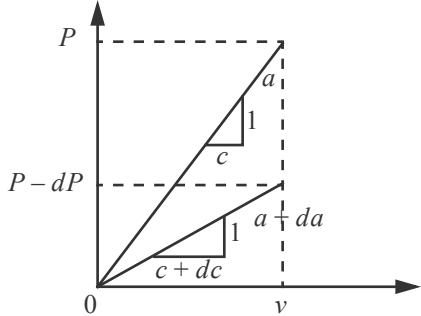


**(a)**  $P = \text{constant}$



**(b)** Fixed grips