHKTM3 ; Checks temperature 3
ADEA1D LDA TMP3NC
C900 CMP #00 ; Is temperature 3 connected?
D00D BNE CHKTM4 ; If it isn't branches to check
temperature 4
A908 LDA #08 ; It is so enables temp. probe 3
8D029A STA $9A02
2026A4 JSR TNEW ; Gets ASCII value from A/D
A02C LDY #44 ; Sets screen location
==4045
208540 JSR PRTEMP ; Prints temperature 3
==4048 CHKTM4 ; Checks temperature 4
ADEB1D LDA TMP4NC
C900 CMP #00 ; Is temperature 4 connected?
D00D BNE CHKTM5 ; If it isn't branches to check
temperature 5
A910 LDA #16 ; It is so enables temp. probe 4
8D029A STA $9A02
2026A4 JSR TNEW ; Gets ASCII value from A/D
A037 LDY #55 ; Sets screen location
==4059
208540 JSR PRTEMP ; Prints temperature 4
==405C CHKTM5 ; Checks temperature 5
ADEC1D LDA TMP5NC
C900 CMP #00 ; Is temperature 5 connected?
D00D BNE CHKTM6 ; If it isn't branches to check
temperature 6
A920 LDA #32 ; It is so enables temp. probe 5
8D029A STA $9A02
2026A4 JSR TNEW ; Gets ASCII value from A/D
A058 LDY #88 ; Sets screen location
==406D
208540 JSR PRTEMP ; Prints temperature 5
==4070 CHKTM6 ; Checks temperature 6
ADED1D LDA TMP6NC
C900 CMP #00 ; Is temperature 6 connected?
D00D BNE RTURN ; If it isn't branches to return
from subroutine

```

```

A940      LDA #64          ; It is so enables temp. probe 6
8D029A    STA $9A02
2026A4    JSR TNEW        ; Gets ASCII value from A/D
A063      LDY #99         ; Sets screen location
==4081
208540    JSR PRTEMP      ; Prints temperature 6
==4084    RTURN
60        RTS             ; Return from subroutine
==4085    PRTEMP          ; Prints a temperature
ADF31D    LDA TEMPH       ; Gets hundred's digit
C930      CMP #$30        ; Is it a zero?
D005      BNE PRONE       ; If it isn't branches to print it
A920      LDA #$20
8DF31D    STA TEMPH       ; It is so space it
==4091    PRONE           ; Prints hundred's digit
99371F    STA 7991,Y
ADF31D    LDA TEMPH
C920      CMP #$20        ; Is the hundred's digit a space?
D00C      BNE PRINTT      ; If it isn't branches to print
                        ten's digit

ADF41D    LDA TEMPT
C930      CMP #$30        ; It is so is ten's digit 0?
D005      BNE PRINTT      ; If it isn't branches to print it
==40A2
A920      LDA #$20
8DF41D    STA TEMPT       ; It is so space it
==40A7    PRINTT          ; Prints ten's digit
ADF41D    LDA TEMPT
99381F    STA 7992,Y
ADF51D    LDA TEMPU
99391F    STA 7993,Y      ; Prints unit's digit
ADF61D    LDA TEMPTH
993B1F    STA 7995,Y      ; Prints tenth's digit
==40B9
60        RTS             ; Returns from subroutine
==40BA    DISABL          ; Disables all flags and resets all
                        constants

A900      LDA #00
8DF91D    STA CHRCNT      ; Resets input character counter to
                        zero
8DF31D    STA TEMPH       ; Sets temperature hundred's digit
                        to zero
8DF41D    STA TEMPT       ; Sets temperature ten's digit to
                        zero
8DF51D    STA TEMPU       ; Sets temperature unit's digit to
                        zero
8DF61D    STA TEMPTH      ; Sets temperature tenth's digit to
                        zero
==40CB
8DC61D    STA ROLFLG      ; Roller pump not being used

```

```

8DC71D   STA PULFLG   ; Pulsatile pump not being used
8DE51D   STA PULSES   ; Sets number of pulses counted to
                zero
8DEF1D   STA DEGUNT   ; Sets degree unit to C
8DEE1D   STA MENFLG   ; Do not return to menu
8DF11D   STA HALFCT   ; Sets half second counter to zero
==40DD
8DCA1D   STA TM1FLG   ; Do not update timer 1
8DE71D   STA TMPCNT   ; Sets temperature update counter to
                zero
8DE61D   STA TMPFLG   ; Do not update temperatures
8DD11D   STA TMR1JF   ; Clears timer 1 jiffy counter to 0
A930     LDA #$30     ; Gets ascii code for 0
8DD01D   STA TMR1SL   ; Sets timer 1 second's LB to 0
==40EE
8DCF1D   STA TMR1SH   ; Sets timer 1 second's HB to 0
8DCE1D   STA TMR1ML   ; Sets timer 1 minute's LB to 0
8DCD1D   STA TMR1MH   ; Sets timer 1 minute's HB to 0
8DCC1D   STA TMR1HL   ; Sets timer 1 hour's LB to 0
8DCB1D   STA TMR1HH   ; Sets timer 1 hour's HB to 0
A900     LDA #00
==40FF
8DD21D   STA TM2FLG   ; Do not update timer 2
8DD91D   STA TMR2JF   ; Clears timer 2 jiffy counter to 0
A930     LDA #$30     ; Gets ascii code for 0
8DD81D   STA TMR2SL   ; Sets timer 2 second's LB to 0
8DD71D   STA TMR2SH   ; Sets timer 2 second's HB to 0
8DD61D   STA TMR2ML   ; Sets timer 2 minute's LB to 0
==4110
8DD51D   STA TMR2MH   ; Sets timer 2 minute's HB to 0
8DD41D   STA TMR2HL   ; Sets timer 2 hour's LB to 0
8DD31D   STA TMR2HH   ; Sets timer 2 hour's HB to 0
A900     LDA #00
8DDA1D   STA TM3FLG   ; Do not update timer 3
8DE11D   STA TMR3JF   ; Clears timer 3 jiffy counter to 0
==4121
A930     LDA #$30     ; Gets ascii code for 0
8DE01D   STA TMR3SL   ; Sets timer 3 second's LB to 0
8DDF1D   STA TMR3SH   ; Sets timer 3 second's HB to 0
8DDE1D   STA TMR3ML   ; Sets timer 3 minute's LB to 0
8DDD1D   STA TMR3MH   ; Sets timer 3 minute's HB to 0
8DDC1D   STA TMR3HL   ; Sets timer 3 hour's LB to 0
==4132
8DDB1D   STA TMR3HH   ; Sets timer 3 hour's HB to 0
A900     LDA #00
8DED1D   STA TMP6NC   ; Temperature probe 6 is connected
8DE31D   STA CLKFLG   ; Do not update clock on screen
8DE41D   STA CLKJIF
8DE21D   STA PRCLKF

```

```
==4143
8DC81D  STA  CENFLG      ; Centrifugal pump is not being used
8DC91D  STA  CENCNT
8DC51D  STA  PMPFLG    ; Do not update pump output
8DEF1D  STA  DEGUNT    ; Sets degree unit to C
8DE81D  STA  TMP1NC    ; Temperature probe 1 is connected
8DE91D  STA  TMP2NC    ; Temperature probe 2 is connected
==4155
8DEA1D  STA  TMP3NC    ; Temperature probe 3 is connected
8DEB1D  STA  TMP4NC    ; Temperature probe 4 is connected
8DEC1D  STA  TMP5NC    ; Temperature probe 5 is connected
A940    LDA  #$40      ; Disables interrupt enable register
8D0E98  STA  IO1IER
60      RTS           ; Returns from subroutine
```

APPENDIX B

Screen Displays

This appendix shows the title and monitor screens displayed following the calls to subroutines SCREN1 and SCREN2, respectively.

```
*****  
* * * * *  
* OPEN HEART SURGERY *  
* * * * *  
* PATIENT MONITOR *  
* * * * *  
* O BLOOD FLOW RATE *  
* * * * *  
* O SIX TEMPERATURES *  
* * * * *  
* O THREE OPERATING *  
* TIMES *  
* * * * *  
*****
```

Figure B1. Title Screen Display after SCREN1 Subroutine Call

```

HEIGHT =      . cm
        =      . in
WEIGHT =      . kg
        =      . lb
BODY SURFACE AREA
        =      . m**2

OUTPUT =      . ml/min
BLOOD FLOW RATE
        =      . ml/min/kg
        =      . ml/min/m**2
TEMPERATURES
1-      . C      2-      . C
3-      . C      4-      . C
5-      . C      6-      . C
CURRENT TIME   :   :
TIME1         :   :
TIME2         :   :
TIME3         :   :

```

Figure B2. Monitor Screen Display after SCREN2 Subroutine Call

## APPENDIX C

### VIC 20 Power-Up Initialization Sequence

The VIC 20 power-up initialization routine is listed in this appendix.

<u>Hex Address</u>	<u>Op Code</u>	<u>Comment</u>
FD22	LDX #\$FF	;
	SEI	;
	TXS	;
		Set stack pointer to \$00FF
	CLD	;
	JSR \$FD3F	;
		Test for Auto-Start sequence
	BNE \$FD2F	;
		If not found, continue
	JMP (\$A000)	;
		If found, jump to user routine
FD2F	JSR \$FD8D	;
	JSR \$FD52	;
	JSR \$FDF9	;
	JSR \$E518	;
	CLI	;
	JMP (\$C000)	;
		Enable Interrupts BASIC Area

## APPENDIX D

This appendix shows the layout of the interface circuit board. All connections were made using wire wrap on tin or gold plated sockets. The sockets were attached to perf board using silicon rubber.

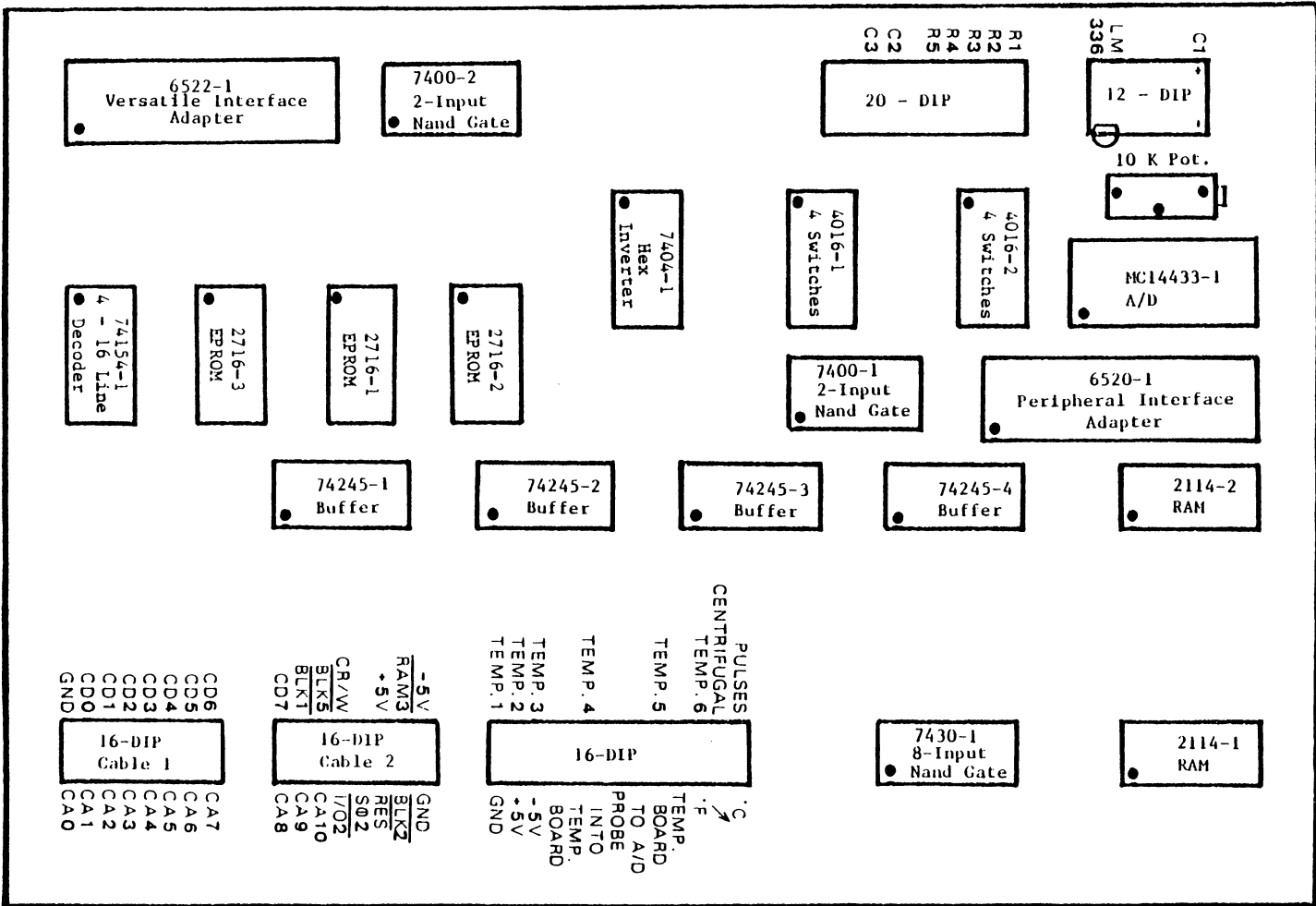


Figure D1. Interface Circuit Board Layout

## APPENDIX E

This appendix shows the VIC 20 schematic. It should be noted, however, that the coding for the components shown in the schematic does not always agree with the coding on the the actual printed circuit board.

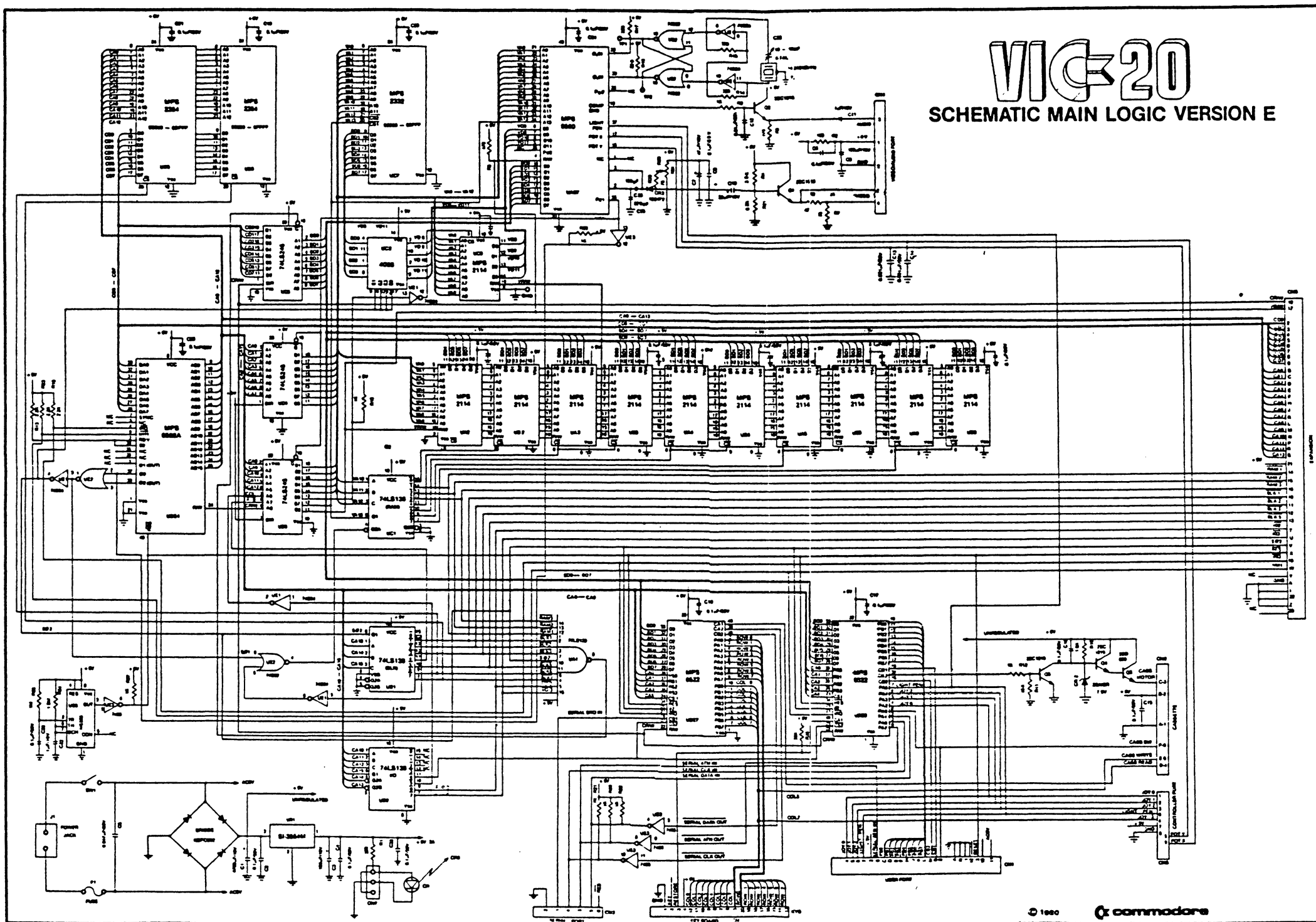


Figure E1. VIC 20 Schematic

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the scanned document**