

List of Illustrations

Figure 1. Block diagram of a VSI fed PMSM drive	14
Figure 2. VSI inverter module models in stationary and rotating coordinates	15
Figure 3. DQ axis orientation in a two pole PMSM	19
Figure 4. PMSM module dq0 models	20
Figure 5. Three-phase filter module models in stationary and rotating coordinates	22
Figure 6. Two-stage cascade controller module model	24
Figure 7. Modulator module models in stationary and rotating coordinates.....	25
Figure 8. Interface blocks for a) Three-phase/d-q module connection and b) Transformation from d-q to α - β coordinates	27
Figure 9. VSI three-phase average modeling - signal transformations	29
Figure 10. Measurement setup for the system impedance evaluation	32
Figure 11. Measurement scheme for current loop transfer functions	34
Figure 12. Model comparison with measurements: a) PMSM drive current control-to-output and b) Sampling delay transfer functions	35
Figure 13. Block diagram of the APU starting mechanism	38
Figure 14. Typical load torque profile on the PMSM shaft during the APU start-up	39
Figure 15. Two stage cascade controller block diagram	41
Figure 16. Forbidden zones interpreted with Nyquist diagram	44
Figure 17. Forbidden zones interpreted with Bode plots	45
Figure 18. VSI fed PMSM drive (plant) d-q average model with a VSI output filter	49
Figure 19. Decoupled PMSM drive small-signal block diagram	52
Figure 20. Decoupling scheme for the PMSM drive with a VSI output filter	54
Figure 21. Dq small-signal average model of the linearized VSI-fed PMSM system with a three-phase EMI filter and without back emf elimination	55
Figure 22. Reference motor torque and speed controller adjustments to active load for the speed loop stabilization	68
Figure 23. Natural output characteristics of a PMSM for series and parallel winding connections and $i_d=0$	70

Figure 24. PMSM current limit d-q polar diagram	72
Figure 25. PMSM voltage limit d-q polar diagram	73
Figure 26. PMSM voltage d-q vector diagram for a) $i_d=0$ and b) $i_d \neq 0$	76
Figure 27. Block diagram of a variable limit PI regulator (VLPI)	78
Figure 28. PMSM voltage d-q vector diagram for CVCP flux-weakening control	85
Figure 29. PMSM voltage d-q vector diagram for CCCP flux-weakening control	88
Figure 30. PMSM voltage d-q vector diagram for OCV flux-weakening control	91
Figure 31. Decoupling Bode Diagrams	100
Figure 32. Current loop gain transfer functions: a) full decoupling and equivalent DC motor with b) unknown load and c) extracted load control methods	101
Figure 33. I_q current loop-gain transfer functions - Nyquist diagrams	102
Figure 34. Closed current loop transfer functions	103
Figure 35. Speed loop transfer functions: a) Nyquist plots and b) Bode plots	104
Figure 36. Speed and current step responses.....	106
Figure 37. “Full-length” flux-weakening: voltage and current d-q polar diagrams	108
Figure 38. “Full-length” flux-weakening: voltage and current phase shifts	109
Figure 39. “Full-length” flux-weakening: voltage and current time diagrams	110
Figure 40. “Full-length” flux-weakening: input power diagrams	111
Figure 41. “Full-length” flux-weakening: motor torque and speed diagrams	113
Figure 42. Full start-up: voltage and current d-q polar diagrams	115
Figure 43. Full start-up: voltage and current time diagrams	116
Figure 44. Full start-up: input power diagrams	117
Figure 45. Full start-up: motor torque and speed profiles	118
Figure A.1 Park’s transformation from three-phase to rotating dq0 coordinate system	129
Figure A.2 Space vector modulation basic principles	131
Figure C.1 Simulation (Simulink) hierarchical model for control design of PMSM drive	143